

Modelling an Underground Nuclear waste Repository

**From the Near Field
To
a Far Field Model**

*Alain Bourgeat; Olivier Gipouloux
UCB-Lyon1, CNRS UMR 5028,
GDR MoMaS*

Modelling an Underground Nuclear waste Repository

- What is a Nuclear waste site (exemple)
- Near Field versus Far Field modelling
- Some problems for Scaling Up the source terms

Geological Storage

where

- Host rock: Brine, Clay, Granite, Argilite, ...

Who (high level, long lived)

- high level of activity and/or long lived elements
 - B Type : low or medium activity level, but long life time
 - C Type : high activity level, $T^{\circ} > 80^{\circ} \text{C}$
- come mainly from industrial activities(power plants)

Question before deciding a Geological Storage for Nuclear waste

- What is the possible **evolution**, and **impact** on the biosphere, of such an underground storage ?
 - Real experiments are not possible at these scales : time (> 500 years)
and space (1X25 X 25 km³)
 - Only predictions based on numerical simulations are possible

Could predictions be based on numerical simulations ??

- There are well established models, but they were derived from the usual scales of measurement (meters, years)
- Two types of simulations are done:
 - Ones based on **Near Field** models (mainly for *Performance Assessment*)
 - and ones based on **Far Field** models (mainly for *Safety Analysis*)

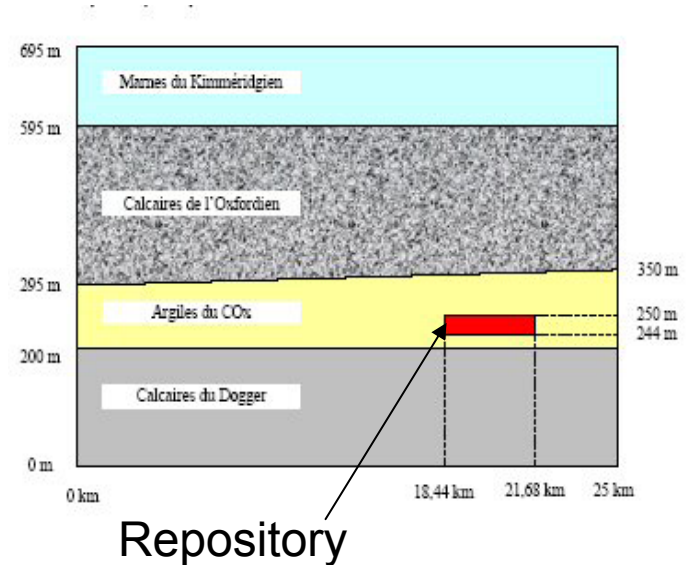
Far Field

1X25 X 25 km³ and > 500 years

Far field region



Far field domain of computation



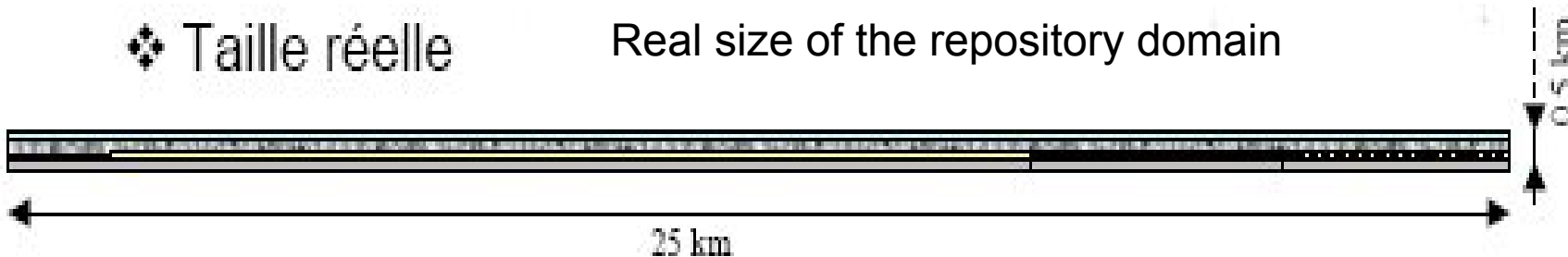
Far Field

1X25 X 25 km³ and > 500 years

- Numerical simulations and predictions are based on **MACROmodels**:
 - Diffusion/Dispersion, Convection, Reaction (by mean of a Retardation factor)
 - The repository is reduced to a very thin homogeneous « source » zone

❖ Taille réelle

Real size of the repository domain



Far Field Simulations

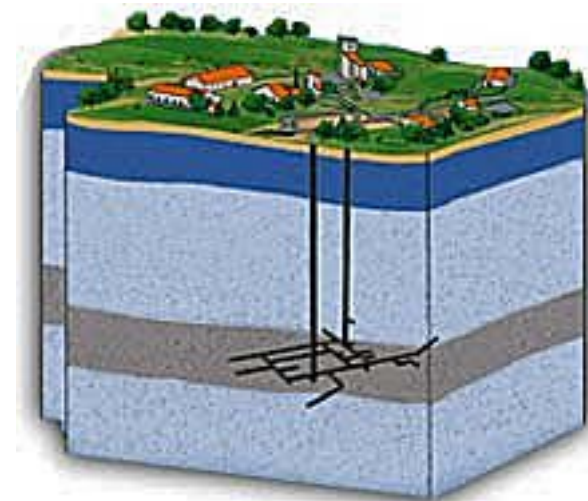
1 General Equations

$$R\omega \frac{\partial \rho}{\partial t} - \nabla \cdot (\mathbf{A} \nabla \rho) + (\mathbf{V} \cdot \nabla) \rho + \lambda R\omega \rho = 0 \quad (1)$$

- R the latency retardation factor,
- ω the porosity,
- \mathbf{v} the Darcy's velocity
- $\lambda = \frac{\log 2}{T}$; T the element radioactivity half life time
- Iodine ^{129}I has half life time $T = 1.57 \cdot 10^7$ years and is releasing during a time $t'_m = 8 \cdot 10^3$ years, with intensity $\Phi' = 10^{-1}$.

– MACRO model:

- Diffusion/Dispersion, Convection, Reaction (by mean of a Retardation factor)



Far Field Models

- **MACROSCOPIC** (**Far Field**) models need to be derived from the **mesoscopic** (**Near Field**) level, which could include :
 - geochemical effects with highly contrasted rock properties for various velocity ratio (reaction / diffusion/flow)
 - geomechanical effects after drilling shafts and tunnels
 - emission from each container or vault
 - ETC.....

