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Relaxation limit of the aggregation equation with pointy potential

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Abstract: This work is devoted to the study of a relaxation limit of the so-called aggregation equation with a pointy potential in one dimensional space. The aggregation equation is by now widely used to model the dynamics of a density of individuals attracting each other through a potential. When this potential is pointy, solutions are known to blow up in final time. For this reason, measure-valued solutions have been defined. In this paper, we investigate an approximation of such measure-valued solutions thanks to a relaxation limit in the spirit of Jin and Xin. We study the convergence of this approximation and give a rigorous estimate of the speed of convergence in one dimension with the Newtonian potential. We also investigate the numerical discretization of this relaxation limit by uniformly accurate schemes.

Keywords: Aggregation equation; Relaxation limit; Scalar conservation law; Finite volume scheme.

1. Introduction

The so-called aggregation equation has been widely used to model the dynamics of a population of individuals in interaction. Let $W : \mathbb{R} \rightarrow \mathbb{R}$, sufficiently smooth, be the interaction potential governing the population. Then, in one dimension in space, the dynamics of the density of individuals, denoted by ρ , is governed by the following equation, for $t > 0$ and $x \in \mathbb{R}$,

$$\partial_t \rho + \partial_x (a[\rho] \rho) = 0, \quad \text{with} \quad a[\rho] = -W' * \rho. \quad (1)$$

Such equations appear in many applications in population dynamics: For instance to describe the collective migration of cells by swarming, the motion of bacteria by chemotaxis, the crowd motion, the flocking of birds, or fishes school see e.g. [1–7]. From a mathematical point of view, these equations have been widely studied. When the potential W is not smooth enough, it is known that weak solutions may blow up in finite time [8,9]. Thus, the existence of weak (measure) solutions has been investigated in e.g. [10,11].

In this paper, we consider a relaxation limit in the spirit of Jin-Xin [12] of the aggregation equation in one space dimension on \mathbb{R} . It is now well-established that such modifications allow to regularize the solutions. For a given $c > \|a\|_\infty$, we introduce the system

$$\partial_t \rho + \partial_x \sigma = 0, \quad (2a)$$

$$\partial_t \sigma + c^2 \partial_x \rho = \frac{1}{\varepsilon} (a[\rho] \rho - \sigma) \quad (2b)$$

$$a[\rho] = -W' * \rho \quad (2c)$$

18 This system is complemented with initial data ρ_0 and $\sigma_0 := a[\rho_0] \rho_0$. It is clear, at least formally, that
 19 when $\varepsilon \rightarrow 0$ the solution ρ of system (2) converges to the one of the aggregation equation (1) (and
 20 actually it is true only if $c > \|a\|_\infty$). We mention that the aggregation equation may also be derived
 21 thanks to a hydrodynamical limit of kinetic equations [6,7,13].

The aim of this work is to study the convergence as $\varepsilon \rightarrow 0$ of the relaxation system (2) towards the aggregation equation. More precisely, we establish a precise estimate of the speed of convergence, and we also illustrate with some numerical simulations. These estimates are obtained only in the case of the Newtonian potential in one dimension $W(x) = \frac{1}{2}|x|$. Indeed, in this particular case we may link the aggregation equation to a scalar conservation law [14,15]. The same link holds for the relaxation system (2): denoting

$$u(t, x) = \frac{1}{2} - \int_{-\infty}^x \rho(t, dy), \quad v(t, x) = \frac{1}{2} - \int_{-\infty}^x \sigma(t, dy),$$

where the notation $\int \rho(t, dy)$ stands for the integral with respect to the probability measure $\rho(t)$, then we verify easily that

$$u = -W' * \rho, \quad \rho = -\partial_x u,$$

so that $a[\rho] = u$. Then, integrating (2), we deduce that (u, v) is a solution to

$$\partial_t u + \partial_x v = 0 \quad (3a)$$

$$\partial_t v + c^2 \partial_x u = \frac{1}{\varepsilon} \left(\frac{1}{2} u^2 - v \right), \quad (3b)$$

which is complemented with initial data $u_0 = \frac{1}{2} - \int_{-\infty}^x \rho_0(dy)$, and $v_0 = \frac{1}{2} - \int_{-\infty}^x \sigma_0(dy)$. Clearly, as $\varepsilon \rightarrow 0$, we expect that the solution of the above system converges to the solution of the following Burgers equation

$$\partial_t u + \frac{1}{2} \partial_x u^2 = 0.$$

Introducing the quantities $a = v - cu$ and $b = v + cu$, (3) is equivalent to the diagonalized system

$$\partial_t a - c \partial_x a = \frac{1}{\varepsilon} \left(\frac{1}{2} \left(\frac{b-a}{2c} \right)^2 - \frac{a+b}{2} \right) \quad (4a)$$

$$\partial_t b + c \partial_x b = \frac{1}{\varepsilon} \left(\frac{1}{2} \left(\frac{b-a}{2c} \right)^2 - \frac{a+b}{2} \right). \quad (4b)$$

22 We will adapt the techniques developed in [16] to obtain convergence estimates for our system.

23 In order to illustrate this convergence result, numerical discretizations of the relaxation system (2)
 24 are investigated. The schemes we propose are such that they are uniform with respect to ε , that is they
 25 satisfy the so-called asymptotic preserving (AP) property [17]. Therefore, such schemes in the limit
 26 $\varepsilon \rightarrow 0$ must be consistent with the aggregation equation. Numerical simulations of solutions of the
 27 aggregation equation for pointy potentials have been studied by several authors see e.g. [11,13,18–22].
 28 In particular, some authors pay attention to recover the correct behavior of the numerical solutions

29 after the blow-up time. To do so, particular attention must be paid to the definition of the product
30 $a[\rho]\rho$ when ρ is a measure.

31 In this article, we propose two discretizations of the relaxation system which satisfy the AP
32 property. In a first approach, we propose a simple splitting algorithm where we split the transport
33 part and the right hand side in system (2). It results in a numerical scheme which is very simple
34 to implement and for which we verify easily the AP property. The second approach relies on a
35 well-balanced discretization in the spirit of [20,23]. This scheme is more expensive to implement than
36 the first scheme, but its numerical solution has less diffusion, as it is illustrated by our numerical
37 results.

38 The outline of the paper is the following. In section 2, after recalling some useful notations, we
39 prove our main result: an estimation of the speed of convergence in the Wasserstein W_1 distance
40 with respect to ε of the solutions of the relaxation system (2) towards the solution of the aggregation
41 equation (1) in the case $W(x) = \frac{1}{2}|x|$. The numerical discretization is investigated in section 3. Two
42 numerical schemes verifying the AP property are proposed. The first scheme is based on a splitting
43 algorithm, whereas the second scheme relies on a well-balanced discretization. Numerical results and
44 comparisons are provided in section 4.

45 2. Convergence result

46 2.1. Notations

Before stating and proving our main results, we first recall some useful notations and results. Since we are dealing with conservation laws (in which the total mass is conserved), we will work in some space of probability measures, namely the Wasserstein space of order $p \geq 1$, which is the space of probability measures with finite order p moment:

$$\mathcal{P}_p(\mathbb{R}^N) = \left\{ \mu \text{ nonnegative Borel measure, } \mu(\mathbb{R}^N) = 1, \int |x|^p \mu(dx) < \infty \right\}.$$

This space is endowed with the Wasserstein distance defined by (see e.g. [24,25])

$$W_p(\mu, \nu) = \inf_{\gamma \in \Gamma(\mu, \nu)} \left\{ \int |y - x|^p \gamma(dx, dy) \right\}^{1/p}, \quad (5)$$

where $\Gamma(\mu, \nu)$ is the set of measures on $\mathbb{R}^N \times \mathbb{R}^N$ with marginals μ and ν , i.e.

$$\Gamma(\mu, \nu) = \left\{ \gamma \in \mathcal{P}_p(\mathbb{R}^N \times \mathbb{R}^N); \forall \zeta \in C_0(\mathbb{R}^N), \int_{\mathbb{R}^{2N}} \zeta(y_0) \gamma(dy_0, dy_1) = \int_{\mathbb{R}^N} \zeta(y_0) \mu(dy_0), \right. \\ \left. \int_{\mathbb{R}^{2N}} \zeta(y_1) \gamma(dy_0, dy_1) = \int_{\mathbb{R}^N} \zeta(y_1) \nu(dy_1) \right\},$$

47 with $C_0(\mathbb{R}^N)$ the set of continuous functions on \mathbb{R}^N that vanish at infinity. From a simple minimization
48 argument, we know that in the definition of W_p the infimum is actually a minimum. A map that
49 realizes the minimum in the definition (5) of W_p is called an optimal transport plan, the set of which is
50 denoted by $\Gamma_0(\mu, \nu)$.

In the one-dimensional framework, we may simplify these definitions. Indeed any probability measure μ on the real line \mathbb{R} can be described in term of its cumulative distribution function $F_\mu(x) = \mu((-\infty, x))$ which is a right-continuous and nondecreasing function with $F_\mu(-\infty) = 0$ and $F_\mu(+\infty) = 1$. Then we can define the generalized inverse F_μ^{-1} of F_μ (or monotone rearrangement of μ) by

$F_\mu^{-1}(z) := \inf\{x \in \mathbb{R} / F_\mu(x) > z\}$, it is a right-continuous and nondecreasing function as well, defined on $[0, 1]$. We have for every nonnegative Borel map ξ ,

$$\int_{\mathbb{R}} \xi(x) \mu(dx) = \int_0^1 \xi(F_\mu^{-1}(z)) dz.$$

In particular, $\mu \in \mathcal{P}_p(\mathbb{R})$ if and only if $F_\mu^{-1} \in L^p(0, 1)$. Moreover, in the one-dimensional setting, there exists a unique optimal transport plan realizing the minimum in (5). More precisely, if μ and ν belong to $\mathcal{P}_p(\mathbb{R})$, with monotone rearrangements F_μ^{-1} and F_ν^{-1} , then $\Gamma_0(\mu, \nu) = \{(F_\mu^{-1}, F_\nu^{-1})_\# \mathbb{L}_{(0,1)}\}$ where $\mathbb{L}_{(0,1)}$ is the restriction of the Lebesgue measure on $(0, 1)$. Thus we have the explicit expression of the Wasserstein distance (see [24,26,27])

$$W_p(\mu, \nu) = \left(\int_0^1 |F_\mu^{-1}(z) - F_\nu^{-1}(z)|^p dz \right)^{1/p}, \quad (6)$$

51 and the map $\mu \mapsto F_\mu^{-1}$ is an isometry between $\mathcal{P}_p(\mathbb{R})$ and the convex subset of (essentially)
52 nondecreasing functions of $L^p(0, 1)$.

53 2.2. Convergence estimates

54 Let us first consider the limit $\varepsilon \rightarrow 0$ for the system (3). Compactness methods have been used in
55 [28] to get L^1_{loc} convergence in space. However, in order to pass to the aggregation equation, one may
56 want global L^1 convergence, which we prove in the following theorem, along the lines of Katsoulakis
57 and Tzavaras [16]:

Theorem 1. *Let $u_0 \in L^\infty \cap BV(\mathbb{R})$, $c > \|u_0\|_{L^\infty}$ and set $v_0 = \frac{u_0^2}{2}$. There exists a constant $C > 0$ such that, for any $\varepsilon > 0$, denoting by $(u^\varepsilon, v^\varepsilon)$ the solution to (3) with initial data (u_0, v_0) , the following estimate holds:*

$$\forall T > 0, \quad \|u(T) - u^\varepsilon(T)\|_{L^1} \leq CTV(u_0)(\sqrt{\varepsilon T} + \varepsilon),$$

58 where u is the entropy solution to the Burgers equation with initial datum u_0 .

