

Complexité des algorithmes

Méthode du simplexe

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- 1. Algorithmes de tri

```
[ > restart:
[ > Seed:=randomize():
[ > tri_insert:=proc(T,n) # tri de T[1..n] par insertion
    local i,j,aux;
    for i from 2 to n do
        aux:=T[i];
        for j from i-1 by -1 to 1 while T[j]>aux do
            T[j+1]:=T[j]
        end do;
        T[j+1]:=aux;
    end do
end proc:
[ > tri_shell:=proc(T,n) # tri de T[1..n] par la méthode Shell
    local h,i,j,aux;
    h:=iquo(n,2);
    while h>=1 do
        for i from h+1 to n do
            aux:=T[i];
            for j from i-h by -h to 1 while T[j]>aux do
                T[j+h]:=T[j]
            end do;
            T[j+h]:=aux
        od;
        h:=iquo(h,2)
    end do;
end proc:
[ > tri_rapide:=proc(T,n) # tri de T[1..n] par quicksort
    local pivot,s1,s2,T1,T2,i,j,k;
    if n<=1 then return(T) end if;
    pivot:=T[1];
    j:=0;k:=0;
    for i from 2 to n do
        if T[i]<=pivot then
            j:=j+1;T1[j]:=T[i]
        else
            k:=k+1;T2[k]:=T[i]
        end if
    end do;
    tri_rapide(T1,j);
    tri_rapide(T2,k);
```

```

        for i to j do T[i]:=T1[i] end do;
        T[j+1]:=pivot;
        for i to k do T[i+j+1]:=T2[i] end do;
    end proc;
[ > nb:=10000;
                                     10000
[ > listedepart:=seq(rand(),i=1..nb)];
[ > for i to nb do T[i]:=listedepart[i]; U[i]:=T[i]; V[i]:=T[i]
    end do;
[ > time(tri_insert(T,nb));
                                     56.624
[ > time(tri_shell(U,nb));
                                     0.744
[ > time(tri_rapide(V,nb));
                                     0.765
[ > time(sort(listedepart)); # fonction de tri prédéfinie
                                     0.010
[ >

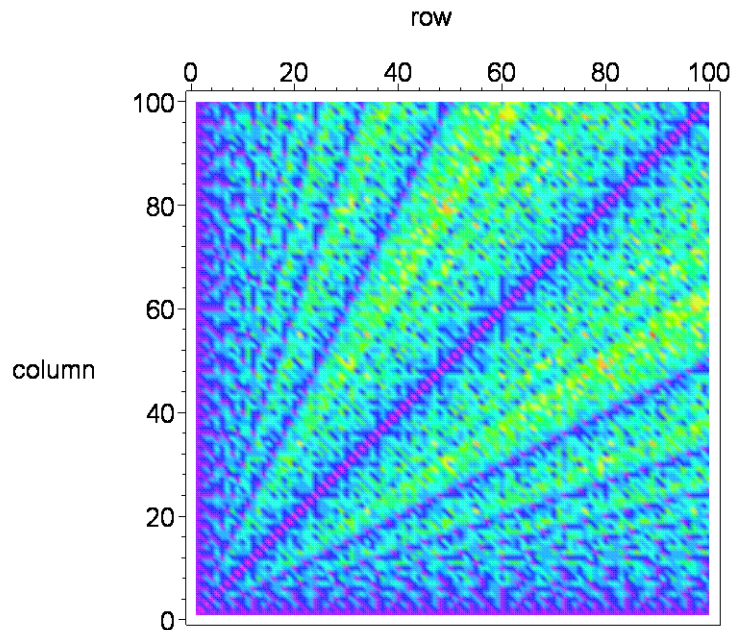
```

2. Algorithme d'Euclide

```

[ > restart:
[ > dist:=proc(i,j)
    local a,b,r,cpt;
    cpt:=0;
    if i<>j then
        a:=max(i,j);b:=min(i,j);r:=irem(a,b);cpt:=cpt+1;
        while r<>0 do a:=b;b:=r;r:=irem(a,b);cpt:=cpt+1 end do
    end if;
    cpt
end proc;
[ > n:=100:
[ > M:=matrix(n,n):
[ > for i to n do for j to n do M[i,j]:=dist(i,j) end do end do:
[ > with(plots):
[ > matrixplot(M,orientation=[-90,0],shading=zhue,style=patchnogr
    id,axes=boxed);

```



On pourrait démontrer que les deux raies de complexité maximale ont pour pentes ϕ et $1/\phi$, où ϕ est le nombre d'Or.