Near Field

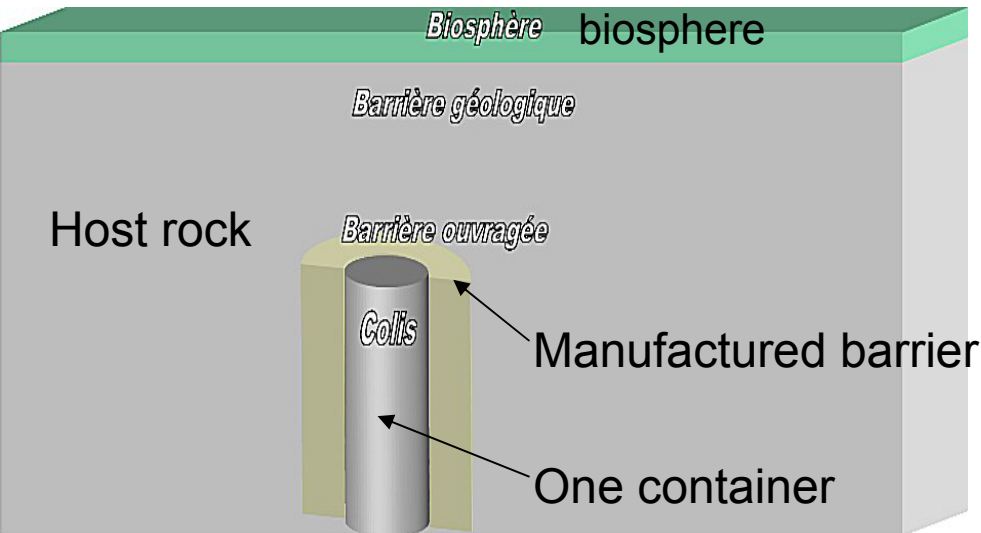
The **Waste** is:

- Inside a matrix (glass, concrete, tar,...)
- Protected by a container (steel, concrete,...)
- Surrounded by manufactured barriers (bentonite, concrete, ...)

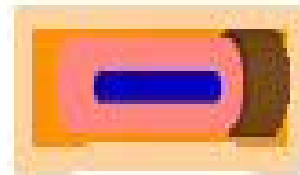
Containers are grouped in Vaults

Vaults are connected by tunnels, galleries, drifts and shafts

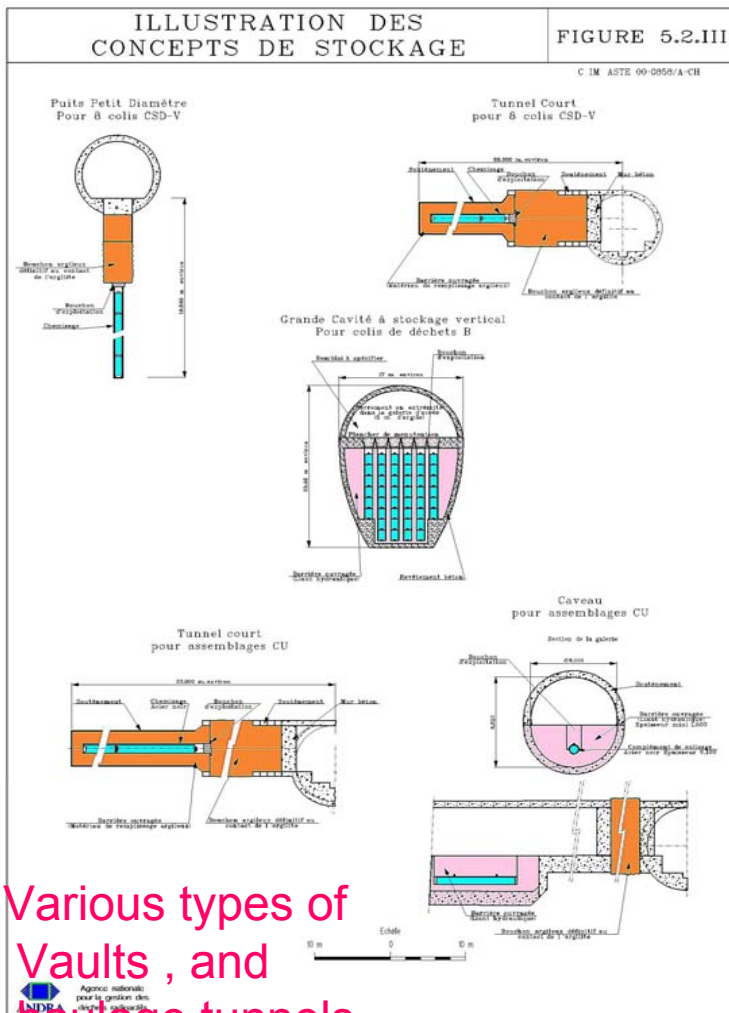
Near Field (Containers)



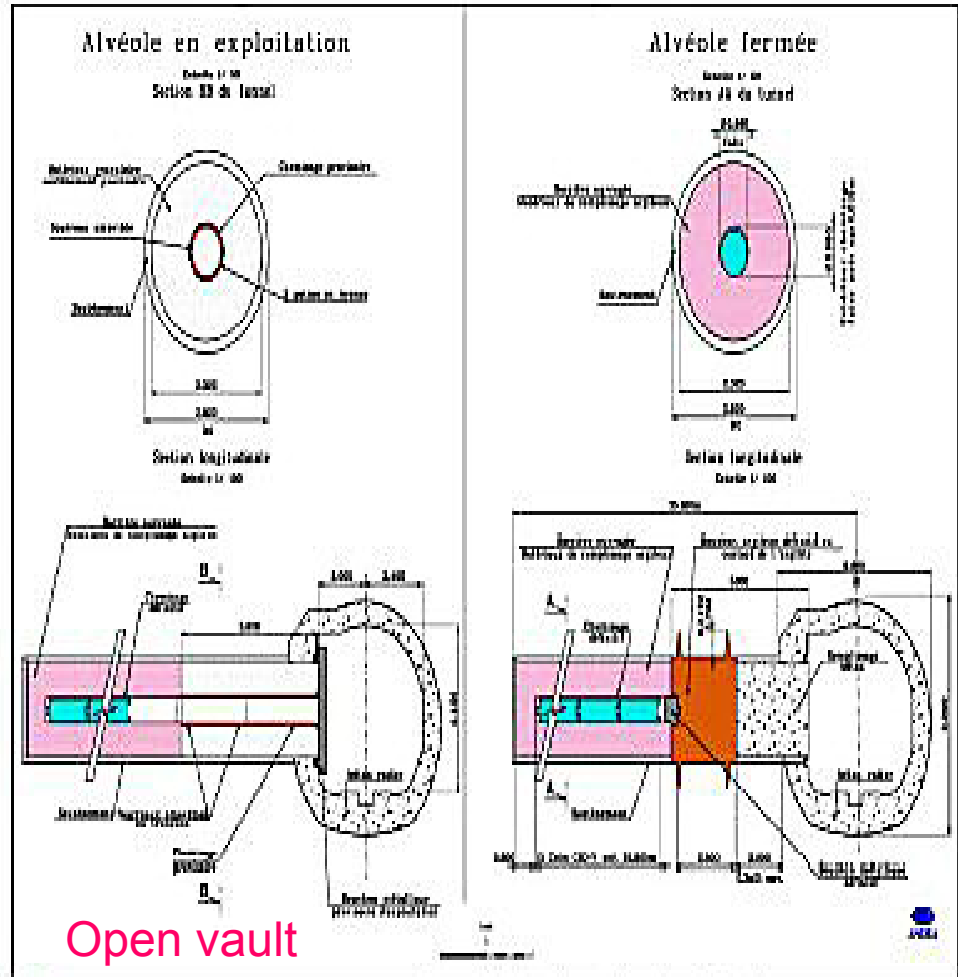
A container
inside a vault



Near Field (Vaults)



