

## Study of the Second Element of the Painlevé 2 hierarchy using various Darboux coordinates and making the link explicit connections with isospectral coordinates.

Loading the Lax pair obtained for the second element of the Painlevé 2 hierarchy in "Hamiltonian representation of isomonodromic deformations of general rational connections on  $\mathbb{C}^2$  ( $\mathbb{C}$ )". In our case we have  $\tau_{\infty,i} = 2t_{\infty,i}$ . The auxiliary matrices thus also get an extra  $2$  factor because of this change of time normalization.

```
> restart;
with(LinearAlgebra):
tau2:=2*t2;
tau1:=2*t1;

tdL:=Matrix(2,2,0):
tdL[1,1]:=-lambda^3+(p1-p2)/(q1-q2)+q1^2+q2*q1+q2^2)*lambda+(-
p1*q2+p2*q1)/(q1-q2)-q1*q2*(q1+q2);
tdL[1,2]:=(lambda-q1)*(lambda-q2):
tdL[2,1]:=(tau2+(2*(p1-p2))/(q1-q2)+2*q1^2+2*q2*q1+2*q2^2)*
lambda^2+(q1+q2)*tau2+tau1+(2*(p1*q1-p2*q2))/(q1-q2)+(2*(q1+q2)
*(q1^2+q2^2))*lambda+(q1+q2)*tau1+(1/4)*tau2^2+(q1^2+q1*q2+q2^2)*
tau2-(p1-p2)^2/(q1-q2)^2-(2*(p1*q2-p2*q1))*(q1+q2)/(q1-q2)+q1^4+
q2^4-q1^2*q2^2+2*tinfinity10;
tdL[2,2]:=-tdL[1,1]:
tdL:

tdA1:=2*Matrix(2,2,[[-(1/2)*q1-(1/2)*q2-(1/2)*lambda,1/2],[
(tau2*(q1-q2)+2*q1^3-2*q2^3+2*p1-2*p2)/(2*q1-2*q2),(1/2)*q1+
(1/2)*q2+(1/2)*lambda]]);

tdA2:=2*Matrix(2,2,[[-q2^3-q1*q2^2+(lambda^2+q1^2)*q2+q1^3-
lambda^2*q1+p1-p2)/(4*q1-4*q2),(1/4)*lambda-(1/4)*q1-(1/4)*q2],
[(2*q1^4+2*lambda*q1^3+q1^2*tau2+(lambda*tau2+2*p1+tau1)*q1-2*
q2^4-2*lambda*q2^3-q2^2*tau2+(-lambda*tau2-2*p2-tau1)*q2+2*(p1-
p2)*lambda)/(4*q1-4*q2),(-q1^3-q1^2*q2+(lambda^2+q2^2)*q1+q2^3-
lambda^2*q2-p1+p2)/(4*q1-4*q2)]]);

Ham1:=2*unapply((p1^2-p2^2)/2/(q1-q2)-(1/2)*(q1+q2)*((q1^2+q2^2)
^2-q1^2*q2^2)
-1/2*(q1^2+q1*q2+q2^2)*tau1-1/2*(q1+q2)*(q1^2+q2^2)*tau2
-1/8*(q1+q2)*tau2^2-1/2*(q1+q2)*(2*tinfinity10-1),q1,q2,p1,p2);

Ham2:=2*unapply((1/4)*(q1*p2^2-q2*p1^2)/(q1-q2)+1/4*(q1^4+q1^3*
```

```

q2+q1^2*q2^2+q1*q2^3+q2^4)*q2*q1
- (1/4)*1*(p1-p2)/(q1-q2)
+(1/4*(q1+q2))*q2*q1*tau1+(1/4*(q1^2+q1*q2+q2^2))*q2*q1*
tau2+1/16*q2*q1*tau2^2
+(1/4)*q2*q1*(2*tinfty10-1), q1,q2,p1,p2);