59 **Proof.** Denote $(a^\varepsilon, b^\varepsilon)$ the solution to (4), and $G(a, b) = \frac{1}{2} \left(\frac{b-a}{2c} \right)^2 - \frac{a+b}{2}$.

60 So as to obtain entropy inequalities on $(a^\varepsilon, b^\varepsilon)$, we need monotonicity properties on G . One can
61 check that $G(a^\varepsilon, b^\varepsilon)$ is decreasing with respect to a^ε and b^ε if the so-called subcharacteristic condition
62 $|u^\varepsilon| < c$ holds. Up to a slight modification of the nonlinear term $f(u^\varepsilon) = \frac{(u^\varepsilon)^2}{2}$ in (3), which does not
63 affect the value of $(a^\varepsilon, b^\varepsilon)$:

$$f(u) := \begin{cases} -\|u_0\|u - \frac{\|u_0\|^2}{2}, & \text{if } u \leq -\|u_0\|, \\ \frac{u^2}{2}, & \text{if } -\|u_0\| \leq u \leq \|u_0\|, \\ \|u_0\|u - \frac{\|u_0\|^2}{2}, & \text{if } \|u_0\| \leq u, \end{cases}$$

64 the choice $c > \|u_0\|_{L^\infty}$ ensures that the subcharacteristic condition and the bound $\|u^\varepsilon(t)\|_{L^\infty} \leq \|u_0\|_{L^\infty}$
65 hold for all time.

66 Now, obtaining entropy inequalities on $(a^\varepsilon, b^\varepsilon)$ consists in making a comparison with constant
67 state solutions to (4). Namely, letting $m = \|u_0\|_{L^\infty} \left(\frac{\|u_0\|_{L^\infty}}{2} - c \right)$, $M = \|u_0\|_{L^\infty} \left(\frac{\|u_0\|_{L^\infty}}{2} + c \right)$ and
68 $h(a) = a + 2c^2 - 2c\sqrt{c^2 + 2a}$, we have $G(k, h(k)) = 0$ for all $k \in [m, M]$, and therefore $(k, h(k))$ is a
69 solution to (4). Thus the following system holds:

$$\partial_t(a^\varepsilon - k) - c\partial_x(a^\varepsilon - k) = \frac{1}{\varepsilon} \left(G(a^\varepsilon, b^\varepsilon) - G(k, h(k)) \right), \quad (7a)$$

$$\partial_t(b^\varepsilon - h(k)) + c\partial_x(b^\varepsilon - h(k)) = \frac{1}{\varepsilon} \left(G(a^\varepsilon, b^\varepsilon) - G(k, h(k)) \right). \quad (7b)$$

Multiplying (7a) by $\text{sgn}(a^\varepsilon - k)$, (7b) by $\text{sgn}(b^\varepsilon - h(k))$ and summing yields:

$$\begin{aligned} \partial_t \left(|a^\varepsilon - k| + |b^\varepsilon - h(k)| \right) - c\partial_x \left(|a^\varepsilon - k| - |b^\varepsilon - h(k)| \right) &= \frac{1}{\varepsilon} \left(\text{sgn}(a^\varepsilon - k) + \text{sgn}(b^\varepsilon - h(k)) \right) \times \\ &\quad \left(G(a^\varepsilon, b^\varepsilon) - G(k, h(k)) \right). \end{aligned}$$

Hence, using the monotonicity of G we get the following entropy inequalities on $(a^\varepsilon, b^\varepsilon)$:

$$\partial_t \left(|a^\varepsilon - k| + |b^\varepsilon - h(k)| \right) - c\partial_x \left(|a^\varepsilon - k| - |b^\varepsilon - h(k)| \right) \leq 0. \quad (8)$$

We now turn to proving entropy inequalities on u^ε . Straightforward computations yield the existence of a constant $C > 0$ such that, for all $a, b \in [m, M]$, one has $|h(a) - b| \leq C|G(a, b)|$. We therefore work on the variable $w^\varepsilon := \frac{h(a^\varepsilon) - a^\varepsilon}{2c}$ in the first place. Let $\kappa \in [-\|u_0\|_{L^\infty}, \|u_0\|_{L^\infty}]$, and $k \in [m, M]$ such that $\kappa = \frac{h(k) - k}{2c}$. We have:

$$|w^\varepsilon - \kappa| = \frac{1}{2c} \left(|h(a^\varepsilon) - h(k)| + |a^\varepsilon - k| \right) = \frac{1}{2c} \left(|a^\varepsilon - k| + |b^\varepsilon - h(k)| + r_1^\varepsilon \right), \quad (9)$$

where $r_1^\varepsilon = |h(a^\varepsilon) - h(k)| - |b^\varepsilon - h(k)|$ verifies $|r_1^\varepsilon| \leq |h(a^\varepsilon) - b^\varepsilon| \leq C|G(a^\varepsilon, b^\varepsilon)|$. Thus, we are left to control $|G(a^\varepsilon, b^\varepsilon)|$. To do so, we formally differentiate this quantity and use (4):

$$\begin{aligned} \partial_t |G(a^\varepsilon, b^\varepsilon)| &= \left(\partial_t a^\varepsilon \partial_a G(a^\varepsilon, b^\varepsilon) + \partial_t b^\varepsilon \partial_b G(a^\varepsilon, b^\varepsilon) \right) \text{sgn}(G(a^\varepsilon, b^\varepsilon)), \\ &= \frac{1}{\varepsilon} \left(\partial_a G(a^\varepsilon, b^\varepsilon) + \partial_b G(a^\varepsilon, b^\varepsilon) \right) |G(a^\varepsilon, b^\varepsilon)| - c \text{sgn}(G(a^\varepsilon, b^\varepsilon)) \left(\partial_x a^\varepsilon \partial_a G(a^\varepsilon, b^\varepsilon) + \partial_x b^\varepsilon \partial_b G(a^\varepsilon, b^\varepsilon) \right), \\ &\leq \frac{1}{\varepsilon} \sup_{[m, M]^2} \left(\partial_a G + \partial_b G \right) |G(a^\varepsilon, b^\varepsilon)| + c \sup_{[m, M]^2} \left(|\partial_a G| + |\partial_b G| \right) \left(|\partial_x a^\varepsilon| + |\partial_x b^\varepsilon| \right). \end{aligned}$$

Integrating in space gives:

$$\frac{d}{dt} \|G(a^\varepsilon, b^\varepsilon)\|_{L^1} \leq -\frac{A}{\varepsilon} \|G(a^\varepsilon, b^\varepsilon)\|_{L^1} + B \left(TV(a_0) + TV(b_0) \right),$$

where $A = -\sup_{[m, M]^2} (\partial_a G + \partial_b G)$ and $B = c \sup_{[m, M]^2} (|\partial_a G| + |\partial_b G|)$ are positive constants which do not depend on ε nor on time. A Gronwall lemma then gives:

$$\|G(a^\varepsilon(t), b^\varepsilon(t))\|_{L^1} \leq C \left(TV(a_0) + TV(b_0) \right) \varepsilon, \quad (10)$$

70 where we still denote $C = B/A$ a constant independent of time and of ε .

Besides, since, $G(a, h(a)) = 0$, one has $\frac{1}{2} \left(\frac{h(a) - a}{2c} \right)^2 = \frac{1}{2} (h(a) + a)$ and therefore:

$$\begin{aligned} \text{sgn}(w^\varepsilon - \kappa) \left(\frac{(w^\varepsilon)^2}{2} - \frac{\kappa^2}{2} \right) &= \frac{1}{2} \text{sgn} \left(h(a^\varepsilon) - h(k) - (a^\varepsilon - k) \right) \left(h(a^\varepsilon) + a^\varepsilon - (h(k) + k) \right), \\ &= \frac{1}{2} \left(|h(a^\varepsilon) - h(k)| - |a^\varepsilon - k| \right), \\ &= \frac{1}{2} \left(|b^\varepsilon - h(k)| - |a^\varepsilon - k| + r_2^\varepsilon \right), \end{aligned} \quad (11)$$

with $|r_2^\varepsilon| \leq C|G(a^\varepsilon, b^\varepsilon)|$. Differentiating (9) in time and (11) in space, and using (8) thus yields:

$$\partial_t |w^\varepsilon - \kappa| + \partial_x \operatorname{sgn}(w^\varepsilon - \kappa) \left(\frac{(w^\varepsilon)^2}{2} - \frac{\kappa^2}{2} \right) \leq \frac{1}{2c} \left(\partial_t r_1^\varepsilon + c \partial_x r_2^\varepsilon \right). \quad (12)$$

Then, we estimate $\|u(t) - w^\varepsilon(t)\|_{L^1}$ using Kuznetsov's doubling of variables technique (see e.g. [29] for scalar conservation laws with viscosity and [30] for a more general formalism) in order to combine (12) with Kruzkov inequalities on the entropy solution u , that read:

$$\partial_t |u - \kappa| + \partial_x \operatorname{sgn}(u - \kappa) (f(u) - f(\kappa)) \leq 0. \quad (13)$$

Writing respectively (13) at point (s, x) for $\kappa = w^\varepsilon(t, y)$ and (12) at point (t, y) for $\kappa = u(s, x)$, we get:

$$\partial_s |u(s, x) - w^\varepsilon(t, y)| + \partial_x \operatorname{sgn}(u(s, x) - w^\varepsilon(t, y)) \left(\frac{u(s, x)^2}{2} - \frac{(w^\varepsilon(t, y))^2}{2} \right) \leq 0, \quad (14a)$$

$$\partial_t |w^\varepsilon(t, y) - u(s, x)| + \partial_y \operatorname{sgn}(w^\varepsilon(t, y) - u(s, x)) \left(\frac{(w^\varepsilon(t, y))^2}{2} - \frac{u(s, x)^2}{2} \right) \leq \frac{1}{2c} \left(\partial_t r_1^\varepsilon(t, y) + c \partial_y r_2^\varepsilon(t, y) \right). \quad (14b)$$