>

- 3. Méthode du simplexe

- 3.1 Problème de l'artisan : solution graphique

```
[ > restart:
[ > with(plots):
[ > grille:=implicitplot({seq(X1=i,i=-0..20),seq(X2=j,j=0..15)
[   },X1=-1..20,X2=-1..15,grid=[2,2],color=green):
[ > D1:=implicitplot(X1+3*X2=18,X1=-1..20,X2=-1..15,grid=[2,2]
[   ,color=blue,thickness=2):
[ > D2:=implicitplot(X1+X2=8,X1=-1..20,X2=-1..15,grid=[2,2],co
[   lor=tan,thickness=2):
[ > D3:=implicitplot(2*X1+X2=14,X1=-1..20,X2=-1..15,grid=[2,2]
[   ,color=brown,thickness=2):
[ > Delta:=Z->implicitplot(20*X1+30*X2=Z,X1=-1..20,X2=-1..15,g
[   rid=[2,2],color=red,thickness=4):
[ > G:=seq(display(grille,D1,D2,D3,Delta(2*k),scaling=constrai
```

```

ned),k=0..105):
> display(G,scaling=constrained,insequence=true);

```



```

>

```

3.2 Résolution algébrique

```

> restart:
> eqs1:={x[3]=18-x[1]-3*x[2],x[4]=8-x[1]-x[2],x[5]=14-2*x[1]-x[2]};
      {x3 = 18 - x1 - 3 x2, x4 = 8 - x1 - x2, x5 = 14 - 2 x1 - x2}
> z1:=20*x[1]+30*x[2];
      20 x1 + 30 x2
> eqs2:=solve(eqs1,{x[2],x[4],x[5]});
      {x2 = -1/3 x3 + 6 - 1/3 x1, x4 = 2 - 2/3 x1 + 1/3 x3, x5 = 8 - 5/3 x1 + 1/3 x3}
> z2:=simplify(z1,eqs2);
      10 x1 + 180 - 10 x3
> eqs3:=solve(eqs2,{x[1],x[2],x[5]});
      {x1 = -3/2 x4 + 3 + 1/2 x3, x2 = -1/2 x3 + 5 + 1/2 x4, x5 = 3 + 5/2 x4 - 1/2 x3}
> z3:=simplify(z2,eqs3);
      210 - 5 x3 - 15 x4
>

```

3.3 Méthode des tableaux

```

> restart:
> with(LinearAlgebra):

```

```

> pivotage:=proc(T,r,s) # pivotage en r,s
  local n,i,pivot,U;
  U:=copy(T);
  n:=RowDimension(U);pivot:=U[r,s];
  for i to n do
    if i<>r then
      U:=RowOperation(U,[i,r],-T[i,s]/pivot)
    end if
  end do;
  U:=RowOperation(U,r,1/pivot);
  U
end:
> T1:=Matrix([[18,1,3,1,0,0],[8,1,1,0,1,0],[14,2,1,0,0,1],[z
,20,30,0,0,0]]);

```

$$T1 := \begin{bmatrix} 18 & 1 & 3 & 1 & 0 & 0 \\ 8 & 1 & 1 & 0 & 1 & 0 \\ 14 & 2 & 1 & 0 & 0 & 1 \\ z & 20 & 30 & 0 & 0 & 0 \end{bmatrix}$$

```

> T2:=pivotage(T1,1,3);

```

$$T2 := \begin{bmatrix} 6 & \frac{1}{3} & 1 & \frac{1}{3} & 0 & 0 \\ 2 & \frac{2}{3} & 0 & -\frac{1}{3} & 1 & 0 \\ 8 & \frac{5}{3} & 0 & -\frac{1}{3} & 0 & 1 \\ z-180 & 10 & 0 & -10 & 0 & 0 \end{bmatrix}$$

```

> T3:=pivotage(T2,2,2);

