

In this Maple file, we compute the evolution equations for the Painlevé 4 equation using the compatibility equation of the Lax system.

We also obtain the expression of the Lax matrices in the geometric gauge without apparent singularities.

```
> restart :
with (LinearAlgebra) :
P011:=sX10+sX20 ;
P022:=sX10*sX20 ;
Pinfty11:=-s12-s22 ;
Pinfty01:=-s11-s21 ;
Pinfty22:=s12*s22 ;
Pinfty12:=s11*s22+s12*s21 ;
Pinfty02:=s12*s20+s10*s22+s11*s21 ;
CoherenceEquation:=s10+s20+sX10+sX20 ;

R1:=unapply( P011/(xi-X1)+Pinfty01+Pinfty11*xi,xi) ;
R2:=unapply( P022/(xi-X1)^2+P012/(xi-X1)+Pinfty02+Pinfty12*xi+
Pinfty22*xi^2,xi) ;
tdR2:=unapply(R2(xi)-P012/(xi-X1),xi) ;

c2bis:=(beta12*s22-beta22*s12)/(2*(s12-s22)) ;
c1bis:=(1/2)*(s12*s21-s11*s22)/(s12-s22)^2*(beta12-beta22)+
(beta11*s22-beta21*s12)/(s12-s22) ;
mubis:=(1/2)*(X1*(s12-s22)-s11+s21)*(Q-X1)/(-s22+s12)^2*(beta12-
beta22)+(beta11-beta21)*(Q-X1)/(s12-s22)+(Q-X1)*betaX1 ;
nuMinus1bis:=(beta12-beta22)/(2*(-s22+s12)) ;
nu0bis:=(1/2)*(s21-s11)/(s12-s22)^2*(beta12-beta22)+(beta11-
beta21)/(s12-s22) ;

dR1dxi:=unapply(diff(R1(xi),xi),xi) :
dR2dxi:=unapply(diff(R2(xi),xi),xi) :
L:=Matrix(2,2,0) :
L[1,1]:=0 :
L[1,2]:=1 :
L[2,1]:=-R2(xi)+P012/(xi-X1) +C/(xi-X1) -h*s12 -h*P/(xi-Q) :
L[2,2]:= R1(xi)-h/(xi-X1)+h/(xi-Q) ;

C01:=C :

A:=Matrix(2,2,0) :
A[1,1]:= c2*xi^2+ c1*xi +c0+rho/(xi-Q) :
```

```

A[1,2]:=nuMinus1*xi+nu0+mu/(xi-Q):
A[2,1]:= AA21(xi):
A[2,2]:= AA22(xi):
dAdxi:=Matrix(2,2,0):
for i from 1 to 2 do for j from 1 to 2 do dAdxi[i,j]:=diff(A[i,
j],xi): od: od:

L;
A;
Q2:=unapply(-P*(Q-X1),xi):
J:=Matrix(2,2,0):
J[1,1]:=1:
J[1,2]:=0:
J[2,1]:=Q2(xi)/(xi-Q):
J[2,2]:=(xi-X1)^1/(xi-Q):
J;
dJdxi:=Matrix(2,2,0):
for i from 1 to 2 do for j from 1 to 2 do dJdxi[i,j]:=diff(J[i,
j],xi): od: od:
J:

LJ:=Matrix(2,2,0):
LJ[1,1]:=0:
LJ[1,2]:=0:
LJ[2,2]:=diff(J[2,2],Q)*LQ+diff(J[2,2],P)*LP+h*diff(J[2,2],X1)*
betaX1:
LJ[2,1]:=diff(J[2,1],Q)*LQ+diff(J[2,1],P)*LP+h*diff(J[2,1],X1)*
betaX1:
LJ:

checkL:=simplify(Multiply(Multiply(J,L),J^(-1))+h*Multiply(dJdxi,
J^(-1))):
checkA:=simplify(Multiply(Multiply(J,A),J^(-1))+Multiply(LJ,J^
(-1))):

```

$$\begin{aligned}
P011 &:= sX10 + sX20 \\
P022 &:= sX10 sX20 \\
Pinfty11 &:= -s12 - s22 \\
Pinfty01 &:= -s11 - s21 \\
Pinfty22 &:= s12 s22 \\
Pinfty12 &:= s11 s22 + s12 s21 \\
Pinfty02 &:= s10 s22 + s11 s21 + s12 s20 \\
CoherenceEquation &:= s10 + s20 + sX10 + sX20 \\
R1 &:= \xi \rightarrow \frac{sX10 + sX20}{\xi - X1} - s11 - s21 + (-s12 - s22) \xi
\end{aligned}$$

(1)

$$\begin{aligned}
R2 &:= \xi \rightarrow \frac{sX10 sX20}{(\xi - X1)^2} + \frac{P012}{\xi - X1} + s10 s22 + s11 s21 + s12 s20 + (s11 s22 + s12 s21) \xi \\
&\quad + s12 s22 \xi^2 \\
tdR2 &:= \xi \rightarrow \frac{sX10 sX20}{(\xi - X1)^2} + s10 s22 + s11 s21 + s12 s20 + (s11 s22 + s12 s21) \xi + s12 s22 \xi^2 \\
c2bis &:= \frac{\beta12 s22 - \beta22 s12}{2 s12 - 2 s22} \\
c1bis &:= \frac{1}{2} \frac{(-s11 s22 + s12 s21) (\beta12 - \beta22)}{(s12 - s22)^2} + \frac{\beta11 s22 - \beta21 s12}{s12 - s22} \\
mubis &:= \frac{1}{2} \frac{(X1 (s12 - s22) - s11 + s21) (Q - X1) (\beta12 - \beta22)}{(s12 - s22)^2} \\
&\quad + \frac{(\beta11 - \beta21) (Q - X1)}{s12 - s22} + (Q - X1) \text{betaX1} \\
nuMinus1bis &:= \frac{\beta12 - \beta22}{2 s12 - 2 s22} \\
nu0bis &:= \frac{1}{2} \frac{(s21 - s11) (\beta12 - \beta22)}{(s12 - s22)^2} + \frac{\beta11 - \beta21}{s12 - s22} \\
L_{2,2} &:= \frac{sX10 + sX20}{\xi - X1} - s11 - s21 + (-s12 - s22) \xi - \frac{h}{\xi - X1} + \frac{h}{\xi - Q} \\
\left[\left[0, 1 \right], \right. \\
&\quad \left[-\frac{sX10 sX20}{(\xi - X1)^2} - s10 s22 - s11 s21 - s12 s20 - (s11 s22 + s12 s21) \xi - s12 s22 \xi^2 \right. \\
&\quad \left. + \frac{C}{\xi - X1} - h s12 - \frac{h P}{\xi - Q}, \frac{sX10 + sX20}{\xi - X1} - s11 - s21 + (-s12 - s22) \xi - \frac{h}{\xi - X1} \right. \\
&\quad \left. \left. + \frac{h}{\xi - Q} \right] \right] \\
&\quad \left[\begin{array}{cc} c2 \xi^2 + c1 \xi + c0 + \frac{\rho}{\xi - Q} & nuMinus1 \xi + \nu0 + \frac{\mu}{\xi - Q} \\ AA21(\xi) & AA22(\xi) \end{array} \right] \\
&\quad \left[\begin{array}{cc} 1 & 0 \\ -\frac{P(Q - X1)}{\xi - Q} & \frac{\xi - X1}{\xi - Q} \end{array} \right]
\end{aligned}$$

Solving the compatibility equations to obtain the Hamiltonian evolutions.

The compatibility equation is $\mathcal{L}L = h \partial_{\xi} A + [A, L]$
Since the first line of L is trivial, we may easily obtain $A[2,1]$ et $A[2,2]$ to obtain the full expression for A

```
> LL:=h*dAdxi+(Multiply(A,L)-Multiply(L,A)):
```

```
Entry11:=LL[1,1]:
```

```
Entry12:=LL[1,2]:
```

```
AA21:=unapply(solve(Entry11=0,AA21(xi)),xi):
```

```
AA21bis:=h*dAdxi[1,1]+A[1,2]*L[2,1]:
```

```
simplify(AA21(xi)-AA21bis);
```

```
AA22:=unapply(solve(Entry12=0,AA22(xi)),xi):
```

```
AA22bis:=h*dAdxi[1,2]+A[1,1]+A[1,2]*L[2,2]:
```

```
simplify(AA22(xi)-AA22bis);
```

```
simplify(Entry11);
```

```
simplify(Entry12);
```

```
0  
0  
0  
0
```

(1.1)

We now compute the action of \mathcal{L} on $L[2,2]$ et $L[2,1]$ to obtain the evolution equations
Evolution of entry $L_{2,2}$

```
> Entry22:=simplify(LL[2,2]);
```

```
Entry22TermxiMinusQCube:=factor(residue(Entry22*(xi-Q)^2,xi=Q))
```

```
;
```

```
Entry22TermxiMinusQSquare:=factor(residue(Entry22*(xi-Q),xi=Q))
```

```
;
```

```
Entry22TermxiMinusQ:=factor(residue(Entry22,xi=Q));
```

```
Entry22TermxiInfy4:=factor(-residue(Entry22/xi^5,xi=infinity))
```

```
;
```

```
Entry22TermxiInfy3:=factor(-residue(Entry22/xi^4,xi=infinity))
```

```
;
```

```
Entry22TermxiInfy2:=factor(-residue(Entry22/xi^3,xi=infinity))
```

```
;
```

```
Entry22TermxiInfy1:=factor(-residue(Entry22/xi^2,xi=infinity))
```

```
;
```

```
Entry22TermxiInfy0:=factor(-residue(Entry22/xi,xi=infinity));
```

```
Entry22TermxiInfyMinus1:=factor(-residue(Entry22/xi^2,xi=infinity));
```

```
Entry22TermxiInfyMinus2:=factor(-residue(Entry22/xi^3,xi=infinity));
```

```
Entry22TermxiTMinus1:=factor(residue(Entry22,xi=X1));
```

```
Entry22TermxiTMinus2:=factor(residue(Entry22*(xi-X1),xi=X1));
```

```

simplify( Entry22-(Entry22TermxiMinusQSquare/(xi-Q)^2+
Entry22TermxiMinusQ/(xi-Q)
+Entry22TermxiInfty0+Entry22TermxiInfty1*xi+
Entry22TermxiInfty2*xi^2+Entry22TermxiInfty3*xi^3+
Entry22TermxiInfty4*xi^4+Entry22TermxiTMinus1/(xi-X1)
+Entry22TermxiTMinus2/(xi-X1)^2) );
L[2,2];

```

$$\begin{aligned}
\text{Entry22} := & -\frac{1}{(-\xi + Q)^2 (-\xi + X1)^2} \left(\left((2s_{12} + 2s_{22}) \text{nuMinus1} - 4c_2 \right) \xi^5 + \left(\left(-4s_{12} - 4s_{22} \right) \text{nuMinus1} + 8c_2 \right) X1 + \left(-4s_{12} - 4s_{22} \right) \text{nuMinus1} + 8c_2 \right) Q \\
& + (s_{21} + s_{11}) \text{nuMinus1} + (s_{12} + s_{22}) \nu_0 - 2c_1 \xi^4 + \left((2s_{12} + 2s_{22}) \text{nuMinus1} - 4c_2 \right) X1^2 + \left((8s_{12} + 8s_{22}) \text{nuMinus1} - 16c_2 \right) Q + (-2s_{11} - 2s_{21}) \text{nuMinus1} \\
& + (-2s_{12} - 2s_{22}) \nu_0 + 4c_1 X1 + 2Q \left((s_{12} + s_{22}) \text{nuMinus1} - 2c_2 \right) Q + (-s_{11} - s_{21}) \text{nuMinus1} + (-s_{12} - s_{22}) \nu_0 + 2c_1 \xi^3 + \left((-4s_{12} - 4s_{22}) \text{nuMinus1} + 8c_2 \right) Q + (s_{21} + s_{11}) \text{nuMinus1} + (s_{12} + s_{22}) \nu_0 - 2c_1 X1^2 + \left((-4s_{12} - 4s_{22}) \text{nuMinus1} + 8c_2 \right) Q^2 + \left(4s_{11} + 4s_{21} \right) \text{nuMinus1} + \left(4s_{12} + 4s_{22} \right) \nu_0 - 8c_1 Q + \text{nuMinus1} (sX10 + sX20 - h) X1 + \left((s_{21} + s_{11}) \text{nuMinus1} + (s_{12} + s_{22}) \nu_0 - 2c_1 \right) Q^2 + \left(\text{nuMinus1} h - \mu (s_{12} + s_{22}) \right) Q + (sX10 + sX20) \nu_0 + \left(-s_{11} - s_{21} \right) \mu + 2\rho \xi^2 + \left(2Q \left((s_{12} + s_{22}) \text{nuMinus1} - 2c_2 \right) Q + (-s_{11} - s_{21}) \text{nuMinus1} + (-s_{12} - s_{22}) \nu_0 + 2c_1 \right) X1^2 + \left((-2s_{11} - 2s_{21}) \text{nuMinus1} + (-2s_{12} - 2s_{22}) \nu_0 + 4c_1 \right) Q^2 + \left((-2sX10 - 2sX20) \text{nuMinus1} + 2\mu (s_{12} + s_{22}) \right) Q - 2h \nu_0 + (2s_{11} + 2s_{21}) \mu - 4\rho X1 - 2(sX10 + sX20 - h) (Q \nu_0 - \mu) \xi + \left((s_{21} + s_{11}) \text{nuMinus1} + (s_{12} + s_{22}) \nu_0 - 2c_1 \right) Q^2 + \left(\text{nuMinus1} h - \mu (s_{12} + s_{22}) \right) Q + h \nu_0 + (-s_{11} - s_{21}) \mu + 2\rho X1^2 + \left(Q^2 \text{nuMinus1} - \mu \right) (sX10 + sX20 - h) X1 + Q (sX10 + sX20 - h) (Q \nu_0 - \mu) h) \\
& \text{Entry22TermxiMinusQCube} := 0 \\
\text{Entry22TermxiMinusQSquare} := & -\frac{1}{Q - X1} \left(\left(Q^2 h \text{nuMinus1} - Q^2 \mu s_{12} - Q^2 \mu s_{22} - Q X1 h \text{nuMinus1} + Q X1 \mu s_{12} + Q X1 \mu s_{22} + Q h \nu_0 - Q \mu s_{11} - Q \mu s_{21} - X1 h \nu_0 + X1 \mu s_{11} + X1 \mu s_{21} + 2Q \rho - 2X1 \rho - h \mu + \mu sX10 + \mu sX20 \right) h \right) \\
& \text{Entry22TermxiMinusQ} := 0 \\
& \text{Entry22TermxiInfty4} := 0 \\
& \text{Entry22TermxiInfty3} := 0 \\
& \text{Entry22TermxiInfty2} := 0 \\
& \text{Entry22TermxiInfty1} := 2(-s_{12} \text{nuMinus1} - s_{22} \text{nuMinus1} + 2c_2) h \\
\text{Entry22TermxiInfty0} := & h(-\nu_0 s_{12} - \nu_0 s_{22} - s_{11} \text{nuMinus1} - s_{21} \text{nuMinus1} + 2c_1) \\
& \text{Entry22TermxiInftyMinus1} := 2(-s_{12} \text{nuMinus1} - s_{22} \text{nuMinus1} + 2c_2) h \\
& \text{Entry22TermxiInftyMinus2} := 0 \\
& \text{Entry22TermxiTMinus1} := 0
\end{aligned} \tag{1.2}$$

$$\text{Entry22TermxiTMinus2} := \frac{1}{Q - XI} (h (-sX10 - sX20 + h) (QXI \text{nuMinus1} - XI^2 \text{nuMinus1} + Q \nu0 - XI \nu0 - \mu))$$

$$0$$

$$\frac{sX10 + sX20}{\xi - XI} - s11 - s21 + (-s12 - s22) \xi - \frac{h}{\xi - XI} + \frac{h}{\xi - Q}$$

Since the deformation operator is $\hbar (\beta_{12} \partial_{t_{\infty^{\{1\}}, 2}} + \beta_{22} \partial_{t_{\infty^{\{2\}}, 2}} + \beta_{11} \partial_{t_{\infty^{\{1\}}, 1}} + \beta_{21} \partial_{t_{\infty^{\{2\}}, 1}})$ we can obtain $L[Q]$

```

> L22Orderxi2 := -residue(L[2, 2]/xi^3, xi=infinity);
L22Orderxi1 := -residue(L[2, 2]/xi^2, xi=infinity);
L22Orderxi0 := -residue(L[2, 2]/xi^1, xi=infinity);
L22OrderxiMinus1 := -residue(L[2, 2]/xi^2, xi=infinity);
L22OrderS1 := residue(L[2, 2], xi=X1);
factor(simplify(h*(beta12*diff(L22Orderxi2, s12)+beta22*diff
(L22Orderxi2, s22)
+beta11*diff(L22Orderxi2, s11)+beta21*diff(L22Orderxi2, s21) +
betaX1*diff(L22Orderxi2, X1) )
- Entry22TermxiInfty2));

Equation0 := Entry22TermxiTMinus2 - h*(sX10+sX20-h)*betaX1;

Equation1 := factor(simplify(h*(beta12*diff(L22Orderxi1, s12)+
beta22*diff(L22Orderxi1, s22)
+beta11*diff(L22Orderxi1, s11)+beta21*diff(L22Orderxi1, s21)+
betaX1*diff(L22Orderxi1, X1) )
- Entry22TermxiInfty1));

Equation2 := simplify(h*(beta12*diff(L22Orderxi0, s12)+beta22*diff
(L22Orderxi0, s22)
+beta11*diff(L22Orderxi0, s11)+beta21*diff(L22Orderxi0, s21)+
betaX1*diff(L22Orderxi0, X1) )
- Entry22TermxiInfty0);

Equation3 := factor(simplify(h*(beta12*diff(L22OrderxiMinus1, s12)
+beta22*diff(L22OrderxiMinus1, s22)
+beta11*diff(L22OrderxiMinus1, s11)+beta21*diff
(L22OrderxiMinus1, s21)+betaX1*diff(L22OrderxiMinus1, X1) )
- Entry22TermxiInftyMinus1));

Equation3bis := factor(simplify(h*(beta12*diff(L22OrderS1, s12)+
beta22*diff(L22OrderS1, s22)
+beta11*diff(L22OrderS1, s11)+beta21*diff(L22OrderS1, s21)+

```

```
betaX1*diff(L22OrderS1,X1))
- Entry22TermxiTMinus1));
```

$$\begin{aligned} L22Orderxi2 &:= 0 \\ L22Orderxi1 &:= -s12 - s22 \\ L22Orderxi0 &:= -s11 - s21 \\ L22OrderxiMinus1 &:= -s12 - s22 \\ &0 \end{aligned} \tag{1.3}$$

$$Equation0 := \frac{1}{Q - XI} (h (-sX10 - sX20 + h) (Q XI nuMinus1 - XI^2 nuMinus1 + Q v0 - XI v0 - \mu)) - h (sX10 + sX20 - h) betaX1$$

$$Equation1 := -h (-2 s12 nuMinus1 - 2 s22 nuMinus1 + \beta12 + \beta22 + 4 c2)$$

$$Equation2 := h ((s21 + s11) nuMinus1 + (s12 + s22) v0 - 2 c1 - \beta11 - \beta21)$$

$$Equation3 := -h (-2 s12 nuMinus1 - 2 s22 nuMinus1 + \beta12 + \beta22 + 4 c2)$$

$$Equation3bis := 0$$

```
> LQ:=factor(Entry22TermxiMinusQSquare/h):
```

```
nu0:=solve(Equation0,nu0);
```

$$v0 := - \frac{Q XI nuMinus1 - XI^2 nuMinus1 + Q betaX1 - XI betaX1 - \mu}{Q - XI} \tag{1.4}$$

We now look at $\mathcal{L}[L[2,1]]$

```
> Entry21:=simplify(LL[2,1]):
```

```
Entry21TermxiMinusQCube:=factor(residue(Entry21*(xi-Q)^2,xi=Q))
```

```
;
```

```
Entry21TermxiMinusQSquare:=factor(residue(Entry21*(xi-Q),xi=Q))
```

```
;
```

```
Entry21TermxiMinusQ:=factor(residue(Entry21,xi=Q));
```

```
Entry21TermxiInfty2:=factor(-residue(Entry21/xi^3,xi=infinity))
```

```
;
```

```
Entry21TermxiInfty1:=factor(-residue(Entry21/xi^2,xi=infinity))
```

```
;
```

```
Entry21TermxiInfty0:=factor(-residue(Entry21/xi,xi=infinity));
```

```
Entry21TermxiS1:=factor(residue(Entry21,xi=X1));
```

```
Entry21TermxiS2:=factor(residue(Entry21*(xi-X1),xi=X1));
```

```
simplify(Entry21-(Entry21TermxiMinusQCube/(xi-Q)^3+
```

```
Entry21TermxiMinusQSquare/(xi-Q)^2+Entry21TermxiMinusQ/(xi-Q)
```

```
+Entry21TermxiInfty0+Entry21TermxiInfty1*
```

```
xi+Entry21TermxiInfty2*xi^2
```

```
+Entry21TermxiS1/(xi-X1)
```

```
));
```

```
L[2,1];
```

$$Entry21TermxiMinusQCube := 3 (P \mu + \rho) h^2 \tag{1.5}$$

$$\begin{aligned}
\text{Entry21TermxiMinusQSquare} := & -\frac{1}{(Q-XI)^2} \left((-2 Q^4 \mu s12 s22 + 4 Q^3 XI \mu s12 s22 \right. \\
& - 2 Q^2 XI^2 \mu s12 s22 - P Q^3 h \text{nuMinus1} + 3 P Q^2 XI h \text{nuMinus1} \\
& - 3 P Q XI^2 h \text{nuMinus1} + P XI^3 h \text{nuMinus1} - 2 Q^3 \mu s11 s22 - 2 Q^3 \mu s12 s21 \\
& + 4 Q^2 XI \mu s11 s22 + 4 Q^2 XI \mu s12 s21 - 2 Q XI^2 \mu s11 s22 - 2 Q XI^2 \mu s12 s21 \\
& + P Q^2 \text{betaXI} h - 2 P Q XI \text{betaXI} h + P XI^2 \text{betaXI} h + Q^3 \rho s12 + Q^3 \rho s22 \\
& - 2 Q^2 XI \rho s12 - 2 Q^2 XI \rho s22 - 2 Q^2 h \mu s12 - 2 Q^2 \mu s10 s22 - 2 Q^2 \mu s11 s21 \\
& - 2 Q^2 \mu s12 s20 + Q XI^2 \rho s12 + Q XI^2 \rho s22 + 4 Q XI h \mu s12 + 4 Q XI \mu s10 s22 \\
& + 4 Q XI \mu s11 s21 + 4 Q XI \mu s12 s20 - 2 XI^2 h \mu s12 - 2 XI^2 \mu s10 s22 \\
& - 2 XI^2 \mu s11 s21 - 2 XI^2 \mu s12 s20 - P Q h \mu + P XI h \mu + Q^2 \rho s11 + Q^2 \rho s21 \\
& - 2 Q XI \rho s11 - 2 Q XI \rho s21 + XI^2 \rho s11 + XI^2 \rho s21 + 2 C Q \mu - 2 C XI \mu + Q h \rho \\
& \left. - Q \rho sX10 - Q \rho sX20 - XI h \rho + XI \rho sX10 + XI \rho sX20 - 2 \mu sX10 sX20) h \right)
\end{aligned}$$