Now, let $\omega_\alpha(t) = \frac{1}{\alpha} \omega\left(\frac{t}{\alpha}\right)$ and $\Omega_\beta(x) = \frac{1}{\beta} \Omega\left(\frac{x}{\beta}\right)$ be two mollifying kernels. Setting $g(s, t, x, y) = \omega_\alpha(s - t) \Omega_\beta(x - y)$ and testing (14a) and (14b) against $g(\cdot, t, \cdot, y) \mathbb{1}_{[0, T]}$ and $g(s, \cdot, x, \cdot) \mathbb{1}_{[0, T]}$ respectively, and integrating over $[0, T] \times \mathbb{R}$, we get on the one hand:

$$\begin{aligned} & \iiint \partial_s g(s, t, x, y) |u(s, x) - w^\varepsilon(t, y)| \, ds \, dx \, dt \, dy \\ & + \iiint \partial_x g(s, t, x, y) \operatorname{sgn}(u(s, x) - w^\varepsilon(t, y)) \left(\frac{u(s, x)^2}{2} - \frac{(w^\varepsilon(t, y))^2}{2} \right) \, ds \, dx \, dt \, dy \\ & - \iiint g(T, t, x, y) |u(T, x) - w^\varepsilon(t, y)| \, dx \, dt \, dy + \iiint g(0, t, x, y) |u(0, x) - w^\varepsilon(t, y)| \, dx \, dt \, dy \geq 0, \end{aligned} \quad (15)$$

and on the other hand:

$$\begin{aligned} & \iiint \partial_t g(s, t, x, y) |w^\varepsilon(t, y) - u(s, x)| \, ds \, dx \, dt \, dy \\ & + \iiint \partial_y g(s, t, x, y) \operatorname{sgn}(w^\varepsilon(t, y) - u(s, x)) \left(\frac{(w^\varepsilon(t, y))^2}{2} - \frac{u(s, x)^2}{2} \right) \, ds \, dx \, dt \, dy \\ & - \iiint g(s, T, x, y) |w^\varepsilon(T, y) - u(s, x)| \, ds \, dx \, dy + \iiint g(s, 0, x, y) |w^\varepsilon(0, y) - u(s, x)| \, ds \, dx \, dy \\ & \geq \frac{1}{2c} \left(\iiint \partial_t g(s, t, x, y) r_1^\varepsilon(t, y) \, ds \, dx \, dt \, dy + c \iiint \partial_y g(s, t, x, y) r_2^\varepsilon(t, y) \, ds \, dx \, dt \, dy \right. \\ & \left. - \iiint g(s, T, x, y) r_1^\varepsilon(T, y) \, ds \, dx \, dy + \iiint g(s, 0, x, y) r_1^\varepsilon(0, y) \, ds \, dx \, dy \right) =: \text{RHS}. \end{aligned} \quad (16)$$

Now, since $|\cdot|$ is even, and $\partial_s g = -\partial_t g$ and $\partial_x g = -\partial_y g$, we deduce by adding (15) and (16):

$$\begin{aligned} & - \iiint g(T, t, x, y) |u(T, x) - w^\varepsilon(t, y)| \, dx \, dt \, dy + \iiint g(0, t, x, y) |u(0, x) - w^\varepsilon(t, y)| \, dx \, dt \, dy \\ & - \iiint g(s, T, x, y) |u(s, x) - w^\varepsilon(T, y)| \, ds \, dx \, dy + \iiint g(s, 0, x, y) |u(s, x) - w^\varepsilon(0, y)| \, ds \, dx \, dy \geq \text{RHS}. \end{aligned} \quad (17)$$

Then, we write:

$$\begin{aligned} \|u(T) - w^\varepsilon(T)\|_{L^1} &= \iiint \omega_\alpha(T-t)\Omega_\beta(x-y)|u(T,y) - w^\varepsilon(T,y)| \, dx \, dt \, dy \\ &\quad + \iiint \omega_\alpha(s-T)\Omega_\beta(x-y)|u(T,y) - w^\varepsilon(T,y)| \, ds \, dx \, dy, \\ &=: I_1 + I_2. \end{aligned} \tag{18}$$

A triangle inequality gives for I_1 :

$$\begin{aligned} I_1 &\leq \iiint \omega_\alpha(T-t)\Omega_\beta(x-y)|u(T,y) - u(T,x)| \, dx \, dt \, dy \\ &\quad + \iiint \omega_\alpha(T-t)\Omega_\beta(x-y)|u(T,x) - w^\varepsilon(t,y)| \, dx \, dt \, dy \\ &\quad + \iiint \omega_\alpha(T-t)\Omega_\beta(x-y)|w^\varepsilon(t,y) - w^\varepsilon(T,y)| \, dx \, dt \, dy \\ &=: T_1 + T_2 + T_3. \end{aligned}$$

with $T_1 \leq C\beta \cdot TV(u_0)$, the second term T_2 appearing in (17) and for the last one we write:

$$T_3 \leq \int_{\mathbb{R}} \Omega_\beta(x-y) \int_0^T \omega_\alpha(T-t) \int_{\mathbb{R}} |w^\varepsilon(t,y) - w^\varepsilon(T,y)| \, dy \, dt \, dx,$$

and then we use the fact that w^ε is uniformly Lipschitz in $L^1(\mathbb{R})$ with respect to ε . Indeed, one has $\partial_t w^\varepsilon = \frac{\partial_t a^\varepsilon (h'(a^\varepsilon) - 1)}{2c}$ with $h'(a^\varepsilon) - 1$ being uniformly bounded with respect to ε as a^ε stays in the compact set $[m, M]$ for all time. In addition, estimating $\|\partial_t a^\varepsilon(t)\|_{L^1}$ can be done reusing (4) and (10):

$$\|\partial_t a^\varepsilon(t)\|_{L^1} \leq c \|\partial_x a^\varepsilon(t)\|_{L^1} + \frac{1}{\varepsilon} \|G(a^\varepsilon(t), b^\varepsilon(t))\|_{L^1} \leq C(TV(a_0) + TV(b_0)).$$

with $C > 0$ still independent of time and of ε . Hence $\|\partial_t w^\varepsilon(t)\|_{L^1} \leq C(TV(a_0) + TV(b_0))$ and $T_3 \leq \alpha C(TV(a_0) + TV(b_0))$. All in all, we get for I_1 :

$$I_1 \leq \iiint \omega_\alpha(T-t)\Omega_\beta(x-y)|u(T,x) - w^\varepsilon(t,y)| \, dx \, dt \, dy + C\beta \cdot TV(u_0) + \alpha C(TV(a_0) + TV(b_0)).$$

And, similarly, for I_2 :

$$I_2 \leq \iiint \omega_\alpha(s-T)\Omega_\beta(x-y)|u(s,x) - w^\varepsilon(T,y)| \, ds \, dx \, dy + C(\alpha + \beta)TV(u_0).$$

Back to (18), we obtain:

$$\|u(T) - w^\varepsilon(T)\|_{L^1} \leq \iiint \omega_\alpha(t)\Omega_\beta(x-y)|u(0,x) - w^\varepsilon(t,y)| \, dx \, dt \, dy \tag{19}$$

$$+ \iiint \omega_\alpha(s)\Omega_\beta(x-y)|u(s,x) - w^\varepsilon(0,y)| \, ds \, dx \, dy - RHS \tag{20}$$

$$+ \alpha C(TV(a_0) + TV(b_0)) + C(\alpha + \beta)TV(u_0). \tag{21}$$

But using a triangle inequality, one can show that:

$$\iiint \omega_\alpha(t)\Omega_\beta(x-y)|u_0(x) - w^\varepsilon(t,y)| \, dx \, dt \, dy \leq C\beta \cdot TV(u_0) + \alpha C(TV(a_0) + TV(b_0)),$$

and similarly:

$$\iiint \omega_\alpha(s)\Omega_\beta(x-y)|u(s,x) - w^\varepsilon(0,y)| \, ds \, dx \, dy \leq C(\alpha + \beta)TV(u_0).$$

We then bound from above the term RHS using inequality $\|r_i^\varepsilon(t)\|_{L^1} \leq C(TV(a_0) + TV(b_0))\varepsilon$ for $i = 1, 2$:

$$\begin{aligned} \left| \text{RHS} \right| &= \frac{1}{2c} \left| \frac{1}{\alpha} \iiint \omega' \left(\frac{s-t}{\alpha} \right) \Omega_\beta(x-y) r_1^\varepsilon(t, y) \, ds \, dx \, dt \, dy + \frac{c}{\beta} \iiint \omega_\alpha(s-t) \Omega'(x-y) r_2^\varepsilon(t, y) \, ds \right. \\ &\quad \left. dx \, dt \, dy - \iiint \omega_\alpha(s-T) \Omega_\beta(x-y) r_1^\varepsilon(T, y) \, ds \, dx \, dy + \iiint \omega_\alpha(s) \Omega_\beta(x-y) r_1^\varepsilon(0, y) \, ds \, dx \, dy \right|, \\ &\leq C \left(\frac{T}{\alpha} + \frac{T}{\beta} + 1 \right) \cdot (TV(a_0) + TV(b_0)) \varepsilon. \end{aligned}$$

Finally, we get:

$$\|u(T) - w^\varepsilon(T)\|_{L^1} \leq C \left(\frac{T}{\alpha} + \frac{T}{\beta} + 1 \right) (TV(a_0) + TV(b_0)) \varepsilon + C(\alpha + \beta)TV(u_0) + \alpha C(TV(a_0) + TV(b_0)),$$

which, after optimizing the values of α and β and noticing that $TV(a_0), TV(b_0) \leq C \cdot TV(u_0)$, gives:

$$\|u(T) - w^\varepsilon(T)\|_{L^1} \leq CTV(u_0)(\sqrt{\varepsilon T} + \varepsilon),$$

71 and this inequality, along with $|h(a) - b| \leq C|G(a, b)|$ and (10) gives in turn the result. \square

72 Denoting $\rho = -\partial_x u$, the convergence of $u^\varepsilon(t)$ towards $u(t)$ in $L^1(\mathbb{R})$ ensures that $\rho(t)$ is a
73 probability measure. Indeed, since for all $\varepsilon > 0$, $\rho^\varepsilon = -\partial_x u^\varepsilon$ is a nonnegative distribution, so is ρ .
74 The Riesz-Markov theorem then ensures that ρ can be represented by a nonnegative Borel measure.
75 Besides, for a.e. $t \geq 0$, $u^\varepsilon(t)$ is a nonincreasing function taking values in $[0, 1]$ and hence converges
76 to a certain limit when x goes to $+\infty$. The same holds true for the limit function $u(t)$. But, since
77 $u^\varepsilon(t) - u(t) \in L^1(\mathbb{R})$, then $u^\varepsilon(t, x) - u(t, x)$ must vanish as x goes to $+\infty$. Therefore the total mass of
78 $\rho(t)$ is 1.

79 Then, passing to the relaxation system (2) for the aggregation equation (1) can be done by using
80 (6) with $p = 1$. As a consequence, Theorem 1 translates as follows for the aggregation:

Theorem 2. *Let $\rho_0 \in \mathcal{P}_2(\mathbb{R})$, $c > 1/2$ and set $\sigma_0 = a[\rho_0]\rho_0$. There exists a constant $C > 0$ such that, for any $\varepsilon > 0$, denoting $(\rho^\varepsilon, \sigma^\varepsilon)$ the solution to (2) with initial data (ρ_0, σ_0) , one has :*

$$\forall T > 0, \quad W_1(\rho(T), \rho^\varepsilon(T)) \leq C(\sqrt{\varepsilon T} + \varepsilon),$$

81 where $\rho \in C([0, +\infty), \mathcal{P}_2(\mathbb{R}))$ is the unique solution (1) with initial datum ρ_0 .

82 3. Numerical discretization

83 From now on, we denote Δt the time step and we introduce a Cartesian mesh of size Δx . We
84 denote $t^n = n\Delta t$ for $n \in \mathbb{N}$ and $x_j = j\Delta x$ for $j \in \mathbb{Z}$. In this section, we extend our framework and
85 consider the aggregation equation (1) with arbitrary pointy potentials W , which satisfy the following
86 conditions:

- 87 (i) W is even and $W(0) = 0$,
- 88 (ii) $W \in \mathcal{C}^1(\mathbb{R} \setminus \{0\})$,
- 89 (iii) W is λ -convex, i.e. there exists $\lambda \in \mathbb{R}$ such that $W(x) - \lambda \frac{|x|^2}{2}$ is convex,
- 90 (iv) W is a_∞ -lipschitz continuous for some $a_\infty \geq 0$.

