

Ex. 1 $\vec{V}(x,y) = (2xy^2 - y)\vec{i} + (2x^2y - x)\vec{j} + 0\vec{k}$

1. $\text{rot } \vec{V} = \vec{k} \left[\frac{\partial}{\partial x}(2x^2y - x) - \frac{\partial}{\partial y}(2xy^2 - y) \right] = \vec{k} \cdot (4xy - 1 - 4xy + 1) = \vec{0}$.

Comme le domaine de définition de \vec{V} est \mathbb{R}^3 qui est simplement connexe, et comme $\text{rot } \vec{V} = \vec{0}$, \vec{V} est bien le gradient d'une fct $f: \mathbb{R}^3 \rightarrow \mathbb{R}$. Cherchons f t.g.

$\vec{V} = \vec{\nabla} f = \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \right)$:

$$\begin{cases} \frac{\partial f}{\partial x} = 2xy^2 - y & \rightarrow f(x,y) = \int (2xy^2 - y) dx + g(y) = x^2y^2 - xy + g(y) \\ \frac{\partial f}{\partial y} = 2x^2y - x & \uparrow \frac{\partial f}{\partial y} = 2x^2y - x + g'(y) = 2x^2y - x \Leftrightarrow g'(y) = 0 \\ \frac{\partial f}{\partial z} = 0 & \Rightarrow f \text{ ne dépend pas de } z \end{cases} \Leftrightarrow g(y) = C$$

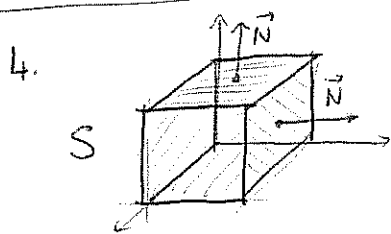
$\Rightarrow f(x,y,z) = x^2y^2 - xy + C$

2. $\int_{C^+} \vec{V} \cdot d\vec{\ell} = \int_{C^+} \vec{\nabla} f \cdot d\vec{\ell} = f(B) - f(A) = f(2,0,0) - f(-2,0,0) = 0$.

The diagram shows a coordinate system with x and y axes. A semicircle labeled C+ is drawn in the upper half-plane, starting at point A (-2,0) and ending at point B (2,0). The curve is oriented counter-clockwise.

3. $\text{div } \vec{V} = \frac{\partial(2xy^2 - y)}{\partial x} + \frac{\partial(2x^2y - x)}{\partial y} = 2y^2 + 2x^2$.

Sur \mathbb{R}^3 , $\vec{V} = \text{rot } \vec{U} \Leftrightarrow \text{div } \vec{V} = 0$. Comme $\text{div } \vec{V} \neq 0$, sauf en (0,0), \vec{V} n'est pas le rotationnel d'un champ \vec{U} .



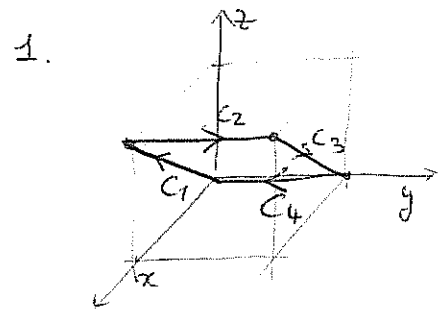
Le cube S est une surface fermée de \mathbb{R}^3 , donc $S = \partial D$ où D est le cube plein de \mathbb{R}^3 qui se trouve dedans S :

$D = \{(x,y,z) \in \mathbb{R}^3, 0 \leq x \leq 1, 0 \leq y \leq 1, 0 \leq z \leq 1\}$.

Par le théorème de Ostrogradski, on a alors:

$$\begin{aligned} \oiint_S \vec{V} \cdot d\vec{S} &= \iiint_D \text{div } \vec{V} \cdot dx dy dz = \int_0^1 \int_0^1 \int_0^1 (2x^2 + 2y^2) dx dy dz = \\ &= 2 \int_0^1 \int_0^1 (x^2 + y^2) [z]_0^1 dx dy = 2 \int_0^1 \int_0^1 (x^2 + y^2) dx dy = 2 \int_0^1 [x^2y + \frac{1}{3}y^3]_0^1 dz \\ &= 2 \int_0^1 (x^2 + \frac{1}{3}) dx = 2 [\frac{1}{3}x^3 + \frac{1}{3}x]_0^1 = 2(\frac{1}{3} + \frac{1}{3}) = 2 \cdot \frac{2}{3} = \frac{4}{3} \end{aligned}$$

2) Ex. 2: $\vec{u}(x,y,z) = xz\vec{i} + y^2\vec{j} + yz\vec{k}$



$\vec{dl} = \begin{pmatrix} dx \\ dy \\ dz \end{pmatrix}$

- $C_1: 0 \leq x \leq 1, z: 0 \rightarrow 1, y=0, z=x$
 $dy=0, dz=dx$
- $C_2: x=1, y: 0 \rightarrow 1, z=1$
 $dx=0, dz=0$
- $C_3: x: 1 \rightarrow 0, y=1, z=x$
 $dy=0, dz=dx$
- $C_4: x=0, y: 1 \rightarrow 0, z=0$
 $dx=0, dz=0$

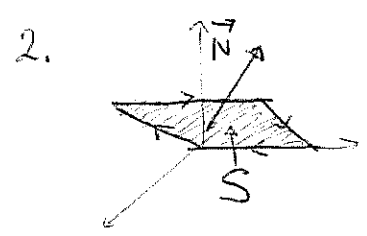
$\int_{C_1} \vec{u} \cdot \vec{dl} = \int_{C_1} (xz \underbrace{dx}_x + y^2 \underbrace{dy}_0 + yz \underbrace{dz}_0) = \int_0^1 x^2 dx = \left[\frac{1}{3} x^3 \right]_0^1 = \frac{1}{3}$

$\int_{C_2} \vec{u} \cdot \vec{dl} = \int_{C_2} (xz \underbrace{dx}_0 + y^2 dy + yz \underbrace{dz}_0) = \int_0^1 y^2 dy = \left[\frac{1}{3} y^3 \right]_0^1 = \frac{1}{3}$

$\int_{C_3} \vec{u} \cdot \vec{dl} = \int_{C_3} (xz \underbrace{dx}_x + y^2 \underbrace{dy}_0 + yz \underbrace{dz}_{1 \cdot x dx}) = \int_1^0 (x^2 + x) dx = \left[\frac{1}{3} x^3 + \frac{1}{2} x^2 \right]_1^0 = -\frac{1}{3} - \frac{1}{2}$

$\int_{C_4} \vec{u} \cdot \vec{dl} = \int_{C_4} (xz \underbrace{dx}_0 + y^2 dy + yz \underbrace{dz}_0) = \int_1^0 y^2 dy = \left[\frac{1}{3} y^2 \right]_1^0 = -\frac{1}{3}$

$\Rightarrow \oint_C \vec{u} \cdot \vec{dl} = \frac{1}{3} + \frac{1}{3} - \frac{1}{3} - \frac{1}{2} - \frac{1}{3} = -\frac{1}{2}$



$S = \text{rectangle tr. } \partial S = C$

Vu l'orientation de S donnée par \vec{N} , le bord orienté de S est exactement la courbe C avec l'orientation donnée.

Par le théorème de Stokes on a donc :

$\iint_S \text{rot } \vec{u} \cdot \vec{dS} = \oint_{C=\partial S} \vec{u} \cdot \vec{dl} = -\frac{1}{2}$