Various types of
Vaults , and
haulage tunnels



Open vault
with a set of
containers

closed vault

Near Field Modelling

- Vault dimensions \approx 1 m diameter, length: 10m
- **Numerical simulations and predictions based on mesoscopic (Near Field) models** including:
 - T-H-M-C couplings
 - Coupling of different materials (steel, glass, concrete, bentonite, clay,)
 - Adsorption / desorption
 -

Near Field Models

- These **MESOSCOPIC** (**Near Field**) models need to be derived from the **microscopic** level(e.g. pores), specially :
 - geomechanical properties of rocks
 - coupling transport/reaction
 - adsorption/desorption
 - swelling of bentonites
 -

Far Field versus Near Field

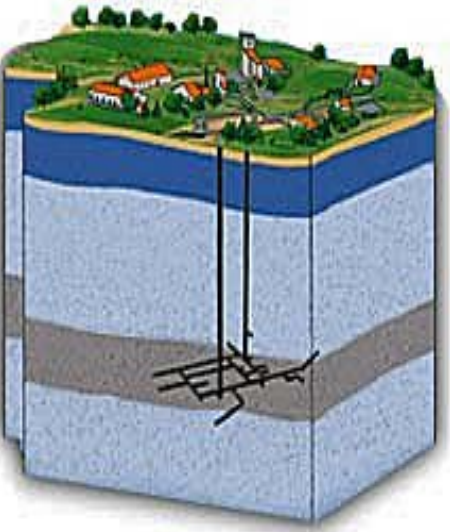
Near Field model

- to be derived from « microscopic » models

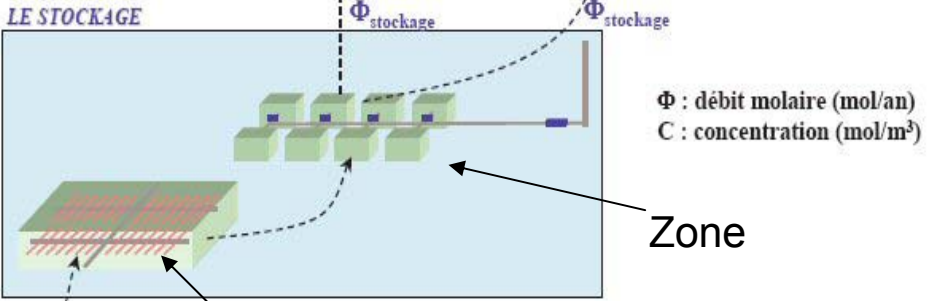
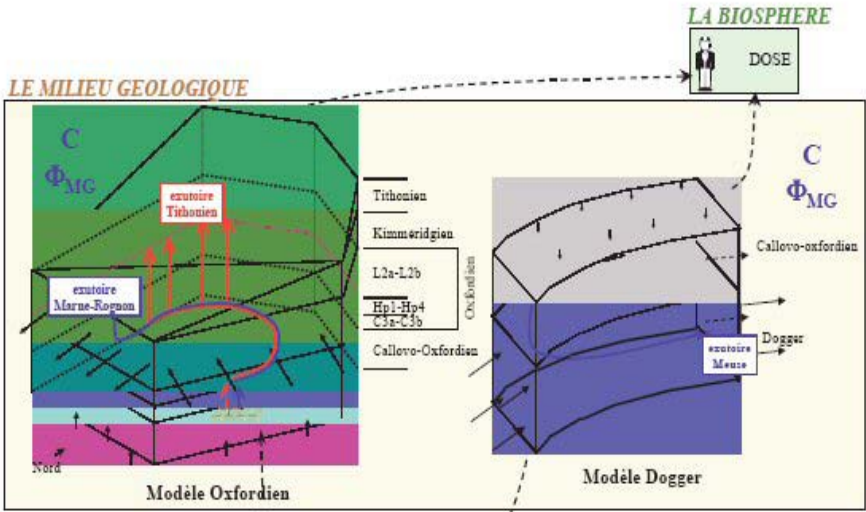
Far Field model

- to be derived from Near Field models

Far Field vs. Near Field



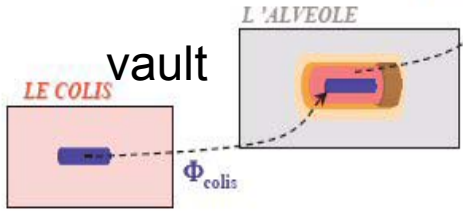
Far field region



repository

Zone

Unit

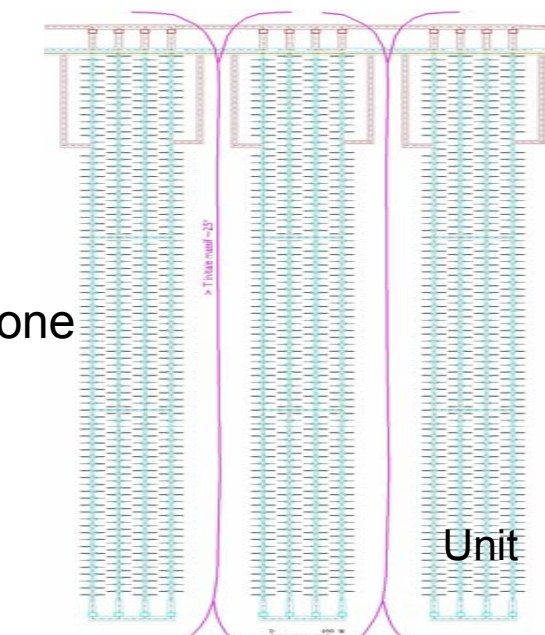
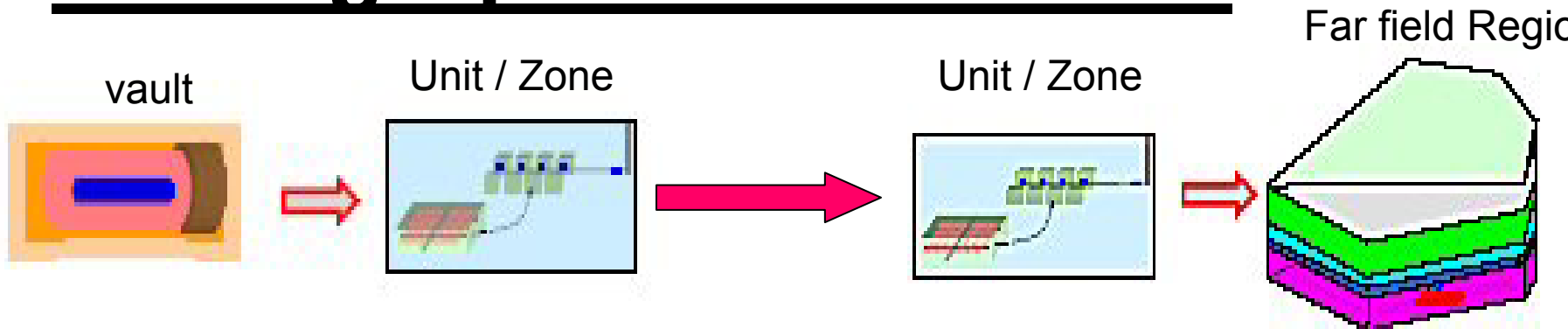