```

```
Hinfy1:=Ham1(q1,q2,p1,p2):
```

```
Hinfy0:=2*Ham2(q1,q2,p1,p2):
```

```
omega:=1;
```

```
dq1dt1:=diff(Ham1(q1,q2,p1,p2),p1):
```

```
dq2dt1:=diff(Ham1(q1,q2,p1,p2),p2):
```

```
dp1dt1:=-diff(Ham1(q1,q2,p1,p2),q1):
```

```
dp2dt1:=-diff(Ham1(q1,q2,p1,p2),q2):
```

```
dq1dt2:=diff(Ham2(q1,q2,p1,p2),p1):
```

```
dq2dt2:=diff(Ham2(q1,q2,p1,p2),p2):
```

```
dp1dt2:=-diff(Ham2(q1,q2,p1,p2),q1):
```

```
dp2dt2:=-diff(Ham2(q1,q2,p1,p2),q2):
```

$$\tau_2 := 2 t_2$$

$$\tau_1 := 2 t_1$$

(1)

$$\begin{aligned}
t dL_{1,1} &:= -\lambda^3 + \left( \frac{p_1 - p_2}{q_1 - q_2} + q_1^2 + q_2 q_1 + q_2^2 \right) \lambda + \frac{-p_1 q_2 + p_2 q_1}{q_1 - q_2} - q_1 q_2 (q_1 + q_2) \\
t dL_{2,1} &:= \left( 2 t_2 + \frac{2 (p_1 - p_2)}{q_1 - q_2} + 2 q_1^2 + 2 q_2 q_1 + 2 q_2^2 \right) \lambda^2 + \left( 2 (q_1 + q_2) t_2 + 2 t_1 \right. \\
&\quad \left. + \frac{2 (p_1 q_1 - p_2 q_2)}{q_1 - q_2} + 2 (q_1 + q_2) (q_1^2 + q_2^2) \right) \lambda + 2 (q_1 + q_2) t_1 + t_2^2 + 2 (q_1^2 \\
&\quad + q_1 q_2 + q_2^2) t_2 - \frac{(p_1 - p_2)^2}{(q_1 - q_2)^2} - \frac{2 (p_1 q_2 - p_2 q_1) (q_1 + q_2)}{q_1 - q_2} + q_1^4 + q_2^4 \\
&\quad - q_1^2 q_2^2 + 2 \text{tinfty}10 \\
&\quad \left[ \begin{array}{cc} -q_1 - q_2 - \lambda & 1 \\ \frac{2 (2 t_2 (q_1 - q_2) + 2 q_1^3 - 2 q_2^3 + 2 p_1 - 2 p_2)}{2 q_1 - 2 q_2} & q_1 + q_2 + \lambda \end{array} \right] \\
&\quad \left[ \left[ \frac{2 (-q_2^3 - q_1 q_2^2 + (\lambda^2 + q_1^2) q_2 + q_1^3 - \lambda^2 q_1 + p_1 - p_2)}{4 q_1 - 4 q_2}, \frac{1}{2} \lambda - \frac{1}{2} q_1 - \frac{1}{2} q_2 \right], \right. \\
&\quad \left. \left[ \frac{1}{4 q_1 - 4 q_2} (2 (2 q_1^4 + 2 \lambda q_1^3 + 2 q_1^2 t_2 + (2 \lambda t_2 + 2 p_1 + 2 t_1) q_1 - 2 q_2^4) \right. \right.
\end{aligned}$$

$$-2\lambda q_2^3 - 2q_2^2 t_2 + (-2\lambda t_2 - 2p_2 - 2t_1) q_2 + 2(p_1 - p_2)\lambda),$$

$$\left. \left. \frac{2(-q_1^3 - q_1^2 q_2 + (\lambda^2 + q_2^2) q_1 + q_2^3 - \lambda^2 q_2 - p_1 + p_2)}{4q_1 - 4q_2} \right] \right]$$

$$\text{Ham1} := 2 \left( (q_1, q_2, p_1, p_2) \rightarrow \frac{1}{2} \frac{p_1^2 - p_2^2}{q_1 - q_2} - \frac{1}{2} (q_1 + q_2) ((q_2^2 + q_1^2)^2 - q_1^2 q_2^2) \right. \\ \left. - (q_1^2 + q_2 q_1 + q_2^2) t_1 - (q_1 + q_2) (q_2^2 + q_1^2) t_2 - \frac{1}{2} (q_1 + q_2) t_2^2 - \frac{1}{2} (q_1 \right. \\ \left. + q_2) (2 \text{tiny}10 - 1) \right)$$