$$\begin{aligned}
\text{Entry21TermxiMinusQ} := & \frac{1}{(Q-XI)^3} \left(h \left(2 Q^4 \mu s12 s22 - 6 Q^3 XI \mu s12 s22 \right. \right. \\
& + 6 Q^2 XI^2 \mu s12 s22 - 2 Q XI^3 \mu s12 s22 - P Q^3 h \text{nuMinus1} + 3 P Q^2 XI h \text{nuMinus1} \\
& - 3 P Q XI^2 h \text{nuMinus1} + P XI^3 h \text{nuMinus1} - 2 Q^4 c2 h + 6 Q^3 XI c2 h \\
& + Q^3 \mu s11 s22 + Q^3 \mu s12 s21 - 6 Q^2 XI^2 c2 h - 3 Q^2 XI \mu s11 s22 - 3 Q^2 XI \mu s12 s21 \\
& + 2 Q XI^3 c2 h + 3 Q XI^2 \mu s11 s22 + 3 Q XI^2 \mu s12 s21 - XI^3 \mu s11 s22 \\
& - XI^3 \mu s12 s21 - Q^3 c1 h - Q^3 \rho s12 - Q^3 \rho s22 + 3 Q^2 XI c1 h + 3 Q^2 XI \rho s12 \\
& + 3 Q^2 XI \rho s22 - 3 Q XI^2 c1 h - 3 Q XI^2 \rho s12 - 3 Q XI^2 \rho s22 + XI^3 c1 h + XI^3 \rho s12 \\
& + XI^3 \rho s22 + C Q \mu - C XI \mu + Q h \rho - Q \rho sX10 - Q \rho sX20 - XI h \rho + XI \rho sX10 \\
& \left. \left. + XI \rho sX20 - 2 \mu sX10 sX20) \right) \right)
\end{aligned}$$

$$\text{Entry21TermxiInfty2} := 2 (-2 s12 s22 \text{nuMinus1} + c2 s12 + c2 s22) h$$

$$\begin{aligned}
\text{Entry21TermxiInfty1} := & \frac{1}{Q-XI} \left(h \left(2 Q XI s12 s22 \text{nuMinus1} - 2 XI^2 s12 s22 \text{nuMinus1} \right. \right. \\
& + 2 Q \text{betaXI} s12 s22 - 3 Q s11 s22 \text{nuMinus1} - 3 Q s12 s21 \text{nuMinus1} \\
& - 2 XI \text{betaXI} s12 s22 + 3 XI s11 s22 \text{nuMinus1} + 3 XI s12 s21 \text{nuMinus1} + Q c1 s12 \\
& + Q c1 s22 + 2 Q c2 s11 + 2 Q c2 s21 - XI c1 s12 - XI c1 s22 - 2 XI c2 s11 \\
& \left. \left. - 2 XI c2 s21 - 2 \mu s12 s22) \right) \right)
\end{aligned}$$

$$\begin{aligned}
\text{Entry21TermxiInfty0} := & \frac{1}{Q-XI} \left(h \left(Q XI s11 s22 \text{nuMinus1} + Q XI s12 s21 \text{nuMinus1} \right. \right. \\
& - XI^2 s11 s22 \text{nuMinus1} - XI^2 s12 s21 \text{nuMinus1} + Q \text{betaXI} s11 s22 \\
& + Q \text{betaXI} s12 s21 - 2 Q h s12 \text{nuMinus1} - 2 Q s10 s22 \text{nuMinus1} \\
& - 2 Q s11 s21 \text{nuMinus1} - 2 Q s12 s20 \text{nuMinus1} - XI \text{betaXI} s11 s22 \\
& - XI \text{betaXI} s12 s21 + 2 XI h s12 \text{nuMinus1} + 2 XI s10 s22 \text{nuMinus1} \\
& + 2 XI s11 s21 \text{nuMinus1} + 2 XI s12 s20 \text{nuMinus1} + Q c1 s11 + Q c1 s21 + 2 Q c2 h \\
& - 2 Q c2 sX10 - 2 Q c2 sX20 - XI c1 s11 - XI c1 s21 - 2 XI c2 h + 2 XI c2 sX10 \\
& \left. \left. + 2 XI c2 sX20 - \mu s11 s22 - \mu s12 s21) \right) \right)
\end{aligned}$$

$$\begin{aligned}
\text{Entry21TermxiS1} := & \frac{1}{(Q-XI)^3} \left((2 Q^3 XI c2 h - 2 Q^3 XI c2 sX10 - 2 Q^3 XI c2 sX20 \right. \\
& \left. - 6 Q^2 XI^2 c2 h + 6 Q^2 XI^2 c2 sX10 + 6 Q^2 XI^2 c2 sX20 + 6 Q XI^3 c2 h \right)
\end{aligned}$$

$$\begin{aligned}
& -6 Q X I^3 c_2 s X I 0 - 6 Q X I^3 c_2 s X I 2 0 - 2 X I^4 c_2 h + 2 X I^4 c_2 s X I 0 + 2 X I^4 c_2 s X I 2 0 \\
& + C Q^3 nuMinus1 - 3 C Q^2 X I nuMinus1 + 3 C Q X I^2 nuMinus1 - C X I^3 nuMinus1 \\
& + Q^3 c_1 h - Q^3 c_1 s X I 0 - Q^3 c_1 s X I 2 0 - 3 Q^2 X I c_1 h + 3 Q^2 X I c_1 s X I 0 \\
& + 3 Q^2 X I c_1 s X I 2 0 + 3 Q X I^2 c_1 h - 3 Q X I^2 c_1 s X I 0 - 3 Q X I^2 c_1 s X I 2 0 - X I^3 c_1 h \\
& + X I^3 c_1 s X I 0 + X I^3 c_1 s X I 2 0 - C Q \mu + C X I \mu - Q h \rho + Q \rho s X I 0 + Q \rho s X I 2 0 \\
& + X I h \rho - X I \rho s X I 0 - X I \rho s X I 2 0 + 2 \mu s X I 0 s X I 2 0) h)
\end{aligned}$$

$$\begin{aligned}
& \text{Entry21TermxiS2} := C h \text{betaX1} \\
& \frac{\text{betaX1} h ((-\xi + X I) C + 2 s X I 0 s X I 2 0)}{(-\xi + X I)^3}
\end{aligned}$$

$$\begin{aligned}
& - \frac{s X I 0 s X I 2 0}{(\xi - X I)^2} - s_{10} s_{22} - s_{11} s_{21} - s_{12} s_{20} - (s_{11} s_{22} + s_{12} s_{21}) \xi - s_{12} s_{22} \xi^2 \\
& + \frac{C}{\xi - X I} - h s_{12} - \frac{h P}{\xi - Q}
\end{aligned}$$

```

> rho:=factor(solve(Entry21TermxiMinusQCube, rho));
simplify(rho-(-P*mu));
simplify(Entry21TermxiMinusQCube);

```

$$\begin{aligned}
\rho & := -P \mu \\
& 0 \\
& 0
\end{aligned}$$

(1.6)

```

> L21Orderxi3:=-residue(L[2,1]/xi^4,xi=infinity);
L21Orderxi2:=-residue(L[2,1]/xi^3,xi=infinity);
L21Orderxi1:=-residue(L[2,1]/xi^2,xi=infinity);
L21Orderxi0:=-residue(L[2,1]/xi^1,xi=infinity);
L21OrderxiMinus1:=-residue(L[2,1]/xi^2,xi=infinity);
L21OrderxiMinus2:=-residue(L[2,1]/xi^3,xi=infinity);
L21TOrder2:=factor(residue(L[2,1]*(xi-X1),xi=X1));
L21TOrder1:=residue(L[2,1],xi=X1);
Equation4:=simplify(h*(beta12*diff(L21Orderxi2,s12)+beta22*diff
(L21Orderxi2,s22)+beta11*diff(L21Orderxi2,s11)+beta21*diff
(L21Orderxi2,s21)+betaX1*diff(L21Orderxi2,X1))-
Entry21TermxiInfty2);
Equation5:=simplify(h*(beta12*diff(L21Orderxi1,s12)+beta22*diff
(L21Orderxi1,s22)+beta11*diff(L21Orderxi1,s11)+beta21*diff
(L21Orderxi1,s21)+betaX1*diff(L21Orderxi1,X1))-
Entry21TermxiInfty1);
Equation6:=simplify(h*(beta12*diff(L21TOrder2,s12)+beta22*diff
(L21TOrder2,s22)+beta11*diff(L21TOrder2,s11)+beta21*diff
(L21TOrder2,s21)+betaX1*diff(L21TOrder2,X1))-Entry21TermxiS2);

```

$$\begin{aligned}
L21Orderxi3 & := 0 \\
L21Orderxi2 & := -s_{12} s_{22} \\
L21Orderxi1 & := -s_{11} s_{22} - s_{12} s_{21} \\
L21Orderxi0 & := -h s_{12} - s_{10} s_{22} - s_{11} s_{21} - s_{12} s_{20} \\
L21OrderxiMinus1 & := -s_{11} s_{22} - s_{12} s_{21}
\end{aligned}$$

(1.7)

$$L21OrderxiMinus2 := -s12 s22$$

$$L21TOrder2 := -sX10 sX20$$

$$L21TOrder1 := \frac{C Q - C X1}{Q - X1}$$

$$Equation4 := -2 \left(\left(-2 s22 nuMinus1 + c2 + \frac{1}{2} \beta22 \right) s12 + s22 \left(c2 + \frac{1}{2} \beta12 \right) \right) h$$

$$Equation5 := -\frac{1}{Q - X1} \left((-2 X1^2 s12 s22 nuMinus1 + (2 Q s12 s22 nuMinus1 + (-2 betaX1 s22 + 3 s21 nuMinus1 - \beta21 - c1) s12 + (3 s11 nuMinus1 - \beta11 - c1) s22 + (-\beta22 - 2 c2) s11 - s21 (\beta12 + 2 c2)) X1 + ((2 betaX1 s22 - 3 s21 nuMinus1 + \beta21 + c1) s12 + (-3 s11 nuMinus1 + \beta11 + c1) s22 + (\beta22 + 2 c2) s11 + s21 (\beta12 + 2 c2)) Q - 2 \mu s12 s22 \right) h$$

$$Equation6 := -C h betaX1$$

```
> c2:=factor(solve(Equation1,c2));
mu:=factor(solve(Equation2,mu));
nuMinus1:=factor(solve(Equation4,nuMinus1));
c1:=factor(solve(Equation5,c1));
c2:=simplify(c2);
mu:=factor(mu);
```

$$c2 := \frac{1}{2} s12 nuMinus1 + \frac{1}{2} s22 nuMinus1 - \frac{1}{4} \beta12 - \frac{1}{4} \beta22 \quad (1.8)$$

$$\mu := \frac{1}{s12 + s22} \left((X1 s12 nuMinus1 + X1 s22 nuMinus1 + betaX1 s12 + betaX1 s22 - s11 nuMinus1 - s21 nuMinus1 + \beta11 + \beta21 + 2 c1) (Q - X1) \right)$$

$$nuMinus1 := \frac{1}{2} \frac{\beta12 - \beta22}{s12 - s22}$$

$$c1 := \frac{1}{2} \frac{1}{(s12 - s22)^2} \left(2 \beta11 s12 s22 - 2 \beta11 s22^2 - \beta12 s11 s22 + \beta12 s12 s21 - 2 \beta21 s12^2 + 2 \beta21 s12 s22 + \beta22 s11 s22 - \beta22 s12 s21 \right)$$

$$c2 := \frac{\beta12 s22 - \beta22 s12}{2 s12 - 2 s22}$$

$$\mu := \frac{1}{2} \frac{1}{(s12 - s22)^2} \left((Q - X1) (X1 \beta12 s12 - X1 \beta12 s22 - X1 \beta22 s12 + X1 \beta22 s22 + 2 betaX1 s12^2 - 4 betaX1 s12 s22 + 2 betaX1 s22^2 + 2 \beta11 s12 - 2 \beta11 s22 - \beta12 s11 + \beta12 s21 - 2 \beta21 s12 + 2 \beta21 s22 + \beta22 s11 - \beta22 s21) \right)$$

```
> simplify(Equation1);
simplify(Equation2);
simplify(Equation3);
simplify(Equation4);
simplify(Equation5);
simplify(c1-clbis);
simplify(c2-c2bis);
simplify(mu-mubis);
simplify(nu0-nu0bis);
```

```
simplify(nuMinus1-nuMinus1bis);
```

```
0
0
0
0
0
0
0
0
0
0
```

(1.9)

```
> simplify(Entry21TermxiMinusQSquare-(-h*P*LQ));
```

```
> LPfunction:=unapply(-Entry21TermxiMinusQ/h,C);
```

```
> Equation7:=unapply(simplify(Entry21TermxiMinusQSquare-(-h*P*LQ)),C):
```

```
Cter:=(Q^4*s12*s22-2*Q^3*X1*s12*s22+Q^2*X1^2*s12*s22+P*Q^3*s12+
P*Q^3*s22-2*P*Q^2*X1*s12-2*P*Q^2*X1*s22+P*Q*X1^2*s12+P*Q*X1^2*
s22+Q^3*s11*s22+Q^3*s12*s21-2*Q^2*X1*s11*s22-2*Q^2*X1*s12*s21+
Q*X1^2*s11*s22+Q*X1^2*s12*s21+h*Q^2*s12-2*h*Q*X1*s12+h*X1^2*
s12+P^2*Q^2-2*P^2*Q*X1+P^2*X1^2+P*Q^2*s11+P*Q^2*s21-2*P*Q*X1*
s11-2*P*Q*X1*s21+P*X1^2*s11+P*X1^2*s21+Q^2*s10*s22+Q^2*s11*s21+
Q^2*s12*s20-2*Q*X1*s10*s22-2*Q*X1*s11*s21-2*Q*X1*s12*s20+X1^2*
s10*s22+X1^2*s11*s21+X1^2*s12*s20+h*P*Q-h*P*X1-P*Q*sX10-P*Q*
sX20+P*sX10*X1+P*sX20*X1+sX10*sX20)/(Q-X1):
```

```
simplify(Equation7(Cter));
```

```
solve(Equation7(C),C):
```

```
Cbis:=(Q-X1)*P^2+h*P-(Q-X1)*R1(Q)*P+(Q-X1)*R2(Q)-P012+h*s12*(Q-
X1);
```

```
simplify(Equation7(Cbis));
```

```
simplify(series(Cter-Cbis,P));
```

```
C:=Cbis:
```

$$C_{bis} := (Q - X1) P^2 + h P - (Q - X1) \left(\frac{sX10 + sX20}{Q - X1} - s11 - s21 + (-s12 - s22) Q \right) P + (Q - X1) \left(\frac{sX10 sX20}{(Q - X1)^2} + \frac{P012}{Q - X1} + s10 s22 + s11 s21 + s12 s20 + (s11 s22 + s12 s21) Q + s12 s22 Q^2 \right) - P012 + h s12 (Q - X1)$$

(1.10)

```
0
0
```

```
> LP:=factor(simplify(LPfunction(Cbis))):
```

```
LPbis:=mu*(P*diff(R1(Q),Q)+P*h*1/(Q-X1)^2-diff(tdR2(Q),Q)-C01/
(Q-X1)^2)+h*nuMinus1*P+h*c1+2*h*c2*Q:
```

```
factor(series(LP-LPbis,P012=0));
```

$$0 \quad (1.11)$$

> LQbis:=2*mu*(P-R1(Q)/2+1/2*h*1/(Q-X1))-h*nu0-h*nuMinus1*Q;
simplify(LQ-LQbis);

$$0 \quad (1.12)$$

> nuMinus1:=nuMinus1;
nu0:=nu0;
c1:=c1;
c2:=c2;

$$\text{nuMinus1} := \frac{1}{2} \frac{\beta_{12} - \beta_{22}}{s_{12} - s_{22}} \quad (1.13)$$

$$\begin{aligned} w_0 := & -\frac{1}{Q-X1} \left(\frac{1}{2} \frac{Q X1 (\beta_{12} - \beta_{22})}{s_{12} - s_{22}} - \frac{1}{2} \frac{X1^2 (\beta_{12} - \beta_{22})}{s_{12} - s_{22}} + Q \text{betaX1} \right. \\ & \left. - X1 \text{betaX1} - \frac{1}{2} \frac{1}{(s_{12} - s_{22})^2} \left((Q - X1) (X1 \beta_{12} s_{12} - X1 \beta_{12} s_{22} \right. \right. \\ & \left. \left. - X1 \beta_{22} s_{12} + X1 \beta_{22} s_{22} + 2 \text{betaX1} s_{12}^2 - 4 \text{betaX1} s_{12} s_{22} + 2 \text{betaX1} s_{22}^2 \right. \right. \\ & \left. \left. + 2 \beta_{11} s_{12} - 2 \beta_{11} s_{22} - \beta_{12} s_{11} + \beta_{12} s_{21} - 2 \beta_{21} s_{12} + 2 \beta_{21} s_{22} + \beta_{22} s_{11} \right. \right. \\ & \left. \left. - \beta_{22} s_{21} \right) \right) \end{aligned}$$

$$\begin{aligned} c1 := & \frac{1}{2} \frac{1}{(s_{12} - s_{22})^2} \left(2 \beta_{11} s_{12} s_{22} - 2 \beta_{11} s_{22}^2 - \beta_{12} s_{11} s_{22} + \beta_{12} s_{12} s_{21} \right. \\ & \left. - 2 \beta_{21} s_{12}^2 + 2 \beta_{21} s_{12} s_{22} + \beta_{22} s_{11} s_{22} - \beta_{22} s_{12} s_{21} \right) \end{aligned}$$

$$c2 := \frac{\beta_{12} s_{22} - \beta_{22} s_{12}}{2 s_{12} - 2 s_{22}}$$

We thus get that

$$L[Q]=2*\mu*Q*(P-R1(Q)/2)-(1/2)*h*Q/(s12-s22)*(beta12-beta22)-h*\mu$$

$$L[P] = -\mu*P^2+\mu*\text{diff}(P*Q*R1(Q)-Q*R2(Q),Q)-h*s12*\mu + 1/2*h*(beta12-beta22)/(s12-s22)*$$

$$P+ h*c1+2*h*c2*Q$$

with

$$\text{nuMinus1} := \frac{\alpha_{12} - \alpha_{22}}{2 (s_{12} - s_{22})}$$

$$\begin{aligned} w_0 := & -\frac{1}{(Q-X1) h} \left(\frac{h Q X1 (\alpha_{12} - \alpha_{22})}{2 (s_{12} - s_{22})} - \frac{h X1^2 (\alpha_{12} - \alpha_{22})}{2 (s_{12} - s_{22})} + \text{betaX1} Q \right. \\ & \left. - \text{betaX1} X1 - \frac{1}{2 (s_{12} - s_{22})^2} \left((Q - X1) (\alpha_{12} h X1 s_{12} - \alpha_{12} h X1 s_{22} \right. \right. \\ & \left. \left. - \alpha_{22} h X1 s_{12} + \alpha_{22} h X1 s_{22} + 2 \text{betaX1} s_{12}^2 - 4 \text{betaX1} s_{12} s_{22} + 2 s_{22}^2 \text{betaX1} \right. \right. \\ & \left. \left. + 2 \alpha_{11} h s_{12} - 2 \alpha_{11} h s_{22} - \alpha_{12} h s_{11} + \alpha_{12} h s_{21} - 2 \alpha_{21} h s_{12} + 2 \alpha_{21} h s_{22} \right. \right. \\ & \left. \left. + \alpha_{22} h s_{11} - \alpha_{22} h s_{21} \right) \right) \end{aligned}$$

$$\begin{aligned} c1 := & \frac{1}{2 (s_{12} - s_{22})^2} \left(2 s_{12} \alpha_{11} s_{22} - 2 s_{22}^2 \alpha_{11} - s_{11} \alpha_{12} s_{22} + s_{21} \alpha_{12} s_{12} - 2 s_{12}^2 \alpha_{21} \right. \\ & \left. + 2 s_{12} \alpha_{21} s_{22} + s_{11} \alpha_{22} s_{22} - s_{21} \alpha_{22} s_{12} \right) \end{aligned}$$

$$c2 := \frac{\alpha_{12} s_{22} - \alpha_{22} s_{12}}{2 s_{12} - 2 s_{22}}$$

> Hamiltonianbis:= mu*(P^2-R1(Q)*P+h*P/(Q-X1) +tdR2(Q)+h*s12)-h*

```

nu0*P-h*nuMinus1*Q*P-h*c1*Q-h*c2*Q^2
:
factor(simplify(LP-(-diff(Hamiltonianbis,Q)))));
simplify(LQ-(diff(Hamiltonianbis,P)));

```

$$\begin{matrix} 0 \\ 0 \end{matrix} \quad (1.14)$$

In order to match the notation with the article, we shall take Hamiltonianbis as the Hamiltonian including the purely time dependent terms.

```

> simplify(series(mu,betaX1));

```

$$-\frac{1}{2} \frac{1}{(s_{12} - s_{22})^2} \left((Q - X1) \left((\beta_{22} - \beta_{12}) X1 - 2 \beta_{11} + 2 \beta_{21} \right) s_{12} + (X1 (\beta_{12} - \beta_{22}) + 2 \beta_{11} - 2 \beta_{21}) s_{22} - (-s_{21} + s_{11}) (\beta_{22} - \beta_{12}) \right) + (Q - X1) \text{betaX1} \quad (1.15)$$

```

> simplify(L[2,1]-(-h*P/(xi-Q)-tdR2(xi)-h*s12+((Q-X1)*(P^2-R1(Q)*
P+h/(Q-X1)*P+tdR2(Q)+h*s12))/(xi-X1)));

```

$$0 \quad (1.16)$$

Expression of the Lax matrix in the geometric gauge and normalisation at infinity

```

> simplify(checkL[1,1]);
simplify(checkL[1,2]);
checkL22bis:=R1(xi)-P*(Q-X1)/(xi-X1);
simplify(checkL[2,2]-checkL22bis);
checkL21:=factor(checkL[2,1]);
simplify(series(checkL[2,1],xi=X1)):
checkL21bis:=(P*(Q-X1)-sX10)*(P*(Q-X1)-sX20)/((Q-X1)*(xi-X1))-
s12*s22*xi^2+((-Q+X1)*s22-s21)*s12-s11*s22)*xi+((-Q^2+Q*X1)*
s22+(-s21-P)*Q+(s21+P)*X1-h-s20)*s12+((-P-s11)*Q+(s11+P)*X1-
s10)*s22-s11*s21:
simplify(checkL21-checkL21bis);