Container

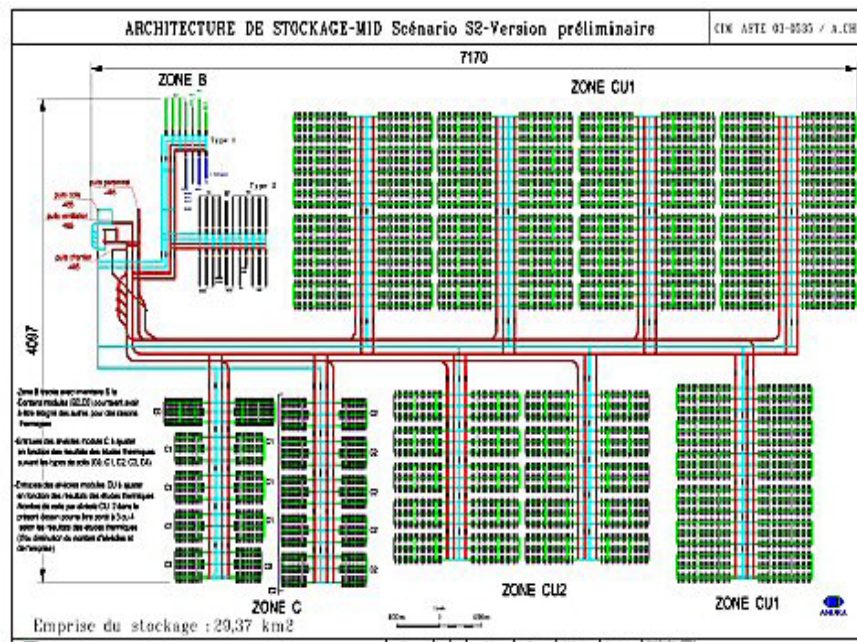
vault

L'ALVEOLE

Scaling Up the Sources ??



Repository



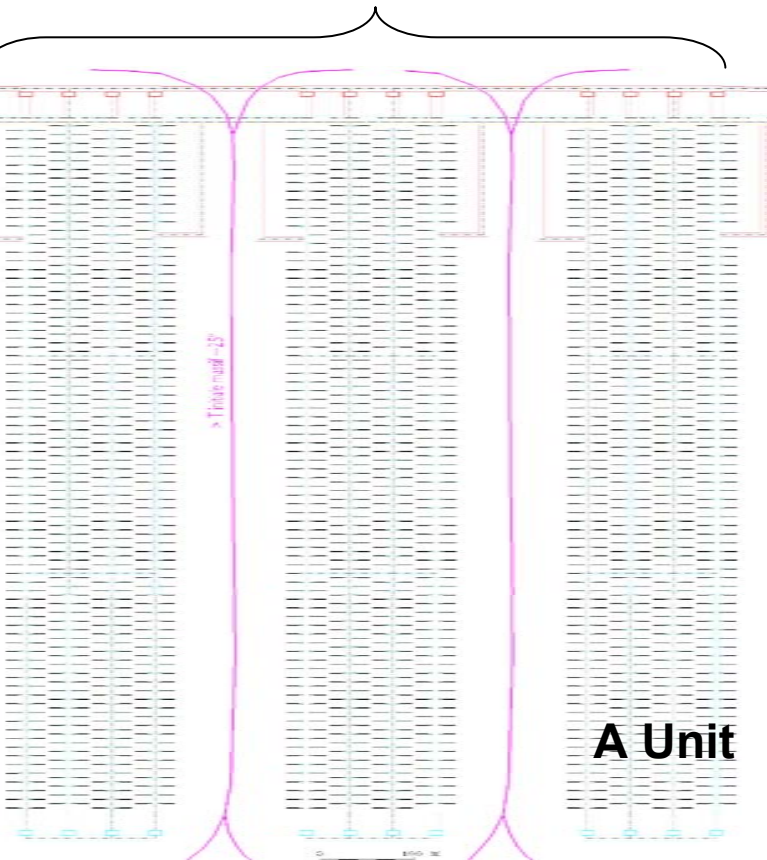
Scaling Up the Sources

There are several levels of possible scaling up:

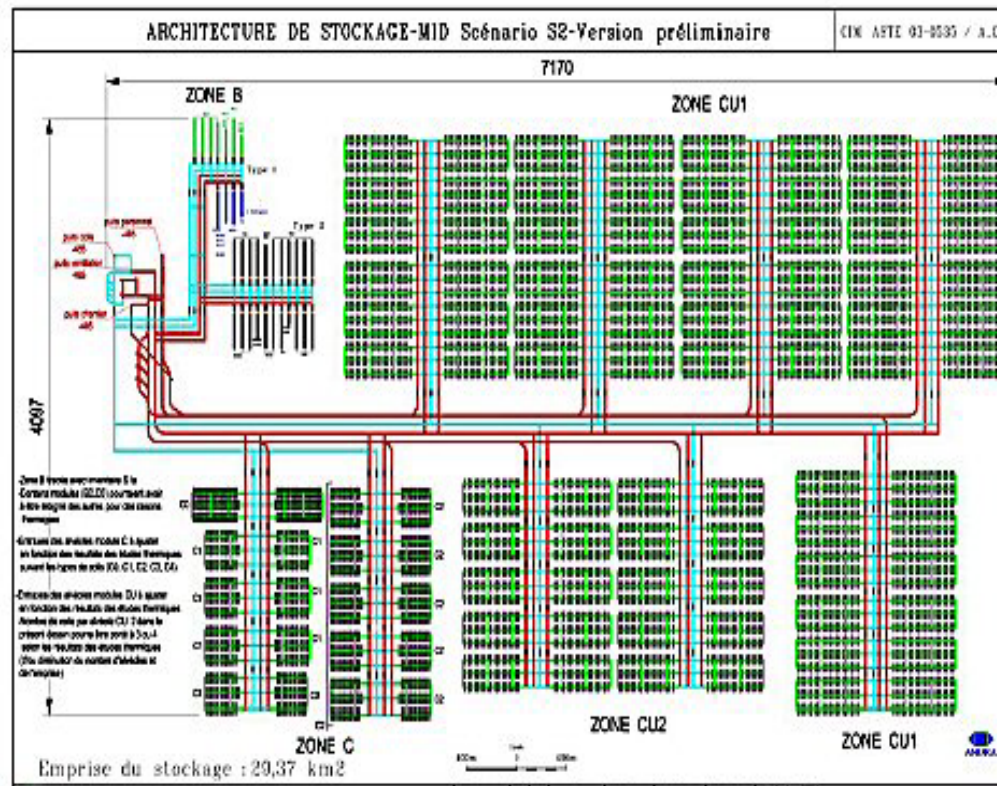
1. from the **waste packages** to a **storage unit** global model
2. from the **storage units** to a **zone** global model
3. from **similar zones** to the **repository** global model

First example of Scaling Up the Sources:

A Zone



A Unit



First example of Scaling Up the Sources:

From the **STORAGE UNITS** to a “**ZONE** global model”

OR, From **Similar ZONES** to the “**REPOSITORY** global model”

.B., O. Gipouloux, E. Marusic-Paloka. Mathematical Modeling of an underground waste disposal site by upscaling. Math. Meth. Appl. Sci., Volume 27, Issue 4; March 2004, p 381-403.