91 In this framework, the convergence of ρ^ε towards ρ for a slightly different problem has also been
92 studied in [7]. Adapting the argument, the convergence still holds provided the subcharacteristic
93 condition $c > a_\infty$ is verified. However, for such general potentials, the authors were not able to obtain
94 the estimates of the speed of convergence as stated in Theorem 2.

95 In this section, we propose some numerical schemes able to capture the limit $\varepsilon \rightarrow 0$, that is
 96 satisfying the so-called asymptotic preserving (AP) property. We consider two approaches, the first
 97 one based on a splitting algorithm, the second one based on a well-balanced discretisation.

98 3.1. A splitting algorithm

99 A first simple approach to discretize system (2) is to use a splitting method. Such a method is
 100 known to be convergent and easy to implement but introduces numerical diffusion.

Notice that the system (2) rewrites, with $\mu = \sigma - c\rho$, $v = \sigma + c\rho$, as:

$$\partial_t \mu - c \partial_x \mu = \frac{1}{\varepsilon} \left(a \left[\frac{v - \mu}{2c} \right] \left(\frac{v - \mu}{2c} \right) - \frac{\mu + v}{2} \right) \quad (22a)$$

$$\partial_t v + c \partial_x v = \frac{1}{\varepsilon} \left(a \left[\frac{v - \mu}{2c} \right] \left(\frac{v - \mu}{2c} \right) - \frac{\mu + v}{2} \right). \quad (22b)$$

The idea of the method is to solve in a first step on $(t^n, t^n + \Delta t)$ the system

$$\begin{aligned} \partial_t \mu &= \frac{1}{\varepsilon} \left(a \left[\frac{v - \mu}{2c} \right] \left(\frac{v - \mu}{2c} \right) - \frac{\mu + v}{2} \right) \\ \partial_t v &= \frac{1}{\varepsilon} \left(a \left[\frac{v - \mu}{2c} \right] \left(\frac{v - \mu}{2c} \right) - \frac{\mu + v}{2} \right), \end{aligned}$$

with initial data $(\mu(t^n), v(t^n)) = (\mu^n, v^n)$. We obtain $\mu_j^{n+\frac{1}{2}} = \mu(t^n + \Delta t, x_j)$ and $v_j^{n+\frac{1}{2}} = v(t^n + \Delta t, x_j)$. Notice that this system may be solved explicetely. Indeed, by adding and subtracting the two equations, we deduce after an integration

$$v_j^{n+\frac{1}{2}} - \mu_j^{n+\frac{1}{2}} = v_j^n - \mu_j^n \quad (23a)$$

$$\mu_j^{n+\frac{1}{2}} + v_j^{n+\frac{1}{2}} = (\mu_j^n + v_j^n) e^{-\Delta t/\varepsilon} + a \left[\frac{v^n - \mu^n}{2c} \right] \left(\frac{v^n - \mu^n}{2c} \right) (1 - e^{-\Delta t/\varepsilon}). \quad (23b)$$

Then, in a second step, we discretize by a classical finite volume upwind scheme the system

$$\partial_t \mu - c \partial_x \mu = 0, \quad \partial_t v + c \partial_x v = 0.$$

That is

$$\mu_j^{n+1} = \mu_j^{n+\frac{1}{2}} + c \frac{\Delta t}{\Delta x} (\mu_{j+1}^{n+\frac{1}{2}} - \mu_j^{n+\frac{1}{2}}), \quad (24a)$$

$$v_j^{n+1} = v_j^{n+\frac{1}{2}} - c \frac{\Delta t}{\Delta x} (v_j^{n+\frac{1}{2}} - v_{j-1}^{n+\frac{1}{2}}). \quad (24b)$$

Coming back to the variables ρ and σ , we obtain

$$\begin{aligned} v_j^{n+\frac{1}{2}} &= c \rho_j^n + \sigma_j^n e^{-\Delta x/\varepsilon} + a_j^n \rho_j^n (1 - e^{-\Delta t/\varepsilon}), \\ \mu_j^{n+\frac{1}{2}} &= -c \rho_j^n + \sigma_j^n e^{-\Delta x/\varepsilon} + a_j^n \rho_j^n (1 - e^{-\Delta t/\varepsilon}), \end{aligned}$$

with $a_j^n = -\sum_{k \neq j} W'(x_j - x_k) \rho_k^n$. Then, the splitting algorithm reads

$$\begin{aligned} \rho_j^{n+1} &= \rho_j^n - \frac{1}{2} \frac{\Delta t}{\Delta x} (\mu_{j+1}^{n+\frac{1}{2}} + v_j^{n+\frac{1}{2}} - \mu_j^{n+\frac{1}{2}} - v_{j-1}^{n+\frac{1}{2}}) \\ &= \rho_j^n - \frac{1}{2} \frac{\Delta t}{\Delta x} \left((\sigma_{j+1}^n - \sigma_{j-1}^n) e^{-\Delta t/\varepsilon} + (1 - e^{-\Delta t/\varepsilon}) (a_{j+1}^n \rho_{j+1}^n - a_{j-1}^n \rho_{j-1}^n) - c(\rho_{j+1}^n - 2\rho_j^n + \rho_{j-1}^n) \right), \end{aligned} \quad (25)$$

and

$$\begin{aligned}
\sigma_j^{n+1} &= \sigma_j^{n+\frac{1}{2}} + \frac{c}{2} \frac{\Delta t}{\Delta x} (\sigma_{j+1}^n - 2\sigma_j^n + \sigma_{j-1}^n) e^{-\Delta t/\varepsilon} \\
&\quad + \frac{c}{2} \frac{\Delta t}{\Delta x} \left((a_{j+1}^n \rho_{j+1}^n - 2a_j^n \rho_j^n + a_{j-1}^n \rho_{j-1}^n) (1 - e^{-\Delta t/\varepsilon}) - c(\rho_{j+1}^n - \rho_{j-1}^n) \right) \\
&= \sigma_j^n e^{-\Delta t/\varepsilon} + a_j^n \rho_j^n (1 - e^{-\Delta t/\varepsilon}) + \frac{c}{2} \frac{\Delta t}{\Delta x} (\sigma_{j+1}^n - 2\sigma_j^n + \sigma_{j-1}^n) e^{-\Delta t/\varepsilon} \\
&\quad + \frac{c}{2} \frac{\Delta t}{\Delta x} \left((a_{j+1}^n \rho_{j+1}^n - 2a_j^n \rho_j^n + a_{j-1}^n \rho_{j-1}^n) (1 - e^{-\Delta t/\varepsilon}) - c(\rho_{j+1}^n - \rho_{j-1}^n) \right).
\end{aligned} \tag{26}$$

Lemma 1. For any $\varepsilon > 0$, if both the CFL condition $\frac{c\Delta t}{\Delta x} \leq 1$ and the subcharacteristic condition $c \geq a_\infty$ hold, then the splitting scheme (23)–(24) is L^1 -stable:

$$\forall n \in \mathbb{N}, \quad \sum_{j \in \mathbb{Z}} \left(|\mu_j^{n+1}| + |v_j^{n+1}| \right) \leq \sum_{j \in \mathbb{Z}} \left(|\mu_j^n| + |v_j^n| \right).$$

Proof. We have:

$$\begin{aligned}
\mu_j^{n+\frac{1}{2}} &= \frac{1}{2} \left(e^{-\Delta t/\varepsilon} \left(1 + \frac{a_j^n}{c} \right) + 1 - \frac{a_j^n}{c} \right) \mu_j^n - \frac{1 - e^{-\Delta t/\varepsilon}}{2} \left(1 - \frac{a_j^n}{c} \right) v_j^n, \\
v_j^{n+\frac{1}{2}} &= -\frac{1 - e^{-\Delta t/\varepsilon}}{2} \left(1 + \frac{a_j^n}{c} \right) \mu_j^n + \frac{1}{2} \left(e^{-\Delta t/\varepsilon} \left(1 - \frac{a_j^n}{c} \right) + 1 + \frac{a_j^n}{c} \right) v_j^n.
\end{aligned}$$

Under the condition $c \geq a_\infty$, in the expression of $\mu_j^{n+\frac{1}{2}}$, the coefficient in front of μ_j^n is nonnegative and the one in front of v_j^n is nonpositive. Similarly, in $v_j^{n+\frac{1}{2}}$, the coefficient of μ_j^n is nonpositive and the one in front of v_j^n is nonnegative. Taking the absolute value and adding up therefore yields:

$$|\mu_j^{n+\frac{1}{2}}| + |v_j^{n+\frac{1}{2}}| \leq |\mu_j^n| + |v_j^n|.$$

It remains to remark that, provided the CFL condition $\frac{c\Delta t}{\Delta x} \leq 1$ is verified, (24) gives:

$$\begin{aligned}
\sum_{j \in \mathbb{Z}} \left(|\mu_j^{n+1}| + |v_j^{n+1}| \right) &\leq \left(1 - \frac{c\Delta t}{\Delta x} \right) \sum_{j \in \mathbb{Z}} \left(|\mu_j^{n+\frac{1}{2}}| + |v_j^{n+\frac{1}{2}}| \right) + \frac{c\Delta t}{\Delta x} \sum_{j \in \mathbb{Z}} |\mu_{j+1}^{n+\frac{1}{2}}| + \frac{c\Delta t}{\Delta x} \sum_{j \in \mathbb{Z}} |v_{j-1}^{n+\frac{1}{2}}|, \\
&\leq \left(1 - \frac{c\Delta t}{\Delta x} \right) \sum_{j \in \mathbb{Z}} \left(|\mu_j^n| + |v_j^n| \right) + \frac{c\Delta t}{\Delta x} \sum_{j \in \mathbb{Z}} |\mu_j^{n+\frac{1}{2}}| + \frac{c\Delta t}{\Delta x} \sum_{j \in \mathbb{Z}} |v_j^{n+\frac{1}{2}}|, \\
&\leq \sum_{j \in \mathbb{Z}} \left(|\mu_j^n| + |v_j^n| \right).
\end{aligned}$$

101 \square

102 Note that similar schemes have also been studied in [31] and proved convergent at rate $\sqrt{\Delta x}$.

Let us now verify the AP property. When $\varepsilon \rightarrow 0$, we verify that the equation on ρ (25) converges to the following Rusanov discretization of (1) (see [21] for numerical simulations using the Rusanov scheme):

$$\rho_j^{n+1} = \rho_j^n - \frac{1}{2} \frac{\Delta t}{\Delta x} \left(a_{j+1}^n \rho_{j+1}^n - a_{j-1}^n \rho_{j-1}^n \right) + \frac{c\Delta t}{2\Delta x} (\rho_{j+1}^n - 2\rho_j^n + \rho_{j-1}^n), \tag{27a}$$

$$a_j^n = - \sum_{k \neq j} W'(x_j - x_k) \rho_k^n. \tag{27b}$$

103 This limiting scheme provides a constant discretization of (1). Indeed, similar scheme has been
 104 extensively studied in [11] using compactness arguments and the following convergence result has
 105 been proved:

Lemma 2. Assume $\rho_0 \in \mathcal{P}_2(\mathbb{R})$ and that the stability conditions $c \frac{\Delta t}{\Delta x} \leq 1$ and $c \geq a_\infty$ are satisfied. Let $T > 0$ and suppose we initialize the scheme (27) with $\rho_j^0 = \frac{1}{\Delta x} \rho_0(C_j)$ where $C_j = [x_{j-\frac{1}{2}}, x_{j+\frac{1}{2}})$. Then, denoting $\rho_{\Delta x}$ the reconstruction given by the scheme (27), that is:

$$\rho_{\Delta x}(t) = \sum_{n \in \mathbb{N}} \sum_{j \in \mathbb{Z}} \rho_j^n \mathbb{1}_{[t^n, t^{n+1})}(t) \delta_{x_j},$$

106 then $\rho_{\Delta x}$ converges weakly in the sense of measures on $[0, T] \times \mathbb{R}$ towards the solution ρ of equation (1) as Δx
 107 goes to 0.

