

# CONVEX BODIES WITH A DENSE PROJECTIVE ORBIT

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ABSTRACT. For every  $n$ , there exists an  $n$ -dimensional convex body such that the set of its images under projective transformations is dense.

Denote by  $\mathcal{K}_n$  the space of nonempty convex compact subsets of the Euclidean space  $\mathbf{R}^n$ . When equipped with the Hausdorff distance,  $\mathcal{K}_n$  is a complete metric space [2, Chapter 1.8].

An homography on  $\mathbf{R}^n$  is a partially defined map of the form  $x \mapsto A(x)/f(x)$ , where  $A : \mathbf{R}^n \rightarrow \mathbf{R}^n$  and  $f : \mathbf{R}^n \rightarrow \mathbf{R}$  are affine maps of maximal rank. If we think of  $\mathbf{R}^n$  as a subset of the projective plane  $\mathbf{P}^n$ , every homography extends to an automorphism of  $\mathbf{P}^n$ . For  $K \in \mathcal{K}_n$ , we consider the *projective orbit* of  $K$

$$\text{Orb}(K) := \{\Phi(K) : \Phi \text{ homography which is well-defined on } K\} \subset \mathcal{K}_n.$$

**Theorem 1.** *For any  $n \geq 2$ , there is a convex body  $K \in \mathcal{K}_n$  with the property that  $\text{Orb}(K)$  is dense in  $\mathcal{K}_n$ .*

Theorem 1 can be reformulated without mentioning explicitly homographies. Identify  $\mathbf{R}^n$  with the hyperplane  $H := \{x_{n+1} = 1\} \subset \mathbf{R}^{n+1}$  and consider the  $(n+1)$ -dimensional cone  $\mathcal{C} := \{(tx, t) : t \geq 0, x \in K\}$ , with  $K$  given by Theorem 1. The cone  $\mathcal{C}$  has the following property: the family of convex compact subsets which appear as  $T(\mathcal{C}) \cap H$  for some  $T \in \text{GL}(n+1, \mathbf{R})$  is dense in  $\mathcal{K}_n$ .

We show actually that a generic  $K$  (in the Baire category sense) satisfies the conclusion of Theorem 1 (for a survey of Baire category methods in convexity, see [1]). The key point is the following lemma.

**Lemma 2.** *Let  $U, V$  be two non-empty open subsets in  $\mathcal{K}_n$ . Then there exists  $K \in U$  such that  $\text{Orb}(K)$  intersects  $V$ .*

It is easy to derive Theorem 1 from Lemma 2. For every nonempty open subset  $V \subset \mathcal{K}_n$ , the set  $\{K \in \mathcal{K}_n : \text{Orb}(K) \cap V \neq \emptyset\}$  is open (this is easy) and dense (this follows from Lemma 2). Since  $\mathcal{K}_n$  is second-countable, Baire category theorem implies that the set  $\{K \in \mathcal{K}_n : \text{Orb}(K) \text{ dense}\}$  is a dense  $G_\delta$  subset of  $\mathcal{K}_n$ ; in particular it is not empty.

Let  $B(0, 1)$  be the unit Euclidean ball, and consider also the family of ellipsoids

$$\mathcal{E}_t := \{(x_1, \dots, x_n) \in \mathbf{R}^n : (x_1 - (1+t))^2 + tx_2^2 + \dots + tx_n^2 \leq t^2\}$$

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which converge to  $\{(1, 0, \dots, 0)\}$  as  $t$  tends to 0. For  $0 < t < 1$ , we define an homography  $\Phi_t$  by

$$\Phi_t(x_1, \dots, x_n) = \frac{(1 + 3t - (1 + t)x_1, 2tx_2, \dots, 2tx_n)}{1 + t - (1 - t)x_1}.$$

The following properties of  $\Phi_t$  can be checked by elementary computations

- (1)  $\Phi_t$  is defined on  $\text{conv}(B(0, 1) \cup \mathcal{E}_t)$ ,
- (2)  $\Phi_t = \Phi_t^{-1}$ ,
- (3)  $\Phi_t(B(0, 1)) = \mathcal{E}_t$ , and therefore  $\Phi_t(\mathcal{E}_t) = B(0, 1)$ .

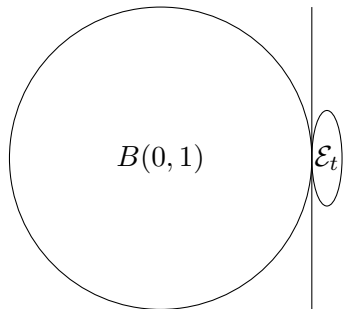


FIGURE 1. The unit disk  $B(0, 1)$  and the ellipse  $\mathcal{E}_t$  for  $t = 1/10$ . The involutive homography  $\Phi_t$  exchanges  $\mathcal{E}_t$  and  $B(0, 1)$ , has the line  $x = 1$  as a set of fixed points, and sends the dotted line  $x = \frac{1+t}{1-t}$  to infinity.

*Proof of Lemma 2.* Fix  $K_1 \in U$  and  $K_2 \in V$ . By replacing  $K_1$  and  $K_2$  with an affine image, we may assume that

$$(1, 0, \dots, 0) \in K_i \subset B(0, 1).$$

For  $t > 0$ , consider the convex body  $L(t) := \text{conv}(K_1 \cup \Phi_t(K_2))$ . Since  $\lim_{t \rightarrow 0} L(t) = K_1$ , we have  $L(t) \in U$  for  $t$  small enough. Similarly,  $\Phi_t(L(t)) = \text{conv}(\Phi_t(K_1) \cup K_2)$  belongs to  $V$  for  $t$  small enough. Therefore, for  $t$  small enough, the choice  $K = L(t)$  satisfies the conclusion of the lemma.  $\square$

#### REFERENCES

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- [2] Rolf Schneider. *Convex bodies: the Brunn-Minkowski theory*, volume 151 of *Encyclopedia of Mathematics and its Applications*. Cambridge University Press, Cambridge, expanded edition, 2014.