```

$$-\frac{P(Q-X1)}{-\xi+X1} \quad (2.1)$$

$$checkL22bis := \frac{sX10 + sX20}{\xi - X1} - s_{11} - s_{21} + (-s_{12} - s_{22}) \xi - \frac{P(Q-X1)}{\xi - X1}$$

$$checkL21 := -\frac{1}{(-\xi+X1)(Q-X1)} \left(Q^3 X1 s_{12} s_{22} - Q^3 s_{12} s_{22} \xi - 2 Q^2 X1^2 s_{12} s_{22} \right. \\ \left. + 3 Q^2 X1 s_{12} s_{22} \xi - Q^2 s_{12} s_{22} \xi^2 + Q X1^3 s_{12} s_{22} - 3 Q X1^2 s_{12} s_{22} \xi \right. \\ \left. + 3 Q X1 s_{12} s_{22} \xi^2 - Q s_{12} s_{22} \xi^3 + X1^3 s_{12} s_{22} \xi - 2 X1^2 s_{12} s_{22} \xi^2 + X1 s_{12} s_{22} \xi^3 \right. \\ \left. + P Q^2 X1 s_{12} + P Q^2 X1 s_{22} - P Q^2 s_{12} \xi - P Q^2 s_{22} \xi - 2 P Q X1^2 s_{12} \right. \\ \left. - 2 P Q X1^2 s_{22} + 2 P Q X1 s_{12} \xi + 2 P Q X1 s_{22} \xi + P X1^3 s_{12} + P X1^3 s_{22} \right)$$

$$\begin{aligned}
& -P X I^2 s_{12} \xi - P X I^2 s_{22} \xi + Q^2 X I s_{11} s_{22} + Q^2 X I s_{12} s_{21} - Q^2 s_{11} s_{22} \xi \\
& - Q^2 s_{12} s_{21} \xi - 2 Q X I^2 s_{11} s_{22} - 2 Q X I^2 s_{12} s_{21} + 3 Q X I s_{11} s_{22} \xi \\
& + 3 Q X I s_{12} s_{21} \xi - Q s_{11} s_{22} \xi^2 - Q s_{12} s_{21} \xi^2 + X I^3 s_{11} s_{22} + X I^3 s_{12} s_{21} \\
& - 2 X I^2 s_{11} s_{22} \xi - 2 X I^2 s_{12} s_{21} \xi + X I s_{11} s_{22} \xi^2 + X I s_{12} s_{21} \xi^2 + P^2 Q^2 \\
& - 2 P^2 Q X I + P^2 X I^2 + Q X I h s_{12} + Q X I s_{10} s_{22} + Q X I s_{11} s_{21} + Q X I s_{12} s_{20} \\
& - Q h s_{12} \xi - Q s_{10} s_{22} \xi - Q s_{11} s_{21} \xi - Q s_{12} s_{20} \xi - X I^2 h s_{12} - X I^2 s_{10} s_{22} \\
& - X I^2 s_{11} s_{21} - X I^2 s_{12} s_{20} + X I h s_{12} \xi + X I s_{10} s_{22} \xi + X I s_{11} s_{21} \xi + X I s_{12} s_{20} \xi \\
& - P Q s_{X10} - P Q s_{X20} + P X I s_{X10} + P X I s_{X20} + s_{X10} s_{X20} \\
& \quad \quad \quad 0
\end{aligned}$$

> Verification:=simplify(LL-h*dAdxi-(Multiply(A,L)-Multiply(L,A))
);

checkL:=simplify(checkL):

$$\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

(2.2)

> LcheckL:=Matrix(2,2,0):

```

for i from 1 to 2 do for j from 1 to 2 do LcheckL[i,j]:=diff
(checkL[i,j],Q)*LQbis+diff(checkL[i,j],P)*LPbis+h*diff(checkL
[i,j],s12)*beta12+ h*diff(checkL[i,j],s22)*beta22+h*diff(checkL
[i,j],s11)*beta11+h*diff(checkL[i,j],s21)*beta21+h*diff(checkL
[i,j],X1)*betaX1: od: od:

```

checkA:=simplify(checkA):

dcheckAdxi:=Matrix(2,2,0):

```

for i from 1 to 2 do for j from 1 to 2 do dcheckAdxi[i,j]:=diff
(checkA[i,j],xi): od: od:

```

Verification:=simplify(LcheckL-h*dcheckAdxi-(Multiply(checkA,
checkL)-Multiply(checkL,checkA))):

$$\begin{bmatrix} 0 & 0 \\ \frac{(\beta_{12} s_{22} - \beta_{22} s_{12})(s_{10} + s_{20} + s_{X10} + s_{X20}) h}{s_{12} - s_{22}} & 0 \end{bmatrix}$$

(2.3)

> G1:=Matrix(2,2,0):

G1[1,1]:=1:

G1[2,2]:=1:

G1[1,2]:=0:

G1[2,1]:=s12*xi+eta0:

eta0:=(Q-X1)*s12+s11;

```
dG1dxi:=Matrix(2,2,0):
for i from 1 to 2 do for j from 1 to 2 do dG1dxi[i,j]:=diff(G1
[i,j],xi): od: od:
```

```
LG1:=Matrix(2,2,0):
for i from 1 to 2 do for j from 1 to 2 do LG1[i,j]:=diff(G1[i,
j],Q)*LQ+diff(G1[i,j],P)*LP+h*diff(G1[i,j],s12)*beta12+ h*diff
(G1[i,j],s22)*beta22+h*diff(G1[i,j],s11)*beta11+h* diff(G1[i,
j],s21)*beta21+h*diff(G1[i,j],X1)*betaX1: od: od:
```

```
tdL:=simplify(Multiply(Multiply(G1,checkL),G1^(-1))+h*Multiply
(dG1dxi,G1^(-1))):
```

```
LtdL:=Matrix(2,2,0):
for i from 1 to 2 do for j from 1 to 2 do LtdL[i,j]:=diff
(tdL[i,j],Q)*LQ+diff(tdL[i,j],P)*LP+h*diff(tdL[i,j],s12)*
beta12+ h*diff(tdL[i,j],s22)*beta22+h*diff(tdL[i,j],s11)*
beta11+h* diff(tdL[i,j],s21)*beta21+ h*diff(tdL[i,j],X1)*
betaX1: od: od:
```

```
tdA:=simplify(Multiply(Multiply(G1,checkA),G1^(-1))+Multiply
(LG1,G1^(-1))):
```

```
dtdAdxi:=Matrix(2,2,0):
for i from 1 to 2 do for j from 1 to 2 do dtdAdxi[i,j]:=diff
(tdA[i,j],xi): od: od:
```

```
Verification1:=simplify(LtdL-h*dtdAdxi-(Multiply(tdA,tdL)-
Multiply(tdL,tdA))):
```

$$\eta_0 := (Q - X1) s12 + s11 \quad (2.4)$$

$$\begin{bmatrix} 0 & 0 \\ \frac{(\beta12 s22 - \beta22 s12) (s10 + s20 + sX10 + sX20) h}{s12 - s22} & 0 \end{bmatrix}$$

```
> simplify(tdL);
series(tdL[1,1],xi=infinity,1);
series(tdL[1,2],xi=infinity,1);
series(tdL[2,1],xi=infinity,1);
```

```
tdL11bis:=(Q-X1)*(Q*s12+P+s11)/(xi-X1)-s12*xi-s11;
tdL12bis:=1+(X1-Q)/(xi-X1);
tdL21bis:=(Q^2*s12+(-X1*s12+P+s11)*Q+(-P-s11)*X1-sX10)*(Q^2*
s12+(-X1*s12+P+s11)*Q+(-P-s11)*X1-sX20)/(Q-X1)/(xi-X1)+(s12-
```

```

s22) * (Q-X1) * P + (s12-s22) * s12 * Q^2 - (s12-s22) * (X1*s12-s11) * Q - (X1 *
s11+sX10+sX20+s20) * s12+s22 * (X1*s11-s10) ;
tdL22bis := (-Q^2*s12 + (X1*s12-P-s11) * Q + (s11+P) * X1 + sX10+sX20) / (xi-
X1) - xi*s22-s21;
simplify(tdL[1,1]-tdL11bis) ;
simplify(tdL[1,2]-tdL12bis) ;
simplify(tdL[2,1]-tdL21bis) ;
simplify(tdL[2,2]-tdL22bis) ;

```

```

L21bis := -h*P / (xi-Q) - tdR2(xi) - h*s12 + (Q-X1) / (xi-X1) * ( P^2-R1(Q) *
P+h / (Q-X1) * P + tdR2(Q) + h*s12) :
simplify(L[2,1]-L21bis) ;
L22bis := h / (xi-Q) + R1(xi) :
simplify(series(tdL[2,2]-tdL22bis,Q=0)) ;

```

$$\left[\left[\frac{-(-\xi + Q)(\xi + Q - XI) s12 + XI P + s11 \xi - (P + s11) Q}{-\xi + XI}, \frac{-\xi + Q}{-\xi + XI} \right], \right. \quad (2.5)$$

$$\left[\frac{1}{(-\xi + XI)(Q - XI)} \left((s12 - s22)(Q s12 + P + s11) XI^3 + ((-3 s12^2 + 2 s12 s22) Q^2 + (-\xi s12^2 + (s22 \xi - 4 P - 4 s11) s12 + 2 s22 (P + s11)) Q + ((-P - s11) \xi + sX10 + sX20 + s20) s12 + s22 (P + s11) \xi - P^2 - 2 P s11 + s10 s22 - s11^2) XI^2 + ((3 s12^2 - s12 s22) Q^3 + (2 \xi s12^2 + (-2 s22 \xi + 5 P + 5 s11) s12 - s22 (P + s11)) Q^2 + ((2 P + 2 s11) \xi - 2 sX10 - 2 sX20 - s20) s12 - 2 s22 (P + s11) \xi + 2 P^2 + 4 P s11 - s10 s22 + 2 s11^2) Q - \xi (sX10 + sX20 + s20) s12 - \xi s10 s22 - (sX10 + sX20) (P + s11) XI - Q^4 s12^2 - 2 s12 \left(\frac{1}{2} s12 \xi - \frac{1}{2} s22 \xi + P + s11 \right) Q^3 + (((-P - s11) \xi + sX10 + sX20) s12 - (P + s11) (-s22 \xi + P + s11)) Q^2 + (\xi (sX10 + sX20 + s20) s12 + \xi s10 s22 + (sX10 + sX20) (P + s11)) Q - sX10 sX20 \right), \frac{1}{-\xi + XI} \left((-Q s12 - s22 \xi - P - s11 - s21) XI + \xi^2 s22 + s21 \xi + Q^2 s12 + (P + s11) Q - sX20 - sX10 \right) \right] \right]$$

$$-s_{12}\xi - s_{11} + O\left(\frac{1}{\xi}\right)$$

$O(1)$

$$\frac{1}{Q-XI} \left(-((-s_{12}^2 + s_{12}s_{22})Q + (-P - s_{11})s_{12} + s_{22}(P + s_{11}))XI^2 - ((2s_{12}^2 - 2s_{12}s_{22})Q^2 + ((2P + 2s_{11})s_{12} - 2s_{22}(P + s_{11}))Q - (s_{X10} + s_{X20} + s_{20})s_{12} - s_{10}s_{22})XI + 2s_{12} \left(\frac{1}{2}s_{12} - \frac{1}{2}s_{22} \right) Q^3 - ((-P - s_{11})s_{12} + s_{22}(P + s_{11}))Q^2 - ((s_{X10} + s_{X20} + s_{20})s_{12} + s_{10}s_{22})Q \right) + O\left(\frac{1}{\xi}\right)$$

$$tdL11bis := \frac{(Q-XI)(Qs_{12} + P + s_{11})}{\xi - XI} - s_{12}\xi - s_{11}$$

$$tdL12bis := 1 + \frac{-Q + XI}{\xi - XI}$$

$$tdL21bis := \frac{1}{(Q-XI)(\xi - XI)} \left((Q^2s_{12} + (-XI s_{12} + P + s_{11})Q + (-P - s_{11})XI - s_{X10})(Q^2s_{12} + (-XI s_{12} + P + s_{11})Q + (-P - s_{11})XI - s_{X20}) + (s_{12} - s_{22})(Q-XI)P + (s_{12} - s_{22})s_{12}Q^2 - (s_{12} - s_{22})(XI s_{12} - s_{11})Q - (XI s_{11} + s_{20} + s_{X10} + s_{X20})s_{12} + s_{22}(XI s_{11} - s_{10}) \right)$$

$$tdL22bis := \frac{-Q^2s_{12} + (XI s_{12} - P - s_{11})Q + (P + s_{11})XI + s_{X10} + s_{X20}}{\xi - XI} - s_{22}\xi - s_{21}$$

0
0
0
0
0
0

> **GeneralSpectralCurvefunction:=unapply(simplify(Determinant(y*IdentityMatrix(2)-tdL)),xi,Q,P,s12,s22,s11,s21,X1,s10,s20,sX10,sX20):**

GeneralSpectralCurve:=GeneralSpectralCurvefunction(xi,Q,P,s12,s22,s11,s21,X1,s10,s20,sX10,sX20);

GeneralSpectralCurvebis:=y^2 -R1(xi)*y+tdR2(xi) +(Q-X1)*(-P^2+R1(Q)*P-tdR2(Q))/(xi-X1) ;

simplify(GeneralSpectralCurve-GeneralSpectralCurvebis) ;

$$GeneralSpectralCurve := \frac{1}{(-\xi + XI)^2 (Q - XI)} \left((-s_{12}s_{22}\xi^2 + ((-s_{21} - y)s_{12} - s_{22}(y + s_{11}))\xi + s_{12}s_{22}Q^2 + ((s_{21} + P)s_{12} + s_{22}(P + s_{11}))Q + (P - y)(P + s_{21} + s_{11} + y))XI^3 + (2s_{22}\xi^3s_{12} + (Qs_{12}s_{22} + (2s_{21} + 2y)s_{12} + 2s_{22}(y + s_{11}))\xi^2 + (-s_{12}s_{22}Q^2 - (s_{12} + s_{22})(P - y)Q + s_{12}s_{20} + s_{10}s_{22} - P^2 + (\right. \quad (2.6)$$

$$\begin{aligned}
& -s_{11} - s_{21}) P + 2y^2 + (2s_{11} + 2s_{21})y + s_{11}s_{21}) \xi - 2s_{12}s_{22}Q^3 + ((-2P \\
& - 2s_{21})s_{12} - 2s_{22}(P + s_{11}))Q^2 + (-s_{12}s_{20} - s_{10}s_{22} - 2P^2 + (-2s_{11} \\
& - 2s_{21})P + y^2 + (s_{21} + s_{11})y - s_{11}s_{21})Q + (s_{X10} + s_{X20})(P - y)XI^2 + (\\
& -s_{12}s_{22}\xi^4 + (-2Qs_{12}s_{22} + (-s_{21} - y)s_{12} - s_{22}(y + s_{11}))\xi^3 + (((-2s_{21} \\
& - 2y)s_{12} - 2s_{22}(y + s_{11}))Q - s_{12}s_{20} - s_{10}s_{22} - (y + s_{11})(s_{21} + y))\xi^2 \\
& + (2s_{12}s_{22}Q^3 + ((2s_{21} + 2P)s_{12} + 2s_{22}(P + s_{11}))Q^2 + 2(P - y)(P + s_{21} \\
& + s_{11} + y)Q - (s_{X10} + s_{X20})(P - y)\xi + (s_{12}s_{22}Q^3 + ((s_{21} + P)s_{12} + s_{22}(P \\
& + s_{11}))Q^2 + (s_{12}s_{20} + s_{10}s_{22} + (P + s_{11})(s_{21} + P))Q - (s_{X10} + s_{X20})(P \\
& - y)Q)XI + Qs_{12}s_{22}\xi^4 + Q((s_{21} + y)s_{12} + s_{22}(y + s_{11}))\xi^3 + (s_{12}s_{20} \\
& + s_{10}s_{22} + (y + s_{11})(s_{21} + y))Q\xi^2 + (-Q^4s_{12}s_{22} + ((-s_{21} - P)s_{12} - s_{22}(P \\
& + s_{11}))Q^3 + (-s_{12}s_{20} - s_{10}s_{22} - (P + s_{11})(s_{21} + P))Q^2 + (s_{X10} + s_{X20})(P \\
& - y)Q - s_{X10}s_{X20})\xi + Qs_{X10}s_{X20})
\end{aligned}$$

$$\begin{aligned}
\text{GeneralSpectralCurvebis} := & y^2 - \left(\frac{s_{X10} + s_{X20}}{\xi - XI} - s_{11} - s_{21} + (-s_{12} - s_{22})\xi \right) y \\
& + \frac{s_{X10}s_{X20}}{(\xi - XI)^2} + s_{10}s_{22} + s_{11}s_{21} + s_{12}s_{20} + (s_{11}s_{22} + s_{12}s_{21})\xi + s_{12}s_{22}\xi^2 \\
& + \frac{1}{\xi - XI} \left((Q - XI) \left(-P^2 + \left(\frac{s_{X10} + s_{X20}}{Q - XI} - s_{11} - s_{21} + (-s_{12} - s_{22})Q \right) P \right. \right. \\
& \left. \left. - \frac{s_{X10}s_{X20}}{(Q - XI)^2} - s_{10}s_{22} - s_{11}s_{21} - s_{12}s_{20} - (s_{11}s_{22} + s_{12}s_{21})Q - s_{12}s_{22}Q^2 \right) \right)
\end{aligned}$$

0

Computation of the Hamiltonian flows in various direction

```

> LQfunction:=unapply(LQ,beta12,beta22,beta11,beta21,betaX1):
LPfunction:=unapply(LP,beta12,beta22,beta11,beta21,betaX1):
Hamiltonianfunction:=unapply(Hamiltonianbis,s12,s22,s11,s21,X1,
beta12,beta22,beta11,beta21,betaX1):
nu0:=simplify(nu0);
clbis:=- (1/2) * (s11*s22-s12*s21) * (beta12-beta22) / (s12-s22)^2+
(beta11*s22-beta21*s12) / (s12-s22);
factor(series(simplify(clbis),beta12));
mubis:=(Q-X1) * (betaX1 + (beta11-beta21) / (s12-s22) + (X1 * (s12-s22)
-s11+s21) * (beta12-beta22) / (2 * (s12-s22)^2) ) :
simplify(series(mu-mubis,beta11=0));

```

$$\nu_0 := \frac{1}{2} \frac{(2\beta_{11} - 2\beta_{21})s_{12} + (-2\beta_{11} + 2\beta_{21})s_{22} - (-s_{21} + s_{11})(\beta_{12} - \beta_{22})}{(s_{12} - s_{22})^2} \quad (2.7)$$

$$clbis := -\frac{1}{2} \frac{(s_{11}s_{22} - s_{12}s_{21})(\beta_{12} - \beta_{22})}{(s_{12} - s_{22})^2} + \frac{\beta_{11}s_{22} - \beta_{21}s_{12}}{s_{12} - s_{22}}$$

Trivial directions

```

> simplify(LQfunction(1,1,0,0,0));

```

```

simplify(LPfunction(1,1,0,0,0));
simplify(Hamiltonianfunction(s12,s22,s11,s21,X1,1,1,0,0,0));
simplify(LQfunction(0,0,1,1,0));
simplify(LPfunction(0,0,1,1,0));
simplify(Hamiltonianfunction(s12,s22,s11,s21,X1,0,0,1,1,0));
simplify(LQfunction(2*s12,2*s22,s11,s21,-X1));
simplify(LPfunction(2*s12,2*s22,s11,s21,-X1));
simplify(Hamiltonianfunction(s12,s22,s11,s21,X1,2*s12,2*s22,
s11,s21,-X1));
simplify(LQfunction(0,0,s12,s22,-1));
simplify(LPfunction(0,0,s12,s22,-1));
simplify(Hamiltonianfunction(s12,s22,s11,s21,X1,0,0,s12,s22,-1)
);

```

$$\begin{array}{r}
0 \\
-Qh \\
\frac{1}{2} Q^2 h \\
0 \\
-h \\
Qh \\
-Qh \\
hP \\
-hPQ \\
-h \\
0 \\
-hP
\end{array} \quad (2.8)$$

Direction X1

```

> simplify(LQfunction(0,0,0,0,1));
simplify(LPfunction(0,0,0,0,1));
HamX1:=unapply( (Q-X1)*(P^2-P*R1(Q)+h*P/(Q-X1)+tdR2(Q)+h*s12),
Q,P);
simplify(Hamiltonianfunction(s12,s22,s11,s21,X1,0,0,0,0,1)
-HamX1(Q,P));
simplify(LQfunction(0,0,0,0,1)-diff(HamX1(Q,P),P));
simplify(LPfunction(0,0,0,0,1)+diff(HamX1(Q,P),Q));

```

$$\begin{aligned}
& (s12 + s22) Q^2 + ((-s12 - s22) XI + 2 P + s11 + s21) Q + (-2 P - s11 - s21) XI \\
& - sX20 + h - sX10 \\
& \frac{1}{(Q - XI)^2} \left(-3 Q^4 s12 s22 + (8 XI s12 s22 + (-2 P - 2 s21) s12 - 2 s22 (P + s11)) Q^3 \right. \\
& + (-7 XI^2 s12 s22 + ((5 P + 5 s21) s12 + 5 s22 (P + s11)) XI + (-s20 - h) s12 \\
& - P^2 + (-s11 - s21) P - s10 s22 - s11 s21) Q^2 + 2 (XI^2 s12 s22 + ((-2 P \\
& - 2 s21) s12 - 2 s22 (P + s11)) XI + (s20 + h) s12 + P^2 + (s21 + s11) P + s10 s22 \\
& + s11 s21) XI Q + ((s21 + P) s12 + s22 (P + s11)) XI^3 + ((-s20 - h) s12 - P^2 + (- \\
& -s11 - s21) P - s10 s22 - s11 s21) XI^2 + sX10 sX20)
\end{aligned} \quad (2.9)$$

$$-s21) XI - sX10 - sX20) P) + \frac{(Q - XI) P^2}{s12 - s22}$$

$$- \frac{((s20 + h) s12 + s10 s22 + s11 s21) XI}{s12 - s22}$$

0
0
0

Non trivial direction

```
> solve({Sinfy1=s11+s21,Sinfy2=s12+s22, S2=sqrt(s12-s22)/sqrt
(2), S1=(s11-s21)/sqrt(2)/sqrt(s12-s22),
tdX1function=S2*X1+S1},{s11,s12,s21,s22,X1});
```

$$\left\{ \begin{aligned} XI &= -\frac{S1 - tdX1function}{S2}, s11 = \frac{1}{2} Sinfy1 + S1 S2, s12 = \frac{1}{2} Sinfy2 + S2^2, s21 = -S1 S2 \\ &+ \frac{1}{2} Sinfy1, s22 = -S2^2 + \frac{1}{2} Sinfy2 \end{aligned} \right\} \quad (2.11)$$

```
> hpartialtdX1functionQ:=simplify(LQfunction(0,0,0,0,sqrt(2)/sqrt
(s12-s22) ));
hpartialtdX1functionP:=simplify(LPfunction(0,0,0,0,sqrt(2)/sqrt
(s12-s22) ));
HamtdX1function:=unapply(2*P*((s12+s22)*Q^2+((-s12-s22)*X1+P+
s11+s21)*Q+(-P-s11-s21)*X1+h-sX10-sX20)/sqrt(2*s12-2*s22)+(2*Q*
(Q*(Q-X1)*s22+Q*s21-X1*s21+h+s20)*(Q-X1)*s12+2*Q*(Q-X1)*(Q*s11-
X1*s11+s10)*s22+2*Q^2*s11*s21-2*Q*X1*s11*s21+2*sX10*sX20)/(sqrt
(2*s12-2*s22)*(Q-X1))
-(2*((s20+h)*s12+s10*s22+s11*s21))*X1/sqrt(2*s12-2*s22)
,Q,P);
simplify(hpartialtdX1functionQ-diff(HamtdX1function(Q,P),P));
simplify(hpartialtdX1functionP+diff(HamtdX1function(Q,P),Q));
simplify(Hamiltonianfunction(s12,s22,s11,s21,X1,0,0,0,0,sqrt(2)
/sqrt(s12-s22))-HamtdX1function(Q,P,s11));
```

$$hpartialtdX1functionQ := \frac{1}{\sqrt{s12-s22}} \left(2 \left(\left(\frac{1}{2} s12 + \frac{1}{2} s22 \right) Q^2 + \left(\left(-\frac{1}{2} s12 - \frac{1}{2} s22 \right) XI + P + \frac{1}{2} s11 + \frac{1}{2} s21 \right) Q + \left(-P - \frac{1}{2} s11 - \frac{1}{2} s21 \right) XI - \frac{1}{2} sX20 + \frac{1}{2} h - \frac{1}{2} sX10 \right) \sqrt{2} \right) \quad (2.12)$$

$$hpartialtdX1functionP := -\frac{1}{\sqrt{s12-s22} (Q-XI)^2} \left(\left((Q-XI)^2 P^2 + 2 (Q-XI)^2 \left(\left(Q - \frac{1}{2} XI \right) s12 + \left(Q - \frac{1}{2} XI \right) s22 + \frac{1}{2} s11 + \frac{1}{2} s21 \right) P + 3 (Q-XI)^2 \left(Q \left(Q - \frac{2}{3} XI \right) s22 + \left(\frac{2}{3} Q - \frac{1}{3} XI \right) s21 + \frac{1}{3} h + \frac{1}{3} s20 \right) s12 + 2 (Q-XI)^2 \left(\left(Q - \frac{1}{2} XI \right) s11 + \frac{1}{2} s10 \right) s22 + s21 (Q-XI)^2 s11 - sX10 sX20 \right) \sqrt{2} \right)$$

$$\begin{aligned}
\text{HamtdXlfunction} := (Q, P) \rightarrow & \frac{1}{\sqrt{2s_{12} - 2s_{22}}} (2P((s_{12} + s_{22})Q^2 + ((-s_{12} \\
& - s_{22})X_1 + P + s_{11} + s_{21})Q + (-P - s_{11} - s_{21})X_1 + h - s_{X10} - s_{X20})) \\
& + \frac{1}{\sqrt{2s_{12} - 2s_{22}}(Q - X_1)} (2Q(Q(Q - X_1)s_{22} + Qs_{21} - X_1s_{21} + h + s_{20})(Q \\
& - X_1)s_{12} + 2Q(Q - X_1)(Qs_{11} - X_1s_{11} + s_{10})s_{22} + 2Q^2s_{11}s_{21} \\
& - 2QX_1s_{11}s_{21} + 2s_{X10}s_{X20}) - \frac{2((s_{20} + h)s_{12} + s_{10}s_{22} + s_{11}s_{21})X_1}{\sqrt{2s_{12} - 2s_{22}}} \\
& \qquad \qquad \qquad 0 \\
& \qquad \qquad \qquad 0 \\
& \qquad \qquad \qquad 0
\end{aligned}$$