108 It has been also proved in [32] that the scheme (27) converges at rate $\sqrt{\Delta x}$.

109 3.2. Well-balanced discretization

110 Although the splitting method provides a simple way to obtain a discretization which is uniform
 111 with respect to the parameter ε , the resulting scheme has strong numerical diffusion and may not have
 112 good large time behaviour. Then, well-balanced schemes have been introduced. A scheme is said to be
 113 well-balanced when it conserves equilibria. The method proposed in this section comes from [20].

Let us assume that for some $n \in \mathbb{N}$ the approximation $(\mu_j^n, v_j^n)_{j \in \mathbb{Z}}$ of $(\mu(t^n, x_j), v(t^n, x_j))_{j \in \mathbb{Z}}$ solution of (22) is known. We construct an approximation at time t^{n+1} using a finite volume upwind discretization of (22), with the discretization of the source terms $H_{\mu,j}^n, H_{v,j}^n$ to be prescribed right afterwards:

$$\mu_j^{n+1} = \mu_j^n + c \frac{\Delta t}{\Delta x} (\mu_{j+1}^n - \mu_j^n) + \frac{\Delta t}{\varepsilon} H_{\mu,j}^n \quad (28a)$$

$$v_j^{n+1} = v_j^n - c \frac{\Delta t}{\Delta x} (v_j^n - v_{j-1}^n) + \frac{\Delta t}{\varepsilon} H_{v,j}^n. \quad (28b)$$

In order to preserve equilibria, we set :

$$H_{\mu,j}^n = \frac{1}{\Delta x} \int_{x_{j-1}}^{x_j} H(\bar{\mu}, \bar{v}) dx, \quad H(\mu, v) = a \left[\frac{v - \mu}{2c} \right] \left(\frac{v - \mu}{2c} \right) - \frac{\mu + v}{2}, \quad (29)$$

where $(\bar{\mu}, \bar{v})$ solve the stationary system with incoming boundary conditions, on (x_{j-1}, x_j) :

$$-c \partial_x \bar{\mu} = \frac{1}{\varepsilon} H(\bar{\mu}, \bar{v}) \quad (30a)$$

$$c \partial_x \bar{v} = \frac{1}{\varepsilon} H(\bar{\mu}, \bar{v}) \quad (30b)$$

$$\bar{\mu}(x_j) = \mu_j^n, \quad \bar{v}(x_{j-1}) = v_{j-1}^n. \quad (30c)$$

And, in the same fashion, $H_{v,j}^n = \frac{1}{\Delta x} \int_{x_j}^{x_{j+1}} H(\tilde{\mu}, \tilde{v}) dx$, where $(\tilde{\mu}, \tilde{v})$ is the solution of the stationary system on (x_j, x_{j+1}) :

$$-c \partial_x \tilde{\mu} = \frac{1}{\varepsilon} H(\tilde{\mu}, \tilde{v}) \quad (31a)$$

$$c \partial_x \tilde{v} = \frac{1}{\varepsilon} H(\tilde{\mu}, \tilde{v}) \quad (31b)$$

$$\tilde{\mu}(x_{j+1}) = \mu_{j+1}^n, \quad \tilde{v}(x_j) = v_j^n, \quad (31c)$$

Reporting equations (30b) and (31a) into the discretization of the source term, we get $H_{v,j}^n = \frac{c\varepsilon}{\Delta x}(\bar{v}(x_j) - v_{j-1})$ and $H_{\mu,j}^n = -\frac{c\varepsilon}{\Delta x}(\mu_j^n - \tilde{\mu}(x_j))$. Hence, one may rewrite the scheme (28) as:

$$\mu_j^{n+1} = \mu_j^n + c \frac{\Delta t}{\Delta x} (\tilde{\mu}(x_j) - \mu_j^n) \quad (32a)$$

$$v_j^{n+1} = v_j^n - c \frac{\Delta t}{\Delta x} (v_j^n - \bar{v}(x_j)). \quad (32b)$$

Remark that the stationary system

$$-c\partial_x \mu = \frac{1}{\varepsilon} H(\mu, v), \quad c\partial_x v = \frac{1}{\varepsilon} H(\mu, v), \quad (33)$$

is equivalent to

$$\partial_x \sigma = 0, \quad c^2 \partial_x \rho = \frac{1}{\varepsilon} (a[\rho] \rho - \sigma). \quad (34)$$

Therefore, denoting $\sigma_{j+\frac{1}{2}} = \frac{\tilde{\mu} + \bar{v}}{2}$ and $\sigma_{j-\frac{1}{2}} = \frac{\bar{\mu} + \bar{v}}{2}$, which are constant respectively on (x_j, x_{j+1}) and (x_{j-1}, x_j) , one has:

$$\tilde{\mu}(x_j) = 2\sigma_{j+\frac{1}{2}} - v_j^n, \quad \bar{v}(x_j) = 2\sigma_{j-\frac{1}{2}} - \mu_j^n. \quad (35)$$

Thus, it turns out that the scheme can be rewritten only in terms of the discretized unknowns and of $\sigma_{j\pm\frac{1}{2}}$:

$$\mu_j^{n+1} = \mu_j^n - c \frac{\Delta t}{\Delta x} (\mu_j^n + v_j^n) + \frac{2c\Delta t}{\Delta x} \sigma_{j+\frac{1}{2}}, \quad (36a)$$

$$v_j^{n+1} = v_j^n - c \frac{\Delta t}{\Delta x} (\mu_j^n + v_j^n) + \frac{2c\Delta t}{\Delta x} \sigma_{j-\frac{1}{2}}. \quad (36b)$$

Or equivalently:

$$\rho_j^{n+1} = \rho_j^n - \frac{\Delta t}{\Delta x} (\sigma_{j+\frac{1}{2}} - \sigma_{j-\frac{1}{2}}), \quad (37a)$$

$$\sigma_j^{n+1} = \sigma_j^n - c \frac{\Delta t}{\Delta x} (2\sigma_j^n - \sigma_{j+\frac{1}{2}} - \sigma_{j-\frac{1}{2}}). \quad (37b)$$

114 However, solving the stationary systems (30) and (31) involves the resolution of a nonlinear and
115 nonlocal ODE. Instead, we propose an approximation in the spirit of [20].

116 We replace the nonlinear term in (30a)–(30b) by $a_{j-\frac{1}{2}}^n \cdot \frac{\bar{v}-\bar{\mu}}{2c}$, where $a_{j-\frac{1}{2}}^n$ stands for a fixed and
117 consistent discretization of $a \left[\frac{\bar{v}-\bar{\mu}}{2c} \right]$ on the interval (x_{j-1}, x_j) , to be specified afterwards. Similarly,
118 we will replace the nonlinear term in (31a)–(31b) by $a_{j+\frac{1}{2}}^n \cdot \frac{\bar{v}-\bar{\mu}}{2c}$ with $a_{j+\frac{1}{2}}^n$ defined accordingly. In the
119 following, we detail the construction for the problem (30a)–(30b) on (x_{j-1}, x_j) .

120 Obviously, the definition of $a_{j-\frac{1}{2}}^n$ should be taken with care [11,20]. In [32], the authors showed
121 that, when discretizing the product $a[\rho]\rho$, if $a[\rho]$ and ρ were not evaluated at the same point, then the
122 resulting scheme produces the wrong dynamics. To take this into account, we will split ρ into one
123 contribution coming from the left and one contribution coming from the right, i.e. we set $\bar{\rho} = \rho_L + \rho_R$
124 and $\bar{\sigma} = \sigma_L + \sigma_R$ where $\rho_L(\Delta x) = 0$ and $\rho_R(0) = 0$. This implies that $\bar{\rho}(\Delta x) = \rho_R(\Delta x)$ and $\bar{\rho}(0) =$
125 $\rho_L(0)$.

More precisely, we solve the two following boundary value problem, on $(0, \Delta x)$,

$$\varepsilon c^2 \frac{d}{dx} \rho_L = a_{j-\frac{1}{2},L}^n \rho_L - \sigma_L, \quad \rho_L(\Delta x) = 0, \quad (38a)$$

$$\varepsilon c^2 \frac{d}{dx} \rho_R = a_{j-\frac{1}{2},R}^n \rho_R - \sigma_R, \quad \rho_R(0) = 0, \quad (38b)$$

We may solve explicitly these linear systems and, since $\rho_L(0) = \bar{\rho}(0)$ and $\rho_R(\Delta x) = \bar{\rho}(\Delta x)$, obtain the relations

$$\sigma_L = \bar{\rho}(0)\kappa_{j-\frac{1}{2},L}^n, \quad \sigma_R = \bar{\rho}(\Delta x)\kappa_{j-\frac{1}{2},R}^n. \quad (39)$$

with

$$\kappa_{j-\frac{1}{2},L}^n = \frac{a_{j-\frac{1}{2},L}^n}{1 - \exp(-a_{j-\frac{1}{2},L}^n \Delta x / (\varepsilon c^2))}, \quad \kappa_{j-\frac{1}{2},R}^n = \frac{a_{j-\frac{1}{2},R}^n}{1 - \exp(a_{j-\frac{1}{2},R}^n \Delta x / (\varepsilon c^2))}. \quad (40)$$

Notice that we have

$$\kappa_{j-\frac{1}{2},L}^n \rightarrow (a_{j-\frac{1}{2},L}^n)_+, \quad \kappa_{j-\frac{1}{2},R}^n \rightarrow -(a_{j-\frac{1}{2},R}^n)_-, \quad \text{when } \varepsilon \rightarrow 0, \quad (41)$$

where we denote $a_+ = \max(0, a) \geq 0$ and $a_- = \max(0, -a) \geq 0$ the positive and negative negative part of a . Using the boundary conditions in (30), we have:

$$\bar{\rho}(0) = \frac{v_{j-1}^n - \bar{\mu}(0)}{2c}, \quad \bar{\rho}(\Delta x) = \frac{\bar{v}(\Delta x) - \mu_j^n}{2c}. \quad (42)$$

with (39) and the fact that $\bar{\sigma} = \sigma_L + \sigma_R$ is constant on $[0, \Delta x]$, we get the following 2×2 system on the unknowns $\bar{\mu}(0), \bar{v}(\Delta x)$:

$$\mu_j^n + \bar{v}(\Delta x) = \bar{\mu}(0) + v_{j-1}^n, \quad (43a)$$

$$\mu_j^n + \bar{v}(\Delta x) = \frac{v_{j-1}^n - \bar{\mu}(0)}{2c} \kappa_{j-\frac{1}{2},L}^n + \frac{\bar{v}(\Delta x) - \mu_j^n}{2c} \kappa_{j-\frac{1}{2},R}^n \quad (43b)$$

