

In this Maple file, we compute the evolution equations for the Painlevé 2 equations using the compatibility equation of the Lax system. We also obtain the expression of the Lax matrices in the geometric gauge without apparent singularities.

The operator is $\hbar(\alpha_{111}\partial_{t_1} + \alpha_{121}\partial_{t_2})$

Lax matrices in the oper gauge from previous Maple files

Summary of previous files: We have the expression for some coefficients of the Lax matrix L and of A.

```
> restart;
with(LinearAlgebra):
P011 := t010+t020;
P111 := t110+t120;
P121 := t111+t121;
P142 := t111*t121;
P132 := t110*t121+t111*t120;
P022 := t010*t020;
CoherenceEquation1:=tinfy10+tinfy20+t010+t020+t110+t120;
P1 := unapply(P011/x+P121/(x-1)^2+P111/(x-1), x);
P2 := unapply(P022/x^2+P012/x+P142/(x-1)^4+P132/(x-1)^3+P122/
(x-1)^2+P112/(x-1), x);
tdP2:=unapply(P2(lambda)-P012/lambda-P112/(lambda-1)-P122/
(lambda-1)^2, lambda);

c1:=(alpha111*t121-alpha121*t111)/(t111-t121);
mu:=(alpha111-alpha121)*q*(q-1)^2/(t111-t121);
nu0:=(alpha111-alpha121)*(q-1)^2/(t111-t121);
nuMinus1:=(alpha111-alpha121)*(q-1)/(t111-t121);

C12:=-a2;
C11:=-a1;
C01:=-a0;
c11:=(alpha111*t121-alpha121*t111)/(t111-t121);

dP1dlambda:=unapply(diff(P1(lambda), lambda), lambda);
dP2dlambda:=unapply(diff(P2(lambda), lambda), lambda);
L:=Matrix(2,2,0);
L[1,1]:=0;
L[1,2]:=1;
L[2,1]:=-P2(lambda)+(P012-a0)/lambda+(P122-a2)/(lambda-1)^2+
(P112-a1)/(lambda-1)-h*p/(lambda-q);
L[2,2]:=P1(lambda)-h/lambda-2*h/(lambda-1)+h/(lambda-q);

Eq1:=a0+a1+h*p;
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Eq2:= h*p*q+t010*t020+a1+a2-(h+tinfy20)*tinfy10;

c0:=0:
A:=Matrix(2,2,0):
A[1,1]:= c1/(lambda-1) +c0+rho/(lambda-q):
A[1,2]:= nuMinus1*lambda+nu0+mu/(lambda-q):
A[2,1]:= AA21(lambda):
A[2,2]:= AA22(lambda):
dAdlambda:=Matrix(2,2,0):
for i from 1 to 2 do for j from 1 to 2 do dAdlambda[i,j]:=diff
(A[i,j],lambda): od: od:

L;
A;
P012 := -P112;
P122 := -t010*t020+tinfy10*tinfy20-P112;

Q2:=unapply(-p*(q-0)*(q-1)^2,lambda):
J:=Matrix(2,2,0):
J[1,1]:=1:
J[1,2]:=0:
J[2,1]:=Q2(lambda)/(lambda-q):
J[2,2]:=(lambda-0)^1*(lambda-1)^2/(lambda-q):
dJdlambda:=Matrix(2,2,0):
for i from 1 to 2 do for j from 1 to 2 do dJdlambda[i,j]:=diff
(J[i,j],lambda): od: od:
J:

LJ:=Matrix(2,2,0):
LJ[1,1]:=0:
LJ[1,2]:=0:
LJ[2,2]:=diff(J[2,2],q)*Lq+diff(J[2,2],p)*Lp+h*alpha111*diff(J
[2,2],t111)+h*alpha121*diff(J[2,2],t121):
LJ[2,1]:=diff(J[2,1],q)*Lq+diff(J[2,1],p)*Lp+h*alpha111*diff(J
[2,1],t111)+h*alpha121*diff(J[2,1],t121):
LJ:

checkL:=simplify(Multiply(Multiply(J,L),J^(-1))+h*Multiply
(dJdlambda,J^(-1))):
checkA:=simplify(Multiply(Multiply(J,A),J^(-1))+Multiply(LJ,J^
(-1))):

```

(1.1)

$$\begin{aligned}
P011 &:= t010 + t020 \\
P111 &:= t110 + t120 \\
P121 &:= t111 + t121 \\
P142 &:= t111 t121 \\
P132 &:= t110 t121 + t111 t120 \\
P022 &:= t010 t020 \\
CoherenceEquation1 &:= tinfty10 + tinfty20 + t010 + t020 + t110 + t120 \\
P1 &:= x \rightarrow \frac{t010 + t020}{x} + \frac{t111 + t121}{(x-1)^2} + \frac{t110 + t120}{x-1} \\
P2 &:= x \rightarrow \frac{t010 t020}{x^2} + \frac{P012}{x} + \frac{t111 t121}{(x-1)^4} + \frac{t110 t121 + t111 t120}{(x-1)^3} + \frac{P122}{(x-1)^2} \\
&+ \frac{P112}{x-1} \\
tP2 &:= \lambda \rightarrow \frac{t010 t020}{\lambda^2} + \frac{t111 t121}{(\lambda-1)^4} + \frac{t110 t121 + t111 t120}{(\lambda-1)^3} \\
c1 &:= \frac{-t111 \alpha121 + t121 \alpha111}{t111 - t121} \\
\mu &:= \frac{(\alpha111 - \alpha121) q (q-1)^2}{t111 - t121} \\
\nu0 &:= \frac{(\alpha111 - \alpha121) (q-1)^2}{t111 - t121} \\
nuMinus1 &:= \frac{(\alpha111 - \alpha121) (q-1)}{t111 - t121} \\
c11 &:= \frac{-t111 \alpha121 + t121 \alpha111}{t111 - t121} \\
Eq1 &:= h p + a0 + a1 \\
Eq2 &:= h p q + t010 t020 + a1 + a2 - (h + tinfty20) tinfty10 \\
&\left[\left[0, 1 \right], \right. \\
&\left[-\frac{t010 t020}{\lambda^2} - \frac{P012}{\lambda} - \frac{t111 t121}{(\lambda-1)^4} - \frac{t110 t121 + t111 t120}{(\lambda-1)^3} - \frac{P122}{(\lambda-1)^2} - \frac{P112}{\lambda-1} \right. \\
&+ \frac{P012 - a0}{\lambda} + \frac{P122 - a2}{(\lambda-1)^2} + \frac{P112 - a1}{\lambda-1} - \frac{h p}{\lambda-q}, \frac{t010 + t020}{\lambda} + \frac{t111 + t121}{(\lambda-1)^2} \\
&\left. + \frac{t110 + t120}{\lambda-1} - \frac{h}{\lambda} - \frac{2h}{\lambda-1} + \frac{h}{\lambda-q} \right] \\
&\left[\left[\frac{-t111 \alpha121 + t121 \alpha111}{(t111 - t121) (\lambda-1)} + \frac{\rho}{\lambda-q}, \frac{(\alpha111 - \alpha121) (q-1) \lambda}{t111 - t121} \right. \right. \\
&\left. + \frac{(\alpha111 - \alpha121) (q-1)^2}{t111 - t121} + \frac{(\alpha111 - \alpha121) q (q-1)^2}{(t111 - t121) (\lambda-q)} \right], \\
&\left[AA21(\lambda), AA22(\lambda) \right] \\
&P012 := -P112 \\
&P122 := -t010 t020 + tinfty10 tinfty20 - P112
\end{aligned}$$

Solving the compatibility equations to obtain the Hamiltonian evolutions.

The compatibility equation is $\mathcal{L}L = h \partial_{\lambda} A + [A, L]$
 Since the first line of L is trivial, we may easily obtain $A[2,1]$ et $A[2,2]$ to obtain the full expression for A

```
> LL:=h*dAdlambda+(Multiply(A,L)-Multiply(L,A)):
```

```
Entry11:=LL[1,1]:
```

```
Entry12:=LL[1,2]:
```

```
AA21:=unapply(solve(Entry11=0,AA21(lambda)),lambda):
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```
AA21bis:=h*dAdlambda[1,1]+A[1,2]*L[2,1]:
```

```
simplify(AA21(lambda)-AA21bis);
```

```
AA22:=unapply(solve(Entry12=0,AA22(lambda)),lambda):
```

```
AA22bis:=h*dAdlambda[1,2]+A[1,1]+A[1,2]*L[2,2]:
```

```
simplify(AA22(lambda)-AA22bis);
```

```
simplify(Entry11);
```

```
simplify(Entry12);
```

```
LL:=h*dAdlambda+(Multiply(A,L)-Multiply(L,A)):
```