```

$$T3 := \begin{bmatrix} 5 & 0 & 1 & \frac{1}{2} & -\frac{1}{2} & 0 \\ 3 & 1 & 0 & -\frac{1}{2} & \frac{3}{2} & 0 \\ 3 & 0 & 0 & \frac{1}{2} & -\frac{5}{2} & 1 \\ z-210 & 0 & 0 & -5 & -15 & 0 \end{bmatrix}$$

```

>

```

3.4 Automatisation

```

> simplexe:=proc(tab,n,m) # n variables, m contraintes
  local h,i,j,r,s,T,sols;
  T:=Copy(tab);
  while true do
    # recherche d'une colonne pivot
    h:=0;
    for j from 2 to n+m+1 do
      if T[m+1,j]>h then h:=T[m+1,j];s:=j fi
    od;

```

```

        if h=0 then # affichage du résultat
            sols:=NULL;
            for j from 1 to n do
                if T[m+1,j+1]=0 then
sols:=sols,x[j]=add(T[i,j+1]*T[i,1],i=1..m)
                    else
                        sols:=sols,x[j]=0
                    end if
                end do;
            return sols,`zmax`=-coeff(T[m+1,1],z,0)
        end if;
        # recherche d'une ligne pivot
        h:=infinity;
        for i from 1 to m do
            if T[i,s]>0 and T[i,1]/T[i,s]<h then
h:=T[i,1]/T[i,s];r:=i end if
        end do;
        if h=infinity then return `zmax`=infinity end if;
        T:=pivotage(T,r,s);
    end do
end proc:
> # exemple du cours :
> T:=Matrix([[18,1,3,1,0,0],[8,1,1,0,1,0],[14,2,1,0,0,1],[z,
20,30,0,0,0]]);

$$T := \begin{bmatrix} 18 & 1 & 3 & 1 & 0 & 0 \\ 8 & 1 & 1 & 0 & 1 & 0 \\ 14 & 2 & 1 & 0 & 0 & 1 \\ z & 20 & 30 & 0 & 0 & 0 \end{bmatrix}$$

> simplexe(T,2,3);

$$x_1 = 3, x_2 = 5, zmax = 210$$

> # autre exemple :
> tab_alea:=proc(n,m) # tableau aléatoire pour n
variables, m contraintes
    local M1,M2,M3,M4,M5,M6;
    M1:=Matrix(m,1,rand(50..100));
    M2:=Matrix(m,n,rand(-4..10));
    M3:=DiagonalMatrix([1$m]);
    M4:=<<z>>;
    M5:=Matrix(1,n,rand(-2..8));
    M6:=Matrix(1,m,0);
    Matrix([[M1,M2,M3],[M4,M5,M6]])
end:
> n:=4;m:=7;

```

4

7

```

[ > T:=tab_alea(n,m):
[ > simplexe(T,n,m);
[ 
$$x_1 = \frac{2719}{497}, x_2 = 0, x_3 = \frac{1074}{497}, x_4 = \frac{1093}{71}, z_{\max} = \frac{57415}{497}$$

[ > # vérification avec la fonction prédéfinie de Maple :
[ > with(simplex):
[ > eqs:=seq(add(T[i,j+1]*x[j],j=1..n)<=T[i,1],i=1..m);
[ 
$$-4x_1 + 5x_2 - 3x_3 + 6x_4 \leq 64, -x_1 + 2x_2 + 8x_3 + 3x_4 \leq 58,$$

[ 
$$-4x_1 + x_2 - x_3 - 4x_4 \leq 61, 2x_1 - 3x_2 + 4x_3 \leq 92, 4x_1 + 4x_2 - x_3 - 2x_4 \leq 74,$$

[ 
$$8x_1 + 10x_2 - x_3 + x_4 \leq 57, -x_1 - x_2 + 5x_3 + 3x_4 \leq 90$$

[ > gain:=add(T[m+1,j+1]*x[j],j=1..n);
[ 
$$-x_1 + 4x_2 - x_3 + 8x_4$$

[ > sol:=maximize(gain,{eqs},NONNEGATIVE);
[ 
$$\{x_4 = \frac{1093}{71}, x_3 = \frac{1074}{497}, x_1 = \frac{2719}{497}, x_2 = 0\}$$

[ > `zmax`=subs(sol,gain);
[ 
$$z_{\max} = \frac{57415}{497}$$

[ >

```