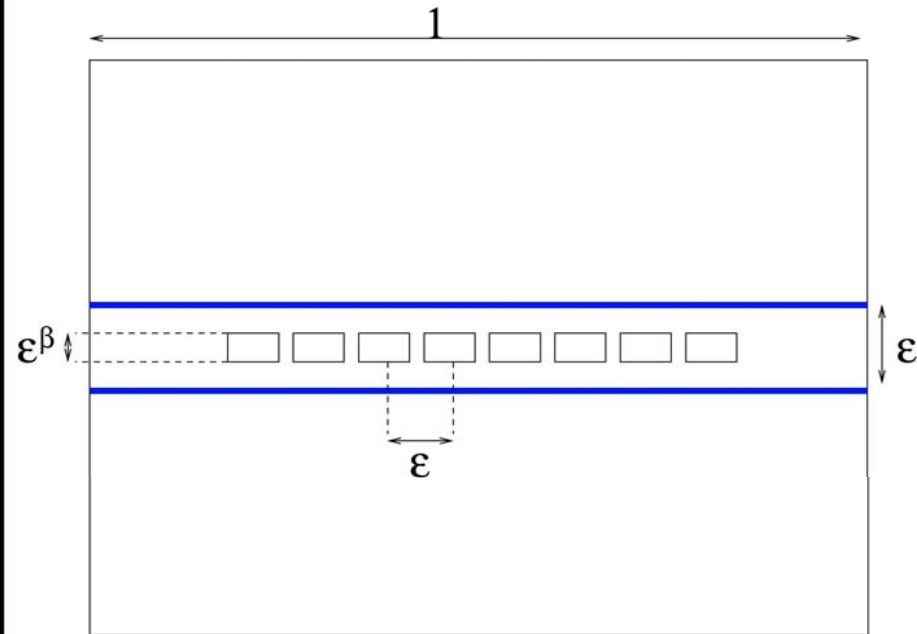
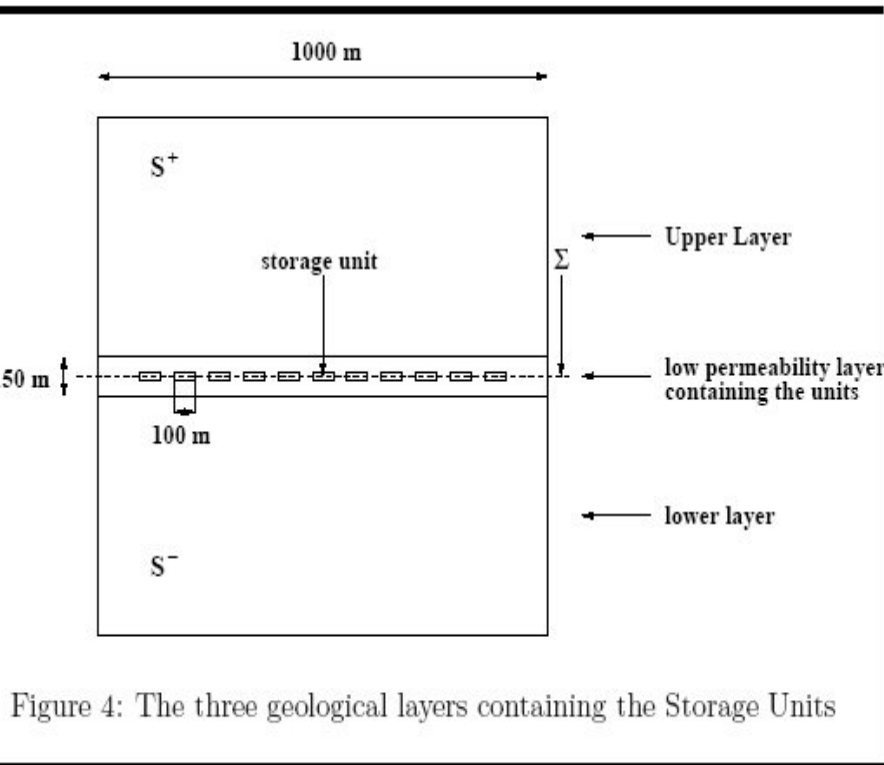
from **storage units** to a **zone** model
(or from **similar zones** to the **repository**)

Avoiding cumbersome computations, we choose:

- a simplified geometry for the units (or zones)
- a simplified model of transport

But same things (methodology and simulations) could be done for real situations

from **storage units** to a **zone** model (or from **similar zones** to the **repository**)



Real domain section

Rescaled domain section

from **storage units** to a **zone** model
(or from **similar zones** to the **repository**)

2 The Equations

$$\omega^\varepsilon \frac{\partial \varphi_\varepsilon}{\partial t} - \operatorname{div}(\mathbf{A}^\varepsilon \nabla \varphi_\varepsilon) + (\mathbf{v}^\varepsilon \cdot \nabla) \varphi_\varepsilon + \lambda \omega^\varepsilon \varphi_\varepsilon = 0 \quad \text{in } \Omega_\varepsilon^T \quad (2)$$

$$\varphi_\varepsilon(0, x) = \varphi_0(x) \quad x \in \Omega_\varepsilon \quad (3)$$

$$\mathbf{n} \cdot \boldsymbol{\sigma} = \mathbf{n} \cdot (\mathbf{A}^\varepsilon \nabla \varphi_\varepsilon - \mathbf{v}^\varepsilon \varphi_\varepsilon) = \Phi(t) \quad \text{on } \Gamma_\varepsilon^T \quad (4)$$

$$\varphi_\varepsilon = 0 \quad \text{on } S_1, \quad (5)$$

$$\mathbf{n} \cdot (\mathbf{A}^\varepsilon \nabla \varphi_\varepsilon - \mathbf{v}^\varepsilon \varphi_\varepsilon) = 0 \quad \text{on } S_2 \quad (6)$$

with

$$\mathbf{A}^\varepsilon(x_2) = \mathbf{A}\left(\frac{x_2}{\varepsilon}\right); \quad \mathbf{v}^\varepsilon(x, t) = \mathbf{v}\left(x, \frac{x_2}{\varepsilon}, t\right); \quad \omega^\varepsilon(x_2) = \omega\left(\frac{x_2}{\varepsilon}\right). \quad (7)$$

from **storage units** to a **zone** model
(or from **similar zones** to the **repository**)