$$\begin{matrix} 0 \\ 0 \\ 0 \\ 0 \end{matrix} \quad (2.1)$$

We now compute the action of \mathcal{L} on $L[2,2]$ et $L[2,1]$ to obtain the evolution equations
 Evolution of entry $L_{2,2}$

```
> Entry22:=simplify(LL[2,2]);
```

```
Entry22TermLambdaMinusqCube:=factor(residue(Entry22*(lambda-q)^2,lambda=q));
```

```
Entry22TermLambdaMinusqSquare:=factor(residue(Entry22*(lambda-q),lambda=q));
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```
Entry22TermLambdaMinusq:=factor(residue(Entry22,lambda=q));
```

```
Entry22TermLambdaInfty1:=factor(-residue(Entry22/lambda^2,lambda=infinity));
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```
Entry22TermLambdaInfty0:=factor(-residue(Entry22/lambda,lambda=infinity));
```

```

Entry22TermLambda1OrderMinus1:=factor(residue(Entry22/
(lambda-1)^0,lambda=1));
Entry22TermLambda1OrderMinus2:=factor(residue
(Entry22*(lambda-1),lambda=1));
Entry22TermLambda1OrderMinus3:=factor(residue(Entry22*
(lambda-1)^2,lambda=1));

Entry22TermLambda0OrderMinus1:=factor(residue(Entry22/(lambda)
^0,lambda=0));
Entry22TermLambda0OrderMinus2:=factor(residue(Entry22*(lambda),
lambda=0));
Entry22TermLambda0OrderMinus3:=factor(residue(Entry22*(lambda)
^2,lambda=0));

simplify(Entry22-(Entry22TermLambdaMinusqSquare/(lambda-q)^2+
Entry22TermLambdaMinusq/(lambda-q)
+Entry22TermLambdaInfity0+Entry22TermLambda1OrderMinus2/
(lambda-1)^2));
L[2,2];

```

$$\begin{aligned}
\text{Entry22} := & \frac{1}{(\lambda-1)^2(\lambda-q)^2(t_{111}-t_{121})} \left(h \left((\alpha_{11}-\alpha_{21})(h-t_{010}-t_{020} \right. \right. & (2.2) \\
& -t_{110}-t_{120})\lambda^2 - 2(\alpha_{11}-\alpha_{21})(h-t_{010}-t_{020}-t_{110}-t_{120})\lambda + (h \\
& -t_{010}-t_{020}-t_{110}+t_{111}-t_{120}-t_{121})\alpha_{11}-\alpha_{21}(h-t_{010}-t_{020}-t_{110} \\
& -t_{111}-t_{120}+t_{121})q^2 + \left(-(\alpha_{11}-\alpha_{21})(h-2t_{010}-2t_{020}-t_{110}+t_{111} \right. \\
& -t_{120}+t_{121})\lambda^2 + ((2h-4t_{010}-4t_{020}-2t_{110}-2t_{120}+4t_{121})\alpha_{11} \\
& -2\alpha_{21}(h-2t_{010}-2t_{020}-t_{110}+2t_{111}-t_{120}))\lambda - (\alpha_{11}-\alpha_{21})(h \\
& -2t_{010}-2t_{020}-t_{110}+t_{111}-t_{120}+t_{121})q + ((-t_{010}-t_{020}+t_{111} \\
& -t_{121})\alpha_{11} + (t_{010}+t_{020}+t_{111}-t_{121})\alpha_{21} - 2\rho(t_{111}-t_{121}))\lambda^2 \\
& + ((2t_{010}+2t_{020})\alpha_{11} + (-2t_{010}-2t_{020})\alpha_{21} + 4\rho(t_{111}-t_{121}))\lambda + (\\
& \left. -t_{010}-t_{020})\alpha_{11} + (t_{010}+t_{020})\alpha_{21} - 2\rho(t_{111}-t_{121})) \right) \\
& \text{Entry22TermLambdaMinusqCube} := 0 \\
\text{Entry22TermLambdaMinusqSquare} := & \frac{1}{t_{111}-t_{121}} \left((hq^2\alpha_{11}-hq^2\alpha_{21} \right. \\
& -q^2t_{010}\alpha_{11}+q^2t_{010}\alpha_{21}-q^2t_{020}\alpha_{11}+q^2t_{020}\alpha_{21}-q^2t_{110}\alpha_{11} \\
& +q^2t_{110}\alpha_{21}-q^2t_{120}\alpha_{11}+q^2t_{120}\alpha_{21}-hq\alpha_{11}+hq\alpha_{21}+2qt_{010}\alpha_{11} \\
& -2qt_{010}\alpha_{21}+2qt_{020}\alpha_{11}-2qt_{020}\alpha_{21}+qt_{110}\alpha_{11}-qt_{110}\alpha_{21} \\
& \left. -qt_{111}\alpha_{11}+qt_{111}\alpha_{21}+qt_{120}\alpha_{11}-qt_{120}\alpha_{21}-qt_{121}\alpha_{11} \right)
\end{aligned}$$

$+ q t_{121} \alpha_{121} - 2 \rho t_{111} + 2 \rho t_{121} - t_{010} \alpha_{111} + t_{010} \alpha_{121} - t_{020} \alpha_{111} + t_{020} \alpha_{121}) h$

```

Entry22TermLambdaMinusq := 0
Entry22TermLambdaInfty1 := 0
Entry22TermLambdaInfty0 := 0
Entry22TermLambda1OrderMinus1 := 0
Entry22TermLambda1OrderMinus2 := (alpha111 + alpha121) h
Entry22TermLambda1OrderMinus3 := 0
Entry22TermLambda0OrderMinus1 := 0
Entry22TermLambda0OrderMinus2 := 0
Entry22TermLambda0OrderMinus3 := 0

```

$$\frac{t_{010} + t_{020}}{\lambda} + \frac{t_{111} + t_{121}}{(\lambda - 1)^2} + \frac{t_{110} + t_{120}}{\lambda - 1} - \frac{h}{\lambda} - \frac{2h}{\lambda - 1} + \frac{h}{\lambda - q}$$

Since the deformation operator is $\hbar(\alpha_{111}\partial_{\{t_1^{(1)},1\}} + \alpha_{121}\partial_{\{t_1^{(2)},1\}})$ it acts on the double pole and gives $h(\alpha_{111} + \alpha_{121})$.

On the simple pole at $\lambda = q$ we find $h^*L[q]$ that should correspond to the double pole of the compatibility equation.

```

> Equation1 := Entry22TermLambda1OrderMinus2 - h*(alpha111 + alpha121)
;

```

$$\text{Equation1} := 0 \quad (2.3)$$

```

> Lq := factor(Entry22TermLambdaMinusqSquare/h) :
Lqbis := -2*rho + mu/q / (q-1)^2 * ( (h - t120 - t010 - t020 - t110) * q^2 - q *
(h - 2*t010 - 2*t020 - t110 + t111 - t120 + t121) - (t010 + t020) ) ;
factor(simplify(Lq - Lqbis)) ;

```

$$Lqbis := -2\rho + \frac{1}{t_{111} - t_{121}} ((\alpha_{111} - \alpha_{121}) ((h - t_{010} - t_{020} - t_{110} - t_{120}) q^2 - q(h - 2t_{010} - 2t_{020} - t_{110} + t_{111} - t_{120} + t_{121}) - t_{010} - t_{020})) \quad (2.4)$$

Evolution of $\mathcal{L}[L[2,1]]$

```

> Entry21 := simplify(LL[2,1]) :
Entry21TermLambdaMinusqCube := factor(residue(Entry21*(lambda - q)^2, lambda = q)) ;
Entry21TermLambdaMinusqSquare := factor(residue(Entry21*(lambda - q), lambda = q)) ;
Entry21TermLambdaMinusq := factor(residue(Entry21, lambda = q)) ;

Entry21TermLambdaInfty1 := factor(-residue(Entry21/lambda^2, lambda = infinity)) ;
Entry21TermLambdaInfty0 := factor(-residue(Entry21/lambda, lambda = infinity)) ;

Entry21TermLambdaZero2 := factor(residue(Entry21*(lambda), lambda = 0)) ;

```

```

Entry21TermLambdaZero1:=factor(residue(Entry21,lambda=0));

Entry21TermLambdaUn5:=factor(residue(Entry21*(lambda-1)^4,
lambda=1));
Entry21TermLambdaUn4:=factor(residue(Entry21*(lambda-1)^3,
lambda=1));
Entry21TermLambdaUn3:=factor(residue(Entry21*(lambda-1)^2,
lambda=1));
Entry21TermLambdaUn2:=factor(residue(Entry21*(lambda-1),lambda=
1));
Entry21TermLambdaUn1:=factor(residue(Entry21,lambda=1));

simplify(Entry21-(Entry21TermLambdaMinusqCube/(lambda-q)^3+
Entry21TermLambdaMinusqSquare/(lambda-q)^2+
Entry21TermLambdaMinusq/(lambda-q)
+Entry21TermLambdaInfity0+Entry21TermLambdaInfity1*lambda
+Entry21TermLambdaZero1/lambda+Entry21TermLambdaUn1/(lambda-1)
));
L[2,1];