> KOldCoordinates := unapply((1/2)*(sX10+s20)*(sX10+s10)*ln((s12 -s22)/2)+(1/2)*X1*((X1*s12+2*s11)*s10+s20*(X1*s22+2*s21)), s11, s21, s12, s22, X1);

$$\begin{aligned}
\text{KOldCoordinates} := (s_{11}, s_{21}, s_{12}, s_{22}, X_1) \rightarrow & \frac{1}{2} (s_{X10} + s_{20})(s_{X10} + s_{10}) \ln\left(\frac{1}{2} s_{12} \right. \\
& \left. - \frac{1}{2} s_{22}\right) + \frac{1}{2} X_1 ((s_{12} X_1 + 2s_{11})s_{10} + s_{20}(s_{22} X_1 + 2s_{21})) \quad (2.13)
\end{aligned}$$

> Hams11:=simplify(Hamiltonianfunction(s12, s22, s11, s21, X1, 0, 0, 1, 0, 0))+
U11(s11, s21, s12, s22, X1)+diff(KOldCoordinates(s11, s21, s12, s22, X1), s11);
Hams21:=simplify(Hamiltonianfunction(s12, s22, s11, s21, X1, 0, 0, 0, 1, 0))+
U21(s11, s21, s12, s22, X1)+diff(KOldCoordinates(s11, s21, s12, s22, X1), s21);
Hams12:=simplify(Hamiltonianfunction(s12, s22, s11, s21, X1, 1, 0, 0, 0, 0))+
U12(s11, s21, s12, s22, X1)+diff(KOldCoordinates(s11, s21, s12, s22, X1), s12);
Hams22:=simplify(Hamiltonianfunction(s12, s22, s11, s21, X1, 0, 1, 0, 0, 0))+
U22(s11, s21, s12, s22, X1)+diff(KOldCoordinates(s11, s21, s12, s22, X1), s22);
HamX1:=simplify(Hamiltonianfunction(s12, s22, s11, s21, X1, 0, 0, 0, 0, 1))+
UX1(s11, s21, s12, s22, X1)+diff(KOldCoordinates(s11, s21, s12, s22, X1), X1);
;

Hams11formula := (-Q^4*s12*s22+(2*X1*s12*s22+(-s12-s22)*P-s11*s22-s12*s21)*Q^3+(-X1^2*s12*s22+(2*s12+2*s22)*P+2*s11*s22+2*s12*s21)*X1-P^2+(-s11-s21)*P+(-s20-h)*s12+(h-s10)*s22-s11*s21)*

$$Q^2 + ((-s12-s22)*P-s12*s21-s11*s22)*X1^2 + (2*P^2 + (2*s11+2*s21)*P + (2*s20+2*h)*s12 + (-h+2*s10)*s22 + 2*s11*s21)*X1 + P*(sX10+sX20)*Q + ((-s20-h)*s12 - P^2 + (-s11-s21)*P - s10*s22 - s11*s21)*X1^2 - P*(sX10+sX20)*X1 - sX10*sX20 / ((Q-X1)*(-s12+s22))$$

+

$$U11(s11, s21, s12, s22, X1) + \text{diff}(KOldCoordinates(s11, s21, s12, s22, X1), s11):$$

$$\text{Hams21formula} := (Q^4*s12*s22 + (-2*X1*s12*s22 + (s12+s22)*P + s11*s22 + s12*s21)*Q^3 + (X1^2*s12*s22 + ((-2*s12-2*s22)*P - 2*s11*s22 - 2*s12*s21)*X1 + P^2 + (s21+s11)*P + s10*s22 + s11*s21 + s12*s20)*Q^2 + ((s12+s22)*P + s11*s22 + s12*s21)*X1^2 + (-2*P^2 + (-2*s11-2*s21)*P + (-h-2*s20)*s12 - 2*s10*s22 - 2*s11*s21)*X1 - P*(sX10+sX20)*Q + ((s20+h)*s12 + P^2 + (s21+s11)*P + s10*s22 + s11*s21)*X1^2 + P*(sX10+sX20)*X1 + sX10*sX20 / ((Q-X1)*(-s12+s22))$$

+

$$U21(s11, s21, s12, s22, X1) + \text{diff}(KOldCoordinates(s11, s21, s12, s22, X1), s21):$$

$$\text{Hams12formula} := (-s12*s22*Q^2 + ((s21+P)*s12 + s22*(P+s11))*Q + (s20+h)*s12 + s10*s22 + (P+s11)*(s21+P))*(-s12+s22)*X1^3 + (2*s22*s12*(-s12+s22)*Q^3 + ((-2*P-2*s21)*s12^2 - 3*s22*(-s21+s11)*s12 + 2*s22^2*(P+s11))*Q^2 + ((-2*s20-2*h)*s12^2 + ((2*h-2*s10+2*s20)*s22 - (2*(P+3*s11*(1/2) - (1/2)*s21))*(s21+P))*s12 + (2*(s10*s22 + (P+s11)*(P - (1/2)*s11 + 3*s21*(1/2))))*s22)*Q + ((sX10+sX20-h)*P - (-s21+s11)*(s20+h))*s12 + ((-sX10-sX20+h)*P - s10*(-s21+s11))*s22 - (-s21+s11)*(s21+P)*(P+s11)*X1^2 + (-s22*s12*(-s12+s22)*Q^4 + ((s21+P)*s12^2 + 3*s22*(-s21+s11)*s12 - s22^2*(P+s11))*Q^3 + ((s20+h)*s12^2 + (s10-s20)*s22 + (s21+P)*(P+3*s11-2*s21))*s12 - s22*(h+s10)*s22 + (P+s11)*(P-2*s11+3*s21))*Q^2 + (((-sX10-sX20+2*h)*P + (2*s20+2*h)*s11 - s21*(h+2*s20))*s12 + ((sX10+sX20-2*h)*P + (-h+2*s10)*s11 - 2*s21*s10)*s22 + (2*(-s21+s11))*(s21+P)*(P+s11))*Q + sX10*sX20*s12 - sX10*sX20*s22 - P*(-s21+s11)*(sX10+sX20)*X1 - s22*(-s21+s11)*s12*Q^4 + ((-s22*h - (-s21+s11)*(s21+P))*s12 - (-s22*h + (-s21+s11)*(P+s11))*s22)*Q^3 + ((-h*P + (-s20-h)*s11 + s20*s21)*s12 + (h*P + (h-s10)*s11 + s21*s10)*s22 - (-s21+s11)*(s21+P)*(P+s11))*Q^2 + P*(-s21+s11)*(sX10+sX20)*Q - sX10*sX20*(-s21+s11) / (2*(-s12+s22)^2*(Q-X1))$$

+

$$U12(s11, s21, s12, s22, X1) + \text{diff}(KOldCoordinates(s11, s21, s12, s22, X1), s12):$$

$$\text{Hams22formula} := ((s12*s22*Q^2 + ((s21+P)*s12 + s22*(P+s11))*Q +$$

```

(s20+h)*s12+s10*s22+(P+s11)*(s21+P))*(-s12+s22)*X1^3+(-2*s22*
s12*(-s12+s22)*Q^3+((2*s21+2*P)*s12^2+3*s22*(-s21+s11)*s12-2*
s22^2*(P+s11))*Q^2+((2*s20+2*h)*s12^2+((-2*h+2*s10-2*s20)*s22+
(2*(P+3*s11*(1/2)-(1/2)*s21))*(s21+P))*s12-(2*(s10*s22+(P+s11)*
(P-(1/2)*s11+3*s21*(1/2))))*s22)*Q+((-sX10-sX20+h)*P+(-s21+s11)
*(s20+h))*s12+((sX10+sX20-h)*P+s10*(-s21+s11))*s22+(-s21+s11)*
(s21+P)*(P+s11))*X1^2+(s22*s12*(-s12+s22)*Q^4+((-s21-P)*s12^2
-3*s22*(-s21+s11)*s12+s22^2*(P+s11))*Q^3+((-2*h-s20)*s12^2+((2*
h-s10+s20)*s22-(s21+P)*(P+3*s11-2*s21))*s12+s22*(s10*s22+(P+
s11)*(P-2*s11+3*s21))*Q^2+(((sX10+sX20-2*h)*P+(-2*s20-2*h)*
s11+s21*(h+2*s20))*s12+((-sX10-sX20+2*h)*P+(h-2*s10)*s11+2*s21*
s10)*s22-(2*(-s21+s11))*(s21+P)*(P+s11))*Q-sX10*sX20*s12+sX10*
sX20*s22+P*(-s21+s11)*(sX10+sX20))*X1+s22*(-s21+s11)*s12*Q^4+
(s12^2*h+(-s22*h+(-s21+s11)*(s21+P))*s12+s22*(-s21+s11)*(P+s11)
)*Q^3+((h*P+(s20+h)*s11-s20*s21)*s12+(-h*P+(-h+s10)*s11-s21*
s10)*s22+(-s21+s11)*(s21+P)*(P+s11))*Q^2-P*(-s21+s11)*(sX10+
sX20)*Q+sX10*sX20*(-s21+s11)/(2*(-s12+s22)^2*(Q-X1))
+
U22(s11,s21,s12,s22,X1)+diff(KOldCoordinates(s11,s21,s12,s22,
X1),s22):

```

```

HamX1formula := (Q^4*s12*s22+(-2*X1*s12*s22+(s12+s22)*P+s11*
s22+s12*s21)*Q^3+(X1^2*s12*s22+((-2*s12-2*s22)*P-2*s11*s22-2*
s12*s21)*X1+(s20+h)*s12+P^2+(s21+s11)*P+s10*s22+s11*s21)*Q^2+((
(s12+s22)*P+s11*s22+s12*s21)*X1^2+(-2*P^2+(-2*s11-2*s21)*P+(-2*
s20-2*h)*s12-2*s10*s22-2*s11*s21)*X1-(sX10+sX20-h)*P)*Q+((s20+
h)*s12+P^2+(s21+s11)*P+s10*s22+s11*s21)*X1^2+(sX10+sX20-h)*P*
X1+sX10*sX20)/(Q-X1)
+
UX1(s11,s21,s12,s22,X1)+diff(KOldCoordinates(s11,s21,s12,s22,
X1),X1):

```

```

simplify(HamX1-HamX1formula);
simplify(Hams11-Hams11formula);
simplify(Hams21-Hams21formula);
simplify(Hams12-Hams12formula);
simplify(Hams22-Hams22formula);

```

$$\begin{aligned}
Hams11 := & \frac{1}{(Q-X1)(-s12+s22)} \left(-Q^4 s12 s22 + (2 X1 s12 s22 + (-s12 - s22) P \right. & (2.14) \\
& - s11 s22 - s12 s21) Q^3 + (-X1^2 s12 s22 + ((2 s12 + 2 s22) P + 2 s11 s22 \\
& + 2 s12 s21) X1 - P^2 + (-s11 - s21) P + (-s20 - h) s12 + (h - s10) s22 \\
& - s11 s21) Q^2 + (((-s12 - s22) P - s12 s21 - s11 s22) X1^2 + (2 P^2 + (2 s11 \\
& + 2 s21) P + (2 s20 + 2 h) s12 + (-h + 2 s10) s22 + 2 s11 s21) X1 + P (sX10
\end{aligned}$$

$$\begin{aligned}
& + sX20)) Q + ((-s20 - h) s12 - P^2 + (-s11 - s21) P - s10 s22 - s11 s21) XI^2 \\
& - P (sX10 + sX20) XI - sX10 sX20) + U11(s11, s21, s12, s22, XI) + XI s10 \\
Hams21 := & \frac{1}{(Q - XI) (-s12 + s22)} (Q^4 s12 s22 + (-2 XI s12 s22 + (s12 + s22) P \\
& + s11 s22 + s12 s21) Q^3 + (XI^2 s12 s22 + ((-2 s12 - 2 s22) P - 2 s11 s22 \\
& - 2 s12 s21) XI + P^2 + (s21 + s11) P + s10 s22 + s11 s21 + s12 s20) Q^2 + (((s12 \\
& + s22) P + s11 s22 + s12 s21) XI^2 + (-2 P^2 + (-2 s11 - 2 s21) P + (-h \\
& - 2 s20) s12 - 2 s10 s22 - 2 s11 s21) XI - P (sX10 + sX20)) Q + ((s20 + h) s12 \\
& + P^2 + (s21 + s11) P + s10 s22 + s11 s21) XI^2 + P (sX10 + sX20) XI + sX10 sX20) \\
& + U21(s11, s21, s12, s22, XI) + XI s20 \\
Hams12 := & \frac{1}{2} \frac{1}{(-s12 + s22)^2 (Q - XI)} \left(-(-s12 + s22) (s12 s22 Q^2 + ((s21 + P) s12 \right. \\
& + s22 (P + s11)) Q + (s20 + h) s12 + s10 s22 + (P + s11) (s21 + P)) XI^3 \\
& + \left(2 s22 s12 (-s12 + s22) Q^3 + ((-2 P - 2 s21) s12^2 - 3 s22 (-s21 + s11) s12 \right. \\
& + 2 s22^2 (P + s11)) Q^2 + \left((-2 s20 - 2 h) s12^2 + \left((2 h - 2 s10 + 2 s20) s22 - 2 \left(P \right. \right. \right. \\
& + \frac{3}{2} s11 - \frac{1}{2} s21) (s21 + P) \left. \left. \left. \right) s12 + 2 s22 \left(s10 s22 + (P + s11) \left(P - \frac{1}{2} s11 \right. \right. \right. \right. \\
& + \frac{3}{2} s21) \left. \left. \left. \right) \right) \right) Q + ((sX10 + sX20 - h) P - (-s21 + s11) (s20 + h)) s12 + ((-sX10 \\
& - sX20 + h) P - s10 (-s21 + s11)) s22 - (-s21 + s11) (s21 + P) (P + s11) \left. \right) XI^2 \\
& + (-s22 s12 (-s12 + s22) Q^4 + ((s21 + P) s12^2 + 3 s22 (-s21 + s11) s12 - s22^2 (P \\
& + s11)) Q^3 + ((s20 + h) s12^2 + ((s10 - s20) s22 + (s21 + P) (P + 3 s11 \\
& - 2 s21)) s12 - s22 ((h + s10) s22 + (P + s11) (P - 2 s11 + 3 s21))) Q^2 + (((\\
& -sX10 - sX20 + 2 h) P + (2 s20 + 2 h) s11 - s21 (h + 2 s20)) s12 + ((sX10 + sX20 \\
& - 2 h) P + (-h + 2 s10) s11 - 2 s21 s10) s22 + 2 (-s21 + s11) (s21 + P) (P \\
& + s11)) Q + sX10 sX20 s12 - sX10 sX20 s22 - P (-s21 + s11) (sX10 + sX20)) XI \\
& - s22 (-s21 + s11) s12 Q^4 + ((-s22 h - (-s21 + s11) (s21 + P)) s12 - s22 (-s22 h \\
& + (-s21 + s11) (P + s11))) Q^3 + ((-h P + (-s20 - h) s11 + s20 s21) s12 + (h P \\
& + (h - s10) s11 + s21 s10) s22 - (-s21 + s11) (s21 + P) (P + s11)) Q^2 + P (-s21 \\
& + s11) (sX10 + sX20) Q - sX10 sX20 (-s21 + s11) + U12(s11, s21, s12, s22, XI) \\
& + \frac{1}{4} \frac{(sX10 + s20) (sX10 + s10)}{\frac{1}{2} s12 - \frac{1}{2} s22} + \frac{1}{2} XI^2 s10 \\
Hams22 := & \frac{1}{2} \frac{1}{(-s12 + s22)^2 (Q - XI)} \left((-s12 + s22) (s12 s22 Q^2 + ((s21 + P) s12 \right. \\
& + s22 (P + s11)) Q + (s20 + h) s12 + s10 s22 + (P + s11) (s21 + P)) XI^3 + \left(\right. \\
& -2 s22 s12 (-s12 + s22) Q^3 + ((2 s21 + 2 P) s12^2 + 3 s22 (-s21 + s11) s12 \\
& - 2 s22^2 (P + s11)) Q^2 + \left((2 s20 + 2 h) s12^2 + \left((-2 h + 2 s10 - 2 s20) s22 + 2 \left(P \right. \right. \right. \\
& \left. \left. \left. \right) \right) \right)
\end{aligned}$$

$$\begin{aligned}
& + \frac{3}{2} s_{11} - \frac{1}{2} s_{21} \Big) (s_{21} + P) \Big) s_{12} - 2 s_{22} \left(s_{10} s_{22} + (P + s_{11}) \left(P - \frac{1}{2} s_{11} \right. \right. \\
& \left. \left. + \frac{3}{2} s_{21} \right) \right) \Big) Q + ((-s_{X10} - s_{X20} + h) P + (-s_{21} + s_{11}) (s_{20} + h)) s_{12} + ((s_{X10} \\
& + s_{X20} - h) P + s_{10} (-s_{21} + s_{11})) s_{22} + (-s_{21} + s_{11}) (s_{21} + P) (P + s_{11}) \Big) X1^2 \\
& + (s_{22} s_{12} (-s_{12} + s_{22}) Q^4 + ((-s_{21} - P) s_{12}^2 - 3 s_{22} (-s_{21} + s_{11}) s_{12} + s_{22}^2 (P \\
& + s_{11})) Q^3 + ((-2 h - s_{20}) s_{12}^2 + ((2 h - s_{10} + s_{20}) s_{22} - (s_{21} + P) (P + 3 s_{11} \\
& - 2 s_{21})) s_{12} + s_{22} (s_{10} s_{22} + (P + s_{11}) (P - 2 s_{11} + 3 s_{21}))) Q^2 + ((s_{X10} \\
& + s_{X20} - 2 h) P + (-2 s_{20} - 2 h) s_{11} + s_{21} (h + 2 s_{20})) s_{12} + ((-s_{X10} - s_{X20} \\
& + 2 h) P + (h - 2 s_{10}) s_{11} + 2 s_{21} s_{10}) s_{22} - 2 (-s_{21} + s_{11}) (s_{21} + P) (P + s_{11})) \\
& Q - s_{X10} s_{X20} s_{12} + s_{X10} s_{X20} s_{22} + P (-s_{21} + s_{11}) (s_{X10} + s_{X20})) X1 + s_{22} (\\
& -s_{21} + s_{11}) s_{12} Q^4 + (s_{12}^2 h + (-s_{22} h + (-s_{21} + s_{11}) (s_{21} + P)) s_{12} + s_{22} (-s_{21} \\
& + s_{11}) (P + s_{11})) Q^3 + ((h P + (s_{20} + h) s_{11} - s_{20} s_{21}) s_{12} + (-h P + (-h \\
& + s_{10}) s_{11} - s_{21} s_{10}) s_{22} + (-s_{21} + s_{11}) (s_{21} + P) (P + s_{11})) Q^2 - P (-s_{21} \\
& + s_{11}) (s_{X10} + s_{X20}) Q + s_{X10} s_{X20} (-s_{21} + s_{11})) + U22(s_{11}, s_{21}, s_{12}, s_{22}, X1) \\
& - \frac{1}{4} \frac{(s_{X10} + s_{20}) (s_{X10} + s_{10})}{\frac{1}{2} s_{12} - \frac{1}{2} s_{22}} + \frac{1}{2} X1^2 s_{20}
\end{aligned}$$

$$\begin{aligned}
HamX1 := & \frac{1}{Q - X1} (Q^4 s_{12} s_{22} + (-2 X1 s_{12} s_{22} + (s_{12} + s_{22}) P + s_{11} s_{22} \\
& + s_{12} s_{21}) Q^3 + (X1^2 s_{12} s_{22} + ((-2 s_{12} - 2 s_{22}) P - 2 s_{11} s_{22} - 2 s_{12} s_{21}) X1 \\
& + (s_{20} + h) s_{12} + P^2 + (s_{21} + s_{11}) P + s_{10} s_{22} + s_{11} s_{21}) Q^2 + (((s_{12} + s_{22}) P \\
& + s_{11} s_{22} + s_{12} s_{21}) X1^2 + (-2 P^2 + (-2 s_{11} - 2 s_{21}) P + (-2 s_{20} - 2 h) s_{12} \\
& - 2 s_{10} s_{22} - 2 s_{11} s_{21}) X1 - (s_{X10} + s_{X20} - h) P) Q + ((s_{20} + h) s_{12} + P^2 \\
& + (s_{21} + s_{11}) P + s_{10} s_{22} + s_{11} s_{21}) X1^2 + (s_{X10} + s_{X20} - h) P X1 + s_{X10} s_{X20}) \\
& + UX1(s_{11}, s_{21}, s_{12}, s_{22}, X1) + \frac{1}{2} (X1 s_{12} + 2 s_{11}) s_{10} + \frac{1}{2} s_{20} (X1 s_{22} + 2 s_{21}) \\
& + \frac{1}{2} X1 (s_{10} s_{12} + s_{20} s_{22})
\end{aligned}$$

0
0
0
0
0

```

> U11 := unapply( ((X1*s22+s21)*s10+(X1*s12+s11)*s20)/(s12-s22)
+s22*X1/(s12-s22)*h,s11,s21,s12,s22,X1);
U21 := unapply(-((X1*s22+s21)*s10+(X1*s12+s11)*s20)/(s12-s22) -
s12*X1/(s12-s22)*h,s11,s21,s12,s22,X1);
U12 := unapply( (X1*(s12-s22)-s11+s21)*((s10*s22+s12*s20)*X1+
s21*s10+s11*s20)/(2*(s12-s22)^2)
+(-s22^2*X1+(X1*s12-s11)*s22+s12*s21)*X1/(2*(s12-s22)^2)*h
,s11,s21,s12,s22,X1);
U22 := unapply(-(X1*(s12-s22)-s11+s21)*((s10*s22+s12*s20)*X1+
s21*s10+s11*s20)/(2*(s12-s22)^2)