By homogenisation (asymptotic analysis) we
obtain a corresponding Zone « global model »

$$\omega^2 \frac{\partial \varphi}{\partial t} - \operatorname{div}(\mathbf{A}^2 \nabla \varphi) + (\mathbf{v}^2 \cdot \nabla) \varphi + \lambda \omega^2 \varphi = 0 \text{ in } \tilde{\Omega}^T \quad (8)$$

$$\varphi(x, 0) = \varphi_0(x) \quad x \in \tilde{\Omega} = \Omega \setminus \Sigma \quad (9)$$

$$\varphi = 0 \quad \text{on } S_1 \quad (10)$$

$$\mathbf{n} \cdot (\mathbf{A}^2 \nabla \varphi - \mathbf{v}^2 \varphi) = 0 \quad \text{on } S_2 \quad (11)$$

$$[\varphi] = 0 \quad , \quad [\mathbf{e}_2 \cdot (\mathbf{A}^2 \nabla \varphi - \mathbf{v}^2 \varphi)] = -|\tilde{M}| \Phi \quad \text{on } \Sigma \quad , \quad (12)$$

where $[\cdot]$ denotes the jump over Σ , and $|\tilde{M}|$ stands for the limit of a normalized unit \mathcal{M}_ε area.

from **storage units** to a **zone** model
(or from **similar zones** to the **repository**)

In order to check the quality of this **zone**
« **global model** »:

We compute the resulting contaminant
transport from all the sources terms

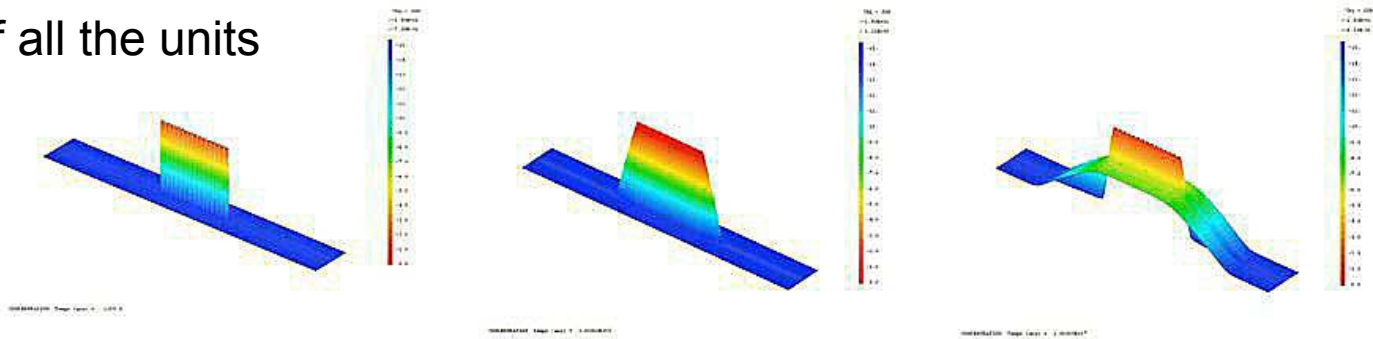
leaking,

using first a detailed model (near field
modelling of all the units)

and compare these simulations to the
ones obtained, using the zone « **global**
model »

from storage units to a zone model (or from similar zones to the repository)

Simulation of all the units



Niveaux de concentration après 1209, 300 000 et 1 000 000 d'années; obtenus par simulations à partir du modèle détaillé (en haut) et du modèle « homogénéisé » (en bas)

Simulation of the zone « global model »

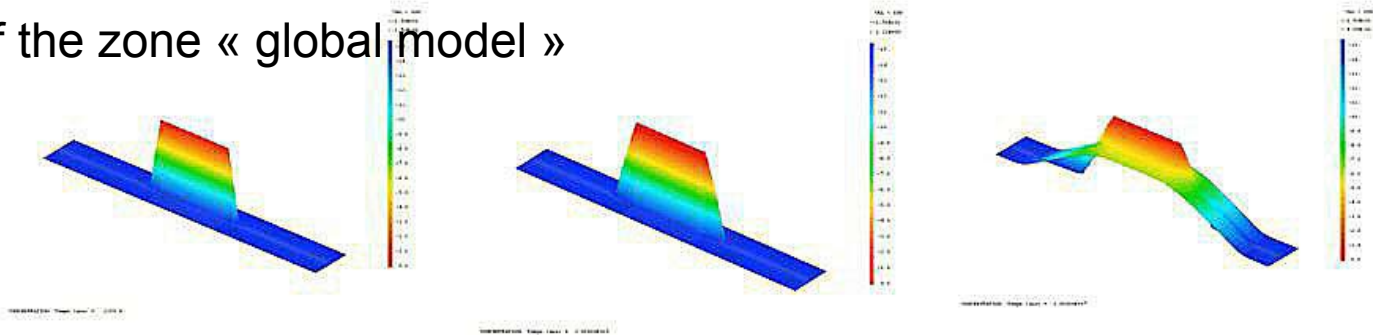


Fig.10 : Comparaison des niveaux de concentration en lode129, obtenus par une simulation détaillée à une échelle fine et ceux obtenus par une simulation basée sur le modèle « homogénéisé » correspondant. Malgré son caractère « global », cette dernière simulation, moins détaillée, rend cependant bien compte des pics de concentration, au voisinage des conteneurs.

A Random scenario ??

The **contents**, and the **leaking starting time** of the **Waste Packages** are **Random**

.B., jointly with A. Piatnitski; work in progress

The "local sources" f_ε are periodically repeated, on a plan Σ . Associated to the randomness of the **contents**, the **leaking starting time** and the **emission time evolution**, of each local source, there is a random dynamical system T characterizing f_ε :

$$f^\varepsilon(x, t) = \mathbb{1}_{B_\varepsilon} \frac{1}{\varepsilon^\gamma} f(T_{X^\varepsilon/\varepsilon} \omega, t)$$

$$\partial_t u^\varepsilon - \operatorname{div}(a(x) \nabla u^\varepsilon) + \operatorname{div}(b(x) u^\varepsilon) = f^\varepsilon;$$

$$u^\varepsilon|_{t=0} = 0, \quad \frac{\partial}{\partial n_a} u^\varepsilon \cdot n(x) - b(x) \cdot n(x) u^\varepsilon + \lambda u^\varepsilon = 0.$$

A Random scenario ??