```

$$\begin{aligned}
\text{Entry21TermLambdaMinusqCube} &:= \frac{1}{t111 - t121} (3 (p q^3 \alpha111 - p q^3 \alpha121 \\
&\quad - 2 p q^2 \alpha111 + 2 p q^2 \alpha121 + p q \alpha111 - p q \alpha121 + \rho t111 - \rho t121) h^2) \tag{2.5} \\
\text{Entry21TermLambdaMinusqSquare} &:= \frac{1}{(q-1)^2 (t111 - t121) q} (h (2 h p q^5 \alpha111 \\
&\quad - 2 h p q^5 \alpha121 + 2 a0 q^5 \alpha111 - 2 a0 q^5 \alpha121 + 2 a1 q^5 \alpha111 - 2 a1 q^5 \alpha121 \\
&\quad - 7 h p q^4 \alpha111 + 7 h p q^4 \alpha121 + 2 q^4 t010 t020 \alpha111 - 2 q^4 t010 t020 \alpha121 \\
&\quad - 8 a0 q^4 \alpha111 + 8 a0 q^4 \alpha121 - 6 a1 q^4 \alpha111 + 6 a1 q^4 \alpha121 + 2 a2 q^4 \alpha111 \\
&\quad - 2 a2 q^4 \alpha121 + 9 h p q^3 \alpha111 - 9 h p q^3 \alpha121 - 8 q^3 t010 t020 \alpha111 \\
&\quad + 8 q^3 t010 t020 \alpha121 + 2 q^3 t110 t121 \alpha111 - 2 q^3 t110 t121 \alpha121 \\
&\quad + 2 q^3 t111 t120 \alpha111 - 2 q^3 t111 t120 \alpha121 + 12 a0 q^3 \alpha111 - 12 a0 q^3 \alpha121 \\
&\quad + 6 a1 q^3 \alpha111 - 6 a1 q^3 \alpha121 - 4 a2 q^3 \alpha111 + 4 a2 q^3 \alpha121 - 5 h p q^2 \alpha111 \\
&\quad + 5 h p q^2 \alpha121 - 3 h q^2 \rho t111 + 3 h q^2 \rho t121 + q^2 \rho t010 t111 - q^2 \rho t010 t121 \\
&\quad + q^2 \rho t020 t111 - q^2 \rho t020 t121 + q^2 \rho t110 t111 - q^2 \rho t110 t121 + q^2 \rho t111 t120 \\
&\quad - q^2 \rho t120 t121 + 12 q^2 t010 t020 \alpha111 - 12 q^2 t010 t020 \alpha121 - 2 q^2 t110 t121 \alpha111 \\
&\quad + 2 q^2 t110 t121 \alpha121 - 2 q^2 t111 t120 \alpha111 + 2 q^2 t111 t120 \alpha121 \\
&\quad + 2 q^2 t111 t121 \alpha111 - 2 q^2 t111 t121 \alpha121 - 8 a0 q^2 \alpha111 + 8 a0 q^2 \alpha121 \\
&\quad - 2 a1 q^2 \alpha111 + 2 a1 q^2 \alpha121 + 2 a2 q^2 \alpha111 - 2 a2 q^2 \alpha121 + h p q \alpha111 \\
&\quad - h p q \alpha121 + 4 h q \rho t111 - 4 h q \rho t121 - 2 q \rho t010 t111 + 2 q \rho t010 t121 \\
&\quad - 2 q \rho t020 t111 + 2 q \rho t020 t121 - q \rho t110 t111 + q \rho t110 t121 + q \rho t111^2 \\
&\quad - q \rho t111 t120 + q \rho t120 t121 - q \rho t121^2 - 8 q t010 t020 \alpha111 + 8 q t010 t020 \alpha121)
\end{aligned}$$

$$+ 2 a_0 q \alpha_{111} - 2 a_0 q \alpha_{121} - h \rho t_{111} + h \rho t_{121} + \rho t_{010} t_{111} - \rho t_{010} t_{121} \\ + \rho t_{020} t_{111} - \rho t_{020} t_{121} + 2 t_{010} t_{020} \alpha_{111} - 2 t_{010} t_{020} \alpha_{121}))$$

$$\text{Entry21TermLambdaMinusq} := - \frac{1}{(q-1)^3 (t_{111} - t_{121}) q^2} ((h p q^6 \alpha_{111} - h p q^6 \alpha_{121} \\ + a_0 q^6 \alpha_{111} - a_0 q^6 \alpha_{121} + a_1 q^6 \alpha_{111} - a_1 q^6 \alpha_{121} - 4 h p q^5 \alpha_{111} \\ + 4 h p q^5 \alpha_{121} + 2 q^5 t_{010} t_{020} \alpha_{111} - 2 q^5 t_{010} t_{020} \alpha_{121} - 5 a_0 q^5 \alpha_{111} \\ + 5 a_0 q^5 \alpha_{121} - 3 a_1 q^5 \alpha_{111} + 3 a_1 q^5 \alpha_{121} + 2 a_2 q^5 \alpha_{111} - 2 a_2 q^5 \alpha_{121} \\ + 6 h p q^4 \alpha_{111} - 6 h p q^4 \alpha_{121} - 10 q^4 t_{010} t_{020} \alpha_{111} + 10 q^4 t_{010} t_{020} \alpha_{121} \\ + 3 q^4 t_{110} t_{121} \alpha_{111} - 3 q^4 t_{110} t_{121} \alpha_{121} + 3 q^4 t_{111} t_{120} \alpha_{111} \\ - 3 q^4 t_{111} t_{120} \alpha_{121} + 10 a_0 q^4 \alpha_{111} - 10 a_0 q^4 \alpha_{121} + 3 a_1 q^4 \alpha_{111} - 3 a_1 q^4 \alpha_{121} \\ - 4 a_2 q^4 \alpha_{111} + 4 a_2 q^4 \alpha_{121} - 4 h p q^3 \alpha_{111} + 4 h p q^3 \alpha_{121} - 3 h q^3 \rho t_{111} \\ + 3 h q^3 \rho t_{121} + h q^3 t_{111} \alpha_{121} - h q^3 t_{121} \alpha_{111} + q^3 \rho t_{010} t_{111} - q^3 \rho t_{010} t_{121} \\ + q^3 \rho t_{020} t_{111} - q^3 \rho t_{020} t_{121} + q^3 \rho t_{110} t_{111} - q^3 \rho t_{110} t_{121} + q^3 \rho t_{111} t_{120} \\ - q^3 \rho t_{120} t_{121} + 20 q^3 t_{010} t_{020} \alpha_{111} - 20 q^3 t_{010} t_{020} \alpha_{121} - 3 q^3 t_{110} t_{121} \alpha_{111} \\ + 3 q^3 t_{110} t_{121} \alpha_{121} - 3 q^3 t_{111} t_{120} \alpha_{111} + 3 q^3 t_{111} t_{120} \alpha_{121} \\ + 4 q^3 t_{111} t_{121} \alpha_{111} - 4 q^3 t_{111} t_{121} \alpha_{121} - 10 a_0 q^3 \alpha_{111} + 10 a_0 q^3 \alpha_{121} \\ - a_1 q^3 \alpha_{111} + a_1 q^3 \alpha_{121} + 2 a_2 q^3 \alpha_{111} - 2 a_2 q^3 \alpha_{121} + h p q^2 \alpha_{111} \\ - h p q^2 \alpha_{121} + 5 h q^2 \rho t_{111} - 5 h q^2 \rho t_{121} - h q^2 t_{111} \alpha_{121} + h q^2 t_{121} \alpha_{111} \\ - 3 q^2 \rho t_{010} t_{111} + 3 q^2 \rho t_{010} t_{121} - 3 q^2 \rho t_{020} t_{111} + 3 q^2 \rho t_{020} t_{121} \\ - q^2 \rho t_{110} t_{111} + q^2 \rho t_{110} t_{121} + 2 q^2 \rho t_{111}^2 - q^2 \rho t_{111} t_{120} + q^2 \rho t_{120} t_{121} \\ - 2 q^2 \rho t_{121}^2 - 20 q^2 t_{010} t_{020} \alpha_{111} + 20 q^2 t_{010} t_{020} \alpha_{121} + 5 a_0 q^2 \alpha_{111} \\ - 5 a_0 q^2 \alpha_{121} - 3 h q \rho t_{111} + 3 h q \rho t_{121} + 3 q \rho t_{010} t_{111} - 3 q \rho t_{010} t_{121} \\ + 3 q \rho t_{020} t_{111} - 3 q \rho t_{020} t_{121} + 10 q t_{010} t_{020} \alpha_{111} - 10 q t_{010} t_{020} \alpha_{121} \\ - a_0 q \alpha_{111} + a_0 q \alpha_{121} + h \rho t_{111} - h \rho t_{121} - \rho t_{010} t_{111} + \rho t_{010} t_{121} \\ - \rho t_{020} t_{111} + \rho t_{020} t_{121} - 2 t_{010} t_{020} \alpha_{111} + 2 t_{010} t_{020} \alpha_{121}) h)$$