```

```

-h*(X1*s12^2+(-X1*s22+s21)*s12-s11*s22)*X1/(2*(s12-s22)^2)
,s11,s21,s12,s22,X1);
UX1 := unapply( (X1*s22+s21)*s10+(X1*s12+s11)*s20,s11,s21,s12,
s22,X1);

```

$$U11 := (s11, s21, s12, s22, X1) \rightarrow \frac{(s22 X1 + s21) s10 + (s12 X1 + s11) s20}{s12 - s22} + \frac{s22 X1 h}{s12 - s22} \quad (2.15)$$

$$U21 := (s11, s21, s12, s22, X1) \rightarrow -\frac{(s22 X1 + s21) s10 + (s12 X1 + s11) s20}{s12 - s22}$$

$$-\frac{s12 X1 h}{s12 - s22}$$

$$U12 := (s11, s21, s12, s22, X1)$$

$$\rightarrow \frac{1}{2} \frac{(X1 (s12 - s22) - s11 + s21) ((s10 s22 + s12 s20) X1 + s10 s21 + s11 s20)}{(s12 - s22)^2}$$

$$+ \frac{1}{2} \frac{(-s22^2 X1 + (s12 X1 - s11) s22 + s12 s21) X1 h}{(s12 - s22)^2}$$

$$U22 := (s11, s21, s12, s22, X1) \rightarrow$$

$$-\frac{1}{2} \frac{(X1 (s12 - s22) - s11 + s21) ((s10 s22 + s12 s20) X1 + s10 s21 + s11 s20)}{(s12 - s22)^2}$$

$$-\frac{1}{2} \frac{h (X1 s12^2 + (-s22 X1 + s21) s12 - s11 s22) X1}{(s12 - s22)^2}$$

$$UX1 := (s11, s21, s12, s22, X1) \rightarrow (s22 X1 + s21) s10 + (s12 X1 + s11) s20$$

JMU differential

First part: Contributions at xi=X_1

```

> ExpMonodromiesX1:=Matrix(2,2,0):

```

```

ExpMonodromiesX1[1,1]:=exp(sX10*ln(xi-X1)/h):

```

```

ExpMonodromiesX1[2,2]:=exp(sX20*ln(xi-X1)/h):

```

```

ExpMonodromiesX1;

```

```

MonodromiesX1:=Matrix(2,2,0):

```

```

MonodromiesX1[1,1]:=sX10/(xi-X1):

```

```

MonodromiesX1[2,2]:=sX20/(xi-X1):

```

```

MonodromiesX1:

```

```

LambdaX1:=Matrix(2,2,0):

```

```

LambdaX1[1,1]:=sX10*ln(xi-X1):

```

```

LambdaX1[2,2]:=sX20*ln(xi-X1):

```

```

LambdaX1:

```

```

N0:=Matrix(2,2,0):

```

```

N1:=Matrix(2,2,0):

```

```

N2:=Matrix(2,2,0):

```

```

N3:=Matrix(2,2,0):

```

```

N4:=Matrix(2,2,0):

```

```

for i from 1 to 2 do for j from 1 to 2 do
N0[i,j]:=n0[i,j]:
N1[i,j]:=n1[i,j]:
N2[i,j]:=n2[i,j]:
N3[i,j]:=n3[i,j]:
N4[i,j]:=n4[i,j]:
od: od:

HatPsiRegX1:=IdentityMatrix(2)+N1*(xi-X1)+N2*(xi-X1)^2+N3*(xi-
X1)^3+N4*(xi-X1)^4:
tdPsiX1:=Multiply(N0,Multiply(HatPsiRegX1,ExpMonodromiesX1)):

dHatPsiRegdxiX1:=Matrix(2,2,0):
for i from 1 to 2 do for j from 1 to 2 do dHatPsiRegdxiX1[i,j]
:=diff(HatPsiRegX1[i,j],xi): od: od:

dtdPsidxiX1:=Matrix(2,2,0):
for i from 1 to 2 do for j from 1 to 2 do dtdPsidxiX1[i,j]:=
diff(tdPsiX1[i,j],xi): od: od:

dLambdaX1dt:=Matrix(2,2,0):
for i from 1 to 2 do for j from 1 to 2 do dLambdaX1dt[i,j]:=
simplify(diff(LambdaX1[i,j],X1)*dX1): od: od:
dLambdaX1dt;

omegaJMUPartX1:=simplify(-h*residue(Trace(Multiply(Multiply
(HatPsiRegX1^(-1),dHatPsiRegdxiX1), dLambdaX1dt)),xi=X1));

ToCancelX1:=simplify(h*dtdPsidxiX1-Multiply(tdL,tdPsiX1)):

$$\begin{bmatrix} e^{\frac{sX10 \ln(\xi - X1)}{h}} & 0 \\ 0 & e^{\frac{sX20 \ln(\xi - X1)}{h}} \end{bmatrix}$$


$$\begin{bmatrix} \frac{sX10 dX1}{-\xi + X1} & 0 \\ 0 & \frac{sX20 dX1}{-\xi + X1} \end{bmatrix}$$


$$\text{omegaJMUPartX1} := h dX1 (sX10 n1_{1,1} + sX20 n1_{2,2})$$

(2.16)
> SingularParttdLxiX1:=Matrix(2,2,0):
for i from 1 to 2 do for j from 1 to 2 do SingularParttdLxiX1
[i,j]:=simplify(residue(tdL[i,j],xi=X1)): od: od:

```

```

MatrixEigenvectorsSingularPartX1:=Matrix(2,2,0):
MatrixEigenvectorsSingularPartX1[1,1]:=Q-X1:
MatrixEigenvectorsSingularPartX1[1,2]:=Q-X1:
MatrixEigenvectorsSingularPartX1[2,1]:=Q^2*s12-Q*X1*s12+P*Q-P*
X1+Q*s11-X1*s11-sX10:
MatrixEigenvectorsSingularPartX1[2,2]:=Q^2*s12-Q*X1*s12+P*Q-P*
X1+Q*s11-X1*s11-sX20:
simplify(Multiply(Multiply(MatrixEigenvectorsSingularPartX1^
(-1),SingularParttdLxiX1),MatrixEigenvectorsSingularPartX1));
GX10:=MatrixEigenvectorsSingularPartX1;

n0[1,1]:=Q-X1;
n0[1,2]:=Q-X1;

```

$$\begin{bmatrix} sX10 & 0 \\ 0 & sX20 \end{bmatrix} \quad (2.17)$$

$$\begin{aligned} & [[Q - X1, Q - X1], \\ & [Q^2 s12 - Q X1 s12 + P Q - P X1 + Q s11 - X1 s11 - sX10, Q^2 s12 - Q X1 s12 + P Q \\ & - P X1 + Q s11 - X1 s11 - sX20]] \\ & n0_{1,1} := Q - X1 \\ & n0_{1,2} := Q - X1 \end{aligned}$$

```

> ToCancelX1Entry11:=simplify(series(simplify(ToCancelX1[1,1]*
(xi-X1)^(-(sX10)/h),xi=X1)):
ToCancelX1Entry12:=simplify(series(simplify(ToCancelX1[1,2]*
(xi-X1)^(-(sX20)/h),xi=X1)):
ToCancelX1Entry21:=simplify(series(simplify(ToCancelX1[2,1]*
(xi-X1)^(-(sX10)/h),xi=X1)):
ToCancelX1Entry22:=simplify(series(simplify(ToCancelX1[2,2]*
(xi-X1)^(-(sX20)/h),xi=X1)):
> n0[2,1]:=simplify(solve(residue(ToCancelX1Entry11,xi=X1),n0[2,
1]));
n0[2,2]:=simplify(solve(residue(ToCancelX1Entry12,xi=X1),n0[2,
2]));
simplify(residue(ToCancelX1Entry21,xi=X1));
simplify(residue(ToCancelX1Entry22,xi=X1));
n021:=P*(Q-X1)+s12*Q^2+(s11-X1*s12)*Q-X1*s11-sX10;
n022:=P*(Q-X1)+s12*Q^2+(s11-X1*s12)*Q-X1*s11-sX20;
simplify(n0[2,1]-n021);
simplify(n0[2,2]-n022);

```

$$\begin{aligned} n0_{2,1} &:= Q^2 s12 + (-X1 s12 + P + s11) Q + (-P - s11) X1 - sX10 \\ n0_{2,2} &:= Q^2 s12 + (-X1 s12 + P + s11) Q + (-P - s11) X1 - sX20 \end{aligned} \quad (2.18)$$

$$\begin{array}{c}
0 \\
0 \\
n021 := P(Q - X1) + Q^2 s12 + (-X1 s12 + s11) Q - X1 s11 - sX10 \\
n022 := P(Q - X1) + Q^2 s12 + (-X1 s12 + s11) Q - X1 s11 - sX20 \\
0 \\
0
\end{array}$$

> n1[1,1] := (Q^4*s12*s22+(-2*X1*s12*s22+(s12+s22)*P+s11*s22+s12*s21)*Q^3+(X1^2*s12*s22+((-2*s12-2*s22)*P-2*s11*s22-2*s12*s21)*X1+P^2+(s21+s11)*P+s10*s22+s11*s21+s12*s20)*Q^2+(((s12+s22)*P+s11*s22+s12*s21)*X1^2+(-2*P^2+(-2*s11-2*s21)*P+(-sX10-2*s20)*s12+(-sX10-2*s10)*s22-2*s11*s21)*X1+(-sX10-sX20)*P-sX10*(s21+s11))*Q+(P^2+(s21+s11)*P+(sX10+s20)*s12+s22*(sX10+s10)+s11*s21)*X1^2+(P*(sX10+sX20)+sX10*(s21+s11))*X1+sX10*sX20)/(Q-X1)*h*(sX10-sX20):

n1[1,2] := (-Q^4*s12*s22+(2*X1*s12*s22+(-s21-P)*s12-s22*(P+s11))*Q^3+(-X1^2*s12*s22+((2*s21+2*P)*s12+2*s22*(P+s11))*X1+(-sX10+sX20-s20)*s12-P^2+(-s11-s21)*P-s10*s22-s11*s21)*Q^2+(((s21-P)*s12-s22*(P+s11))*X1^2+((2*sX10-sX20+2*s20)*s12+2*P^2+(2*s11+2*s21)*P+(sX20+2*s10)*s22+2*s11*s21)*X1+2*sX20*(P+(1/2)*s11+(1/2)*s21))*Q+((-sX10-s20)*s12-P^2+(-s11-s21)*P+(-sX20-s10)*s22-s11*s21)*X1^2-2*sX20*(P+(1/2)*s11+(1/2)*s21)*X1-sX20^2)/((sX10-sX20)*(-h+sX10-sX20)*(Q-X1)):

n1[2,1] := (-Q^4*s12*s22+(2*X1*s12*s22+(-s21-P)*s12-s22*(P+s11))*Q^3+(-X1^2*s12*s22+((2*s21+2*P)*s12+2*s22*(P+s11))*X1+(sX10-sX20-s20)*s12-P^2+(-s11-s21)*P-s10*s22-s11*s21)*Q^2+(((s21-P)*s12-s22*(P+s11))*X1^2+((-sX10+2*sX20+2*s20)*s12+2*P^2+(2*s11+2*s21)*P+(sX10+2*s10)*s22+2*s11*s21)*X1+(2*(P+(1/2)*s11+(1/2)*s21))*sX10)*Q+((-sX20-s20)*s12-P^2+(-s11-s21)*P+(-sX10-s10)*s22-s11*s21)*X1^2-(2*(P+(1/2)*s11+(1/2)*s21))*sX10*X1-sX10^2)/((h+sX10-sX20)*(sX10-sX20)*(Q-X1)):

n1[2,2] := -(Q^4*s12*s22-2*Q^3*X1*s12*s22+Q^2*X1^2*s12*s22+P*Q^3*s12+P*Q^3*s22-2*P*Q^2*X1*s12-2*P*Q^2*X1*s22+P*Q*X1^2*s12+P*Q*X1^2*s22+Q^3*s11*s22+Q^3*s12*s21-2*Q^2*X1*s11*s22-2*Q^2*X1*s12*s21+Q*X1^2*s11*s22+Q*X1^2*s12*s21+P^2*Q^2-2*P^2*Q*X1+P^2*X1^2+P*Q^2*s11+P*Q^2*s21-2*P*Q*X1*s11-2*P*Q*X1*s21+P*X1^2*s11+P*X1^2*s21+Q^2*s10*s22+Q^2*s11*s21+Q^2*s12*s20-2*Q*X1*s10*s22-2*Q*X1*s11*s21-2*Q*X1*s12*s20-Q*X1*s12*sX20-Q*X1*s22*sX20+X1^2*s10*s22+X1^2*s11*s21+X1^2*s12*s20+X1^2*s12*sX20+X1^2*s22*sX20-P*Q*sX10-P*Q*sX20+P*X1*sX10+P*X1*sX20-Q*s11*sX20-Q*s21*sX20+X1*s11*sX20+X1*s21*sX20+sX10*sX20)/(Q-X1)*h*(sX10-sX20):

```

simplify(residue( ToCancelX1Entry11/(xi-X1),xi=X1));
simplify(residue( ToCancelX1Entry12/(xi-X1),xi=X1));
simplify(residue( ToCancelX1Entry21/(xi-X1),xi=X1));
simplify(residue( ToCancelX1Entry22/(xi-X1),xi=X1));

```

(2.19)

```

0
0
0
0

```

```

> omegaJMUPartX1:=simplify(omegaJMUPartX1):

```

Second part: Contributions at infinity

```

> ExpXiInfinity:=Matrix(2,2,0):

```

```

ExpXiInfinity[1,1]:=exp(-(s11*xi+s12*xi^2/2)/h):

```

```

ExpXiInfinity[2,2]:=exp(-(s21*xi+s22*xi^2/2)/h):

```

```

ExpXiInfinity;

```

```

XiInfinity:=Matrix(2,2,0):

```

```

XiInfinity[1,1]:=-(s10*ln(xi)+s11*xi+s12*xi^2/2):

```

```

XiInfinity[2,2]:=-(s20*ln(xi)+s21*xi+s22*xi^2/2):

```

```

XiInfinity;

```

```

dXiInfinitydxi:=Matrix(2,2,0):

```

```

for i from 1 to 2 do for j from 1 to 2 do dXiInfinitydxi[i,j]:=

```

```

diff(XiInfinity[i,j],xi): od: od:

```

```

dXiInfinitydxi;

```

```

ExpMonodromiesInf:=Matrix(2,2,0):

```

```

ExpMonodromiesInf[1,1]:=exp(-s10*ln(xi)/h):

```

```

ExpMonodromiesInf[2,2]:=exp(-s20*ln(xi)/h):

```

```

ExpMonodromiesInf;

```

```

MonodromiesInf:=Matrix(2,2,0):

```

```

MonodromiesInf[1,1]:=-s10/xi:

```

```

MonodromiesInf[2,2]:=-s20/xi:

```

```

MonodromiesInf;

```

```

J1:=Matrix(2,2,0):

```

```

J2:=Matrix(2,2,0):

```

```

J3:=Matrix(2,2,0):

```

```

J4:=Matrix(2,2,0):

```

```

for i from 1 to 2 do for j from 1 to 2 do J1[i,j]:=j1[i,j]:

```

```

J2[i,j]:=j2[i,j]:

```

```

J3[i,j]:=j3[i,j]:

```

```

J4[i,j]:=j4[i,j]:

```

od: od:

```
HatPsiRegInf:=IdentityMatrix(2)+J1/xi+J2/xi^2+J3/xi^3+J4/xi^4:
tdPsiInf:=Multiply(Multiply(HatPsiRegInf,ExpXiInfinity),
ExpMonodromiesInf):
```

```
dHatPsiRegdxiInf:=Matrix(2,2,0):
for i from 1 to 2 do for j from 1 to 2 do dHatPsiRegdxiInf[i,j]
:=diff(HatPsiRegInf[i,j],xi): od: od:
```

```
dtdPsidxiInf:=Matrix(2,2,0):
for i from 1 to 2 do for j from 1 to 2 do dtdPsidxiInf[i,j]:=
diff(tdPsiInf[i,j],xi): od: od:
```

```
dXiInfinitydt:=Matrix(2,2,0):
for i from 1 to 2 do for j from 1 to 2 do dXiInfinitydt[i,j]:=
simplify(diff(XiInfinity[i,j],s11)*ds11+diff(XiInfinity[i,j],
s21)*ds21+diff(XiInfinity[i,j],s12)*ds12+diff(XiInfinity[i,j],
s22)*ds22) od: od:
dXiInfinitydt:
```

```
omegaJMUPartInfinity:=-h*residue(Trace(Multiply(Multiply
(HatPsiRegInf^(-1),dHatPsiRegdxiInf), dXiInfinitydt)),xi=
infinity):
```

```
ToCancelInf:=simplify(h*dtdPsidxiInf-Multiply(tdL,tdPsiInf)):
```

$$\begin{bmatrix} e^{-\frac{s11\xi + \frac{1}{2}\xi^2 s12}{h}} & 0 \\ 0 & e^{-\frac{s21\xi + \frac{1}{2}\xi^2 s22}{h}} \end{bmatrix} \begin{bmatrix} e^{-\frac{s10\ln(\xi)}{h}} & 0 \\ 0 & e^{-\frac{s20\ln(\xi)}{h}} \end{bmatrix}$$

(2.20)

$$\begin{aligned} \omega_{JMUPartInfinity} := & -h \left(-j_{1,1} ds_{11} + \frac{1}{2} (j_{1,1}^2 + j_{1,2} j_{2,1} - 2 j_{2,1}) ds_{12} \right. \\ & \left. - j_{2,2} ds_{21} + \frac{1}{2} (j_{1,2} j_{2,1} + j_{2,2}^2 - 2 j_{2,2}) ds_{22} \right) \end{aligned}$$

```
> series(simplify(ToCancelInf[1,1])*exp((xi^2*s12+2*s10*ln(xi))+2*
```



```

s11*xi)/(2*h)),xi=infinity):
j1[2,1]:=simplify(solve(residue(simplify(ToCancelInf[1,1]*exp(
(xi^2*s12+2*s10*ln(xi)+2*s11*xi)/(2*h)),
,xi=infinity),j1[2,1]));
j2[2,1]:=simplify(solve(residue(simplify(ToCancelInf[1,1]*exp(
(xi^2*s12+2*s10*ln(xi)+2*s11*xi)/(2*h))*xi
,xi=infinity),j2[2,1]));
j3[2,1]:=simplify(solve(residue(simplify(ToCancelInf[1,1]*exp(
(xi^2*s12+2*s10*ln(xi)+2*s11*xi)/(2*h))*xi^2
,xi=infinity),j3[2,1]));

```

$$\begin{aligned}
j_{2,1} &:= -Q^2 s_{12} + (X_1 s_{12} - P - s_{11}) Q + (P + s_{11}) X_1 - s_{10} & (2.21) \\
j_{2,1} &:= -s_{12} Q^3 + (X_1 s_{12} - s_{12} j_{1,1} - P - s_{11}) Q^2 + ((X_1 s_{12} - P - s_{11}) j_{1,1} + (P \\
&\quad + s_{11}) X_1 - s_{10}) Q + ((P + s_{11}) X_1 - h - s_{10}) j_{1,1} + X_1 s_{10}
\end{aligned}$$

```

> series(simplify(ToCancelInf[1,2]*exp((xi^2*s22+2*s20*ln(xi)+2*
s21*xi)/(2*h)),xi=infinity):
j1[1,2]:=simplify(solve(residue(simplify(ToCancelInf[1,2]*exp(
(xi^2*s22+2*s20*ln(xi)+2*s21*xi)/(2*h))/xi
,xi=infinity),j1[1,2]));
j2[1,2]:=simplify(solve(residue(simplify(ToCancelInf[1,2]*exp(
(xi^2*s22+2*s20*ln(xi)+2*s21*xi)/(2*h))
,xi=infinity),j2[1,2]));
j3[1,2]:=simplify(solve(residue(simplify(ToCancelInf[1,2]*exp(
(xi^2*s22+2*s20*ln(xi)+2*s21*xi)/(2*h))*xi
,xi=infinity),j3[1,2]));

```

$$\begin{aligned}
j_{1,2} &:= \frac{1}{s_{12} - s_{22}} & (2.22) \\
j_{2,2} &:= \frac{(j_{1,2} - Q + X_1) s_{12} + (Q - X_1 - j_{1,2}) s_{22} - s_{11} + s_{21}}{(s_{12} - s_{22})^2}
\end{aligned}$$

```

> sX20:=-s10-s20-sX10:
series(simplify(ToCancelInf[2,1]*exp((xi^2*s12+2*s10*ln(xi)+2*
s11*xi)/(2*h)) -s12*(s10+s20+sX10+sX20),xi=infinity):
j1[1,1]:=simplify(solve(residue(simplify(ToCancelInf[2,1]*exp(
(xi^2*s12+2*s10*ln(xi)+2*s11*xi)/(2*h))
,xi=infinity),j1[1,1]));
j2[1,1]:=simplify(solve(residue(simplify(ToCancelInf[2,1]*exp(
(xi^2*s12+2*s10*ln(xi)+2*s11*xi)/(2*h))*xi
,xi=infinity),j2[1,1]));