Solving this system yields:

$$\bar{\mu}(0) = -v_{j-1}^n \frac{c - \kappa_{j-\frac{1}{2},R}^n - \kappa_{j-\frac{1}{2},L}^n}{c - \kappa_{j-\frac{1}{2},R}^n + \kappa_{j-\frac{1}{2},L}^n} - \mu_j^n \frac{\kappa_{j-\frac{1}{2},R}^n}{c - \kappa_{j-\frac{1}{2},R}^n + \kappa_{j-\frac{1}{2},L}^n}, \quad (44a)$$

$$\bar{v}(\Delta x) = v_{j-1}^n \frac{\kappa_{j-\frac{1}{2},L}^n}{c - \kappa_{j-\frac{1}{2},R}^n + \kappa_{j-\frac{1}{2},L}^n} - \mu_j^n \frac{c + \kappa_{j-\frac{1}{2},R}^n + \kappa_{j-\frac{1}{2},L}^n}{c - \kappa_{j-\frac{1}{2},R}^n + \kappa_{j-\frac{1}{2},L}^n}. \quad (44b)$$

From which we deduce with (42)

$$\rho_{j-\frac{1}{2},L}^n := \bar{\rho}(0) = \frac{1}{c} \left(\frac{(c - \kappa_{j-\frac{1}{2},R}^n)v_{j-1}^n + \kappa_{j-\frac{1}{2},R}^n \mu_j^n}{c + \kappa_{j-\frac{1}{2},L}^n - \kappa_{j-\frac{1}{2},R}^n} \right) \quad (45a)$$

$$\rho_{j-\frac{1}{2},R}^n := \bar{\rho}(\Delta x) = \frac{1}{c} \left(\frac{\kappa_{j-\frac{1}{2},L}^n v_{j-1}^n - (c + \kappa_{j-\frac{1}{2},L}^n) \mu_j^n}{c + \kappa_{j-\frac{1}{2},L}^n - \kappa_{j-\frac{1}{2},R}^n} \right) \quad (45b)$$

and with (39)

$$\bar{\sigma}_{j-\frac{1}{2}} := \sigma_L + \sigma_R = \rho_{j-\frac{1}{2},L}^n \kappa_{j-\frac{1}{2},L}^n + \rho_{j-\frac{1}{2},R}^n \kappa_{j-\frac{1}{2},R}^n = \frac{v_{j-1}^n \kappa_{j-\frac{1}{2},L}^n - \mu_j^n \kappa_{j-\frac{1}{2},R}^n}{c - \kappa_{j-\frac{1}{2},R}^n + \kappa_{j-\frac{1}{2},L}^n}, \quad (46)$$

(the above quantities are well-defined since $\kappa_{j-\frac{1}{2},L}^n \geq 0$ and $\kappa_{j-\frac{1}{2},R}^n \leq 0$). Injecting into (37), it gives the following scheme

$$\mu_j^{n+1} = \left(1 - \frac{c\Delta t}{\Delta x}\right) \mu_j^n - \frac{c\Delta t}{\Delta x} \frac{c - \kappa_{j+\frac{1}{2},R}^n - \kappa_{j+\frac{1}{2},L}^n}{c - \kappa_{j+\frac{1}{2},R}^n + \kappa_{j+\frac{1}{2},L}^n} v_j^n - \frac{2c\Delta t}{\Delta x} \frac{\kappa_{j+\frac{1}{2},R}^n}{c - \kappa_{j+\frac{1}{2},R}^n + \kappa_{j+\frac{1}{2},L}^n} \mu_{j+1}^n, \quad (47a)$$

$$v_j^{n+1} = \left(1 - \frac{c\Delta t}{\Delta x}\right) v_j^n - \frac{c\Delta t}{\Delta x} \frac{c + \kappa_{j-\frac{1}{2},R}^n + \kappa_{j-\frac{1}{2},L}^n}{c - \kappa_{j-\frac{1}{2},R}^n + \kappa_{j-\frac{1}{2},L}^n} \mu_j^n + \frac{2c\Delta t}{\Delta x} \frac{\kappa_{j-\frac{1}{2},L}^n}{c - \kappa_{j-\frac{1}{2},R}^n + \kappa_{j-\frac{1}{2},L}^n} v_{j-1}^n, \quad (47b)$$

where the coefficients $\kappa_{j-\frac{1}{2},L/R}^n$ are defined in (40). Equivalently for the variable (ρ, σ) the scheme reads

$$\rho_j^{n+1} = \rho_j^n - \frac{\Delta t}{\Delta x} \left(\frac{v_j^n \kappa_{j+\frac{1}{2},L}^n - \mu_{j+1}^n \kappa_{j+\frac{1}{2},R}^n}{c - \kappa_{j+\frac{1}{2},R}^n + \kappa_{j+\frac{1}{2},L}^n} - \frac{v_{j-1}^n \kappa_{j-\frac{1}{2},L}^n - \mu_j^n \kappa_{j-\frac{1}{2},R}^n}{c - \kappa_{j-\frac{1}{2},R}^n + \kappa_{j-\frac{1}{2},L}^n} \right) \quad (48a)$$

$$\sigma_j^{n+1} = \sigma_j^n - c \frac{\Delta t}{\Delta x} \left(2\sigma_j^n - \frac{v_j^n \kappa_{j+\frac{1}{2},L}^n - \mu_{j+1}^n \kappa_{j+\frac{1}{2},R}^n}{c - \kappa_{j+\frac{1}{2},R}^n + \kappa_{j+\frac{1}{2},L}^n} - \frac{v_{j-1}^n \kappa_{j-\frac{1}{2},L}^n - \mu_j^n \kappa_{j-\frac{1}{2},R}^n}{c - \kappa_{j-\frac{1}{2},R}^n + \kappa_{j-\frac{1}{2},L}^n} \right), \quad (48b)$$

126 where we recall that $\mu_j^n = \sigma_j^n - c\rho_j^n$ and $v_j^n = \sigma_j^n + c\rho_j^n$.

It remains to define the velocities $a_{j-\frac{1}{2},L/R}^n$ used in (38) and in (40). We take

$$a_{j-\frac{1}{2},L/R}^n = - \sum_{k \neq j} W'(x_j - x_k) \rho_{k-\frac{1}{2},L/R}^n.$$

127 However, this discretization implies the resolution of a nonlinear problem, since the quantities $\rho_{k-\frac{1}{2},L/R}^n$
128 depends nonlinearly on $a_{j-\frac{1}{2},L/R}^n$.

129 Then, we implement a fixed point method initialized with $a_{j-\frac{1}{2},L}^{n,(0)} := a_{j-1}^n$ and $a_{j-\frac{1}{2},R}^{n,(0)} := a_j^n$.
130 Solving, on each cell (x_{j-1}, x_j) , the system of ODEs (38) with these values for the velocities gives two
131 sequences $(\rho_{j-\frac{1}{2},L}^{(1)})_{j \in \mathbb{Z}}$ and $(\rho_{j-\frac{1}{2},R}^{(1)})_{j \in \mathbb{Z}}$. Then, we assign the next value of the velocity to $a_{j-\frac{1}{2},L/R}^{n,(1)} :=$
132 $-\sum_{k \neq j} W'(x_j - x_k) \rho_{k-\frac{1}{2},L/R}^{(1)}$ which allows us to compute new values for the left and right densities
133 $(\rho_{j-\frac{1}{2},L}^{(2)})_{j \in \mathbb{Z}}$ and $(\rho_{j-\frac{1}{2},R}^{(2)})_{j \in \mathbb{Z}}$ through (38). We iterate until $W_2(\rho_L^{(i)}, \rho_L^{(i+1)})$ and $W_2(\rho_R^{(i)}, \rho_R^{(i+1)})$ pass
134 below a certain threshold. Notice that the velocities $a_{j-\frac{1}{2},L/R}^{n,(i)}$ always remain bounded by a_∞ . In
135 practice, only a few iterations are needed.

136 The resulting scheme is consistent for any $\varepsilon > 0$ and stable under standard stability conditions, as
137 show the following lemmas.

Lemma 3 (L^1 stability). *Under the CFL condition $\frac{c\Delta t}{\Delta x} \leq 1$ and the subcharacteristic condition $c \geq a_\infty$, there holds that the sequence $(\mu_j^n, v_j^n)_{j,n}$ defined by the scheme (47) verifies the following L^1 stability property:*

$$\forall n \in \mathbb{N}, \quad \sum_{j \in \mathbb{Z}} \left(|\mu_j^{n+1}| + |v_j^{n+1}| \right) \leq \sum_{j \in \mathbb{Z}} \left(|\mu_j^n| + |v_j^n| \right).$$

Proof. In each combination of (47), the first coefficient is nonnegative under the CFL condition $\frac{c\Delta t}{\Delta x} \leq 1$, and so is the last one since $\kappa_{j+\frac{1}{2},L}^n \geq 0$ and $\kappa_{j+\frac{1}{2},R}^n \leq 0$. Moreover, under the subcharacteristic condition

$c \geq a_\infty$, it holds that $-c \leq \kappa_{j\pm\frac{1}{2},R} + \kappa_{j\pm\frac{1}{2},L} \leq c$ so the remaining coefficient is nonpositive. Thus, applying the triangle inequality and reindexing the sums appropriately,

$$\begin{aligned} \sum_{j \in \mathbb{Z}} (|\mu_j^{n+1}| + |v_j^{n+1}|) &\leq \sum_{j \in \mathbb{Z}} \left(1 - \frac{c\Delta t}{\Delta x}\right) |\mu_j^n| + \sum_{j \in \mathbb{Z}} \frac{c\Delta t}{\Delta x} \frac{c - \kappa_{j+\frac{1}{2},R}^n - \kappa_{j+\frac{1}{2},L}^n}{c - \kappa_{j+\frac{1}{2},R}^n + \kappa_{j+\frac{1}{2},L}^n} |v_j^n| \\ &\quad - \sum_{j \in \mathbb{Z}} \frac{2c\Delta t}{\Delta x} \frac{\kappa_{j+\frac{1}{2},R}^n}{c - \kappa_{j+\frac{1}{2},R}^n + \kappa_{j+\frac{1}{2},L}^n} |\mu_{j+1}^n| + \sum_{j \in \mathbb{Z}} \left(1 - \frac{c\Delta t}{\Delta x}\right) |v_j^n| \\ &\quad + \sum_{j \in \mathbb{Z}} \frac{c\Delta t}{\Delta x} \frac{c + \kappa_{j+\frac{1}{2},R}^n + \kappa_{j+\frac{1}{2},L}^n}{c - \kappa_{j+\frac{1}{2},R}^n + \kappa_{j+\frac{1}{2},L}^n} |\mu_{j+1}^n| + \frac{2c\Delta t}{\Delta x} \frac{\kappa_{j+\frac{1}{2},L}^n}{c - \kappa_{j+\frac{1}{2},R}^n + \kappa_{j+\frac{1}{2},L}^n} |v_j^n|, \\ &\leq \left(1 - \frac{c\Delta t}{\Delta x}\right) \sum_{j \in \mathbb{Z}} (|\mu_j^n| + |v_j^n|) + \frac{c\Delta t}{\Delta x} \sum_{j \in \mathbb{Z}} |\mu_{j+1}^n| + \frac{c\Delta t}{\Delta x} \sum_{j \in \mathbb{Z}} |v_j^n|, \\ &\leq \sum_{j \in \mathbb{Z}} (|\mu_j^n| + |v_j^n|). \end{aligned}$$

138 It concludes the proof. \square

139 **Lemma 4** (Consistency for smooth solutions). Assume that, for all $j \in \mathbb{Z}$, we have $a_{j-\frac{1}{2},L/R}^n =$
140 $-\sum_{k \neq j} W'(x_j - x_k) \rho_{k-\frac{1}{2},L/R}$. Then, for any $\varepsilon > 0$, the scheme (37) is consistent with (2) provided that the
141 solutions are smooth enough.