$$\text{Ham2} := 2 \left( (q_1, q_2, p_1, p_2) \rightarrow \frac{1}{4} \frac{-p_1^2 q_2 + p_2^2 q_1}{q_1 - q_2} + \frac{1}{4} (q_1^4 + q_1^3 q_2 + q_1^2 q_2^2 + q_1 q_2^3 \right. \\ \left. + q_2^4) q_2 q_1 - \frac{1}{4} \frac{p_1 - p_2}{q_1 - q_2} + \frac{1}{2} (q_1 + q_2) q_2 q_1 t_1 + \frac{1}{2} (q_1^2 + q_2 q_1 \right. \\ \left. + q_2^2) q_2 q_1 t_2 + \frac{1}{4} q_2 q_1 t_2^2 + \frac{1}{4} q_2 q_1 (2 \text{tiny}10 - 1) \right)$$

$$\omega := 1$$

**First change of Darboux coordinates: From (q,p) to (Q,P). This change is time-independent and symplectic.**

We first compute the change of coordinates and the evolutions of the new variables Qinfy0, Qinfy1, Pinfty0, Pinfty1.

```
> solve({p1=omega*Pinfty0*q2-omega*Pinfty1,p2=omega*Pinfty0*q1-
omega*Pinfty1},{Pinfty0,Pinfty1});
q1sol:=(-Qinfy1-sqrt(Qinfy1^2-4*omega*Qinfy0))/2/omega;
q2sol:=(-Qinfy1+sqrt(Qinfy1^2-4*omega*Qinfy0))/2/omega;
p1sol:=omega*Pinfty0*q2-omega*Pinfty1;
p2sol:=omega*Pinfty0*q1-omega*Pinfty1;
simplify(Qinfy1-(-omega*(q1sol+q2sol)));
simplify(Qinfy0-(omega*q1sol*q2sol));
Qinfy1sol:=-omega*(q1+q2);
Qinfy0sol:=omega*q1*q2;
Pinfty0sol := -(p1-p2)/(q1-q2);
Pinfty1sol := -(p1*q1-p2*q2)/(q1-q2);
simplify(p1sol-(omega*Pinfty0*q2-omega*Pinfty1));
simplify(p2sol-(omega*Pinfty0*q1-omega*Pinfty1));

dQinfy1dt1inter:=unapply(simplify(diff(Qinfy1sol,q1)*
dq1dt1+diff(Qinfy1sol,q2)*dq2dt1
+diff(Qinfy1sol,p1)*dp1dt1+diff(Qinfy1sol,p2)*dp2dt1+diff
(Qinfy1sol,t1)),p1,p2);
dQinfy0dt1inter:=unapply(simplify(diff(Qinfy0sol,q1)*dq1dt1+
diff(Qinfy0sol,q2)*dq2dt1
+diff(Qinfy0sol,p1)*dp1dt1+diff(Qinfy0sol,p2)*dp2dt1+diff
```

```

(Qinfy0sol, t1), p1, p2):
dPinfty1dt1inter:=unapply( simplify( diff(Pinfy1sol, q1)*dq1dt1+
diff(Pinfy1sol, q2)*dq2dt1
+diff(Pinfy1sol, p1)*dp1dt1+diff(Pinfy1sol, p2)*dp2dt1+diff
(Pinfy1sol, t1), p1, p2):
dPinfty0dt1inter:=unapply( simplify( diff(Pinfy0sol, q1)*dq1dt1+
diff(Pinfy0sol, q2)*dq2dt1
+diff(Pinfy0sol, p1)*dp1dt1+diff(Pinfy0sol, p2)*dp2dt1+diff
(Pinfy0sol, t1), p1, p2):

dQinfy1dt1inter2:=unapply(simplify(dQinfy1dt1inter(p1sol, p2sol)
), q1, q2):
dQinfy0dt1inter2:=unapply(simplify(dQinfy0dt1inter(p1sol, p2sol)
), q1, q2):
dPinfy1dt1inter2:=unapply(simplify(dPinfy1dt1inter(p1sol, p2sol)
), q1, q2):
dPinfy0dt1inter2:=unapply(simplify(dPinfy0dt1inter(p1sol, p2sol)
), q1, q2):

dQinfy1dt1:=simplify(dQinfy1dt1inter2(q1sol, q2sol));
dQinfy0dt1:=simplify(dQinfy0dt1inter2(q1sol, q2sol));
dPinfy1dt1:=simplify(dPinfy1dt1inter2(q1sol, q2sol));
dPinfy0dt1:=simplify(dPinfy0dt1inter2(q1sol, q2sol));

dQinfy1dt2inter:=unapply( simplify( diff(Qinfy1sol, q1)*dq1dt2+
diff(Qinfy1sol, q2)*dq2dt2
+diff(Qinfy1sol, p1)*dp1dt2+diff(Qinfy1sol, p2)*dp2dt2+diff
(Qinfy1sol, t2), p1, p2):
dQinfy0dt2inter:=unapply( simplify( diff(Qinfy0sol, q1)*dq1dt2+
diff(Qinfy0sol, q2)*dq2dt2
+diff(Qinfy0sol, p1)*dp1dt2+diff(Qinfy0sol, p2)*dp2dt2+diff
(Qinfy0sol, t2), p1, p2):
dPinfy1dt2inter:=unapply( simplify( diff(Pinfy1sol, q1)*dq1dt2+
diff(Pinfy1sol, q2)*dq2dt2
+diff(Pinfy1sol, p1)*dp1dt2+diff(Pinfy1sol, p2)*dp2dt2+diff
(Pinfy1sol, t2), p1, p2):
dPinfy0dt2inter:=unapply( simplify( diff(Pinfy0sol, q1)*dq1dt2+
diff(Pinfy0sol, q2)*dq2dt2
+diff(Pinfy0sol, p1)*dp1dt2+diff(Pinfy0sol, p2)*dp2dt2+diff
(Pinfy0sol, t2), p1, p2):

