

ABOUT THE DYNAMICAL YANG-BAXTER EQUATION(S)

AN INVITATION TO DYNAMICAL QUANTUM GROUPS

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ABSTRACT. These are the notes of a short talk given on some aspects of the dynamical Yang-Baxter equation during the meeting of the *GDR "Tresses"* in Clermont-Ferrand (September 3-6, 2006). It is largely inspired from the lecture notes of ICM talks by Felder [2] and Etingof [1].

I thank the organizers for giving me the occasion to give this talk, and for the excellent atmosphere during the conference.

1. THE (QUANTUM) DYNAMICAL YANG-BAXTER EQUATION

Let \mathfrak{h} be a finite dimensional abelian Lie algebra, V a semi-simple \mathfrak{h} -module and $\hbar \in \mathbb{C}^\times$.

For any (meromorphic) function $R(\lambda, z) : \mathfrak{h}^* \times \mathbb{C} \rightarrow \text{End}_{\mathfrak{h}}(V \otimes V)$, the *quantum dynamical Yang-Baxter equation* (QDYBE) with step \hbar reads:

$$\begin{aligned} R^{1,2}(\lambda - \hbar h^{(3)}, z_1 - z_2) R^{1,3}(\lambda, z_1 - z_3) R^{2,3}(\lambda - \hbar h^{(1)}, z_2 - z_3) \\ = R^{2,3}(\lambda, z_2 - z_3) R^{1,3}(\lambda - \hbar h^{(2)}, z_1 - z_3) R^{1,2}(\lambda, z_1 - z_2). \end{aligned}$$

Here we adopt the *dynamical notation*: $R^{1,2}(\lambda - \hbar h^{(3)}, z)$ is defined by

$$R^{1,2}(\lambda - \hbar h^{(3)}, z)(v_1 \otimes v_2 \otimes v_3) := R(\lambda - \hbar \mu, z)(v_1 \otimes v_2) \otimes v_3,$$

where $v_1, v_2 \in V$, $v_3 \in V[\mu]$, and $V[\mu]$ denotes the weight subspace of weight μ .

1.1. An example motivated by quantum integrable models. In [2] Felder proved that any solution of the QDYBE produces solutions of the famous star-triangle relation that is useful to construct solvable models of statistical mechanics. The following example produces the so-called $A_{n-1}^{(1)}$ face model: let V be the vector representation of \mathfrak{gl}_n , \mathfrak{h} the subalgebra of diagonal matrices, and denote by E_{ij} the elementary matrix defined by $(E_{ij})_{kl} = \delta_{ik}\delta_{jl}$. Then we write $\lambda = (\lambda_1, \dots, \lambda_n) \in \mathfrak{h}^*$, with $\lambda_i = E_{ii}^*$, and define

$$R(\lambda, z) = \sum_{i=1}^n E_{ii} \otimes E_{ii} + \sum_{1 \leq i \neq j \leq n} \left(\frac{\theta(\lambda_i - \lambda_j + \hbar)\theta(z)}{\theta(\lambda_i - \lambda_j)\theta(z - \hbar)} E_{ii} \otimes E_{jj} \frac{\theta(z - \lambda_j + \lambda_i)\theta(\hbar)}{\theta(z - \hbar)\theta(\lambda_j - \lambda_i)} E_{ij} \otimes E_{ji} \right),$$

where $\theta(z) := \theta(z|\tau)$ is the standard theta-function, with normalization $\partial_z \theta(0) = 1$. It is a solution of the QDYBE.

Remark. One can replace $\theta(z)$ by $\sin(z)$ or z . In these two last cases taking the limit $z \rightarrow \infty$ one obtains new solutions of the QDYBE, that are z -independent.

1.2. An example coming from representation theory. We follow [1]. Let \mathfrak{g} be a semi-simple Lie algebra over \mathbb{C} with Cartan subalgebra \mathfrak{h} . For any $\lambda \in \mathfrak{h}^*$ let us denote by M_λ the corresponding Verma module with highest weight λ , v_λ its highest weight vector, and v_λ^* the lowest weight vector of its dual module.

To any intertwining operator $\Phi : M_\lambda \rightarrow M_\mu \otimes V$, where V is a finite dimensional \mathfrak{g} -module and $\lambda, \mu \in \mathfrak{h}^*$, we associate its *expectation value* $\langle \Phi \rangle := v_\mu^*(\Phi v_\lambda) \in V[\lambda - \mu]$. Assume that M_μ be irreducible (this holds for generic μ). Then it is known that the expectation value defines an isomorphism $\text{Hom}_{\mathfrak{g}}(M_\lambda, M_\mu \otimes V) \rightarrow V[\lambda - \mu]$ for any $\lambda \in \mathfrak{h}^*$ and any finite dimensional \mathfrak{g} -module V . Therefore one can define the intertwining operator Φ_λ^v such that $\langle \Phi_\lambda^v \rangle = v$ ($v \in V$ of weight $|v| = \lambda - \mu$).