```

$$\begin{aligned}
j_{1,1} &:= \frac{1}{(Q - X_1)(-s_{12} + s_{22})h} (-Q^4 s_{12} s_{22} + (2 X_1 s_{12} s_{22} + (-s_{12} - s_{22}) P \\
&\quad - s_{11} s_{22} - s_{12} s_{21}) Q^3 + (-X_1^2 s_{12} s_{22} + ((2 s_{12} + 2 s_{22}) P + 2 s_{11} s_{22} \\
&\quad + 2 s_{12} s_{21}) X_1 - P^2 + (-s_{11} - s_{21}) P - s_{10} s_{22} - s_{11} s_{21} - s_{12} s_{20}) Q^2 + (((-s_{12} \\
&\quad - s_{22}) P - s_{12} s_{21} - s_{11} s_{22}) X_1^2 + (2 P^2 + (2 s_{11} + 2 s_{21}) P + (-s_{10} + s_{20}) s_{12}
\end{aligned} \tag{2.23}$$

$$+ 2 s_{10} s_{22} + 2 s_{11} s_{21}) X_1 + P (-s_{10} - s_{20}) - s_{21} s_{10} - s_{11} s_{20}) Q + (s_{10} s_{12} - P^2 + (-s_{11} - s_{21}) P - s_{11} s_{21} - s_{10} s_{22}) X_1^2 + ((s_{10} + s_{20}) P + s_{21} s_{10} + s_{11} s_{20}) X_1 + s_{X10} (s_{X10} + s_{10} + s_{20})$$

```
> series(simplify(ToCancelInf[2,2]*exp((xi^2*s22+2*s20*ln(xi)+2*s21*xi)/(2*h)),xi=infinity):
j1[2,2]:=simplify(solve(residue(simplify(ToCancelInf[2,2]*exp((xi^2*s22+2*s20*ln(xi)+2*s21*xi)/(2*h)))*xi,xi=infinity),j1[2,2]));
j2[2,2]:=simplify(solve(residue(simplify(ToCancelInf[2,2]*exp((xi^2*s22+2*s20*ln(xi)+2*s21*xi)/(2*h)))*xi^2,xi=infinity),j2[2,2]));
```

$$j_{1,2} := \frac{1}{(-s_{12} + s_{22})(Q - X_1)h} (Q^4 s_{12} s_{22} + (-2 X_1 s_{12} s_{22} + (s_{12} + s_{22}) P + s_{11} s_{22} + s_{12} s_{21}) Q^3 + (X_1^2 s_{12} s_{22} + ((-2 s_{12} - 2 s_{22}) P - 2 s_{11} s_{22} - 2 s_{12} s_{21}) X_1 + P^2 + (s_{21} + s_{11}) P + s_{10} s_{22} + s_{11} s_{21} + s_{12} s_{20}) Q^2 + ((s_{12} + s_{22}) P + s_{11} s_{22} + s_{12} s_{21}) X_1^2 + (-2 P^2 + (-2 s_{11} - 2 s_{21}) P + (-s_{10} + s_{20}) s_{22} - 2 s_{11} s_{21} - 2 s_{12} s_{20}) X_1 + (s_{10} + s_{20}) P + s_{21} s_{10} + s_{11} s_{20}) Q + (P^2 + (s_{21} + s_{11}) P - s_{20} s_{22} + s_{11} s_{21} + s_{12} s_{20}) X_1^2 + (P (-s_{10} - s_{20}) - s_{21} s_{10} - s_{11} s_{20}) X_1 - s_{X10} (s_{X10} + s_{10} + s_{20})) \quad (2.24)$$

```
> omegaJMUPartInfinity:=simplify(omegaJMUPartInfinity):
> omegaJMUP4:=omegaJMUPartX1+omegaJMUPartInfinity:
> omegaJMUP4ds11:=simplify(residue(omegaJMUP4/ds11^2,ds11=0)):
omegaJMUP4ds21:=simplify(residue(omegaJMUP4/ds21^2,ds21=0)):
omegaJMUP4ds12:=simplify(residue(omegaJMUP4/ds12^2,ds12=0)):
omegaJMUP4ds22:=simplify(residue(omegaJMUP4/ds22^2,ds22=0)):
omegaJMUP4dX1:=simplify(residue(omegaJMUP4/dX1^2,dX1=0)):
> simplify(omegaJMUP4ds11-residue(Hams11/h,h=0));
simplify(omegaJMUP4ds21-residue(Hams21/h,h=0));
simplify(omegaJMUP4ds12-residue(Hams12/h,h=0));
simplify(omegaJMUP4ds22-residue(Hams22/h,h=0));
simplify(omegaJMUP4dX1-residue(HamX1/h,h=0));
```

$$\begin{matrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{matrix} \quad (2.25)$$

```
> omegaJMUP4:=simplify(omegaJMUP4):
omegaJMUP4formula:= ((2*(-1/2)*(ds12-ds22)*(-s12+s22)*X1+dX1*s12^2+(-2*dX1*s22+ds11-ds21)*s12+dX1*s22^2+(-ds11+ds21)*s22-(1/2)*(-s21+s11)*(ds12-ds22))*s22*s12*Q^4+(2*(-1/2)*(ds12-ds22)*(-s12+s22)*X1+dX1*s12^2+(-2*dX1*s22+ds11-ds21)*s12+dX1*s22^2+(-ds11+ds21)*s22-(1/2)*(-s21+s11)*(ds12-ds22))*(-2*X1*s12*s22+(s21+P)*s12+s22*(P+s11))*Q^3+(2*(-1/2)*(ds12-ds22)*(-
```

$$\begin{aligned}
& s_{12}+s_{22}) * X_1+dX_1*s_{12}^2+(-2*dX_1*s_{22}+ds_{11}-ds_{21}) * s_{12}+dX_1*s_{22}^2+(- \\
& ds_{11}+ds_{21}) * s_{22}-(1/2) * (-s_{21}+s_{11}) * (ds_{12}-ds_{22})) * (X_1^2*s_{12}*s_{22}+(\\
& (-2*P-2*s_{21}) * s_{12}-2*s_{22} * (P+s_{11})) * X_1+s_{12}*s_{20}+s_{10}*s_{22}+(P+s_{11}) * \\
& (s_{21}+P)) * Q^2+(-(-s_{12}+s_{22}) * ((s_{21}+P) * s_{12}+s_{22} * (P+s_{11})) * (ds_{12}-ds_{22}) \\
& * X_1^3+(2*dX_1 * (s_{21}+P) * s_{12}^3+(-2*dX_1 * (P-s_{11}+2*s_{21}) * s_{22}+(2*ds_{11}-2* \\
& ds_{21}) * P+(2*ds_{11}-2*ds_{21}) * s_{21}+(s_{10}-s_{20}) * ds_{12}+2*ds_{22}*s_{20}) * s_{12}^2+ \\
& (-2*dX_1 * (P+2*s_{11}-s_{21}) * s_{22}^2+(2*ds_{11}-2*ds_{21}) * s_{11}+(-2*ds_{11}+2* \\
& ds_{21}) * s_{21}+(-3*s_{10}+s_{20}) * ds_{12}+ds_{22} * (s_{10}-3*s_{20})) * s_{22}-(2 * (P+3*s_{11} * \\
& (1/2)-(1/2) * s_{21})) * (ds_{12}-ds_{22}) * (s_{21}+P)) * s_{12}+2*s_{22} * (dX_1 * (P+s_{11}) * \\
& s_{22}^2+((-ds_{11}+ds_{21}) * P+(-ds_{11}+ds_{21}) * s_{11}+ds_{12}*s_{10}-(1/2) * ds_{22} * (s_{10} \\
& -s_{20})) * s_{22}+(P-(1/2) * s_{11}+3*s_{21} * (1/2)) * (ds_{12}-ds_{22}) * (P+s_{11})) * \\
& X_1^2+(2*dX_1 * (s_{10}-s_{20}) * s_{12}^3+(-6*dX_1 * (s_{10}-s_{20}) * s_{22}-4*P^2*dX_1-4* \\
& dX_1 * (s_{21}+s_{11}) * P-4*dX_1*s_{11}*s_{21}+2*ds_{11}*s_{10}-2*s_{20} * (ds_{11}-2*ds_{21})) * \\
& s_{12}^2+(6*dX_1 * (s_{10}-s_{20}) * s_{22}^2+(8*P^2*dX_1+8*dX_1 * (s_{21}+s_{11}) * P+8* \\
& dX_1*s_{11}*s_{21}+(-6*ds_{11}+2*ds_{21}) * s_{10}+2*s_{20} * (ds_{11}-3*ds_{21})) * s_{22}+(-4* \\
& ds_{11}+4*ds_{21}) * P^2+((-4*ds_{11}+4*ds_{21}) * s_{11}+(-4*ds_{11}+4*ds_{21}) * s_{21}+ \\
& (s_{10}+s_{20}) * (ds_{12}-ds_{22})) * P+((-4*ds_{11}+4*ds_{21}) * s_{21}+2*s_{20} * (ds_{12}- \\
& ds_{22})) * s_{11}+s_{21} * (s_{10}-s_{20}) * (ds_{12}-ds_{22})) * s_{12}-2*dX_1 * (s_{10}-s_{20}) * \\
& s_{22}^3+(-4*P^2*dX_1-4*dX_1 * (s_{21}+s_{11}) * P-4*dX_1*s_{11}*s_{21}+(4*ds_{11}-2* \\
& ds_{21}) * s_{10}+2*ds_{21}*s_{20}) * s_{22}^2+((4*ds_{11}-4*ds_{21}) * P^2+((4*ds_{11}-4* \\
& ds_{21}) * s_{11}+(4*ds_{11}-4*ds_{21}) * s_{21}-(s_{10}+s_{20}) * (ds_{12}-ds_{22})) * P+((4*ds_{11} \\
& -4*ds_{21}) * s_{21}+(s_{10}-s_{20}) * (ds_{12}-ds_{22})) * s_{11}-2*s_{21}*s_{10} * (ds_{12}-ds_{22})) * \\
& s_{22}+(2 * (-s_{21}+s_{11})) * (s_{21}+P) * (P+s_{11}) * (ds_{12}-ds_{22})) * X_1+2*dX_1 * (s_{10}+ \\
& s_{20}) * (P+s_{11}+s_{21}) * s_{12}^2+(-4*dX_1 * (s_{10}+s_{20}) * (P+s_{11}+s_{21}) * s_{22}+(2 * \\
& (s_{10}+s_{20})) * (ds_{11}-ds_{21}) * P+2*s_{20} * (ds_{11}-ds_{21}) * s_{11}+2*s_{10} * (ds_{11}- \\
& ds_{21}) * s_{21}+(s_{10}+s_{20}) * (s_{10}+s_{10}) * (ds_{12}-ds_{22})) * s_{12}+2*dX_1 * (s_{10}+ \\
& s_{20}) * (P+s_{11}+s_{21}) * s_{22}^2+(-(2 * (s_{10}+s_{20})) * (ds_{11}-ds_{21}) * P-2*s_{20} * \\
& (ds_{11}-ds_{21}) * s_{11}-2*s_{10} * (ds_{11}-ds_{21}) * s_{21}-(s_{10}+s_{20}) * (s_{10}+s_{10}) * \\
& (ds_{12}-ds_{22})) * s_{22}-(ds_{12}-ds_{22}) * ((s_{10}+s_{20}) * P+s_{21}*s_{10}+s_{11}*s_{20}) * (- \\
& s_{21}+s_{11})) * Q-(-s_{12}+s_{22}) * ((-ds_{12}*s_{10}-ds_{22}*s_{20}) * s_{12}+(ds_{12}*s_{10}+ \\
& ds_{22}*s_{20}) * s_{22}+(s_{21}+P) * (P+s_{11}) * (ds_{12}-ds_{22})) * X_1^3+(-2*dX_1*s_{10} * \\
& s_{12}^3+((4 * (s_{10}-(1/2) * s_{20})) * dX_1*s_{22}+2*P^2*dX_1+2*dX_1 * (s_{21}+s_{11})) * \\
& P+2*dX_1*s_{11}*s_{21}-2*ds_{11}*s_{10}-2*ds_{21}*s_{20}) * s_{12}^2+(-2*dX_1 * (s_{10}-2* \\
& s_{20}) * s_{22}^2+(-4*P^2*dX_1-4*dX_1 * (s_{21}+s_{11}) * P-4*dX_1*s_{11}*s_{21}+4*ds_{11} * \\
& s_{10}+4*ds_{21}*s_{20}) * s_{22}+(2*ds_{11}-2*ds_{21}) * P^2+((2*ds_{11}-2*ds_{21}) * s_{11}+ \\
& (2*ds_{11}-2*ds_{21}) * s_{21}-(s_{10}+s_{20}) * (ds_{12}-ds_{22})) * P+((2*ds_{11}-2*ds_{21}) * \\
& s_{21}-s_{20} * (ds_{12}-ds_{22})) * s_{11}-s_{21}*s_{10} * (ds_{12}-ds_{22})) * s_{12}-2*s_{22}^3*dX_1 * \\
& s_{20}+(2*P^2*dX_1+2*dX_1 * (s_{21}+s_{11}) * P+2*dX_1*s_{11}*s_{21}-2*ds_{11}*s_{10}-2* \\
& ds_{21}*s_{20}) * s_{22}^2+((-2*ds_{11}+2*ds_{21}) * P^2+((-2*ds_{11}+2*ds_{21}) * s_{11}+ \\
& (-2*ds_{11}+2*ds_{21}) * s_{21}+(s_{10}+s_{20}) * (ds_{12}-ds_{22})) * P+((-2*ds_{11}+2*ds_{21}) \\
& * s_{21}+s_{20} * (ds_{12}-ds_{22})) * s_{11}+s_{21}*s_{10} * (ds_{12}-ds_{22})) * s_{22}-(-s_{21}+s_{11}) * \\
& (s_{21}+P) * (P+s_{11}) * (ds_{12}-ds_{22})) * X_1^2+(-2*dX_1 * (s_{10}+s_{20}) * (P+s_{11}+s_{21})
\end{aligned}$$

```

*s12^2+(4*dX1*(s10+s20)*(P+s11+s21)*s22-(2*(s10+s20))*(ds11-
ds21)*P-2*s20*(ds11-ds21)*s11-2*s10*(ds11-ds21)*s21-(2*((sX10+
(1/2)*s20)*s10+sX10*(sX10+s20)))*(ds12-ds22))*s12-2*dX1*(s10+
s20)*(P+s11+s21)*s22^2+((2*(s10+s20))*(ds11-ds21)*P+2*s20*(ds11
-ds21)*s11+2*s10*(ds11-ds21)*s21+(2*((sX10+(1/2)*s20)*s10+sX10*
(sX10+s20)))*(ds12-ds22))*s22+(ds12-ds22)*((s10+s20)*P+s21*s10+
s11*s20)*(-s21+s11))*X1-2*sX10*(sX10+s10+s20)*(dX1*s12^2+(-2*
dX1*s22+ds11-ds21)*s12+dX1*s22^2+(-ds11+ds21)*s22-(1/2)*(-s21+
s11)*(ds12-ds22)))/((2*(Q-X1))*(-s12+s22)^2):
simplify(omegaJMUP4-omegaJMUP4formula);
K0:=unapply(KOldCoordinates(s11,s21,s12,s22,X1),s11,s21,s12,
s22,X1);
dK0:=unapply(diff(K0(s11,s21,s12,s22,X1),s11)*ds11+diff(K0
(s11,s21,s12,s22,X1),s21)*ds21+diff(K0(s11,s21,s12,s22,X1),s12)
*ds12+diff(K0(s11,s21,s12,s22,X1),s22)*ds22+diff(K0(s11,s21,
s12,s22,X1),X1)*dX1,s11,s21,s12,s22,X1);
simplify(omegaJMUP4-(residue(Hams11/h,h=0)*ds11+residue
(Hams21/h,h=0)*ds21+residue(Hams12/h,h=0)*ds12+residue
(Hams22/h,h=0)*ds22+residue(HamX1/h,h=0)*dX1));

```

$$\begin{aligned}
& K0 := (s11, s21, s12, s22, X1) \rightarrow \frac{1}{2} (sX10 + s20) (sX10 + s10) \ln\left(\frac{1}{2} s12 - \frac{1}{2} s22\right) \\
& \quad + \frac{1}{2} X1 ((s12 X1 + 2 s11) s10 + s20 (s22 X1 + 2 s21)) \\
& dK0 := (s11, s21, s12, s22, X1) \rightarrow X1 s10 ds11 + X1 s20 ds21 \\
& \quad + \left(\frac{1}{4} \frac{(sX10 + s20) (sX10 + s10)}{\frac{1}{2} s12 - \frac{1}{2} s22} + \frac{1}{2} X1^2 s10 \right) ds12 + \left(\right. \\
& \quad - \frac{1}{4} \frac{(sX10 + s20) (sX10 + s10)}{\frac{1}{2} s12 - \frac{1}{2} s22} + \frac{1}{2} X1^2 s20 \left. \right) ds22 + \left(\frac{1}{2} (s12 X1 + 2 s11) s10 \right. \\
& \quad \left. + \frac{1}{2} s20 (s22 X1 + 2 s21) + \frac{1}{2} X1 (s10 s12 + s20 s22) \right) dX1
\end{aligned} \tag{2.26}$$

Definition of the shifted Darboux coordinates

```

> checkQfunction:=S2*Q+S1;
checkPfunction=1/S2*(P-1/2*R1(Q));
SolQ:=- (S1-checkQ)/S2;
SolP:=checkP*S2+(1/2)*R1(- (S1-checkQ)/S2);
simplify(checkQ-(S2*SolQ+S1));
simplify(checkP-(1/S2*(SolP-1/2*R1(SolQ))));
checkQfunction := Q S2 + S1

```

(2.27)

$$checkPfunction = \frac{P - \frac{1}{2} \frac{-s10 - s20}{Q - X1} + \frac{1}{2} s11 + \frac{1}{2} s21 - \frac{1}{2} (-s12 - s22) Q}{S2}$$

$$SolQ := -\frac{S1 - checkQ}{S2}$$

$$SolP := checkP S2 + \frac{1}{2} \frac{-s10 - s20}{-\frac{S1 - checkQ}{S2} - X1} - \frac{1}{2} s11 - \frac{1}{2} s21 - \frac{1}{2} \frac{(-s12 - s22) (S1 - checkQ)}{S2}$$

0
0

```

> Sinfty2function:=s12+s22;
Sinfty1function:=s11+s21;
S2function:=sqrt(s12-s22)/sqrt(2);
S1function:=(s11-s21)/sqrt(2)/sqrt(s12-s22);
tdX1function:=X1*S2function+S1function;
solve( {s12+s22=Sinfty2,s11+s21=Sinfty1, S2=sqrt(s12-s22)/sqrt
(2),
S1=(s11-s21)/sqrt(2)/sqrt(s12-s22),
tdX1=X1*S2function+S1function}, {s12,s22,s11,s21,X1});
X1function := unapply( -(S1-tdX1)/S2 ,Sinfty1,Sinfty2,S1,S2,
tdX1);
s11function:= unapply( S2*S1+(1/2)*Sinfty1, Sinfty1,Sinfty2,S1,
S2,tdX1);
s12function:= unapply( S2^2+(1/2)*Sinfty2, Sinfty1,Sinfty2,S1,
S2,tdX1);
s21function:= unapply( -S2*S1+(1/2)*Sinfty1, Sinfty1,Sinfty2,
S1,S2,tdX1);
s22function:= unapply( -S2^2+(1/2)*Sinfty2, Sinfty1,Sinfty2,S1,
S2,tdX1 );
simplify(X1function(Sinfty1function, Sinfty2function, S1function,
S2function,tdX1function));
simplify(s11function(Sinfty1function, Sinfty2function,
S1function, S2function, tdX1function));
simplify(s12function(Sinfty1function, Sinfty2function,
S1function, S2function, tdX1function));
simplify(s21function(Sinfty1function, Sinfty2function,
S1function, S2function, tdX1function));
simplify(s22function(Sinfty1function, Sinfty2function,
S1function, S2function, tdX1function));

partialtdX1function:=simplify(diff(s11function(Sinfty1, Sinfty2,
S1, S2, tdX1), tdX1))*partials11+

```

```

simplify(diff(s21function(Sinfy1,Sinfy2,S1,S2,tdX1),tdX1))
*partials21
+simplify(diff(s12function(Sinfy1,Sinfy2,S1,S2,tdX1),tdX1))
*partials12
+simplify(diff(s22function(Sinfy1,Sinfy2,S1,S2,tdX1),tdX1))
*partials22
+simplify(diff(X1function(Sinfy1,Sinfy2,S1,S2,tdX1),tdX1))*
partialX1;

```

$$\text{Sinfy2function} := s12 + s22 \quad (2.28)$$

$$\text{Sinfy1function} := s21 + s11$$

$$\text{S2function} := \frac{1}{2} \sqrt{s12 - s22} \sqrt{2}$$

$$\text{S1function} := \frac{1}{2} \frac{(-s21 + s11) \sqrt{2}}{\sqrt{s12 - s22}}$$

$$\text{tdX1function} := \frac{1}{2} X1 \sqrt{s12 - s22} \sqrt{2} + \frac{1}{2} \frac{(-s21 + s11) \sqrt{2}}{\sqrt{s12 - s22}}$$

$$\left\{ X1 = -\frac{S1 - tdX1}{S2}, s11 = \frac{1}{2} \text{Sinfy1} + S1 S2, s12 = \frac{1}{2} \text{Sinfy2} + S2^2, s21 = -S1 S2 + \frac{1}{2} \text{Sinfy1}, s22 = -S2^2 + \frac{1}{2} \text{Sinfy2} \right\}$$

$$\text{X1function} := (\text{Sinfy1}, \text{Sinfy2}, S1, S2, \text{tdX1}) \rightarrow -\frac{S1 - tdX1}{S2}$$

$$\text{s11function} := (\text{Sinfy1}, \text{Sinfy2}, S1, S2, \text{tdX1}) \rightarrow \frac{1}{2} \text{Sinfy1} + S1 S2$$

$$\text{s12function} := (\text{Sinfy1}, \text{Sinfy2}, S1, S2, \text{tdX1}) \rightarrow \frac{1}{2} \text{Sinfy2} + S2^2$$

$$\text{s21function} := (\text{Sinfy1}, \text{Sinfy2}, S1, S2, \text{tdX1}) \rightarrow -S1 S2 + \frac{1}{2} \text{Sinfy1}$$

$$\text{s22function} := (\text{Sinfy1}, \text{Sinfy2}, S1, S2, \text{tdX1}) \rightarrow -S2^2 + \frac{1}{2} \text{Sinfy2}$$

X1

s11

s12

s21

s22

$$\text{partialtdX1function} := \frac{\text{partialX1}}{S2}$$

```

> ds11function:=diff(s11function(Sinfy1,Sinfy2,S1,S2,tdX1),
Sinfy1)*dSinfy1+ diff(s11function(Sinfy1,Sinfy2,S1,S2,
tdX1),Sinfy2)*dSinfy2+diff(s11function(Sinfy1,Sinfy2,S1,S2,
tdX1),S1)*dS1+ diff(s11function(Sinfy1,Sinfy2,S1,S2,tdX1),S2)
*dS2 +diff(s11function(Sinfy1,Sinfy2,S1,S2,tdX1),tdX1)*dtdX1;
ds21function:=diff(s21function(Sinfy1,Sinfy2,S1,S2,tdX1),
Sinfy1)*dSinfy1+ diff(s21function(Sinfy1,Sinfy2,S1,S2,
tdX1),Sinfy2)*dSinfy2+diff(s21function(Sinfy1,Sinfy2,S1,

```

```

S2,tdX1),S1)*dS1+ diff(s21function( Sinfty1,Sinfty2,S1,S2,
tdX1),S2)*dS2 +diff(s21function( Sinfty1,Sinfty2,S1,S2,tdX1),
tdX1)*dtdX1;
ds12function:=diff(s12function( Sinfty1,Sinfty2,S1,S2,tdX1),
Sinfty1)*dSinfty1+ diff(s12function( Sinfty1,Sinfty2,S1,S2,
tdX1),Sinfty2)*dSinfty2+diff(s12function( Sinfty1,Sinfty2,S1,
S2,tdX1),S1)*dS1+ diff(s12function( Sinfty1,Sinfty2,S1,S2,
tdX1),S2)*dS2 +diff(s12function( Sinfty1,Sinfty2,S1,S2,tdX1),
tdX1)*dtdX1;
ds22function:=diff(s22function( Sinfty1,Sinfty2,S1,S2,tdX1),
Sinfty1)*dSinfty1+ diff(s22function( Sinfty1,Sinfty2,S1,S2,
tdX1),Sinfty2)*dSinfty2+diff(s22function( Sinfty1,Sinfty2,S1,
S2,tdX1),S1)*dS1+ diff(s22function( Sinfty1,Sinfty2,S1,S2,
tdX1),S2)*dS2 +diff(s22function( Sinfty1,Sinfty2,S1,S2,tdX1),
tdX1)*dtdX1;
dX1function:=diff(X1function( Sinfty1,Sinfty2,S1,S2,tdX1),
Sinfty1)*dSinfty1+ diff(X1function( Sinfty1,Sinfty2,S1,S2,
tdX1),Sinfty2)*dSinfty2+diff(X1function( Sinfty1,Sinfty2,S1,S2,
tdX1),S1)*dS1+ diff(X1function( Sinfty1,Sinfty2,S1,S2,tdX1),S2)
*dS2 +diff(X1function( Sinfty1,Sinfty2,S1,S2,tdX1),tdX1)*dtdX1;

solve({ds11function=ds11,ds21function=ds21,ds12function=
ds12,ds22function=ds22,dX1function=dX1,ds11function=ds11},{dS1,
dS2,dSinfty1,dSinfty2,dtdX1});

```

```

dS1function := ((2*ds11-2*ds21)*S2-S1*(ds12-ds22))/(4*S2^2);
dS2function := (ds12-ds22)/(4*S2);
dtdX1function :=(4*S2^3*dX1+(2*ds11-2*ds21)*S2-(2*(S1-(1/2)*
tdX1))*(ds12-ds22))/(4*S2^2);
dSinfty1function := ds11+ds21;
dSinfty2function := ds12+ds22;