```

```

dQinfy1dt2inter2:=unapply(simplify(dQinfy1dt2inter(p1sol,p2sol)
),q1,q2):
dQinfy0dt2inter2:=unapply(simplify(dQinfy0dt2inter(p1sol,p2sol)
),q1,q2):
dPinfy1dt2inter2:=unapply(simplify(dPinfy1dt2inter(p1sol,p2sol)
),q1,q2):
dPinfy0dt2inter2:=unapply(simplify(dPinfy0dt2inter(p1sol,p2sol)
),q1,q2):

```

```

dQinfy1dt2:=simplify(dQinfy1dt2inter2(q1sol,q2sol));
dQinfy0dt2:=simplify(dQinfy0dt2inter2(q1sol,q2sol));
dPinfy1dt2:=simplify(dPinfy1dt2inter2(q1sol,q2sol));
dPinfy0dt2:=simplify(dPinfy0dt2inter2(q1sol,q2sol));

```

$$\left\{ \begin{aligned} P_{infy0} &= -\frac{p1-p2}{q1-q2}, P_{infy1} = -\frac{p1q1-p2q2}{q1-q2} \end{aligned} \right\} \quad (2)$$

$$q1sol := -\frac{1}{2} Q_{infy1} - \frac{1}{2} \sqrt{Q_{infy1}^2 - 4 Q_{infy0}}$$

$$q2sol := -\frac{1}{2} Q_{infy1} + \frac{1}{2} \sqrt{Q_{infy1}^2 - 4 Q_{infy0}}$$

$$p1sol := P_{infy0} q2 - P_{infy1}$$

$$p2sol := P_{infy0} q1 - P_{infy1}$$

$$\begin{matrix} 0 \\ 0 \\ 0 \\ 0 \end{matrix}$$

$$dQ_{infy1}dt1 := 2 P_{infy0}$$

$$dQ_{infy0}dt1 := 2 P_{infy0} Q_{infy1} + 2 P_{infy1}$$

$$dP_{infy1}dt1 := -5 Q_{infy1}^4 + (-6 t2 + 12 Q_{infy0}) Q_{infy1}^2 + 4 Q_{infy1} t1 - t2^2 + 4 Q_{infy0} t2 - P_{infy0}^2 - 3 Q_{infy0}^2 - 2 t_{infy10} + 1$$