Proof. For $j \in \mathbb{Z}$, one has, using Taylor expansions as $\Delta x \rightarrow 0$,

$$\begin{aligned} \frac{\kappa_{j-\frac{1}{2},L}^n}{c - \kappa_{j-\frac{1}{2},R}^n + \kappa_{j-\frac{1}{2},L}^n} &= \frac{1}{2} - \frac{1}{4\varepsilon c^2} \left(c - \frac{a_{j-\frac{1}{2},L}^n + a_{j-\frac{1}{2},R}^n}{2} \right) \Delta x + O(\Delta x^2), \\ \frac{\kappa_{j-\frac{1}{2},R}^n}{c - \kappa_{j-\frac{1}{2},R}^n + \kappa_{j-\frac{1}{2},L}^n} &= -\frac{1}{2} + \frac{1}{4\varepsilon c^2} \left(c + \frac{a_{j-\frac{1}{2},L}^n + a_{j-\frac{1}{2},R}^n}{2} \right) \Delta x + O(\Delta x^2). \end{aligned}$$

Thus,

$$\begin{aligned} \sigma_{j-\frac{1}{2}} &= \frac{\sigma_{j-1}^n + \sigma_j^n}{2} + c \frac{\rho_{j-1}^n - \rho_j^n}{2} - \frac{1}{4\varepsilon c^2} \left(\left(c - \frac{a_{j-\frac{1}{2},L}^n + a_{j-\frac{1}{2},R}^n}{2} \right) (\sigma_{j-1}^n + c\rho_{j-1}^n) \right. \\ &\quad \left. + \left(c + \frac{a_{j-\frac{1}{2},L}^n + a_{j-\frac{1}{2},R}^n}{2} \right) (\sigma_j^n - c\rho_j^n) \right) \Delta x + O(\Delta x^2). \end{aligned}$$

In particular, $\sigma_{j-\frac{1}{2}}$ is clearly consistent with $\sigma(t^n, x_{j-\frac{1}{2}})$ as long as the solution (ρ, σ) is smooth enough to perform standard consistency analysis for finite differences. This shows that (37a) is consistent with $\partial_t \rho + \partial_x \sigma = 0$. As for the consistency of (37b) with $\partial_t \sigma + c^2 \partial_x \rho = \frac{1}{\varepsilon} (a[\rho] \rho - \sigma)$, we write:

$$\begin{aligned} \sigma_{j+\frac{1}{2}} + \sigma_{j-\frac{1}{2}} - 2\sigma_j^n &= \frac{\sigma_{j+1}^n - 2\sigma_j^n + \sigma_{j-1}^n}{2} + c \frac{\rho_{j-1}^n - \rho_{j+1}^n}{2} - \frac{\Delta x}{4\varepsilon c^2} \left[c(\sigma_{j-1}^n + 2\sigma_j^n + \sigma_{j+1}^n) \right. \\ &\quad + \frac{a_{j-\frac{1}{2},L}^n + a_{j-\frac{1}{2},R}^n}{2} (\sigma_j^n - \sigma_{j-1}^n) + \frac{a_{j+\frac{1}{2},L}^n + a_{j+\frac{1}{2},R}^n}{2} (\sigma_{j+1}^n - \sigma_j^n) + c^2(\rho_{j-1}^n - \rho_{j+1}^n) \\ &\quad \left. - c \left(\frac{a_{j-\frac{1}{2},L}^n + a_{j-\frac{1}{2},R}^n}{2} \rho_{j-1}^n + \frac{a_{j-\frac{1}{2},L}^n + a_{j-\frac{1}{2},R}^n + a_{j+\frac{1}{2},L}^n + a_{j+\frac{1}{2},R}^n}{2} \rho_j^n + \frac{a_{j+\frac{1}{2},L}^n + a_{j+\frac{1}{2},R}^n}{2} \rho_{j+1}^n \right) \right] + O(\Delta x^2). \end{aligned}$$

Using Taylor expansions, we have, for smooth solutions $\sigma(t^n, x_{j+1}) - 2\sigma(t^n, x_j) + \sigma(t^n, x_{j-1}) = O(\Delta x^2)$, $\rho(t^n, x_{j-1}) - \rho(t^n, x_{j+1}) = O(\Delta x)$, $\sigma(t^n, x_j) - \sigma(t^n, x_{j-1}) = O(\Delta x)$ and $\sigma(t^n, x_{j+1}) - \sigma(t^n, x_j) = O(\Delta x)$. Along with the bound $|a_{j\pm\frac{1}{2},L/R}^n| \leq a_\infty$, this implies:

$$\begin{aligned} \sigma_{j+\frac{1}{2}} + \sigma_{j-\frac{1}{2}} - 2\sigma_j^n &= c \frac{\rho_{j-1}^n - \rho_{j+1}^n}{2} - \frac{1}{4\epsilon c^2} \left[c(\sigma_{j-1}^n + 2\sigma_j^n + \sigma_{j+1}^n) - c \left(\frac{a_{j-\frac{1}{2},L}^n + a_{j-\frac{1}{2},R}^n}{2} \rho_{j-1}^n \right. \right. \\ &\quad \left. \left. + \frac{a_{j-\frac{1}{2},L}^n + a_{j-\frac{1}{2},R}^n + a_{j+\frac{1}{2},L}^n + a_{j+\frac{1}{2},R}^n}{2} \rho_j^n + \frac{a_{j+\frac{1}{2},L}^n + a_{j+\frac{1}{2},R}^n}{2} \rho_{j+1}^n \right) \right] \Delta x + O(\Delta x^2). \end{aligned}$$

Clearly, $c \frac{\rho_{j-1}^n - \rho_{j+1}^n}{2}$ and $c(\sigma_{j-1}^n + 2\sigma_j^n + \sigma_{j+1}^n)$ are consistent with accuracy $O(\Delta x^2)$ and $O(\Delta x)$ respectively with $-c\partial_x \rho(t^n, x_j)$ and $4c\sigma(t^n, x_j)$. For the remaining terms, let us recall that, with the notations of (42):

$$\rho_{j-\frac{1}{2},L} = \frac{v_{j-1}^n - \bar{\mu}(0)}{2c} = \frac{v_{j-1}^n - \sigma_{j-\frac{1}{2}}}{c}, \quad \rho_{j-\frac{1}{2},R} = \frac{\bar{v}(\Delta x) - \mu_j^n}{2c} = \frac{\sigma_{j-\frac{1}{2}} - \mu_j}{c}.$$

Hence $\rho_{j-\frac{1}{2},L} + \rho_{j-\frac{1}{2},R} = \frac{v_{j-1}^n - \mu_j^n}{c} = \frac{\sigma_{j-1}^n - \sigma_j^n}{c} + \rho_{j-1}^n + \rho_j^n$. Since $\sigma(t^n, x_{j-1}) - \sigma(t^n, x_j) = O(\Delta x)$, and assuming that:

$$a_{j-\frac{1}{2},L/R}^n = - \sum_{k \neq j} W'(x_j - x_k) \rho_{k-\frac{1}{2},L/R}$$

- 142 we deduce that $a_{j-\frac{1}{2},L}^n + a_{j-\frac{1}{2},R}^n$ is consistent with $a[\rho(t^n)](x_{j-1}) + a[\rho(t^n)](x_j)$ with accuracy $O(\Delta x)$.
 143 It follows that $\sigma_{j+\frac{1}{2}} + \sigma_{j-\frac{1}{2}} - 2\sigma_j^n$ is consistent with $-\partial_x \rho(t^n, x_j) - \frac{1}{\epsilon} (\sigma(t^n, x_j) - a[\rho(t^n)](x_j) \rho(t^n, x_j))$,
 144 again with accuracy $O(\Delta x)$, and this concludes the proof. \square

The stability conditions in Lemma 3 are independent on ϵ , we recover in the limit $\epsilon \rightarrow 0$, using (41), the scheme of [20]:

$$\rho_j^{n+1} = \rho_j^n - \frac{\Delta t}{\Delta x} \left(\frac{v_j^n (a_{j+\frac{1}{2},L}^n)_+ + \mu_{j+1}^n (a_{j+\frac{1}{2},R}^n)_-}{c + (a_{j+\frac{1}{2},R}^n)_- + (a_{j+\frac{1}{2},L}^n)_+} - \frac{v_{j-1}^n (a_{j-\frac{1}{2},L}^n)_+ + \mu_j^n (a_{j-\frac{1}{2},R}^n)_-}{c + (a_{j-\frac{1}{2},R}^n)_- + (a_{j-\frac{1}{2},L}^n)_+} \right) \quad (49a)$$

$$\sigma_j^{n+1} = \sigma_j^n - c \frac{\Delta t}{\Delta x} \left(2\sigma_j^n - \frac{v_j^n (a_{j+\frac{1}{2},L}^n)_+ + \mu_{j+1}^n (a_{j+\frac{1}{2},R}^n)_-}{c + (a_{j+\frac{1}{2},R}^n)_- + (a_{j+\frac{1}{2},L}^n)_+} - \frac{v_{j-1}^n (a_{j-\frac{1}{2},L}^n)_+ + \mu_j^n (a_{j-\frac{1}{2},R}^n)_-}{c + (a_{j-\frac{1}{2},R}^n)_- + (a_{j-\frac{1}{2},L}^n)_+} \right), \quad (49b)$$

which is stable under the conditions $\frac{c\Delta t}{\Delta x} \leq 1$ and $c \geq a_\infty$. Notice that with the notation in (46), equation (49a) may be rewritten

$$\rho_j^{n+1} = \rho_j^n - \frac{\Delta t}{\Delta x} \left(\rho_{j+\frac{1}{2},L}^n (a_{j+\frac{1}{2},L}^n)_+ - \rho_{j+\frac{1}{2},R}^n (a_{j+\frac{1}{2},R}^n)_- - \rho_{j-\frac{1}{2},L}^n (a_{j-\frac{1}{2},L}^n)_+ + \rho_{j-\frac{1}{2},R}^n (a_{j-\frac{1}{2},R}^n)_- \right).$$

145 4. Numerical experiments

146 We present some numerical illustrations for the two schemes described in the previous section. In
 147 addition to the potential $W(x) = \frac{|x|}{2}$, we also consider the smooth potential $W(x) = \frac{x^2}{2}$.