$$\text{Entry21TermLambdaInfty1} := 0$$

$$\text{Entry21TermLambdaInfty0} := 0$$

$$\text{Entry21TermLambdaZero2} := 0$$

$$\text{Entry21TermLambdaZero1} := - \frac{1}{q^2 (t_{111} - t_{121})} (h (-h q^2 t_{111} \alpha_{121} + h q^2 t_{121} \alpha_{111} \\ - 2 q^2 t_{010} t_{020} \alpha_{111} + 2 q^2 t_{010} t_{020} \alpha_{121} + q^2 t_{010} t_{111} \alpha_{121} - q^2 t_{010} t_{121} \alpha_{111} \\ + q^2 t_{020} t_{111} \alpha_{121} - q^2 t_{020} t_{121} \alpha_{111} + a_0 q^2 \alpha_{111} - a_0 q^2 \alpha_{121} \\ + 4 q t_{010} t_{020} \alpha_{111} - 4 q t_{010} t_{020} \alpha_{121} - a_0 q \alpha_{111} + a_0 q \alpha_{121} + h \rho t_{111} \\ - h \rho t_{121} - \rho t_{010} t_{111} + \rho t_{010} t_{121} - \rho t_{020} t_{111} + \rho t_{020} t_{121} - 2 t_{010} t_{020} \alpha_{111} \\ + 2 t_{010} t_{020} \alpha_{121}))$$

$$\text{Entry21TermLambdaUn5} := 0$$

$$\text{Entry21TermLambdaUn4} := - (t_{111} \alpha_{121} + t_{121} \alpha_{111}) h$$

$$\text{Entry21TermLambdaUn3} := - (t_{110} \alpha_{121} + t_{120} \alpha_{111}) h$$

$$\text{Entry21TermLambdaUn2} := \frac{1}{(q-1)^2 (t_{111} - t_{121})} ((h q^2 t_{111} \alpha_{121} - h q^2 t_{121} \alpha_{111} \\ - q^2 t_{010} t_{111} \alpha_{121} + q^2 t_{010} t_{121} \alpha_{111} - q^2 t_{020} t_{111} \alpha_{121} + q^2 t_{020} t_{121} \alpha_{111}$$

$$\begin{aligned}
& + q^2 t110 t121 \alpha11 - q^2 t110 t121 \alpha21 + q^2 t111 t120 \alpha11 - q^2 t111 t120 \alpha21 \\
& - h q t111 \alpha21 + h q t121 \alpha11 + 2 q t010 t111 \alpha21 - 2 q t010 t121 \alpha11 \\
& + 2 q t020 t111 \alpha21 - 2 q t020 t121 \alpha11 - q t110 t121 \alpha11 + q t110 t121 \alpha21 \\
& - q t111 t120 \alpha11 + q t111 t120 \alpha21 + 2 q t111 t121 \alpha11 - 2 q t111 t121 \alpha21 \\
& + \rho t111^2 - \rho t121^2 - t010 t111 \alpha21 + t010 t121 \alpha11 - t020 t111 \alpha21 \\
& + t020 t121 \alpha11) h)
\end{aligned}$$

$$\begin{aligned}
\text{Entry21TermLambdaUn1} := & \frac{1}{(q-1)^3 (t111 - t121)} \left((-h q^3 t111 \alpha21 + h q^3 t121 \alpha11 \right. \\
& + q^3 t010 t111 \alpha21 - q^3 t010 t121 \alpha11 + q^3 t020 t111 \alpha21 - q^3 t020 t121 \alpha11 \\
& + a1 q^3 \alpha11 - a1 q^3 \alpha21 + 2 a2 q^3 \alpha11 - 2 a2 q^3 \alpha21 + 3 h q^2 t111 \alpha21 \\
& - 3 h q^2 t121 \alpha11 - 3 q^2 t010 t111 \alpha21 + 3 q^2 t010 t121 \alpha11 - 3 q^2 t020 t111 \alpha21 \\
& + 3 q^2 t020 t121 \alpha11 + 3 q^2 t110 t121 \alpha11 - 3 q^2 t110 t121 \alpha21 \\
& + 3 q^2 t111 t120 \alpha11 - 3 q^2 t111 t120 \alpha21 - 3 a1 q^2 \alpha11 + 3 a1 q^2 \alpha21 \\
& - 4 a2 q^2 \alpha11 + 4 a2 q^2 \alpha21 - 2 h q \rho t111 + 2 h q \rho t121 - 2 h q t111 \alpha21 \\
& + 2 h q t121 \alpha11 + q \rho t110 t111 - q \rho t110 t121 + q \rho t111 t120 - q \rho t120 t121 \\
& + 3 q t010 t111 \alpha21 - 3 q t010 t121 \alpha11 + 3 q t020 t111 \alpha21 - 3 q t020 t121 \alpha11 \\
& - 3 q t110 t121 \alpha11 + 3 q t110 t121 \alpha21 - 3 q t111 t120 \alpha11 + 3 q t111 t120 \alpha21 \\
& + 4 q t111 t121 \alpha11 - 4 q t111 t121 \alpha21 + 3 a1 q \alpha11 - 3 a1 q \alpha21 \\
& + 2 a2 q \alpha11 - 2 a2 q \alpha21 + 2 h \rho t111 - 2 h \rho t121 - \rho t110 t111 + \rho t110 t121 \\
& + 2 \rho t111^2 - \rho t111 t120 + \rho t120 t121 - 2 \rho t121^2 - t010 t111 \alpha21 + t010 t121 \alpha11 \\
& \left. - t020 t111 \alpha21 + t020 t121 \alpha11 - a1 \alpha11 + a1 \alpha21) h \right) \\
- & \frac{1}{(q-1)^2 (t111 - t121) (\lambda - 1)^4} \left(h \left(\left((-t120 \alpha11 - \alpha21 (h - t010 - t020 \right. \right. \right. \\
& \left. \left. - t120) \right) t111 + ((h - t010 - t020 - t110) \alpha11 + t110 \alpha21) t121) \lambda^2 \right. \\
& + \left(\left(3 t120 \alpha11 + 2 \left(h - t010 - t020 + \frac{1}{2} t110 - t120 \right) \alpha21 \right) t111 - 2 t121 \left(\left(h \right. \right. \right. \\
& \left. \left. - t010 - t020 - t110 + \frac{1}{2} t120 \right) \alpha11 + \frac{3}{2} t110 \alpha21 \right) \right) \lambda + \alpha21 t111^2 + ((\alpha11 \\
& - \alpha21) t121 - 2 t120 \alpha11 - \alpha21 (h - t010 - t020 + t110 - t120)) t111 + (\\
& - t121 \alpha11 + (h - t010 - t020 - t110 + t120) \alpha11 + 2 t110 \alpha21) t121) q^2 + (((\\
& - 2 \alpha11 + 2 \alpha21) t121 + t120 \alpha11 + \alpha21 (h - 2 t010 - 2 t020 - t120)) t111 \\
& - ((h - 2 t010 - 2 t020 - t110) \alpha11 + t110 \alpha21) t121) \lambda^2 + (((4 \alpha11 \\
& - 4 \alpha21) t121 - 4 t120 \alpha11 - 2 \alpha21 (h - 2 t010 - 2 t020 + t110 - t120)) t111 \\
& + 2 t121 ((h - 2 t010 - 2 t020 - t110 + t120) \alpha11 + 2 t110 \alpha21)) \lambda \\
& - 2 \alpha21 t111^2 + ((-4 \alpha11 + 4 \alpha21) t121 + 3 t120 \alpha11 + \alpha21 (h - 2 t010
\end{aligned}$$

$$\begin{aligned}
& -2 t020 + 2 t110 - t120)) t111 - t121 (-2 t121 \alpha111 + (h - 2 t010 - 2 t020 - t110 \\
& + 2 t120) \alpha111 + 3 t110 \alpha21)) q + (-\rho t111^2 + \alpha21 (t010 + t020) t111 - (\\
& -\rho t121 + \alpha111 (t010 + t020)) t121) \lambda^2 + \left(2 \rho t111^2 + \left(t120 \alpha111 - 2 \alpha21 \left(t010 \right. \right. \right. \\
& \left. \left. \left. + t020 - \frac{1}{2} t110 \right) \right) t111 + 2 \left(-\rho t121 + \left(t010 + t020 - \frac{1}{2} t120 \right) \alpha111 \right. \right. \\
& \left. \left. - \frac{1}{2} t110 \alpha21 \right) t121 \right) \lambda + (\alpha21 - \rho) t111^2 + ((\alpha111 - \alpha21) t121 - t120 \alpha11 \\
& + \alpha21 (t010 + t020 - t110)) t111 - ((\alpha111 - \rho) t121 + (t010 + t020 \\
& - t120) \alpha111 - t110 \alpha21) t121)) \\
& - \frac{t010 t020}{\lambda^2} + \frac{P112}{\lambda} - \frac{t111 t121}{(\lambda - 1)^4} - \frac{t110 t121 + t111 t120}{(\lambda - 1)^3} \\
& - \frac{-t010 t020 + t110 t121 - P112}{(\lambda - 1)^2} - \frac{P112}{\lambda - 1} + \frac{-P112 - a0}{\lambda} \\
& + \frac{-t010 t020 + t110 t121 - P112 - a2}{(\lambda - 1)^2} + \frac{P112 - a1}{\lambda - 1} - \frac{h p}{\lambda - q}
\end{aligned}$$

```

> rho:=factor(solve(Entry21TermLambdaMinusqCube, rho));
simplify(rho-(-p*mu));
simplify(Entry21TermLambdaMinusqCube);
Lqter:=2*mu*(p-P1(q)/2+h/2/q+2*h/2/(q-1))-h*nu0 -h*nuMinus1*q;
factor(simplify(Lqbis-Lqter));