Let V, W be finite dimensional \mathfrak{g} -modules and consider $v \in V$, $w \in W$ homogeneous vectors. The expectation value $\langle \Phi_\lambda^{v,w} \rangle$ of the composition of two intertwining operators

$$\Phi_\lambda^{v,w} := (\Phi_{\lambda-|w|}^v \otimes \text{id}) \circ \Phi_\lambda^w : M_\lambda \rightarrow M_{\lambda-|v|-|w|} \otimes V \otimes W$$

is a bilinear function of v and w . Therefore there exists $J_{V,W}(\lambda) \in \text{End}_{\mathfrak{h}}(V \otimes W)$ such that $\langle \Phi_\lambda^{v,w} \rangle = J_{V,W}(\lambda)(v \otimes w)$.

Then one can prove that $J_{V,W}(\lambda)$ is an invertible meromorphic function of λ , and satisfies the *dynamical twists equation* (DTE):

$$J_{V_1 \otimes V_2, V_3}(\lambda) J_{V_1, V_2}(\lambda - h^{(3)}) = J_{V_1, V_2 \otimes V_3}(\lambda) J_{V_2, V_3}(\lambda).$$

The DTE implies that $R(\lambda) := J_{V,V}(\lambda)^{-1} J_{V,V}^{2,1}(\lambda)$ is a (z -independent) solution of the QDYBE with step 1.

1.3. Categorical interpretation of the DTE. Let $\mathcal{C} = \text{Rep}(U\mathfrak{g})$ and $\mathcal{M} = \text{Rep}(\text{Mer}(\mathfrak{h}^*))$. For any finite dimensional \mathfrak{g} -module V one has an algebra morphism $\text{Mer}(\mathfrak{h}^*) \rightarrow \text{End}(V) \otimes \text{Mer}(\mathfrak{h}^*)$; $f(\lambda) \mapsto f(\lambda - h)$. Therefore one has a functor

$$\otimes : \mathcal{C} \times \mathcal{M} \rightarrow \mathcal{M}.$$

Let us now interpret $J_{V,W}(\lambda)$ as a natural ‘‘associativity isomorphism’’

$$V \otimes (W \otimes M) \xrightarrow{\sim} (V \otimes W) \otimes M \quad (V, W \in \mathcal{C}, M \in \mathcal{M}).$$

Then the DTE implies that J defines a structure of a \mathcal{C} -module category on \mathcal{M} (in fact it is equivalent). Namely, the following diagram commutes:

$$\begin{array}{ccc} - \otimes (- \otimes (- \otimes \bullet)) & \xrightarrow{1 \otimes J_{V_2, V_3}(\lambda)} & - \otimes ((- \otimes -) \otimes \bullet) & \xrightarrow{J_{V_1, V_2 \otimes V_3}(\lambda)} & (- \otimes (- \otimes -)) \otimes \bullet \\ \downarrow J_{V_1, V_2}(\lambda - h^{(3)}) & & & & \parallel \\ (- \otimes -) \otimes (- \otimes \bullet) & \xrightarrow{J_{V_1 \otimes V_2, V_3}(\lambda)} & & & ((- \otimes -) \otimes -) \otimes \bullet \end{array}$$

2. CLASSICAL LIMIT

If $R(\lambda, z) = \text{id}_{V \otimes V} - \hbar r(\lambda, z) + O(\hbar^2) \in \text{Mer}(\mathfrak{h}^* \times \mathbb{C}, \text{End}_{\mathfrak{h}}(V \otimes V))$ is a solution of the QDYBE with step \hbar , then $r(\lambda, z)$ satisfies the *classical dynamical Yang-Baxter equation* (CDYBE):

$$\begin{aligned} & [r^{1,2}(\lambda, z_1 - z_2), r^{2,3}(\lambda, z_2 - z_3)] + [r^{1,2}(\lambda, z_1 - z_2), r^{1,3}(\lambda, z_1 - z_3)] + [r^{1,3}(\lambda, z_1 - z_3), r^{2,3}(\lambda, z_2 - z_3)] \\ & + \sum_{\nu} (h_{\nu}^{(1)} \frac{\partial r^{2,3}}{\partial \lambda^{\nu}}(\lambda, z_2 - z_3) - h_{\nu}^{(2)} \frac{\partial r^{1,3}}{\partial \lambda^{\nu}}(\lambda, z_1 - z_3) + h_{\nu}^{(3)} \frac{\partial r^{1,2}}{\partial \lambda^{\nu}}(\lambda, z_1 - z_2)) = 0 \end{aligned}$$

2.1. Relation to integrable systems. In [2] Felder proved that given a solution of the CDYBE one can define a compatible system of differential equations as follows:

$$\partial_{z_i} F(z_1, \dots, z_n) = \sum_{j|j \neq i} r^{i,j}(\lambda, z_i - z_j) \cdot F - \sum_{\nu} h_{\nu}^{(i)} \cdot \frac{\partial F}{\partial \lambda^{\nu}} \quad (i = 1, \dots, n),$$

where $F(z_1, \dots, z_n) : \mathbb{C}^n \rightarrow V^{\otimes n}$.