```

$$ds11function := \frac{1}{2} dSinfty1 + S2 dS1 + S1 dS2 \quad (2.29)$$

$$ds21function := \frac{1}{2} dSinfty1 - S2 dS1 - S1 dS2$$

$$ds12function := \frac{1}{2} dSinfty2 + 2 S2 dS2$$

$$ds22function := \frac{1}{2} dSinfty2 - 2 S2 dS2$$

$$dX1function := -\frac{dS1}{S2} + \frac{(S1 - tdX1) dS2}{S2^2} + \frac{dtdX1}{S2}$$

$$\left\{ dS1 = -\frac{1}{4} \frac{S1 ds12 - S1 ds22 - 2 S2 ds11 + 2 S2 ds21}{S2^2}, dS2 = \frac{1}{4} \frac{ds12 - ds22}{S2}, dtdX1 = \right.$$

$$-\frac{1}{4} \frac{1}{S_2^2} \left(-4 S_2^3 dX_1 + 2 S_1 ds_{12} - 2 S_1 ds_{22} - 2 S_2 ds_{11} + 2 S_2 ds_{21} - ds_{12} tdX_1 + ds_{22} tdX_1 \right), d\text{Sinfty}1 = ds_{11} + ds_{21}, d\text{Sinfty}2 = ds_{12} + ds_{22} \}$$

$$dS_1\text{function} := \frac{1}{4} \frac{(2 ds_{11} - 2 ds_{21}) S_2 - S_1 (ds_{12} - ds_{22})}{S_2^2}$$

$$dS_2\text{function} := \frac{1}{4} \frac{ds_{12} - ds_{22}}{S_2}$$

$$dtdX_1\text{function} := \frac{1}{4} \frac{1}{S_2^2} \left(4 S_2^3 dX_1 + (2 ds_{11} - 2 ds_{21}) S_2 - 2 \left(S_1 - \frac{1}{2} tdX_1 \right) (ds_{12} - ds_{22}) \right)$$

$$d\text{Sinfty}1\text{function} := ds_{11} + ds_{21}$$

$$d\text{Sinfty}2\text{function} := ds_{12} + ds_{22}$$

Rewriting the JMU differential in terms of $(\check{Q}, \check{P}, S_1, S_2, S_{\infty 1}, S_{\infty 2}, tdX_1)$

```
> omegaJMUP4function1:=unapply(omegaJMUP4,Q,P):
omegaJMUP4function2:=unapply(simplify
(omegaJMUP4function1(SolQ,SolP)),s11,s21,s12,s22,X1,ds11,ds21,
ds12,ds22,dX1):
omegaJMUP4function3:=simplify(omegaJMUP4function2(s11function
(Sinfty1,Sinfty2,S1,S2,tdX1),s21function(Sinfty1,Sinfty2,S1,S2,
tdX1),s12function(Sinfty1,Sinfty2,S1,S2,tdX1),s22function
(Sinfty1,Sinfty2,S1,S2,tdX1),X1function(Sinfty1,Sinfty2,S1,S2,
tdX1),
ds11function,ds21function,ds12function,ds22function,dX1function)
):
```

```
> omegaJMUP4NewCoordinates:=simplify(omegaJMUP4function3):
CoeffdS1:=simplify(residue(omegaJMUP4NewCoordinates/dS1^2,dS1=
0));
CoeffdS2:=simplify(residue(omegaJMUP4NewCoordinates/dS2^2,dS2=
0));
CoeffdSinfty1:=simplify(residue
(omegaJMUP4NewCoordinates/dSinfty1^2,dSinfty1=0));
CoeffdSinfty2:=simplify(residue
(omegaJMUP4NewCoordinates/dSinfty2^2,dSinfty2=0));
CoeffdtdX1:=simplify(residue(omegaJMUP4NewCoordinates/dtdX1^2,
dtdX1=0));
```

$$\text{CoeffdS1} := \frac{1}{2} \frac{1}{S_2^2} \left(-2 S_1 (s_{10} - s_{20}) S_2^2 - \text{Sinfty}1 (s_{10} + s_{20}) S_2 + \text{Sinfty}2 (s_{10} + s_{20}) (S_1 - tdX_1) \right) \quad (2.30)$$

$$\text{CoeffdS2} := \frac{1}{2} \frac{1}{S_2^3} \left(2 (s_{X10} + s_{20}) (s_{X10} + s_{10}) S_2^2 + \text{Sinfty}1 (s_{10} + s_{20}) (S_1 - tdX_1) S_2 - \text{Sinfty}2 (S_1 - tdX_1)^2 (s_{10} + s_{20}) \right)$$

$$\text{CoeffdSinfty1} := -\frac{1}{2} \frac{(s10 + s20) (S1 - tdX1)}{S2}$$

$$\text{CoeffdSinfty2} := \frac{1}{4} \frac{(S1 - tdX1)^2 (s10 + s20)}{S2^2}$$

$$\text{CoeffdtdX1} := \frac{1}{4} \frac{1}{S2^2 (tdX1 - \text{checkQ})} \left((-4 \text{checkP}^2 + 4 \text{checkQ}^2 + 4 s10 - 4 s20) tdX1^2 - 8 \text{checkQ} (-\text{checkP}^2 + \text{checkQ}^2 + s10 - s20) tdX1 + 4 \text{checkQ}^4 + (-4 \text{checkP}^2 + 4 s10 - 4 s20) \text{checkQ}^2 + (s10 + s20 + 2 sX10)^2 S2^2 + 2 \text{Sinfty1} (tdX1 - \text{checkQ}) (s10 + s20) S2 - 2 \text{Sinfty2} (tdX1 - \text{checkQ}) (s10 + s20) (S1 - tdX1) \right)$$

$$\text{> CoeffdtdX1bis} := (\text{checkQ} - tdX1) * \text{checkP}^2 - \text{checkQ}^3 + tdX1 * \text{checkQ}^2 - (s10 - s20) * \text{checkQ}$$

$$+ (- (sX10 - sX20)^2) / 4 / (\text{checkQ} - tdX1) :$$

$$\text{PartConstantCoefftdX1bis} := \text{simplify}(\text{CoeffdtdX1} - \text{CoeffdtdX1bis}) ;$$

$$\text{PartConstantCoefftdX1bis} := \frac{1}{2} \frac{1}{S2^2} (2 tdX1 (s10 - s20) S2^2 + \text{Sinfty1} (s10 + s20) S2 - \text{Sinfty2} (s10 + s20) (S1 - tdX1)) \quad (2.31)$$

$$\text{> pdsolve}(\{\text{CoeffdS1} = \text{diff}(\text{MM}(\text{Sinfty1}, \text{Sinfty2}, S1, S2, tdX1), S1), \text{CoeffdS2} = \text{diff}(\text{MM}(\text{Sinfty1}, \text{Sinfty2}, S1, S2, tdX1), S2), \text{CoeffdSinfty1} = \text{diff}(\text{MM}(\text{Sinfty1}, \text{Sinfty2}, S1, S2, tdX1), \text{Sinfty1}), \text{CoeffdSinfty2} = \text{diff}(\text{MM}(\text{Sinfty1}, \text{Sinfty2}, S1, S2, tdX1), \text{Sinfty2}), \text{PartConstantCoefftdX1bis} = \text{diff}(\text{MM}(\text{Sinfty1}, \text{Sinfty2}, S1, S2, tdX1), tdX1)\}, \{\text{MM}(\text{Sinfty1}, \text{Sinfty2}, S1, S2, tdX1)\}) ;$$

$$\text{M} := \text{unapply}((4 * S2^2 * (sX10 + s20) * (sX10 + s10) * \ln(S2) + ((-2 * S1^2 + 2 * tdX1^2) * s10 + (2 * S1^2 - 2 * tdX1^2) * s20) * S2^2 - 2 * \text{Sinfty1} * (s10 + s20) * (S1 - tdX1) * S2 + \text{Sinfty2} * (S1 - tdX1)^2 * (s10 + s20)) / 4 / S2^2, \text{Sinfty1}, \text{Sinfty2}, S1, S2, tdX1) ;$$

$$\text{simplify}(\text{CoeffdS1} - \text{diff}(\text{M}(\text{Sinfty1}, \text{Sinfty2}, S1, S2, tdX1), S1)) ;$$

$$\text{simplify}(\text{CoeffdS2} - \text{diff}(\text{M}(\text{Sinfty1}, \text{Sinfty2}, S1, S2, tdX1), S2)) ;$$

$$\text{simplify}(\text{CoeffdSinfty1} - \text{diff}(\text{M}(\text{Sinfty1}, \text{Sinfty2}, S1, S2, tdX1), \text{Sinfty1})) ;$$

$$\text{simplify}(\text{CoeffdSinfty2} - \text{diff}(\text{M}(\text{Sinfty1}, \text{Sinfty2}, S1, S2, tdX1), \text{Sinfty2})) ;$$

$$\text{simplify}(\text{PartConstantCoefftdX1bis} - \text{diff}(\text{M}(\text{Sinfty1}, \text{Sinfty2}, S1, S2, tdX1), tdX1)) ;$$

$$\left\{ \text{MM}(\text{Sinfty1}, \text{Sinfty2}, S1, S2, tdX1) = \frac{1}{4} \frac{1}{S2^2} (4 S2^2 (sX10 + s20) (sX10 + s10) \ln(S2) + ((-2 S1^2 + 2 tdX1^2) s10 + (2 S1^2 - 2 tdX1^2) s20 + 4 _C1) S2^2 - 2 \text{Sinfty1} (s10 + s20) (S1 - tdX1) S2 + \text{Sinfty2} (S1 - tdX1)^2 (s10 + s20)) \right\} \quad (2.32)$$

$$\text{M} := (\text{Sinfty1}, \text{Sinfty2}, S1, S2, tdX1) \rightarrow \frac{1}{4} \frac{1}{S2^2} (4 S2^2 (sX10 + s20) (sX10 + s10) \ln(S2)$$

$$+ ((-2 S1^2 + 2 tdX1^2) s10 + (2 S1^2 - 2 tdX1^2) s20) S2^2 - 2 Sinfty1 (s10 + s20) (S1 - tdX1) S2 + Sinfty2 (S1 - tdX1)^2 (s10 + s20)$$

0
0
0
0
0

```
> KNewCoordinates:=unapply( simplify(KOldCoordinates(s11function
(Sinfty1,Sinfty2,S1,S2,tdX1),s21function(Sinfty1,Sinfty2,S1,S2,
tdX1),s12function(Sinfty1,Sinfty2,S1,S2,tdX1),s22function
(Sinfty1,Sinfty2,S1,S2,tdX1),X1function(Sinfty1,Sinfty2,S1,S2,
tdX1)),symbolic),Sinfty1,Sinfty2,S1,S2,tdX1);
simplify(KNewCoordinates(Sinfty1,Sinfty2,S1,S2,tdX1)-M(Sinfty1,
Sinfty2,S1,S2,tdX1));
KNewCoordinates2:=unapply((sX10+s20)*(sX10+s10)*ln(S2)-(1/2)*
(S1-tdX1)*(s10+s20)*Sinfty1/S2
+(1/4)*(S1-tdX1)^2*(s10+s20)*Sinfty2/S2^2-(1/2)*(S1-tdX1)*(s10-
s20)*(S1+tdX1)
,Sinfty1,Sinfty2,S1,S2,tdX1);
simplify(KNewCoordinates(Sinfty1,Sinfty2,S1,S2,tdX1)
-KNewCoordinates2(Sinfty1,Sinfty2,S1,S2,tdX1),symbolic);
```

$$KNewCoordinates := (Sinfty1, Sinfty2, S1, S2, tdX1) \rightarrow \frac{1}{4} \frac{1}{S2^2} \left(4 S2^2 (sX10 + s20) (sX10 \right. \quad (2.33)$$

$$+ s10) \ln(S2) - 2 (S1 - tdX1) \left((s10 - s20) (S1 + tdX1) S2^2 + Sinfty1 (s10 + s20) S2 - \frac{1}{2} Sinfty2 (s10 + s20) (S1 - tdX1) \right) \Big)$$

$$KNewCoordinates2 := (Sinfty1, Sinfty2, S1, S2, tdX1) \rightarrow (sX10 + s20) (sX10 + s10) \ln(S2) - \frac{1}{2} \frac{(s10 + s20) (S1 - tdX1) Sinfty1}{S2} + \frac{1}{4} \frac{(S1 - tdX1)^2 (s10 + s20) Sinfty2}{S2^2} - \frac{1}{2} (S1 - tdX1) (s10 - s20) (S1 + tdX1)$$

0

Obtaining the only non-trivial Hamiltonians for (checkQ,checkP)

```
> assume (S2>0) :
hpartialtdX1functioncheckQfunction:= unapply(diff(S2*Q+S1,Q)*
hpartialtdX1functionQ+diff(S2*Q+S1,P)*hpartialtdX1functionP
+h/S2*(diff(S2function*Q+S1function,X1)),Q,P):
hpartialtdX1functioncheckQfunction2:=unapply( simplify
(hpartialtdX1functioncheckQfunction(SolQ,SolP)),s12,s22,s11,
s21,X1):
hpartialtdX1functioncheckQ:=simplify
(hpartialtdX1functioncheckQfunction2(s12function(Sinfty1,
```

```
Sinfy2 , S1 , S2 , tdX1) , s22function (Sinfy1 , Sinfy2 , S1 , S2 ,
tdX1) , s11function (Sinfy1 , Sinfy2 , S1 , S2 , tdX1) , s21function
(Sinfy1 , Sinfy2 , S1 , S2 , tdX1) , X1function (Sinfy1 , Sinfy2 , S1 , S2 ,
tdX1)) :
```

```
hpartialtdX1functioncheckPfunction:= unapply (diff (1/S2* (P-1/2*
R1 (Q) ) , Q) *hpartialtdX1functionQ+diff (1/S2* (P-1/2*R1 (Q) ) , P) *
hpartialtdX1functionP
+h/S2* (diff (1/S2function* (P-1/2*R1 (Q) ) , X1) ) , Q , P) :
```

```
hpartialtdX1functioncheckPfunction2:=unapply ( simplify
(hpartialtdX1functioncheckPfunction (SolQ , SolP) ) , s12 , s22 , s11 ,
s21 , X1) :
```

```
hpartialtdX1functioncheckP:=simplify
(hpartialtdX1functioncheckPfunction2 (s12function (Sinfy1 ,
Sinfy2 , S1 , S2 , tdX1) , s22function (Sinfy1 , Sinfy2 , S1 , S2 , tdX1) ,
s11function (Sinfy1 , Sinfy2 , S1 , S2 , tdX1) , s21function (Sinfy1 ,
Sinfy2 , S1 , S2 , tdX1) , X1function (Sinfy1 , Sinfy2 , S1 , S2 , tdX1) )
+1/ (4*S2^2* (tdX1-checkQ) ^2) *2*Sinfy2* (tdX1-checkQ) ^2* (s10+s20+
sX10+sX20)
):
```

```
HamtdX1checkQcheckP:=unapply ( ( (checkQ-tdX1) *checkP+h) *checkP
+ (4*checkQ^4-8*tdX1*checkQ^3+ (4*tdX1^2-4*h+4*s10-4*s20) *
checkQ^2+4*tdX1* (h+s20-s10) *checkQ+sX10^2+ (-2*sX20) *sX10-2*
sX20* (- (1/2) *sX20) ) /4/ (tdX1-checkQ)
, checkQ , checkP) :
```

```
simplify (hpartialtdX1functioncheckQ-diff (HamtdX1checkQcheckP
(checkQ , checkP) , checkP) ) ;
```

```
simplify (series (simplify (hpartialtdX1functioncheckP+diff
(HamtdX1checkQcheckP (checkQ , checkP) , checkQ) ) , h=0) ) ;
```

```
HamtdX1checkQcheckPbis:=unapply ( (checkQ-tdX1) *checkP^2+h*
checkP-checkQ^3+tdX1*checkQ^2- (s10-s20-h) *checkQ
+ (- (sX10-sX20) ^2) /4/ (checkQ-tdX1) , checkQ , checkP) ;
simplify (HamtdX1checkQcheckP (checkQ , checkP)
-HamtdX1checkQcheckPbis (checkQ , checkP) ) ;
```

(2.34)

$$HamtdX1checkQcheckPbis := (checkQ, checkP) \rightarrow \frac{(-tdX1 + checkQ) checkP^2 + h checkP - checkQ^3 + tdX1 checkQ^2 - (-h + s10 - s20) checkQ - \frac{1}{4} \frac{(s10 + s20 + 2 sX10)^2}{-tdX1 + checkQ}}{0}$$

```
> K0NewCoordinates:=unapply (KNewCoordinates (Sinfy1 , Sinfy2 , S1 ,
S2 , tdX1) , Sinfy1 , Sinfy2 , S1 , S2 , tdX1) : dK0NewCoordinates:=
```

```

unapply( diff(K0NewCoordinates(Sinfty1, Sinfty2, S1, S2, tdX1),
Sinfty1)*dSinfty1+ diff(K0NewCoordinates(Sinfty1, Sinfty2, S1,
S2, tdX1),Sinfty2)*dSinfty2+diff(K0NewCoordinates(Sinfty1,
Sinfty2, S1, S2, tdX1),S1)*dS1
+diff(K0NewCoordinates(Sinfty1, Sinfty2, S1, S2, tdX1),S2)*
dS2+diff(K0NewCoordinates(Sinfty1, Sinfty2, S1, S2, tdX1),tdX1)
*dtdX1
,Sinfty1, Sinfty2, S1, S2, tdX1):
simplify(omegaJMUP4NewCoordinates-(residue
(HamtdX1checkQcheckPbis(checkQ,checkP)/h,h=0)*dtdX1
+dK0NewCoordinates(Sinfty1, Sinfty2, S1, S2, tdX1)));

```

0

(2.35)

```

> tdL:=tdL:
tdA:=simplify(tdA):

```

General expressions for reduction

```

> c0:=0:
tdL11function:=unapply(tdL[1,1],s12,s22,s11,s21,X1):
tdL12function:=unapply(tdL[1,2],s12,s22,s11,s21,X1):
tdL21function:=unapply(tdL[2,1],s12,s22,s11,s21,X1):
tdL22function:=unapply(tdL[2,2],s12,s22,s11,s21,X1):

tdA11function:=unapply(tdA[1,1],s12,s22,s11,s21,X1,beta12,
beta22,beta11,beta21,betaX1):
tdA12function:=unapply(tdA[1,2],s12,s22,s11,s21,X1,beta12,
beta22,beta11,beta21,betaX1):
tdA21function:=unapply(tdA[2,1],s12,s22,s11,s21,X1,beta12,
beta22,beta11,beta21,betaX1):
tdA22function:=unapply(tdA[2,2],s12,s22,s11,s21,X1,beta12,
beta22,beta11,beta21,betaX1):
SolQfunction:=unapply(simplify(SolQ),s12,s22,s11,s21,X1):
SolPfunction:=unapply(simplify(SolP),s12,s22,s11,s21,X1):
tdX1functionfunction:=unapply(tdX1function,s12,s22,s11,s21,X1):

S1function:=unapply(S1,s12,s22,s11,s21,X1):
S2function:=unapply(S2,s12,s22,s11,s21,X1):
R1function:=unapply(R1(xi),xi,s12,s22,s11,s21,X1):

LQfunction:=unapply(LQ,s12,s22,s11,s21,X1,beta12,beta22,beta11,
beta21,betaX1):
LPfunction:=unapply(LP,s12,s22,s11,s21,X1,beta12,beta22,beta11,

```

beta21,betaX1) :

**Hamiltonianfunction:=unapply(Hamiltonianbis,s12,s22,s11,s21,X1,
beta12,beta22,beta11,beta21,betaX1) :**

$$\text{SolQfunction} := (s12, s22, s11, s21, X1) \rightarrow \frac{-S1 + \text{checkQ}}{S2\sim} \quad (3.1)$$

SolPfunction := (s12, s22, s11, s21, X1)

$$\rightarrow \frac{1}{2} \frac{1}{(S2\sim X1 + S1 - \text{checkQ}) S2\sim} (2 S2\sim^3 X1 \text{checkP} + (-2 \text{checkP} \text{checkQ} \\ + 2 S1 \text{checkP} + (-s11 - s21) X1 + s10 + s20) S2\sim^2 + ((s22 + s12) X1 - s11 \\ - s21) (S1 - \text{checkQ}) S2\sim + (S1 - \text{checkQ})^2 (s22 + s12))$$

tdX1functionfunction := (s12, s22, s11, s21, X1) $\rightarrow \frac{1}{2} X1 \sqrt{s12 - s22} \sqrt{2}$

$$+ \frac{1}{2} \frac{(s11 - s21) \sqrt{2}}{\sqrt{s12 - s22}}$$

S1function := (s12, s22, s11, s21, X1) $\rightarrow S1$

S2function := (s12, s22, s11, s21, X1) $\rightarrow S2\sim$

R1function := (ξ , s12, s22, s11, s21, X1) $\rightarrow \frac{-s10 - s20}{\xi - X1} - s11 - s21 + (-s12 - s22) \xi$

Jimbo-Miwa case: We take s12=1 and s22=-1 and X_1=0 and s21=-s11. The time is sigma=s11. The direction is beta21=-1 and beta11=1.

```
> simplify(SolQfunction(1,-1,sigma,-sigma,0));  
simplify(series(SolPfunction(1,-1,sigma,-sigma,0),checkP));  
tdX1functionfunction(1,-1,sigma,-sigma,0);  
S1function(1,-1,sigma,-sigma,0);  
S2function(1,-1,sigma,-sigma,0);  
R1function(xi,1,-1,sigma,-sigma,0);  
solve({SolQfunction(1,-1,sigma,-sigma,0)=QQ,SolPfunction(1,  
-1,sigma,-sigma,0)=PP},{checkQ,checkP});  
tdLReduced:=Matrix(2,2,0):  
tdL11function0:=unapply(tdL11function(1,-1,sigma,-sigma,0),Q,  
P):  
tdL12function0:=unapply(tdL12function(1,-1,sigma,-sigma,0),Q,  
P):  
tdL21function0:=unapply(tdL21function(1,-1,sigma,-sigma,0),Q,  
P):  
tdL22function0:=unapply(tdL22function(1,-1,sigma,-sigma,0),Q,  
P):  
tdLReduced[1,1]:=simplify(tdL11function(1,-1,sigma,-sigma,0)):  
tdLReduced[1,2]:=simplify(tdL12function(1,-1,sigma,-sigma,0)):  
tdLReduced[2,1]:=simplify(tdL21function(1,-1,sigma,-sigma,0)):
```

```

tdLReduced[2,2]:=simplify(tdL22function(1,-1,sigma,-sigma,0)):
tdLReduced:
tdLReduced2:=Matrix(2,2,0):
tdLReduced2[1,1]:=simplify(tdL11function0(SolQfunction(1,
-1,sigma,-sigma,0),SolPfunction(1,-1,sigma,-sigma,0))):
tdLReduced2[1,2]:=simplify(tdL12function0(SolQfunction(1,
-1,sigma,-sigma,0),SolPfunction(1,-1,sigma,-sigma,0))):
tdLReduced2[2,1]:=simplify(tdL21function0(SolQfunction(1,
-1,sigma,-sigma,0),SolPfunction(1,-1,sigma,-sigma,0))):
tdLReduced2[2,2]:=simplify(tdL22function0(SolQfunction(1,
-1,sigma,-sigma,0),SolPfunction(1,-1,sigma,-sigma,0))):
tdLReduced2;