$$dP_{infy0}dt1 := 4 Q_{infy1}^3 + (4 t2 - 6 Q_{infy0}) Q_{infy1} - 2 t1$$

$$dQ_{infy1}dt2 := P_{infy0} Q_{infy1} + P_{infy1}$$

$$dQ_{infy0}dt2 := P_{infy0} Q_{infy1}^2 - P_{infy0} Q_{infy0} + P_{infy1} Q_{infy1} + \frac{1}{2}$$

$$dP_{infy1}dt2 := 3 Q_{infy0}^2 Q_{infy1} + (-2 Q_{infy1}^3 - 2 Q_{infy1} t2 + t1) Q_{infy0} - P_{infy0}^2 Q_{infy1} - P_{infy0} P_{infy1}$$

$$dP_{infy0}dt2 := -\frac{1}{2} Q_{infy1}^4 + \frac{1}{2} (-2 t2 + 6 Q_{infy0}) Q_{infy1}^2 + Q_{infy1} t1 - \frac{1}{2} t2^2 + 2 Q_{infy0} t2 + \frac{1}{2} P_{infy0}^2 - \frac{3}{2} Q_{infy0}^2 - t_{infy10} + \frac{1}{2}$$

We compute the associated Hamiltonians. Since the change of coordinates is time-independent and symplectic and since we know that (q,p) are canonical coordinates, we may simply replace the variables in the former Hamiltonians.

```

> Ham1intermediate:=unapply(simplify(Ham1(q1,q2,p1sol,p2sol)),q1,
q2):
Ham1QP:=simplify(Ham1intermediate(q1sol,q2sol)):

```

```

Ham1QPbis:=2*(Pinfty0*Pinfty1*omega^2+(1/2)*Pinfty0^2*Qinfty1*
omega+(1/2)*Qinfty1^5/omega^5+(1/2)*(omega*tau2-4*Qinfty0)*
Qinfty1^3/omega^4 -(1/2)*Qinfty1^2*tau1/omega^2+3*Qinfty0^2*
Qinfty1/2/omega^3-Qinfty0*Qinfty1*tau2/omega^2+(1/2)*Qinfty1*
(tau2^2/4+2*tinfty10-1) /omega+(1/2)*Qinfty0*tau1/omega) ;
simplify(Ham1QP-Ham1QPbis);

```

```

Ham2intermediate:=unapply( simplify(Ham2(q1,q2,p1sol,p2sol)),q1,
q2):
Ham2QP:=simplify(Ham2intermediate(q1sol,q2sol)):

```

```

Ham2QPbis:=2*( (1/4)*Pinfty1^2*omega^2+(1/2)*omega*Qinfty1*
Pinfty0*Pinfty1-(1/4)*omega*Qinfty0*Pinfty0^2 +(1/4)*Qinfty1^2*
Pinfty0^2+(1/4)*1*Pinfty0*omega+(1/4)*Qinfty0^3/omega^3-3/4*
Qinfty1^2*Qinfty0^2/omega^4-(1/4)*tau2*Qinfty0^2/omega^2+(1/4)*
Qinfty0*Qinfty1^4/omega^5+(1/4)*Qinfty0*tau2*Qinfty1^2/omega^3-
(1/4)*tau1*Qinfty0*Qinfty1/omega^2+Qinfty0*(tau2^2/4+2*
tinfty10-1)/(4*omega));
simplify(series(Ham2QP-Ham2QPbis,Qinfty1));

```

```

simplify(dQinfty1dt1-diff(Ham1QP,Pinfty1));
simplify(dQinfty0dt1-diff(Ham1QP,Pinfty0));
simplify(dPinfty1dt1-(-diff(Ham1QP,Qinfty1)));
simplify(dPinfty0dt1-(-diff(Ham1QP,Qinfty0)));

```

```

simplify(dQinfty1dt2-diff(Ham2QP,Pinfty1));
simplify(dQinfty0dt2-diff(Ham2QP,Pinfty0));
simplify(dPinfty1dt2-(-diff(Ham2QP,Qinfty1)));
simplify(dPinfty0dt2-(-diff(Ham2QP,Qinfty0)));