```

$$\rho := - \frac{p q (q - 1)^2 (\alpha111 - \alpha21)}{t111 - t121} \quad (2.6)$$

$$\begin{aligned}
Lqter := & \frac{1}{t111 - t121} \left(2 (\alpha111 - \alpha21) q (q - 1)^2 \left(p - \frac{1}{2} \frac{t010 + t020}{q} \right. \right. \\
& \left. \left. - \frac{1}{2} \frac{t111 + t121}{(q - 1)^2} - \frac{1}{2} \frac{t110 + t120}{q - 1} + \frac{1}{2} \frac{h}{q} + \frac{h}{q - 1} \right) \right) \\
& - \frac{h (\alpha111 - \alpha21) (q - 1)^2}{t111 - t121} - \frac{h (\alpha111 - \alpha21) (q - 1) q}{t111 - t121}
\end{aligned}$$

```

> Lp:=simplify(-Entry21TermLambdaMinusq/h):

```

```

Eq5:=simplify(Entry21TermLambdaMinusqSquare-(-p*h*Lq));

```

$$\begin{aligned}
Eq5 := & \frac{1}{(q - 1)^2 (t111 - t121) q} \left(6 h (\alpha111 - \alpha21) \left(\frac{1}{3} p^2 q^6 + \left(-\frac{4}{3} p^2 + \left(h \right. \right. \right. \right. \\
& \left. \left. \left. - \frac{1}{3} t110 - \frac{1}{3} t120 - \frac{1}{3} t010 - \frac{1}{3} t020 \right) p + \frac{1}{3} a0 + \frac{1}{3} a1 \right) q^5 + \left(2 p^2 + \left(\right. \right. \right. \\
& \left. \left. \left. - \frac{10}{3} h - \frac{1}{3} t111 + t120 - \frac{1}{3} t121 + \frac{4}{3} t010 + \frac{4}{3} t020 + t110 \right) p + \frac{1}{3} t010 t020 \right. \right. \\
& \left. \left. \left. \right) \right)
\end{aligned} \quad (2.7)$$

$$\begin{aligned}
& -\frac{4}{3} a_0 - a_1 + \frac{1}{3} a_2) q^4 + \left(-\frac{4}{3} p^2 + \left(4h + \frac{2}{3} t_{111} - t_{120} + \frac{2}{3} t_{121} - 2 t_{010} \right. \right. \\
& \left. \left. - 2 t_{020} - t_{110} \right) p + \frac{1}{3} t_{111} t_{120} + \frac{1}{3} t_{110} t_{121} - \frac{4}{3} t_{010} t_{020} + 2 a_0 + a_1 \right. \\
& \left. - \frac{2}{3} a_2 \right) q^3 + \left(\frac{1}{3} p^2 + \left(-2h - \frac{1}{3} t_{111} + \frac{1}{3} t_{120} - \frac{1}{3} t_{121} + \frac{4}{3} t_{010} + \frac{4}{3} t_{020} \right. \right. \\
& \left. \left. + \frac{1}{3} t_{110} \right) p + 2 t_{010} t_{020} + \left(-\frac{1}{3} t_{120} + \frac{1}{3} t_{121} \right) t_{111} - \frac{1}{3} t_{110} t_{121} - \frac{4}{3} a_0 \right. \\
& \left. - \frac{1}{3} a_1 + \frac{1}{3} a_2 \right) q^2 + \left(\left(\frac{1}{3} h - \frac{1}{3} t_{010} - \frac{1}{3} t_{020} \right) p - \frac{4}{3} t_{010} t_{020} + \frac{1}{3} a_0 \right) q \\
& \left. + \frac{1}{3} t_{010} t_{020} \right)
\end{aligned}$$

```

> a0 := factor(- (p^2*q^6+h*p*q^5-4*p^2*q^5-p*q^5*t010-p*q^5*t020-
p*q^5*t110-p*q^5*t120-4*h*p*q^4+h*q^4*tinfy10+6*p^2*q^4+4*p*
q^4*t010+4*p*q^4*t020+3*p*q^4*t110-p*q^4*t111+3*p*q^4*t120-p*
q^4*t121+q^4*tinfy10*tinfy20+6*h*p*q^3-2*h*q^3*tinfy10-4*
p^2*q^3-6*p*q^3*t010-6*p*q^3*t020-3*p*q^3*t110+2*p*q^3*t111-3*
p*q^3*t120+2*p*q^3*t121-2*q^3*t010*t020+q^3*t110*t121+q^3*t111*
t120-2*q^3*tinfy10*tinfy20-4*h*p*q^2+h*q^2*tinfy10+p^2*
q^2+4*p*q^2*t010+4*p*q^2*t020+p*q^2*t110-p*q^2*t111+p*q^2*t120-
p*q^2*t121+5*q^2*t010*t020-q^2*t110*t121-q^2*t111*t120+q^2*
t111*t121+q^2*tinfy10*tinfy20+h*p*q-p*q*t010-p*q*t020-4*q*
t010*t020+t010*t020) / (q*(q^2-2*q+1)) );
a1 :=factor( (p^2*q^6+h*p*q^5-4*p^2*q^5-p*q^5*t010-p*q^5*t020-
p*q^5*t110-p*q^5*t120-4*h*p*q^4+h*q^4*tinfy10+6*p^2*q^4+4*p*
q^4*t010+4*p*q^4*t020+3*p*q^4*t110-p*q^4*t111+3*p*q^4*t120-p*
q^4*t121+q^4*tinfy10*tinfy20+5*h*p*q^3-2*h*q^3*tinfy10-4*
p^2*q^3-6*p*q^3*t010-6*p*q^3*t020-3*p*q^3*t110+2*p*q^3*t111-3*
p*q^3*t120+2*p*q^3*t121-2*q^3*t010*t020+q^3*t110*t121+q^3*t111*
t120-2*q^3*tinfy10*tinfy20-2*h*p*q^2+h*q^2*tinfy10+p^2*
q^2+4*p*q^2*t010+4*p*q^2*t020+p*q^2*t110-p*q^2*t111+p*q^2*t120-
p*q^2*t121+5*q^2*t010*t020-q^2*t110*t121-q^2*t111*t120+q^2*
t111*t121+q^2*tinfy10*tinfy20-p*q*t010-p*q*t020-4*q*t010*
t020+t010*t020) / (q*(q^2-2*q+1)) )
;
a2:= factor(- (p^2*q^6+h*p*q^5-4*p^2*q^5-p*q^5*t010-p*q^5*t020-
p*q^5*t110-p*q^5*t120-3*h*p*q^4+h*q^4*tinfy10+6*p^2*q^4+4*p*
q^4*t010+4*p*q^4*t020+3*p*q^4*t110-p*q^4*t111+3*p*q^4*t120-p*
q^4*t121+q^4*tinfy10*tinfy20+3*h*p*q^3-3*h*q^3*tinfy10-4*
p^2*q^3-6*p*q^3*t010-6*p*q^3*t020-3*p*q^3*t110+2*p*q^3*t111-3*
p*q^3*t120+2*p*q^3*t121-q^3*t010*t020+q^3*t110*t121+q^3*t111*
t120-3*q^3*tinfy10*tinfy20-h*p*q^2+3*h*q^2*tinfy10+p^2*
q^2+4*p*q^2*t010+4*p*q^2*t020+p*q^2*t110-p*q^2*t111+p*q^2*t120-
p*q^2*t121+3*q^2*t010*t020-q^2*t110*t121-q^2*t111*t120+q^2*

```

```

t111*t121+3*q^2*tinfty10*tinfty20-h*q*tinfty10-p*q*t010-p*q*
t020-3*q*t010*t020-q*tinfty10*tinfty20+t010*t020)/(q*(q^2-2*
q+1));
simplify(Eq1);
simplify(Eq2);
simplify(Eq5);