The contents, and the leaking starting time of the Waste Packages are Random

.B., jointly with A. Piatnitski; work in progress

Under the assumptions :

The "local sources" f^e are statistically homogeneous and the associated random dynamical system T is ergodic

We may then characterize the global model:

$$\partial_t u^0 - \operatorname{div}(a(x)\nabla u^0) + \operatorname{div}(b(x)u^0) = F(t)\delta_\Sigma(x);$$

$$F(t) = \mathbf{E}\{f(\cdot, t)\}.$$

Application of Scaling up to obtain global model in situations where the near field is damaged

How a global (far field) model could be affected by the damaged zones in the near field models

On the following two examples of scaling up, our goal will be to characterize the influence of the degree of damaging (in the EDZ zone) on the global (or far field) mathematical model

Second example of Scaling Up:

From a "**WASTE PACKAGES** model" to a "**Storage UNIT** Global model", **including a possibly damaged zone** (A. B, E. Marusic-Paloka. A homogenized model of an underground waste repository including a disturbed zone. To appear in SIAM J.on Multiscale Modeling and Simulation, 2005.)

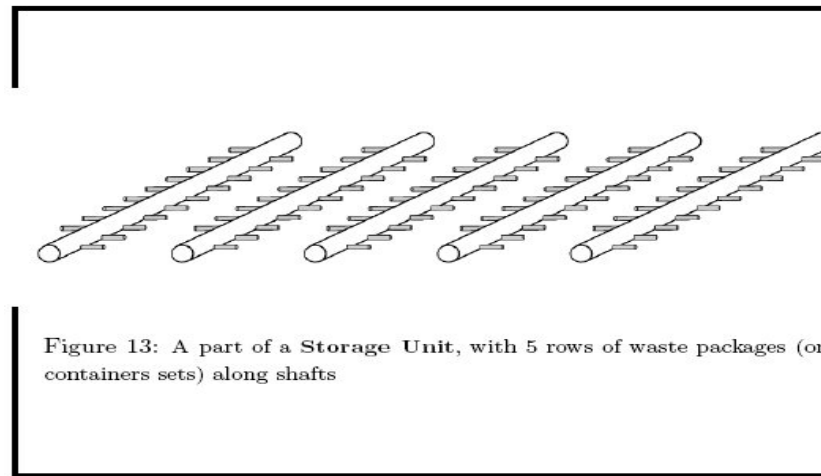
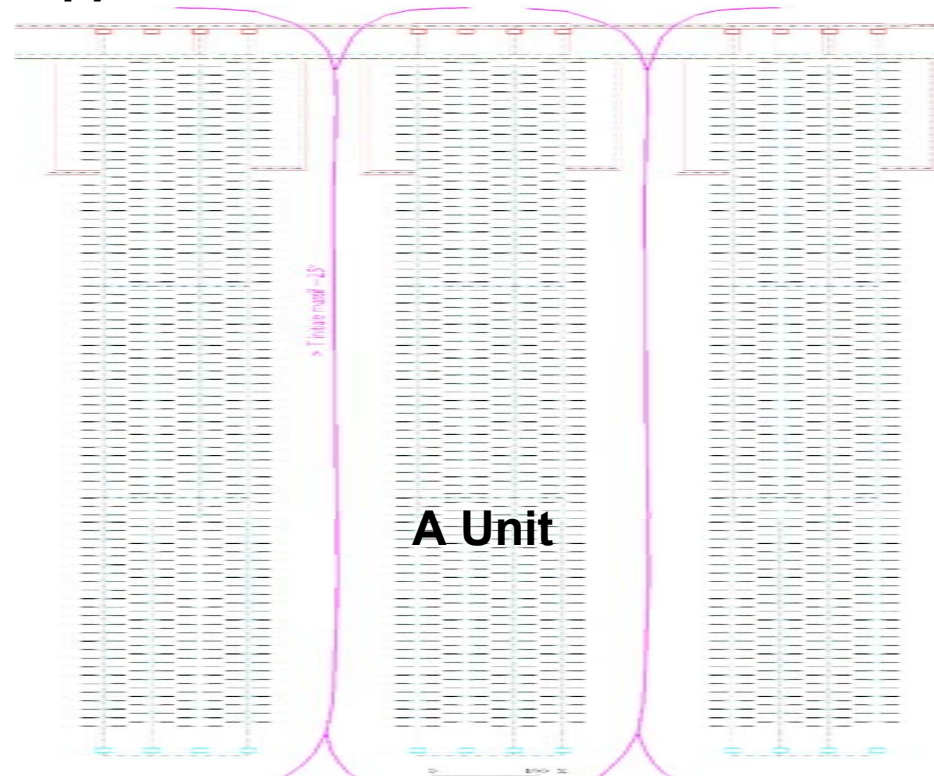
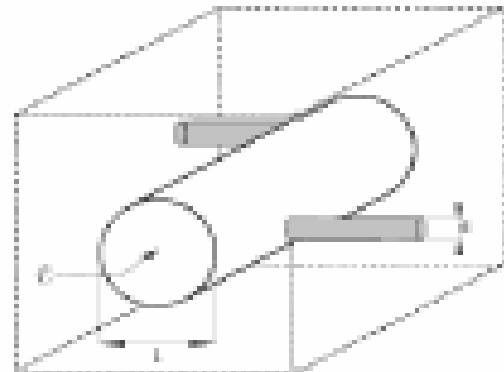


Figure 13: A part of a Storage Unit, with 5 rows of waste packages (or containers sets) along shafts



The "Mesoscopic" model of a storage unit

$$\omega^\varepsilon \frac{\partial \varphi_\varepsilon}{\partial t} - \operatorname{div}(\mathbf{A}^\varepsilon \nabla \varphi_\varepsilon) + (\mathbf{v}^\varepsilon \cdot \nabla) \varphi_\varepsilon + \lambda \omega^\varepsilon \varphi_\varepsilon = 0 \quad \text{in } \Omega_\varepsilon^T \quad (13)$$

$$\varphi_\varepsilon(0, x) = \varphi_0(x) \quad x \in \Omega_\varepsilon \quad (14)$$

$$\mathbf{n} \cdot (\mathbf{A}^\varepsilon \nabla \varphi_\varepsilon - \mathbf{v}^\varepsilon \varphi_\varepsilon) = \Phi_\varepsilon(t) \quad \text{on } \Gamma_\varepsilon^T \quad (15)$$

$$\mathbf{n} \cdot (\mathbf{A}^\varepsilon \nabla \varphi_\varepsilon - \mathbf{v}^\varepsilon \varphi_\varepsilon) = \kappa (\varphi_\varepsilon - g_\varepsilon) \quad \text{on } \mathcal{K}_\varepsilon^T \cup \mathcal{H}_\varepsilon^T \quad (16)$$

$$\varphi_\varepsilon = 0 \quad \text{on } \mathcal{Z}_\varepsilon^T . \quad (17)$$

$\mathcal{Z}_\varepsilon^T$ the Drifts Bottoms (sealed), $\mathcal{H}_\varepsilon^T$ the drifts tops and $\mathcal{K}_\varepsilon^T$ the rest of the exterior boundary of Ω , Γ_ε the Waste Packages boundary $\times(0, T)$;

g_ε measure the concentration entering at the drifts tops. A parameter β is introduced for characterizing the degree of damaging by mean of the Darcy's velocity range .

from a " **WASTE PACKAGES** model" to a " **Storage UNIT**
Global model", including a possibly **damaged zone**