```

$$\begin{aligned}
& \frac{-SI + checkQ}{S2\sim} \\
& \frac{(s10 + s20) S2\sim}{2 SI - 2 checkQ} + S2\sim checkP \\
& \begin{matrix} \sigma \\ SI \\ S2\sim \\ -s10 - s20 \\ \xi \end{matrix} \\
& \left\{ checkP = \frac{1}{2} \frac{2 PP QQ + s10 + s20}{QQ S2\sim}, checkQ = QQ S2\sim + SI \right\} \\
& \left[\left[\frac{1}{2} \frac{1}{\xi S2\sim^2} \left((-2 SI checkP + 2 checkP checkQ - 2 \sigma \xi - 2 \xi^2 - s10 - s20) S2\sim^2 \right. \right. \right. \\
& \left. \left. - 2 \sigma (SI - checkQ) S2\sim + 2 (SI - checkQ)^2 \right), \frac{S2\sim \xi + SI - checkQ}{\xi S2\sim} \right], \\
& \left[\frac{1}{4} \frac{1}{S2\sim^3 \xi (SI - checkQ)} \left(-4 \left(SI checkP - checkP checkQ + sX10 + \frac{1}{2} s10 \right. \right. \right. \\
& \left. \left. + \frac{1}{2} s20 \right) \left(SI checkP - checkP checkQ - sX10 - \frac{1}{2} s10 - \frac{1}{2} s20 \right) S2\sim^4 - 8 (SI \right. \\
& \left. - checkQ) \left(-checkP (\xi + \sigma) checkQ + checkP (\xi + \sigma) SI - \frac{1}{2} \xi (s10 \right. \right. \\
& \left. \left. - s20) \right) S2\sim^3 + 8 (SI - checkQ)^2 \left(-checkP checkQ + SI checkP - \left(\xi \right. \right. \right. \\
& \left. \left. + \frac{1}{2} \sigma \right) \sigma \right) S2\sim^2 + 8 (SI - checkQ)^3 (\xi + \sigma) S2\sim - 4 (SI - checkQ)^4 \right), \\
& \left. \frac{1}{2} \frac{1}{\xi S2\sim^2} \left((2 SI checkP - 2 checkP checkQ + 2 \sigma \xi + 2 \xi^2 - s10 - s20) S2\sim^2 \right. \right. \\
& \left. \left. + 2 \sigma (SI - checkQ) S2\sim - 2 (SI - checkQ)^2 \right) \right] \right]
\end{aligned} \tag{4.1}$$

```

> series(tdLReduced2[1,1],xi=infinity);
series(tdLReduced2[1,2],xi=infinity);
series(tdLReduced2[2,2],xi=infinity);
series(tdLReduced2[2,1],xi=0):
tdLReduced221bis:=((checkP+checkQ)^2*(checkQ-sigma)-(sX10-sX20)
^2/4/(checkQ-sigma))/xi
+2*(checkQ-sigma)*(checkP+checkQ)+s10-s20;
simplify(series(tdLReduced2[2,1]-tdLReduced221bis,xi=0));

```

$$\begin{aligned}
& -\xi - \sigma + \frac{1}{2} \frac{1}{S2\sim^2 \xi} \left((-2 S1 checkP + 2 checkP checkQ - s10 - s20) S2\sim^2 - 2 \sigma (S1 \right. \\
& \quad \left. - checkQ) S2\sim + 2 (S1 - checkQ)^2 \right) \\
& \quad \quad \quad 1 + \frac{S1 - checkQ}{S2\sim \xi} \\
& \xi + \sigma + \frac{1}{2} \frac{1}{S2\sim^2 \xi} \left((2 S1 checkP - 2 checkP checkQ - s10 - s20) S2\sim^2 + 2 \sigma (S1 \right. \\
& \quad \left. - checkQ) S2\sim - 2 (S1 - checkQ)^2 \right) \\
& \quad \quad \quad \frac{(checkP + checkQ)^2 (checkQ - \sigma) - \frac{1}{4} \frac{(s10 + s20 + 2 sX10)^2}{checkQ - \sigma}}{\xi} \\
tdLReduced221bis := & \frac{\xi}{\xi} \\
& + 2 (checkQ - \sigma) (checkP + checkQ) + s10 - s20 \\
\frac{1}{\xi} \left(\frac{1}{4} \frac{1}{(S1 - checkQ) S2\sim^3 (-checkQ + \sigma)} \left(-4 (-checkQ + \sigma) \left(S1 checkP \right. \right. \right. \\
& \left. \left. - checkP checkQ - sX10 - \frac{1}{2} s10 - \frac{1}{2} s20 \right) \left(S1 checkP - checkP checkQ + sX10 \right. \right. \\
& \left. \left. + \frac{1}{2} s10 + \frac{1}{2} s20 \right) S2\sim^4 - 8 \left(-\frac{1}{2} checkQ^4 + (\sigma - checkP) checkQ^3 + \left(-\frac{1}{2} \sigma^2 \right. \right. \right. \\
& \left. \left. + 3 checkP \sigma - \frac{1}{2} checkP^2 \right) checkQ^2 - \sigma checkP (S1 + 2 \sigma - checkP) checkQ \right. \\
& \left. + checkP \left(S1 - \frac{1}{2} checkP \right) \sigma^2 + \frac{1}{8} (s10 + s20 + 2 sX10)^2 \right) (S1 - checkQ) S2\sim^3 \\
& + 8 (-checkQ + \sigma) (S1 - checkQ)^2 \left(-checkP checkQ + S1 checkP - \frac{1}{2} \sigma^2 \right) S2\sim^2 \\
& + 8 \sigma (S1 - checkQ)^3 (-checkQ + \sigma) S2\sim - 4 (S1 - checkQ)^4 (-checkQ + \sigma) \left. \right) \\
& \left. \right) + \frac{1}{S2\sim^2} \left((-2 checkQ^2 + 2 \sigma checkQ - 2 checkP (S1 - \sigma)) S2\sim^2 - 2 \sigma (S1 \right. \\
& \quad \left. - checkQ) S2\sim + 2 (S1 - checkQ)^2 \right)
\end{aligned}
\tag{4.2}$$

```

> tdAReduced:=Matrix(2,2,0):
tdA11function0:=unapply(tdA11function(1,-1,sigma,-sigma,0,0,0,
1,-1,0),Q,P):
tdA12function0:=unapply(tdA12function(1,-1,sigma,-sigma,0,0,0,
1,-1,0),Q,P):
tdA21function0:=unapply(tdA21function(1,-1,sigma,-sigma,0,0,0,

```

```

1, -1, 0), Q, P):
tdA22function0:=unapply( tdA22function(1, -1, sigma, -sigma, 0, 0, 0,
1, -1, 0), Q, P):
tdAReduced[1,1]:=simplify(tdA11function(1, -1, sigma, -sigma, 0, 0,
0, 1, -1, 0) ):
tdAReduced[1,2]:=simplify(tdA12function(1, -1, sigma, -sigma, 0, 0,
0, 1, -1, 0) ):
tdAReduced[2,1]:=simplify(tdA21function(1, -1, sigma, -sigma, 0, 0,
0, 1, -1, 0) ):
tdAReduced[2,2]:=simplify(tdA22function(1, -1, sigma, -sigma, 0, 0,
0, 1, -1, 0) ):
tdAReduced:
tdAReduced2:=Matrix(2, 2, 0):
tdAReduced2[1,1]:=factor(simplify(tdA11function0(SolQfunction
(1, -1, sigma, -sigma, 0), SolPfunction(1, -1, sigma, -sigma, 0)))):
tdAReduced2[1,2]:=factor(simplify(tdA12function0(SolQfunction
(1, -1, sigma, -sigma, 0), SolPfunction(1, -1, sigma, -sigma, 0)))):
tdAReduced2[2,1]:=factor(simplify(tdA21function0(SolQfunction
(1, -1, sigma, -sigma, 0), SolPfunction(1, -1, sigma, -sigma, 0)))):
tdAReduced2[2,2]:=factor(simplify(tdA22function0(SolQfunction
(1, -1, sigma, -sigma, 0), SolPfunction(1, -1, sigma, -sigma, 0)))):
tdAReduced2;
factor(2*checkP*checkQ-2*checkP*sigma+2*checkQ^2-2*checkQ*
sigma);

```

$$\left[\left[\frac{-S2\sim\sigma - S2\sim\xi + S1 - checkQ}{S2\sim}, 1 \right], \right. \tag{4.3}$$

$$\left[\frac{1}{S2\sim^2} \left(-2 S1 S2\sim^2 checkP + 2 S2\sim^2 checkP checkQ - 2 S1 S2\sim\sigma + S2\sim^2 s10 \right. \right.$$

$$\left. \left. - S2\sim^2 s20 + 2 S2\sim checkQ\sigma + 2 S1^2 - 4 S1 checkQ + 2 checkQ^2 \right), \right.$$

$$\left. \left. - \frac{-S2\sim\sigma - S2\sim\xi + S1 - checkQ}{S2\sim} \right] \right]$$

$$2 (checkQ - \sigma) (checkP + checkQ)$$

```

> tDR2function:=unapply(tdR2(xi), s12, s22, s11, s21, X1):
tdR2function(1, -1, sigma, -sigma, 0);
R1function:=unapply(R1(xi), s12, s22, s11, s21, X1):
R1function(1, -1, sigma, -sigma, 0);
L22function:=unapply(simplify(L[2,2]), s12, s22, s11, s21, X1):
simplify(L22function(1, -1, sigma, -sigma, 0)-h/(xi-Q));

Allfunction:=unapply(simplify(A[1,1]), s12, s22, s11, s21, X1,

```



```

beta12,beta22,beta11,beta21,betaX1):
A12function:=unapply( simplify(A[1,2]), s12,s22,s11,s21,X1,
beta12,beta22,beta11,beta21,betaX1):
A21function:=unapply( simplify(A[2,1]), s12,s22,s11,s21,X1,
beta12,beta22,beta11,beta21,betaX1):
A22function:=unapply( simplify(A[2,2]), s12,s22,s11,s21,X1,
beta12,beta22,beta11,beta21,betaX1):
A11function(1,-1,sigma,-sigma,0,0,0,1,-1,0);
A12function(1,-1,sigma,-sigma,0,0,0,1,-1,0);
simplify(A21function(1,-1,sigma,-sigma,0,0,0,1,-1,0)):
simplify(A22function(1,-1,sigma,-sigma,0,0,0,1,-1,0)):
factor(residue(simplify(A21function(1,-1,sigma,-sigma,0,0,0,1,
-1,0)),xi=0));
A21bis:=P*(P*Q-sX10-sX20)/(xi-Q)+sX10*sX20/Q/xi+xi^2+xi*Q+2*xi*
sigma+Q^2+2*Q*sigma+sigma^2-h+s10-s20;
factor(A21function(1,-1,sigma,-sigma,0,0,0,1,-1,0)-A21bis);

```

$$\frac{sX10(-s10-s20-sX10)}{\xi^2} - s10 - \sigma^2 + s20 - 2\sigma\xi - \xi^2 \quad (4.4)$$

$$\frac{-s10-s20}{\xi}$$

$$\frac{-s10-s20-h}{\xi}$$

$$\frac{PQ}{-\xi+Q}$$

$$-\frac{\xi}{-\xi+Q}$$

$$A21bis := \frac{P(PQ+s10+s20)}{\xi-Q} + \frac{sX10(-s10-s20-sX10)}{Q\xi} + \xi^2 + \xi Q + 2\sigma\xi + Q^2$$

$$+ 2Q\sigma + \sigma^2 - h + s10 - s20$$

```

> simplify(LQfunction(1,-1,X1,-X1,0,0,0,1,-1,0));
simplify(LPfunction(1,-1,X1,-X1,0,0,0,1,-1,0));
simplify(Hamiltonianfunction(1,-1,X1,-X1,0,0,0,1,-1,0));

```

$$\frac{2PQ+s10+s20}{Q^2} \quad (4.5)$$

$$\frac{3Q^4+4Q^3X1+(-P^2+X1^2-h+s10-s20)Q^2-sX10(sX10+s10+s20)}{Q^2}$$

$$\frac{1}{Q}(-Q^4-2Q^3X1+(P^2-X1^2+h-s10+s20)Q^2+(s10+s20)PQ-sX10(sX10+s10+s20))$$

Case of $t_{1,2}=1, t_{2,2}=-1, t_{1,1}=0, t_{2,1}=0$ and $\sigma=X_1$ position of the pole.

We take $s_{12}=1$ and $s_{22}=-1$ and $s_{11}=0$ and $s_{21}=0$

```

> SolQfunction(1,-1,0,0,sigma);
simplify(series(SolPfunction(1,-1,0,0,sigma),checkP));
tdL1functionfunction(1,-1,0,0,sigma);
S1function(1,-1,0,0,sigma);
S2function(1,-1,0,0,sigma);
R1function(xi,1,-1,0,0,sigma);
solve({SolQfunction(1,-1,0,0,sigma)=QQ,SolPfunction(1,-1,0,0,sigma)=PP},{checkQ,checkP});
tdLReduced:=Matrix(2,2,0):
tdL11function0:=unapply(tdL11function(1,-1,0,0,sigma),Q,P):
tdL12function0:=unapply(tdL12function(1,-1,0,0,sigma),Q,P):
tdL21function0:=unapply(tdL21function(1,-1,0,0,sigma),Q,P):
tdL22function0:=unapply(tdL22function(1,-1,0,0,sigma),Q,P):
tdLReduced[1,1]:=simplify(tdL11function(1,-1,0,0,sigma)):
tdLReduced[1,2]:=simplify(tdL12function(1,-1,0,0,sigma)):
tdLReduced[2,1]:=simplify(tdL21function(1,-1,0,0,sigma)):
tdLReduced[2,2]:=simplify(tdL22function(1,-1,0,0,sigma)):
tdLReduced;
tdLReduced2:=Matrix(2,2,0):
tdLReduced2[1,1]:=simplify(tdL11function0(SolQfunction(1,-1,0,0,sigma),SolPfunction(1,-1,0,0,sigma))):
tdLReduced2[1,2]:=simplify(tdL12function0(SolQfunction(1,-1,0,0,sigma),SolPfunction(1,-1,0,0,sigma))):
tdLReduced2[2,1]:=simplify(tdL21function0(SolQfunction(1,-1,0,0,sigma),SolPfunction(1,-1,0,0,sigma))):
tdLReduced2[2,2]:=simplify(tdL22function0(SolQfunction(1,-1,0,0,sigma),SolPfunction(1,-1,0,0,sigma))):
tdLReduced2;

```

$$\begin{aligned}
 & \frac{\frac{checkQ - S1}{S2\sim}}{2 S2\sim \sigma + 2 S1 - 2 checkQ} + S2\sim checkP \\
 & \frac{\sigma}{S1} \\
 & \frac{-s10 - s20}{\xi} + 1 + (-\xi - 1) \xi
 \end{aligned}
 \tag{5.1}$$

$$\left\{ \text{checkP} = \frac{1}{2} \frac{2 PP QQ - 2 PP \sigma + s10 + s20}{S2\sim (QQ - \sigma)}, \text{checkQ} = QQ S2\sim + SI \right\}$$

$$\left[\left[\frac{(-Q + \xi - P) \sigma - \xi^2 + Q(Q + P)}{\xi - \sigma}, \frac{-\xi + Q}{-\xi + \sigma} \right], \right.$$

$$\left[\frac{1}{(\xi - \sigma)(Q - \sigma)} (Q^4 + (2P - 4\sigma + 2\xi) Q^3 + (5\sigma^2 + (-6P - 4\xi)\sigma + P^2 + 2\xi P + s10 + s20) Q^2 + (-2\sigma^3 + (6P + 2\xi)\sigma^2 + (-2P^2 - 4P\xi - 3s10 - s20)\sigma + (s10 + s20)P + 2s10\xi) Q - 2\sigma^3 P + (P^2 + 2P\xi + 2s10)\sigma^2 + (-2s10\xi + P(-s10 - s20))\sigma - sX10(sX10 + s10 + s20) \right),$$

$$\left. \frac{(Q - \xi + P)\sigma - PQ - Q^2 + \xi^2 - s10 - s20}{\xi - \sigma} \right] \left] \right.$$

$$\left[\left[\frac{1}{2} \frac{1}{(\xi - \sigma) S2\sim^2} (-2 S2\sim^3 \sigma \text{checkP} + (-2 SI \text{checkP} + 2 \text{checkP} \text{checkQ} + 2 \sigma \xi - 2 \xi^2 - s10 - s20) S2\sim^2 + 2 \sigma (SI - \text{checkQ}) S2\sim + 2 (SI - \text{checkQ})^2), \right. \right.$$

$$\left. \frac{S2\sim \xi + SI - \text{checkQ}}{(\xi - \sigma) S2\sim} \right],$$

$$\left[\frac{1}{4} \frac{1}{S2\sim^3 (\xi - \sigma) (S2\sim \sigma + SI - \text{checkQ})} \left(-4 S2\sim^6 \text{checkP}^2 \sigma^2 - 8 \text{checkP} \sigma (-\sigma^2 + \sigma \xi + \text{checkP} (SI - \text{checkQ})) S2\sim^5 + \left((24 SI \text{checkP} - 24 \text{checkP} \text{checkQ} - 4 s10 + 4 s20) \sigma^2 - 16 \left(SI \text{checkP} - \text{checkP} \text{checkQ} - \frac{1}{4} s10 + \frac{1}{4} s20 \right) \xi \sigma - 4 \left(SI \text{checkP} - \text{checkP} \text{checkQ} + sX10 + \frac{1}{2} s10 + \frac{1}{2} s20 \right) \left(SI \text{checkP} - \text{checkP} \text{checkQ} - sX10 - \frac{1}{2} s10 - \frac{1}{2} s20 \right) \right) S2\sim^4 - 8 (SI - \text{checkQ}) \left(\sigma^3 - \sigma^2 \xi + \left(-3 SI \text{checkP} + 3 \text{checkP} \text{checkQ} + \frac{1}{2} s10 - \frac{1}{2} s20 \right) \sigma + \xi \left(SI \text{checkP} - \text{checkP} \text{checkQ} - \frac{1}{2} s10 + \frac{1}{2} s20 \right) \right) S2\sim^3 + 8 (SI - \text{checkQ})^2 \left(-\frac{5}{2} \sigma^2 + 2 \sigma \xi + \text{checkP} (SI - \text{checkQ}) \right) S2\sim^2 + 8 (SI - \text{checkQ})^3 (\xi - 2 \sigma) S2\sim - 4 (SI$$

$$\left. \left. \left. -checkQ)^4 \right), \frac{1}{2} \frac{1}{(\xi - \sigma) S2^2} \left(2 S2^3 \sigma checkP + (2 SI checkP \right. \right. \right.$$

$$\left. \left. - 2 checkP checkQ - 2 \sigma \xi + 2 \xi^2 - sI0 - s20 \right) S2^2 - 2 \sigma (SI - checkQ) S2^2 \right. \left. \left. - 2 (SI - checkQ)^2 \right) \right] \right]$$

```

> tdAReduced:=Matrix(2,2,0):
tdA11function0:=unapply( tdA11function(1,-1,0,0,sigma,0,0,0,0,
1),Q,P):
tdA12function0:=unapply( tdA12function(1,-1,0,0,sigma,0,0,0,0,
1),Q,P):
tdA21function0:=unapply( tdA21function(1,-1,0,0,sigma,0,0,0,0,
1),Q,P):
tdA22function0:=unapply( tdA22function(1,-1,0,0,sigma,0,0,0,0,
1),Q,P):
tdAReduced[1,1]:=simplify(tdA11function(1,-1,0,0,sigma,0,0,0,0,
1) ):
tdAReduced[1,2]:=simplify(tdA12function(1,-1,0,0,sigma,0,0,0,0,
1) ):
tdAReduced[2,1]:=simplify(tdA21function(1,-1,0,0,sigma,0,0,0,0,
1) ):
tdAReduced[2,2]:=simplify(tdA22function(1,-1,0,0,sigma,0,0,0,0,
1) ):
tdAReduced;
tdAReduced2:=Matrix(2,2,0):
tdAReduced2[1,1]:=factor(simplify(tdA11function0(SolQfunction
(1,-1,0,0,sigma),SolPfunction(1,-1,0,0,sigma)) )):
tdAReduced2[1,2]:=factor(simplify(tdA12function0(SolQfunction
(1,-1,0,0,sigma),SolPfunction(1,-1,0,0,sigma)) )):
tdAReduced2[2,1]:=factor(simplify(tdA21function0(SolQfunction
(1,-1,0,0,sigma),SolPfunction(1,-1,0,0,sigma)) )):
tdAReduced2[2,2]:=factor(simplify(tdA22function0(SolQfunction
(1,-1,0,0,sigma),SolPfunction(1,-1,0,0,sigma)) )):
tdAReduced2;

```

$$\left[\left[\begin{array}{c} -\frac{(Q - \sigma)(Q + P + \xi - \sigma)}{-\sigma + \xi}, \frac{Q - \sigma}{-\sigma + \xi} \\ -\frac{(Q^2 + (-\sigma + P)Q - P\sigma - sX20)(Q^2 + (-\sigma + P)Q - P\sigma - sX10)}{(-\sigma + \xi)(Q - \sigma)}, \\ \frac{\sigma^2 + (-P - 2Q - \xi)\sigma + Q^2 + (\xi + P)Q - sX10 - sX20}{-\sigma + \xi} \end{array} \right] \right] \quad (5.2)$$

$$\left[\left[\frac{1}{2} \frac{1}{-\xi + \sigma} \left(2 checkP checkQ - 2 checkP \sigma + 2 checkQ^2 - 4 checkQ \sigma + 2 checkQ \xi \right. \right. \right.$$

$$\begin{aligned}
& + 2 \sigma^2 - 2 \sigma \xi + sX10 + sX20), - \frac{checkQ - \sigma}{-\xi + \sigma} \Big] \\
& \left[\frac{1}{4} \frac{1}{(checkQ - \sigma) (-\xi + \sigma)} \left((2 checkP checkQ - 2 checkP \sigma + 2 checkQ^2 \right. \right. \\
& \left. \left. - 2 checkQ \sigma + sX10 - sX20) (2 checkP checkQ - 2 checkP \sigma + 2 checkQ^2 \right. \right. \\
& \left. \left. - 2 checkQ \sigma - sX10 + sX20) \right), - \frac{1}{2} \frac{1}{-\xi + \sigma} \left(2 checkP checkQ - 2 checkP \sigma \right. \right. \\
& \left. \left. + 2 checkQ^2 - 4 checkQ \sigma + 2 checkQ \xi + 2 \sigma^2 - 2 \sigma \xi - sX10 - sX20) \right) \right]
\end{aligned}$$

> simplify(LQfunction(1,-1,0,0,sigma,0,0,0,0,1));
simplify(LPfunction(1,-1,0,0,sigma,0,0,0,0,1));
simplify(Hamiltonianfunction(1,-1,0,0,sigma,0,0,0,0,1));

$$\begin{aligned}
& (2 Q - 2 \sigma) P + h - sX10 - sX20 \tag{5.3} \\
& \frac{1}{(Q - \sigma)^2} (3 Q^4 - 8 Q^3 \sigma + (-P^2 + 7 \sigma^2 - h + s10 - s20) Q^2 + 2 \sigma (P^2 - \sigma^2 + h - s10 \\
& + s20) Q + (-P^2 - h + s10 - s20) \sigma^2 + sX10 sX20) \\
& \frac{1}{Q - \sigma} (-Q^4 + 2 Q^3 \sigma + (P^2 - \sigma^2 + h - s10 + s20) Q^2 + ((-2 P^2 - 2 h + 2 s10 \\
& - 2 s20) \sigma + (-sX10 - sX20 + h) P) Q + (P^2 + h - s10 + s20) \sigma^2 - P (-sX10 \\
& - sX20 + h) \sigma + sX10 sX20)
\end{aligned}$$