```

$$a0 := -\frac{1}{q(q-1)^2} (p^2 q^6 + h p q^5 - 4 p^2 q^5 - p q^5 t010 - p q^5 t020 - p q^5 t110 \quad (2.8)$$

$$\begin{aligned}
& - p q^5 t120 - 4 h p q^4 + h q^4 \text{tinfty10} + 6 p^2 q^4 + 4 p q^4 t010 + 4 p q^4 t020 \\
& + 3 p q^4 t110 - p q^4 t111 + 3 p q^4 t120 - p q^4 t121 + q^4 \text{tinfty10 tinfty20} + 6 h p q^3 \\
& - 2 h q^3 \text{tinfty10} - 4 p^2 q^3 - 6 p q^3 t010 - 6 p q^3 t020 - 3 p q^3 t110 + 2 p q^3 t111 \\
& - 3 p q^3 t120 + 2 p q^3 t121 - 2 q^3 t010 t020 + q^3 t110 t121 + q^3 t111 t120 \\
& - 2 q^3 \text{tinfty10 tinfty20} - 4 h p q^2 + h q^2 \text{tinfty10} + p^2 q^2 + 4 p q^2 t010 + 4 p q^2 t020 \\
& + p q^2 t110 - p q^2 t111 + p q^2 t120 - p q^2 t121 + 5 q^2 t010 t020 - q^2 t110 t121 \\
& - q^2 t111 t120 + q^2 t111 t121 + q^2 \text{tinfty10 tinfty20} + h p q - p q t010 - p q t020 \\
& - 4 q t010 t020 + t010 t020)
\end{aligned}$$

$$a1 := \frac{1}{q(q-1)^2} (p^2 q^6 + h p q^5 - 4 p^2 q^5 - p q^5 t010 - p q^5 t020 - p q^5 t110 - p q^5 t120$$

$$\begin{aligned}
& - 4 h p q^4 + h q^4 \text{tinfty10} + 6 p^2 q^4 + 4 p q^4 t010 + 4 p q^4 t020 + 3 p q^4 t110 \\
& - p q^4 t111 + 3 p q^4 t120 - p q^4 t121 + q^4 \text{tinfty10 tinfty20} + 5 h p q^3 - 2 h q^3 \text{tinfty10} \\
& - 4 p^2 q^3 - 6 p q^3 t010 - 6 p q^3 t020 - 3 p q^3 t110 + 2 p q^3 t111 - 3 p q^3 t120 \\
& + 2 p q^3 t121 - 2 q^3 t010 t020 + q^3 t110 t121 + q^3 t111 t120 - 2 q^3 \text{tinfty10 tinfty20} \\
& - 2 h p q^2 + h q^2 \text{tinfty10} + p^2 q^2 + 4 p q^2 t010 + 4 p q^2 t020 + p q^2 t110 - p q^2 t111 \\
& + p q^2 t120 - p q^2 t121 + 5 q^2 t010 t020 - q^2 t110 t121 - q^2 t111 t120 + q^2 t111 t121 \\
& + q^2 \text{tinfty10 tinfty20} - p q t010 - p q t020 - 4 q t010 t020 + t010 t020)
\end{aligned}$$

$$a2 := -\frac{1}{q(q-1)^2} (p^2 q^6 + h p q^5 - 4 p^2 q^5 - p q^5 t010 - p q^5 t020 - p q^5 t110$$

$$\begin{aligned}
& - p q^5 t120 - 3 h p q^4 + h q^4 \text{tinfty10} + 6 p^2 q^4 + 4 p q^4 t010 + 4 p q^4 t020 \\
& + 3 p q^4 t110 - p q^4 t111 + 3 p q^4 t120 - p q^4 t121 + q^4 \text{tinfty10 tinfty20} + 3 h p q^3 \\
& - 3 h q^3 \text{tinfty10} - 4 p^2 q^3 - 6 p q^3 t010 - 6 p q^3 t020 - 3 p q^3 t110 + 2 p q^3 t111 \\
& - 3 p q^3 t120 + 2 p q^3 t121 - q^3 t010 t020 + q^3 t110 t121 + q^3 t111 t120 \\
& - 3 q^3 \text{tinfty10 tinfty20} - h p q^2 + 3 h q^2 \text{tinfty10} + p^2 q^2 + 4 p q^2 t010 + 4 p q^2 t020 \\
& + p q^2 t110 - p q^2 t111 + p q^2 t120 - p q^2 t121 + 3 q^2 t010 t020 - q^2 t110 t121 \\
& - q^2 t111 t120 + q^2 t111 t121 + 3 q^2 \text{tinfty10 tinfty20} - h q \text{tinfty10} - p q t010 \\
& - p q t020 - 3 q t010 t020 - q \text{tinfty10 tinfty20} + t010 t020)
\end{aligned}$$

0
0
0

```
> V:=Matrix(3,3,0):
```

```
V[1,1]:=1:
```

```
V[1,2]:=1:
```

```
V[1,3]:=0:
```

```
V[2,1]:=0:
```

```

V[2,2]:=1:
V[2,3]:=1:
V[3,1]:=1/q:
V[3,2]:=1/(q-1):
V[3,3]:=1/(q-1)^2:
V;
B:=Matrix(3,1,0):
B[1,1]:=h*p:
B[2,1]:=h*p*q +t010*t020-tinfty10*(tinfty20+h):
B[3,1]:=p^2-(P1(q)-h*1/q-h*2/(q-1))*p+tdP2(q):
B;
VectorC:=simplify(Multiply(V^(-1),B)):

```

$$\begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ \frac{1}{q} & \frac{1}{q-1} & \frac{1}{(q-1)^2} \end{bmatrix}$$

(2.9)

$$\begin{bmatrix} h & p \end{bmatrix},$$

$$\begin{bmatrix} h p q + t010 t020 - (h + tinfty20) tinfty10 \end{bmatrix},$$

$$\begin{bmatrix} p^2 - \left(\frac{t010 + t020}{q} + \frac{t111 + t121}{(q-1)^2} + \frac{t110 + t120}{q-1} - \frac{h}{q} - \frac{2h}{q-1} \right) p + \frac{t010 t020}{q^2} \\ + \frac{t111 t121}{(q-1)^4} + \frac{t110 t121 + t111 t120}{(q-1)^3} \end{bmatrix}$$

```

> factor(simplify(VectorC[1,1]-C01));
factor(simplify(VectorC[2,1]-C11));
factor(simplify(VectorC[3,1]-C12));

```

$$\begin{matrix} 0 \\ 0 \\ 0 \end{matrix}$$

(2.10)

```

> Lp:=simplify(Lp);

```

```

Lpbis:=mu*(p*diff(P1(q),q)+h*p*(1/q^2+2/(q-1)^2)-diff(tdP2(q),
q)-C01/q^2-C11/(q-1)^2-2*C12/(q-1)^3)
+h*nuMinus1*p-h*c11/(q-1)^2:
factor(simplify(Lp-Lpbis));

```

$$Lp := \frac{1}{(q-1)^3 (t111 - t121) q^2} \left(-3 p^2 (\alpha111 - \alpha121) q^7 - 2 \left(h - \frac{13}{2} p - t010 - t020 - t110 - t120 \right) (\alpha111 - \alpha121) p q^6 - (\alpha111 - \alpha121) (22 p^2 + (-7 h + 8 t010 + 8 t020 + 7 t110 - t111 + 7 t120 - t121) p + (h + tinfty20) tinfty10) q^5 + 3 (\alpha111 - \alpha121) (6 p^2 + (-3 h + 4 t010 + 4 t020 + 3 t110 - t111 + 3 t120 \right. \right. \quad (2.11)$$

$$\begin{aligned}
& -t_{121}) p + (h + t_{\infty 20}) t_{\infty 10} q^4 + \left((-7 \alpha_{11} + 7 \alpha_{21}) p^2 + 5 \left(h - \frac{8}{5} t_{010} \right. \right. \\
& \left. \left. - \frac{8}{5} t_{020} - t_{110} + \frac{3}{5} t_{111} - t_{120} + \frac{3}{5} t_{121} \right) (\alpha_{11} - \alpha_{21}) p + ((-3 t_{\infty 10} \right. \\
& \left. - t_{121}) h + (t_{120} + t_{121}) t_{111} - 3 t_{\infty 10} t_{\infty 20} + t_{010} t_{020} + t_{110} t_{121}) \alpha_{11} \right. \\
& \left. + 3 \alpha_{21} \left(\left(t_{\infty 10} + \frac{1}{3} t_{111} \right) h + \left(-\frac{1}{3} t_{120} - \frac{1}{3} t_{121} \right) t_{111} + t_{\infty 10} t_{\infty 20} \right. \right. \\
& \left. \left. - \frac{1}{3} t_{010} t_{020} - \frac{1}{3} t_{110} t_{121} \right) \right) q^3 + (p^2 (\alpha_{11} - \alpha_{21}) - (\alpha_{11} - \alpha_{21}) (h \\
& - 2 t_{010} - 2 t_{020} - t_{110} + t_{111} - t_{120} + t_{121}) p + ((t_{\infty 10} + t_{121}) h + (-t_{120} \\
& + t_{121}) t_{111} + t_{\infty 10} t_{\infty 20} - 3 t_{010} t_{020} - t_{110} t_{121}) \alpha_{11} - \alpha_{21} ((t_{\infty 10} \\
& + t_{111}) h + (-t_{120} + t_{121}) t_{111} + t_{\infty 10} t_{\infty 20} - 3 t_{010} t_{020} - t_{110} t_{121}) q^2 \\
& + 3 t_{010} t_{020} (\alpha_{11} - \alpha_{21}) q - t_{010} t_{020} (\alpha_{11} - \alpha_{21})) \\
& 0
\end{aligned}$$