Modelling all range of damaging

($\varepsilon^{-\beta}$ characterize the Darcy's velocity range inside the drifts)

$$v^\varepsilon(x) = \begin{cases} v^h(x) & \text{in the host rock } \Omega_\varepsilon \setminus \mathcal{S}_\varepsilon \\ \varepsilon^{-\beta} v^d(x', x_2/\varepsilon; x_3/\varepsilon) & \text{in the drifts } \mathcal{S}_\varepsilon \end{cases} .$$

The Diffusion/Dispersion

$$A^\varepsilon(x) = \begin{cases} A^h(x) & \text{in the host rock } \Omega_\varepsilon \setminus \mathcal{S}_\varepsilon \\ d(x) I + \varepsilon^{-\beta} A^d(x_2, x_2/\varepsilon, x_3/\varepsilon) & \text{in the drifts } \mathcal{S}_\varepsilon \end{cases} .$$

THEN:

in the corresponding Macroscopic model *Depending on β (characterizing the degree of damaging, i.e. the Darcy's velocity range) we have three different cases.*

From a " **WASTE PACKAGES** model" to a "Storage **UNIT** Global model", including a possibly **damaged zone**

According to the range of damaging, we see 3 storage **unit** global models

- $0 \leq \beta < 1$; The storage site is undisturbed.

The drifts do not make any contribution, i.e. the repository behaves as if they were not there. $\varphi_\varepsilon \rightarrow \varphi$ the solution of an equation, similar to the one associated to the mesoscopic model.

- $\beta = 1$; galleries and drifts with damaged sealings.

The transport processes, inside and outside the "damaged" drifts are comparable and there are interactions between them.

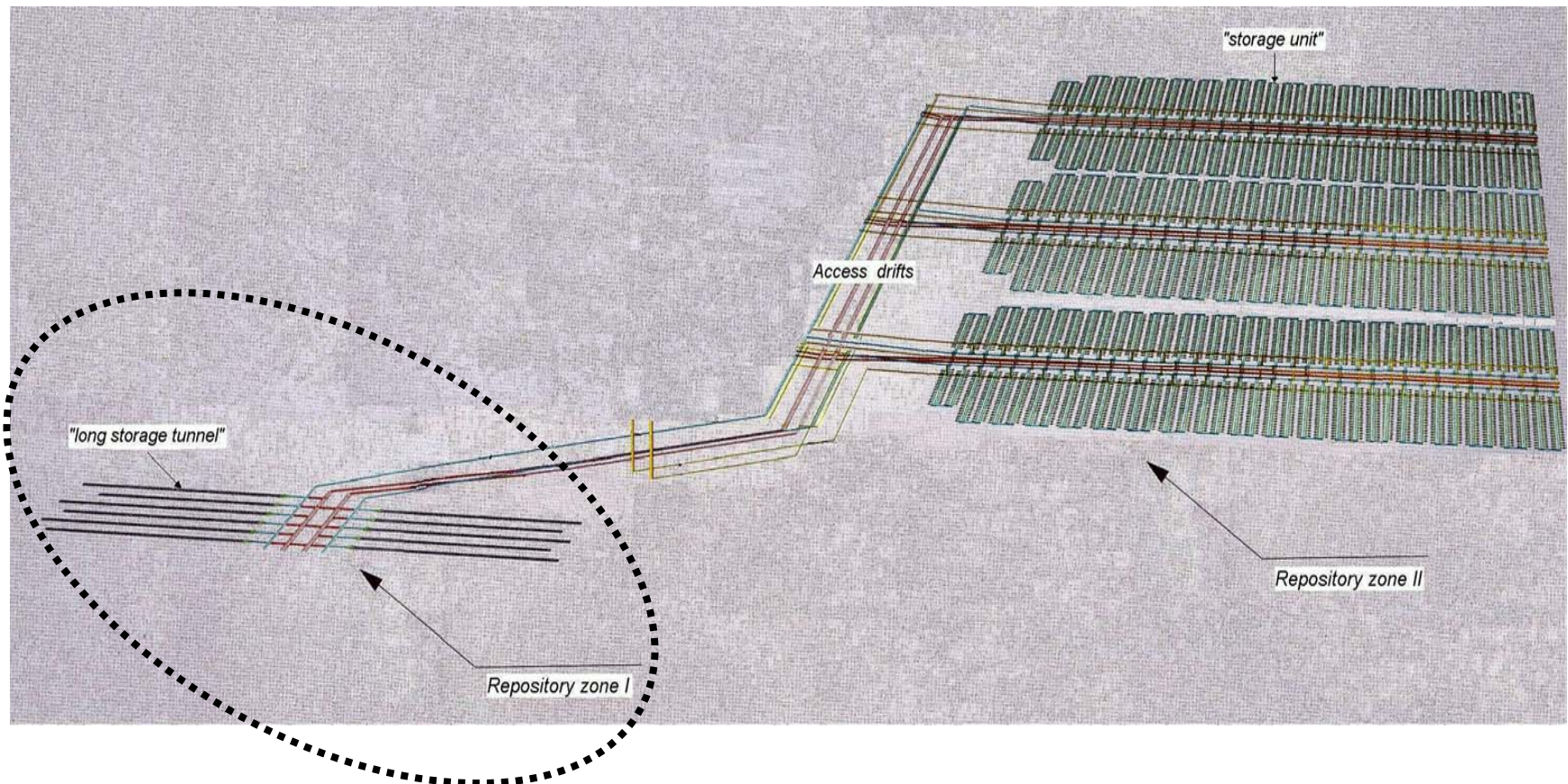
- $2 > \beta > 1$; The storage site is highly disturbed.

The Transport process in the drifts is dominant and we do not see anything else outside the drifts in the corresponding global model .

Third example of Scaling Up:

From the **LONG STORAGE UNITS** to a “**ZONE** global model”

.B., jointly with A. Piatnitski and E. Marusic-Paloka. ; work in progress.



Third example of Scaling Up:

From the **LONG STORAGE UNITS** to a “**ZONE** global model” (A.B., jointly with A. Piatnitski and E. Marusic-Paloka. ; work in progress.)

The repository **zone**, is made of a high number of similar long waste filled storage units, linked by backfilled working and haulage drifts. .

Like previously, **the parameter β characterize de degree of damaging (scaling the Darcy's velocity range)**

Third example of Scaling Up:

From the **LONG STORAGE UNITS** to a “**ZONE** global model” (*A.B., jointly with A. Piatnitski and E. Marusic-Paloka. ; work in progress.*)

In the first example there was no damaged zone at all, while in the second one the damaged drifts were periodically repeated, allowing to use the technique of singular measures.

The main difference compared to the 2 previously studied situations, is the singular behavior of the only one damaged drift which reduces to a 1-D object in the scaled up model, leading to technical difficulties

Third exemple of Scaling Up:

From the **LONG STORAGE UNITS** to a “**ZONE** global model” (A.B., jointly with A. Piatnitski and E. Marusic-Paloka. ; work in progress.)

Finally we prove:

- *The Zone global model is independent of the choice of β and only higher order correctors terms differ, according to β .*

THE END



Thank you for your attention