```

$$\begin{aligned}
Ham1QPbis := & 2 Pinfty0 Pinfty1 + Pinfty0^2 Qinfty1 + Qinfty1^5 + (2 t2 - 4 Qinfty0) Qinfty1^3 \\
& - 2 t1 Qinfty1^2 + 3 Qinfty0^2 Qinfty1 - 4 Qinfty0 Qinfty1 t2 + Qinfty1 (t2^2 + 2 tinfty10 - 1) \\
& + 2 Qinfty0 t1
\end{aligned} \tag{3}$$

$$\begin{aligned}
Ham2QPbis := & \frac{1}{2} Pinfty1^2 + Pinfty0 Pinfty1 Qinfty1 - \frac{1}{2} Pinfty0^2 Qinfty0 \\
& + \frac{1}{2} Pinfty0^2 Qinfty1^2 + \frac{1}{2} Pinfty0 + \frac{1}{2} Qinfty0^3 - \frac{3}{2} Qinfty0^2 Qinfty1^2 - Qinfty0^2 t2 \\
& + \frac{1}{2} Qinfty0 Qinfty1^4 + Qinfty0 Qinfty1^2 t2 - Qinfty0 Qinfty1 t1 + \frac{1}{2} Qinfty0 (t2^2 \\
& + 2 tinfty10 - 1)
\end{aligned}$$

0  
0  
0

0  
0  
0  
0  
0  
0

We may also verify the formula for  $Hinfy0$  and  $Hinfy1$  appearing in the computation.

```
> Hinfy1function:=unapply(Hinfy1,p1,p2):
Hinfy1intermediate:=unapply(simplify(Hinfy1function(p1sol,
p2sol)),q1,q2):
Hinfy1QP:=simplify(Hinfy1intermediate(q1sol,q2sol));
```

```
Hinfy0function:=unapply(Hinfy0,p1,p2):
Hinfy0intermediate:=unapply(simplify(Hinfy0function(p1sol,
p2sol)),q1,q2):
Hinfy0QP:=simplify(Hinfy0intermediate(q1sol,q2sol));
```

$$\begin{aligned}
Hinfy1QP &:= QinfyI^5 + (2t2 - 4Qinfy0)QinfyI^3 - 2t1QinfyI^2 + (Pinfty0^2 + 3Qinfy0^2 \\
&\quad - 4Qinfy0t2 + t2^2 + 2tinfy10 - 1)QinfyI + 2Qinfy0t1 + 2Pinfty0Pinfty1 \\
Hinfy0QP &:= Qinfy0^3 + (-3QinfyI^2 - 2t2)Qinfy0^2 + (QinfyI^4 + 2QinfyI^2t2 - Pinfty0^2 \\
&\quad - 2QinfyI t1 + t2^2 + 2tinfy10 - 1)Qinfy0 + Pinfty0^2QinfyI^2 \\
&\quad + 2Pinfty0Pinfty1QinfyI + PinftyI^2 + Pinfty0
\end{aligned} \tag{4}$$

We may also rewrite the Lax matrix in the variables (Q,P).

```
> tdL11function:=unapply(tdL[1,1],p1,p2):
tdL11intermediate:=unapply(tdL11function(p1sol,p2sol),q1,q2):
tdL11QP:=simplify(tdL11intermediate(q1sol,q2sol));
```

```
tdL12function:=unapply(tdL[1,2],p1,p2):
tdL12intermediate:=unapply(tdL12function(p1sol,p2sol),q1,q2):
tdL12QP:=simplify(tdL12intermediate(q1sol,q2sol));
```

```
tdL21function:=unapply(tdL[2,1],p1,p2):
tdL21intermediate:=unapply(tdL21function(p1sol,p2sol),q1,q2):
tdL21QP:=simplify(tdL21intermediate(q1sol,q2sol));
```