We have obtained the evolution of the Darboux coordinates

$$L[q] = 2 * \mu * (p - P1(q)/2 + h/2/q + 2 * h/2/(q-1)) - h * \nu_0 - h * \nu_{\text{Minus}1} * q$$

$$L[p] = \mu * (p * \text{diff}(P1(q), q) + h * p * (1/q^2 + 2/(q-1)^2) - \text{diff}(tdP2(q), q) - C01/q^2 - C11/(q-1)^2 - 2 * C12/(q-1)^3)$$

$$+ h * \nu_{\text{Minus}1} * p - h * c11/(q-1)^2$$

```

> Hamiltonian := mu * (p^2 - P1(q) * p + h * p * (1/q + 2/(q-1)) + tdP2(q)) - h *
nu0 * p - h * nuMinus1 * q * p - h * c11 / (q-1)
- nuMinus1 * (t010 * t020 - tinfy10 * (tinfy20 + h)) :
factor(series(simplify(Lp - (-diff(Hamiltonian, q))), h=0));
simplify(Lq - (diff(Hamiltonian, p)));

```

0
0

(2.12)

Computation of $td\{L\}$ and verification of the gauge transformation

```

> simplify(checkL[1, 1]);
checkL11 := -Q2(lambda) / (lambda - 0) / (lambda - 1)^2;
simplify(checkL[1, 1] - checkL11);
simplify(checkL[1, 2]);
checkL12 := (lambda - q) / (lambda - 0) / (lambda - 1)^2;
simplify(checkL[1, 2] - checkL12);
checkL22bis := P1(lambda) + Q2(lambda) / (lambda - 0) / (lambda - 1)^2;
simplify(checkL[2, 2] - checkL22bis);
checkL21bis := h * diff(Q2(lambda) / (lambda - q), lambda) +
L[2, 1] * (lambda - 0) * (lambda - 1)^2 / (lambda - q) - P1(lambda) * Q2(lambda)
/ (lambda - q) - Q2(lambda)^2 / (lambda - q) / (lambda - 0) / (lambda - 1)^2;
simplify(checkL[2, 1] - checkL21bis);

```

(3.1)

(3.1)

$$\begin{aligned}
 & \frac{pq(q-1)^2}{\lambda(\lambda-1)^2} \\
 checkL11 & := \frac{pq(q-1)^2}{\lambda(\lambda-1)^2} \\
 & 0 \\
 & \frac{\lambda-q}{\lambda(\lambda-1)^2} \\
 checkL12 & := \frac{\lambda-q}{\lambda(\lambda-1)^2} \\
 & 0 \\
 checkL22bis & := \frac{t010+t020}{\lambda} + \frac{t111+t121}{(\lambda-1)^2} + \frac{t110+t120}{\lambda-1} - \frac{pq(q-1)^2}{\lambda(\lambda-1)^2} \\
 & 0 \\
 & 0
 \end{aligned}$$

```

> G1:=Matrix(2,2,0):
G1[1,1]:=1:
G1[1,2]:=0:
G1[2,1]:=tinfty10*lambda+eta0:
G1[2,2]:=1:

dG1dlambda:=Matrix(2,2,0):
for i from 1 to 2 do for j from 1 to 2 do dG1dlambda[i,j]:=diff
(G1[i,j],lambda): od: od:

Ltilde:=simplify(Multiply(Multiply(G1,checkL),G1^(-1))+h*
Multiply(dG1dlambda,G1^(-1))):
series(Ltilde[1,1],lambda=infinity,2);
series(Ltilde[1,2],lambda=infinity,2);
series(Ltilde[2,2],lambda=infinity,2);
series(Ltilde[2,1],lambda=infinity,2);

tinfty10+t010+t020+t110+t120-CoherenceEquation1;
factor(-residue(Ltilde[2,1]/lambda,lambda=infinity)+
CoherenceEquation1*tinfty10);
eta0:=factor(solve(factor(-residue(Ltilde[2,1],lambda=infinity)
),eta0));
eta0theo:=1/(tinfty10-tinfty20)*
-(2*0*P022+1*P132)+(0^2*C01+1^2*C11+2*1*C12)-h*p*q^2-
tinfty10*((t111+t121)+0*(t010+t020)+1*(t110+t120))
+tinfty10*(tinfty10-tinfty20-h)*(q-1*0-2*1):
factor(simplify(eta0-eta0theo+1/(t010+t020+t110+t120+2*

```

```

tinfty10)*CoherenceEquation1*eta0theo));
simplify(-residue(Ltilde[2,1]/lambda,lambda=infinity)+tinfty10*
CoherenceEquation1);
simplify(-residue(Ltilde[2,1],lambda=infinity));

```

$$\begin{aligned}
& O\left(\frac{1}{\lambda}\right) \\
& O\left(\frac{1}{\lambda^2}\right) \\
& O\left(\frac{1}{\lambda}\right) \\
& O(1) \\
& -tinfty20 \\
& 0
\end{aligned} \tag{3.2}$$

$$\begin{aligned}
\eta_0 := & (p^2 q^6 - 4 p^2 q^5 - p q^5 t_{010} - p q^5 t_{020} - p q^5 t_{110} - p q^5 t_{120} + 6 p^2 q^4 \\
& + 4 p q^4 t_{010} + 4 p q^4 t_{020} + 3 p q^4 t_{110} - p q^4 t_{111} + 3 p q^4 t_{120} - p q^4 t_{121} \\
& + q^4 tinfty10^2 - 4 p^2 q^3 - 6 p q^3 t_{010} - 6 p q^3 t_{020} - 3 p q^3 t_{110} + 2 p q^3 t_{111} \\
& - 3 p q^3 t_{120} + 2 p q^3 t_{121} - q^3 t_{110} tinfty10 - q^3 t_{111} tinfty10 - q^3 t_{120} tinfty10 \\
& - q^3 t_{121} tinfty10 - 4 q^3 tinfty10^2 + p^2 q^2 + 4 p q^2 t_{010} + 4 p q^2 t_{020} + p q^2 t_{110} \\
& - p q^2 t_{111} + p q^2 t_{120} - p q^2 t_{121} + q^2 t_{010} t_{020} + q^2 t_{110} t_{121} + 2 q^2 t_{110} tinfty10 \\
& + q^2 t_{111} t_{120} + q^2 t_{111} t_{121} + 2 q^2 t_{111} tinfty10 + 2 q^2 t_{120} tinfty10 \\
& + 2 q^2 t_{121} tinfty10 + 5 q^2 tinfty10^2 - p q t_{010} - p q t_{020} - 2 q t_{010} t_{020} - q t_{110} t_{121} \\
& - q t_{110} tinfty10 - q t_{111} t_{120} - q t_{111} tinfty10 - q t_{120} tinfty10 - q t_{121} tinfty10 \\
& - 2 q tinfty10^2 + t_{010} t_{020}) / (q (q - 1)^2 (t_{010} + t_{020} + t_{110} + t_{120} + 2 tinfty10)) \\
& 0 \\
& 0 \\
& 0
\end{aligned}$$

Expression of the Lax matrices in the geometric gauge after the symplectic reduction and the Painlevé 2 equation

Simplification of the formulas after the reduction and expression of the Lax matrices in the geometric gauge after reduction. In this case, we have $\check{q}=q$ and $\check{p}=p=td\{p\}$.

```

> t111:=1/2*t:
alpha111:=1/2:
alpha121:=-1/2:
t121:=-t111:
t020:=-t010:
t120:=-t110:
tinfty20:=-tinfty10:
q:=checkq:
p:=checkp:
simplify(CoherenceEquation1);

```



```

simplify(Trace(L));
simplify(Trace(A));
simplify(Trace(checkL));
simplify(Trace(checkA));

```

$$\begin{aligned}
& \frac{h \left(3 \text{checkq} \lambda - 2 \lambda^2 - \text{checkq} \right)}{\lambda (\lambda - 1) (-\lambda + \text{checkq})} \\
& \frac{(\text{checkq} - 1) \left(2 \text{checkp} \text{checkq}^2 - 2 \text{checkp} \text{checkq} + h \lambda \right)}{t (-\lambda + \text{checkq})} \\
& \frac{h (\text{checkq} - 1)}{t}
\end{aligned} \tag{4.1}$$

```

> Ltilde12:=Ltilde[1,2];
factor(simplify(Ltilde[2,2]+Ltilde[1,1]));
eta0bis:=-1/2/tinfty20*( checkq*(checkq-1)^2*checkp^2 -
t010^2/checkq-t^2/4/(checkq-1)^2-t/4*(4*t110+t)/(checkq-1)+
(checkq-2)*tinfty20^2
);
factor(eta0-eta0bis);