Numerical tests are conducted on the domain $[-1, 1]$ with the initial data $\rho_0 = \frac{1}{2}\delta_{-0.5} + \frac{1}{2}\delta_{0.5}$, $\sigma_0 = a[\rho_0]\rho_0$ and both schemes are initialized with

$$\rho_j^0 = \frac{1}{\Delta x} \rho_0(C_j), \quad \sigma_j^0 = \frac{1}{\Delta x} \sigma_0(C_j).$$

148 Figure 1 shows that both schemes recover the correct dynamics in the limit $\varepsilon \rightarrow 0$: for the potential
 149 $W(x) = \frac{|x|}{2}$, one can compute the exact velocity of both Dirac masses for the aggregation equation (1)
 150 and see that they should be located respectively in $x = -0.2$ and $x = 0.2$ in final time $T = 1.2$.

151 This test is set up with $\varepsilon = 10^{-7}$, on a cartesian mesh of $[-1, 1]$ with 1500 cells, $c = 1$ and the CFL
 152 $c \frac{\Delta t}{\Delta x} = 0.9$. Both schemes (27) and (49) display the correct velocity for the Dirac masses, but one can
 153 notice that the Rusanov scheme (27) shows more numerical diffusion. Note that both schemes being
 154 written in conservation form, they preserve the total mass of ρ , which is also verified numerically.

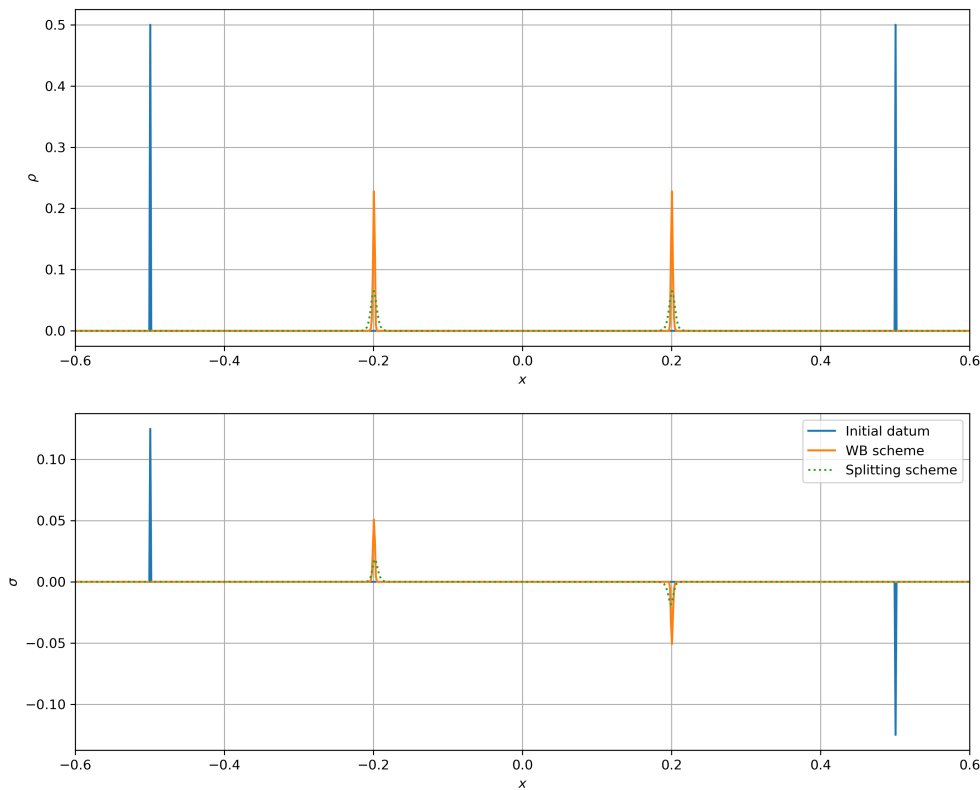


Figure 1. Dynamics of two Dirac masses for the potential $W(x) = \frac{|x|}{2}$ in time $T = 1.2$.

155 We then investigate the order of convergence when Δx goes to 0 with ε fixed, in Wasserstein
 156 distance W_1 (the numerical results are the same for W_2).

157 After performing tests for several values of ε , it appears that the convergence rate does not depend
 158 on the size of ε . Therefore, as an example, we propose simulations in final time $T = 0.5$, with the same
 159 initial data and stability parameters as above, and with $\varepsilon = 2 \times 10^{-6}$ for Figure 2 and with $\varepsilon = 10^{-2}$ for
 160 Figure 3.

161 For a fixed value of ε , both schemes seem to converge with order 1/2 with respect to Δx for the
 162 smooth potential $W(x) = \frac{x^2}{2}$ (see Figure 2) whereas they seem of order 1 for the potential $W(x) = \frac{|x|}{2}$
 163 (see Figure 3). This can be explained as both schemes possess some numerical diffusion which is
 164 somehow counterbalanced by the aggregation phenomenon in the case of a pointy potential, as already
 165 observed in [21]. Due to the link with the Burgers equation, this superconvergence phenomenon is
 166 directly linked to the results of Després [33] which should be rigorously extended to our case (the mere
 167 extension to the upwind scheme of [11] for the aggregation is not straightforward).

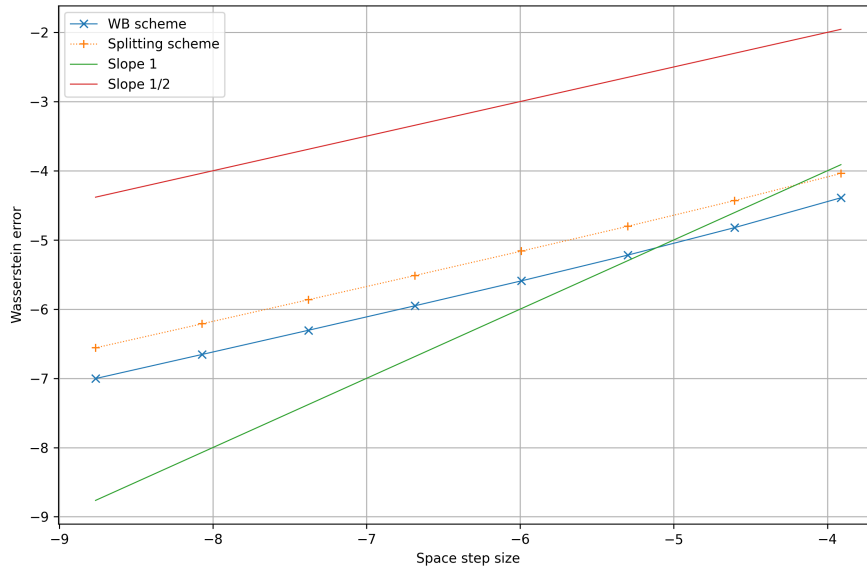


Figure 2. Order of convergence of the splitting scheme and the well-balanced scheme for the smooth potential $W(x) = \frac{x^2}{2}$.

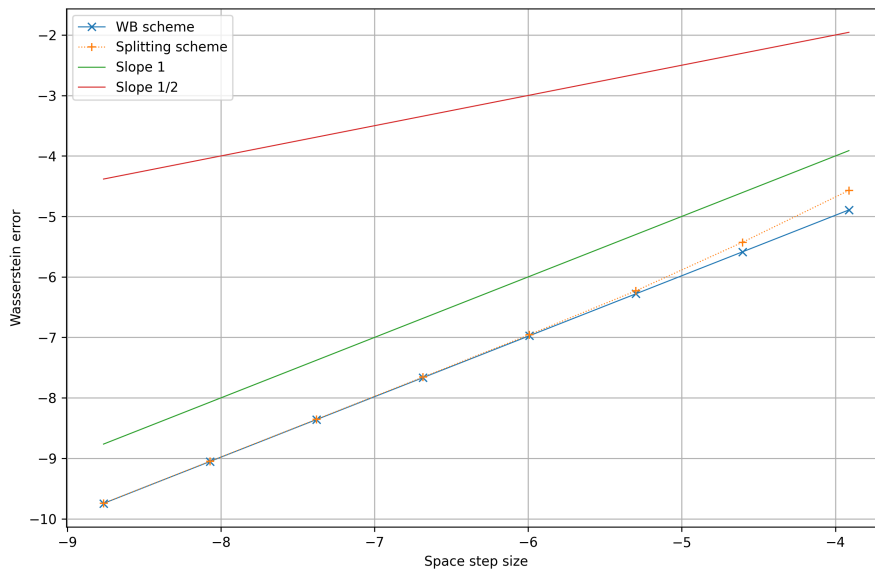


Figure 3. Order of convergence of the splitting scheme and the well-balanced scheme for the pointy potential $W(x) = \frac{|x|}{2}$.

Finally, we also verify the well-balanced property of the scheme (48) by computing the W_1 distance between the approximated solution at time $T = 0.5$ and the stationary solution of (2) given by:

$$\rho(t, x) = \rho_0(x) := \frac{1}{8\epsilon c^2} \left(1 - \tanh^2 \left(\frac{x}{4\epsilon c^2} \right) \right).$$

168 The test is conducted with $\varepsilon = 2 \times 10^{-4}$, with the exact boundary conditions given by the above
 169 formula, and for several values of Δx . As we show in Figure 4, the scheme (48) preserves well the
 170 above equilibrium for any Δx (although we have replaced the resolution of the systems (30) and
 171 (31) with linear systems, see (38)), while, for the splitting scheme, we recover the linear convergence
 172 towards ρ_0 which is, in this case, the exact solution.

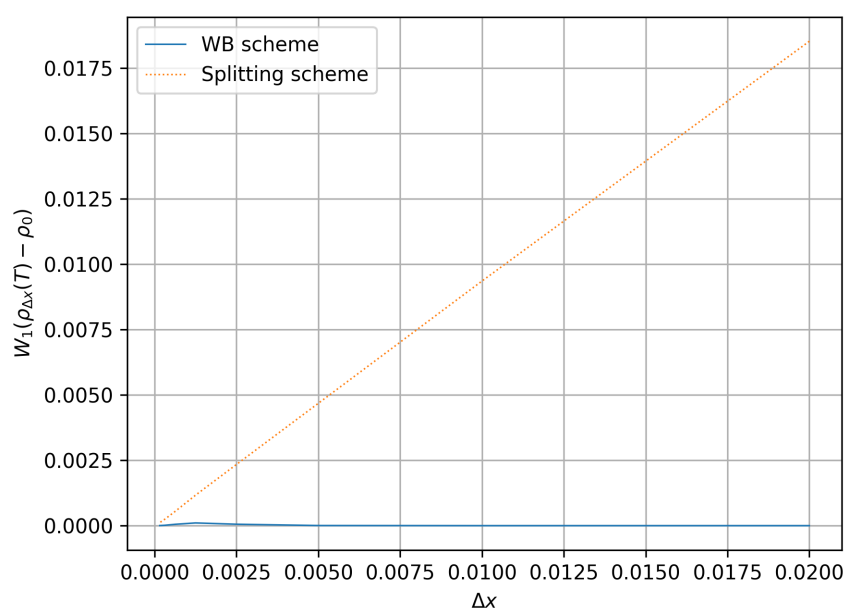


Figure 4. Distance to the equilibrium for the splitting scheme and the well-balanced scheme and for the pointy potential $W(x) = \frac{|x|}{2}$.

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175 Abbreviations

176 The following abbreviations are used in this manuscript:

177 MDPI Multidisciplinary Digital Publishing Institute
 178 DOAJ Directory of open access journals
 AS asymptotic preserving

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246 **Sample Availability:** Samples of the compounds are available from the authors.

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