$$\begin{aligned}
tdL11QP &:= -\lambda^3 + (QinfyI^2 - Pinfty0 - Qinfy0)\lambda + (-Pinfty0 + Qinfy0)QinfyI - PinftyI \\
tdL12QP &:= QinfyI\lambda + \lambda^2 + Qinfy0 \\
tdL21QP &:= QinfyI^4 - 2QinfyI^3\lambda + (2\lambda^2 + 2Pinfty0 - 4Qinfy0 + 2t2)QinfyI^2 + ( \\
&\quad -2t2 + 4Qinfy0)\lambda - 2t1 + 2Pinfty1)QinfyI + (2t2 - 2Pinfty0 - 2Qinfy0)\lambda^2 \\
&\quad + (2t1 - 2Pinfty1)\lambda + t2^2 - 2Qinfy0t2 - Pinfty0^2 + Qinfy0^2 + 2tinfy10
\end{aligned} \tag{5}$$

Computation of the spectral invariants and verification of Theorem 5.2 relating Hamiltonians and spectral invariants

```
> assume(q1>q2):
lambdaplus:=series(simplify(series(Eigenvalues(tdL)[1],lambda=
infinity)),lambda=infinity):
```

```

CoefflambdaplusLambda3:=simplify(-residue(lambdaplus/lambda^4,
lambda=infinity));
CoefflambdaplusLambda2:=simplify(-residue(lambdaplus/lambda^3,
lambda=infinity));
CoefflambdaplusLambda1:=simplify(-residue(lambdaplus/lambda^2,
lambda=infinity));
CoefflambdaplusLambda0:=simplify(-residue(lambdaplus/lambda^1,
lambda=infinity));
CoefflambdaplusLambdaMinus1:=simplify(-residue
(lambdaplus/lambda^0,lambda=infinity));
CoefflambdaplusLambdaMinus2:=simplify(-residue(lambdaplus/lambda^
(-1),lambda=infinity));
CoefflambdaplusLambdaMinus3:=simplify(-residue(lambdaplus/lambda^
(-2),lambda=infinity));

```

```

I1:=CoefflambdaplusLambdaMinus2;
I2:=1/2*CoefflambdaplusLambdaMinus3;

```

```

I1function:=unapply(I1,p1,p2);
I2function:=unapply(I2,p1,p2);
I1inter:=unapply(I1function(p1sol,p2sol),q1,q2);
I2inter:=unapply(I2function(p1sol,p2sol),q1,q2);
I1QP:=unapply(simplify(I1inter(q1sol,q2sol)),Qinfy0,Qinfy1,
Pinfty0,Pinfty1);
I2QP:=unapply(simplify(I2inter(q1sol,q2sol)),Qinfy0,Qinfy1,
Pinfty0,Pinfty1);

```

```

simplify(Ham1QP-2*I1QP(Qinfy0,Qinfy1,Pinfty0,Pinfty1));
-residue(lambda^(-2)*tdL[1,2]*diff(tdL[1,1]/tdL[1,2],lambda),
lambda=infinity);
-Qinfy1sol;

```

```

simplify(Ham2QP-2*I2QP(Qinfy0,Qinfy1,Pinfty0,Pinfty1));
simplify(-residue(lambda^(-1)*tdL[1,2]*diff(tdL[1,1]/tdL[1,2],
lambda),lambda=infinity));
simplify(-1/2*Qinfy0sol+Pinfty0sol/2);

```

```

CoefflambdaplusLambda3 := 1
CoefflambdaplusLambda2 := 0
CoefflambdaplusLambda1 := t2
CoefflambdaplusLambda0 := t1
CoefflambdaplusLambdaMinus1 := tinfty10

```

(6)

$$II := \frac{1}{2q1\sim - 2q2\sim} (-q1\sim^6 - 2q1\sim^4 t2 - 2q1\sim^3 t1 + (-t2^2 - 2tinfty10) q1\sim^2 - 2t2 t1 q1\sim$$



$$I2 := \frac{1}{2} \frac{1}{2 q1\sim - 2 q2\sim} (q1\sim^6 q2\sim + 2 q1\sim^4 q2\sim t2 + 2 q1\sim^3 q2\sim t1 + (t2^2 + 2 \text{tiny}10) q2\sim^2 + 2 t2 t1 q2\sim + p1^2 - p2^2) \\ + 2 \text{tiny}10) q2\sim q1\sim^2 + (-q2\sim^6 - 2 q2\sim^4 t2 - 2 q2\sim^3 t1 + (-t2^2 - 2 \text{tiny}10) q2\sim^2 \\ + p2^2 - t1^2 - 2 \text{tiny}10 t2) q1\sim - q2\sim (p1^2 - t1^2 - 2 t2 \text{tiny}10)$$