2.2. The universal classical dynamical Yang-Baxter equation and infinitesimal braids on the torus.

Definition. The Lie algebra of *infinitesimal (pure) braids on the torus* is the graded Lie algebra generated by x_i 's and y_i 's ($1 \leq i \leq n$) in degree 1 and t_{ij} 's ($1 \leq i \neq j \leq n$) in degree 2, with relations

$$(1) \quad [x_i, x_j] = [y_i, y_j] = [x_i, y_j] = 0 \text{ and } [x_i, y_j] = t_{ij} = [x_j, y_i] \quad (i \neq j);$$

$$(2) \quad [x_i, y_i] = - \sum_{j:j \neq i} t_{ij} \quad (\forall i); \quad [x_i, t_{jk}] = [y_i, t_{jk}] = 0 \quad (\#\{i, j, k\} = 3).$$

One can easily check that the usual infinitesimal pure braid relations on the plane ($t_{ij} = t_{ji}$, $[t_{ij}, t_{ik} + t_{jk}] = 0$, $[t_{ij}, t_{kl}] = 0$) are consequences of (1-2).

Let $i \neq j \in \{1, \dots, n\}$. There is a Lie algebra morphism $\mathfrak{t}_{1,2} \rightarrow \mathfrak{t}_{1,n}$; $\alpha \mapsto \alpha^{i,j}$ defined by $x_k^{i,j} = \delta_{1k} x_i + \delta_{2k} x_j$ and $y_k^{i,j} = \delta_{1k} y_i + \delta_{2k} y_j$ ($k = 1, 2$).

For a (meromorphic) function $r(z) : \mathbb{C} \rightarrow \widehat{\mathfrak{t}_{1,2}}$, the *universal CDYBE* reads

$$\begin{aligned} & [r(z_1 - z_2)^{1,2}, r(z_2 - z_3)^{2,3}] + [r(z_1 - z_2)^{1,2}, r(z_1 - z_3)^{1,3}] + [r(z_1 - z_3)^{1,3}, r(z_2 - z_3)^{2,3}] \\ & = [y_1, r(z_2 - z_3)^{2,3}] + [y_2, r(z_1 - z_3)^{1,3}] + [y_3, r(z_1 - z_2)^{1,2}]. \end{aligned}$$

Here $\widehat{}$ means ‘‘the degree completion of’’ and the universal CDYBE takes place in $\widehat{\mathfrak{t}_{1,3}}$. It implies that the following system of differential equations is compatible:

$$\partial_{z_i} F(z_1, \dots, z_n) = \sum_{j|j \neq i} r(z_i - z_j)^{i,j} \cdot F - y_i \cdot F \quad (i = 1, \dots, n),$$

where $F(z_1, \dots, z_n) : \mathbb{C}^n \rightarrow \widehat{\mathfrak{t}_{1,n}}$.

Example ([3]). Let $\theta(z) = \theta(z|\tau)$ be, as before, the standard theta-function. Then

$$r(z) = \left(\frac{\theta(x_1 + z)}{\theta(x_1)\theta(z)} - \frac{1}{x_1} \right) (t_{12})$$

is a solution of the universal CDYBE. The system of differential equations that we obtain actually defines a holomorphic flat connection on a principal $\exp(\widehat{\mathfrak{t}_{1,n}})$ -bundle over the configuration space of n points on the elliptic curve $E_{\tau} = \mathbb{C}/(\mathbb{Z} + \tau\mathbb{Z})$. Then one has a group homomorphism $PB_{1,n} \rightarrow \exp(\widehat{\mathfrak{t}_{1,n}})$, where $PB_{1,n}$ denotes the pure braid group of the torus. If we denote by $\mathfrak{pb}_{1,n}$ be the Malcev Lie algebra of $PB_{1,n}$ (i.e. the Lie algebra of its pronipotent completion), then it induces a Lie algebra morphism $\mathfrak{pb}_{1,n} \rightarrow \widehat{\mathfrak{t}_{1,n}}$.

Proposition ([3]). It is an isomorphism.

REFERENCES

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