```

$$Ltilde12 := \frac{\lambda - \text{checkq}}{\lambda (\lambda - 1)^2} \tag{4.2}$$

$$\begin{aligned}
\eta_{0bis} := & \frac{1}{2} \frac{1}{\text{tinfty}10} \left(\text{checkq} (\text{checkq} - 1)^2 \text{checkp}^2 - \frac{t010^2}{\text{checkq}} - \frac{1}{4} \frac{t^2}{(\text{checkq} - 1)^2} \right. \\
& \left. - \frac{1}{4} \frac{t(4t110+t)}{\text{checkq} - 1} + (\text{checkq} - 2) \text{tinfty}10^2 \right)
\end{aligned}$$

```

> Ltilde111Order2:=factor(simplify(residue(Ltilde[1,1]*
(lambda-1),lambda=1)));
Ltilde111Order1:=factor(simplify(residue(Ltilde[1,1],lambda=1)
));
Ltilde110Order1:=factor(simplify(residue(Ltilde[1,1],lambda=0)
));
Ltilde[1,1]:
Ltilde11bis:= Ltilde111Order2/(lambda-1)^2+Ltilde111Order1/
(lambda-1)+Ltilde110Order1/lambda:
simplify(Ltilde[1,1]-Ltilde11bis);
Ltilde111Order2bis:=(checkq-1)*eta0+(checkq-1)*(checkp*checkq^2
-checkp*checkq+tinfty10):
simplify(Ltilde111Order2-Ltilde111Order2bis);
Ltilde111Order1bis:=-checkq*eta0 -checkp*checkq*(checkq-1)^2-
tinfty10:

```

```

simplify(Ltilde111Order1-Ltilde111Order1bis);
Ltilde110Order1bis:=checkq*eta0+checkp*checkq*(checkq-1)^2:
simplify(Ltilde110Order1-Ltilde110Order1bis);
0
0
0
0

```

(4.3)

```

> Ltilde211Order2:=factor(simplify(residue(Ltilde[2,1]*
(lambda-1),lambda=1))):
Ltilde211Order1:=factor(simplify(residue(Ltilde[2,1],lambda=1)
)):
Ltilde210Order1:=factor(simplify(residue(Ltilde[2,1],lambda=0)
)):
Ltilde21bis:= Ltilde211Order2/(lambda-1)^2+Ltilde211Order1/
(lambda-1)+Ltilde210Order1/lambda:
simplify(Ltilde[2,1]-Ltilde21bis);

```

```

Ltilde211Order2bis:=(checkq-1)*((eta0+checkp*checkq*(checkq-1)+
tinfy10)^2-(t111^2)/(checkq-1)^2):
simplify(Ltilde211Order2-Ltilde211Order2bis);
Ltilde211Order1bis:=-checkq*((eta0+checkp*(checkq-1)^2)^2 -
t010^2/checkq^2):
simplify(Ltilde211Order1-Ltilde211Order1bis);
Ltilde210Order1bis:=checkq*((eta0+checkp*(checkq-1)^2)^2 -
t010^2/checkq^2):
simplify(Ltilde210Order1-Ltilde210Order1bis);

```

(4.4)

```

0
0
0
0

```

```

> dqdt:=1/h*Lq:
dpdt:=simplify(1/h*Lp):
dcheckqdt:=dqdt;
dcheckpdt:=dpdt;
dG1dt:=Matrix(2,2,0):
for i from 1 to 2 do for j from 1 to 2 do dG1dt[i,j]:=diff(G1
[i,j],t)+diff(G1[i,j],checkq)*dcheckqdt+diff(G1[i,j],checkp)
*dcheckpdt: od: od:
Atilde:=simplify(Multiply(Multiply(G1,checkA),G1^(-1))+h*
Multiply(dG1dt,G1^(-1))):

```

$$dcheckqdt := \frac{2 \text{checkp} \text{checkq} (\text{checkq} - 1)^2 + h \text{checkq}^2 - h \text{checkq}}{h t} \quad (4.5)$$

$$dcheckpdt := \frac{1}{4} \frac{1}{h (\text{checkq} - 1)^3 t \text{checkq}^2} (-12 \text{checkp}^2 \text{checkq}^7 + (52 \text{checkp}^2$$

$$\begin{aligned}
& -8 \text{checkp} h) \text{checkq}^6 + (-88 \text{checkp}^2 + 28 h \text{checkp} - 4 (h \\
& - \text{tinfty10} \text{tinfty10}) \text{checkq}^5 + (72 \text{checkp}^2 - 36 h \text{checkp} + 12 (h \\
& - \text{tinfty10} \text{tinfty10}) \text{checkq}^4 + (-28 \text{checkp}^2 + 20 \text{checkp} h - 12 h \text{tinfty10} - t^2 \\
& - 4 t \text{t110} - 4 t \text{t010}^2 + 12 \text{tinfty10}^2) \text{checkq}^3 + (4 \text{checkp}^2 - 4 \text{checkp} h + 4 h \text{tinfty10} \\
& - t^2 + 4 t \text{t110} + 12 t \text{t010}^2 - 4 \text{tinfty10}^2) \text{checkq}^2 - 12 \text{checkq} t \text{t010}^2 + 4 t \text{t010}^2)
\end{aligned}$$

```

> Atilde12:=simplify(Atilde[1,2]);
simplify(Atilde[1,1]+Atilde[2,2]);

```

$$\begin{aligned}
\text{Atilde12} := & \frac{\text{checkq} - 1}{(\lambda - 1) t} \\
& - \frac{h (\text{checkq} - 1)}{t}
\end{aligned} \tag{4.6}$$

```

> Atilde111Order2:=factor(simplify(residue(Atilde[1,1]*
(lambda-1),lambda=1)));
Atilde111Order1:=factor(simplify(residue(Atilde[1,1],lambda=1)
)):
Atilde110Order1:=factor(simplify(residue(Atilde[1,1],lambda=0)
));
Atilde11OrderConstant:=factor(-simplify(residue(Atilde[1,1]
/lambda,lambda=infinity)));
Atilde[1,1]:
Atilde11bis:= Atilde111Order1/(lambda-1)+Atilde11OrderConstant:
simplify(Atilde[1,1]-Atilde11bis);
Atilde11OrderConstantbis:=-tinfty10*(checkq-1)/t:
simplify(Atilde11OrderConstant-Atilde11OrderConstantbis):
Atilde111Order1bis:=- (checkq-1) * (eta0+checkp*checkq^2
-checkp*checkq+tinfty10)/t:
simplify(Atilde111Order1-Atilde111Order1bis);

```

```

Atilde221Order2:=factor(simplify(residue(Atilde[2,2]*
(lambda-1),lambda=1)));
Atilde221Order1:=factor(simplify(residue(Atilde[2,2],lambda=1)
)):
Atilde220Order1:=factor(simplify(residue(Atilde[2,2],lambda=0)
)):
Atilde22OrderConstant:=factor(-simplify(residue(Atilde[2,2]
/lambda,lambda=infinity)));
Atilde22bis:= Atilde221Order1/(lambda-1)+Atilde22OrderConstant:
simplify(Atilde[2,2]-Atilde22bis);
Atilde22OrderConstantbis:=(tinfty10-h) * (checkq-1)/t:

```

```

simplify(Atilde22OrderConstant-Atilde22OrderConstantbis);
Atilde221Order1bis:=(checkq-1)*(eta0+checkp*checkq^2
-checkp*checkq+tinfty10)/t:
simplify(Atilde221Order1-Atilde221Order1bis);

```

$$\begin{aligned}
& \text{Atilde111Order2} := 0 \\
& \text{Atilde110Order1} := 0 \\
& \text{Atilde11OrderConstant} := -\frac{(\text{checkq} - 1) \text{tinfty10}}{t} \\
& \quad 0 \\
& \quad 0 \\
& \text{Atilde221Order2} := 0 \\
& \text{Atilde22OrderConstant} := -\frac{(\text{checkq} - 1) (h - \text{tinfty10})}{t} \\
& \quad 0 \\
& \quad 0 \\
& \quad 0
\end{aligned}$$

(4.7)

```

> Atilde211Order2:=factor(simplify(residue(Atilde[2,1]*
(lambda-1),lambda=1)));
Atilde211Order1:=factor(simplify(residue(Atilde[2,1],lambda=1)
)):
Atilde210Order1:=factor(simplify(residue(Atilde[2,1],lambda=0)
));
Atilde21OrderConstant:=factor(-simplify(residue(Atilde[2,1]
/lambda,lambda=infinity)));
Atilde[2,1]:
Atilde21bis:= Atilde211Order1/(lambda-1):
simplify(Atilde[2,1]-Atilde21bis);
Atilde211Order1bis:=- (checkq-1)/t*((eta0+checkp*checkq*
(checkq-1)+tinfty10)^2-t^2/4) - (checkq-2)*checkq*t/(4*(checkq-1)
):
factor(series(simplify(Atilde211Order1-Atilde211Order1bis),p=0)
);

```

$$\begin{aligned}
& \text{Atilde211Order2} := 0 \\
& \text{Atilde210Order1} := 0 \\
& \text{Atilde21OrderConstant} := 0 \\
& \quad 0 \\
& \quad 0
\end{aligned}$$

(4.8)