$$IIQP := (Q\text{infty}0, Q\text{infty}1, P\text{infty}0, P\text{infty}1) \rightarrow \frac{1}{2} Q\text{infty}I^5 + \frac{1}{2} (2 t2 - 4 Q\text{infty}0) Q\text{infty}I^3 \\ - Q\text{infty}I^2 t1 + \frac{1}{2} (P\text{infty}0^2 + 3 Q\text{infty}0^2 - 4 Q\text{infty}0 t2 + t2^2 + 2 \text{tiny}10) Q\text{infty}1 - t2 t1 \\ + Q\text{infty}0 t1 + P\text{infty}0 P\text{infty}1$$

$$I2QP := (Q\text{infty}0, Q\text{infty}1, P\text{infty}0, P\text{infty}1) \rightarrow \frac{1}{4} Q\text{infty}0^3 + \frac{1}{4} (-3 Q\text{infty}I^2 - 2 t2) Q\text{infty}0^2 \\ + \frac{1}{4} (Q\text{infty}I^4 + 2 Q\text{infty}I^2 t2 - P\text{infty}0^2 - 2 Q\text{infty}1 t1 + t2^2 + 2 \text{tiny}10) Q\text{infty}0 \\ + \frac{1}{4} P\text{infty}0^2 Q\text{infty}I^2 + \frac{1}{2} P\text{infty}0 P\text{infty}1 Q\text{infty}1 - \frac{1}{4} t1^2 - \frac{1}{2} \text{tiny}10 t2 \\ + \frac{1}{4} P\text{infty}1^2$$

$$\frac{2 t1 t2 - Q\text{infty}1}{q1\sim + q2\sim} \\ \frac{q1\sim + q2\sim}{q1\sim + q2\sim} \\ - \frac{1}{2} Q\text{infty}0 + \frac{1}{2} P\text{infty}0 + \frac{1}{2} t1^2 + \text{tiny}10 t2 \\ \frac{-q1\sim^2 q2\sim + q1\sim q2\sim^2 - p1 + p2}{q1\sim - q2\sim} \\ \frac{-q1\sim^2 q2\sim + q1\sim q2\sim^2 - p1 + p2}{2 q1\sim - 2 q2\sim}$$

## Second change of Darboux coordinates: From (Q,P) to (Q,R).

Definition of the change of coordinates and its inverse. This change is time-independent but not symplectic so the evolutions are not canonically

```
> Pinfty0sol2 := Qinfty1^2 - Qinfty0 - Rinfty1;
Pinfty1sol2 := -Qinfty1^3 + 2*Qinfty0*Qinfty1 + Qinfty1*Rinfty1 -
Rinfty0;
simplify(Rinfty1 - (-Pinfty0sol2 - Qinfty0 + Qinfty1^2));
simplify(Rinfty0 - (-Pinfty1sol2 - Pinfty0sol2*Qinfty1 + Qinfty0*
Qinfty1));
Rinfty1sol := -Pinfty0 - Qinfty0 + Qinfty1^2;
Rinfty0sol := -Pinfty1 - Pinfty0*Qinfty1 + Qinfty0*Qinfty1;
```

$$Pinfty0sol2 := Q\text{infty}I^2 - Q\text{infty}0 - R\text{infty}1 \\ Pinfty1sol2 := -Q\text{infty}I^3 + 2 Q\text{infty}0 Q\text{infty}1 + Q\text{infty}1 R\text{infty}1 - R\text{infty}0 \\ 0 \\ 0$$

$$R\text{infty}1sol := Q\text{infty}I^2 - P\text{infty}0 - Q\text{infty}0 \\ R\text{infty}0sol := -P\text{infty}0 Q\text{infty}1 + Q\text{infty}0 Q\text{infty}1 - P\text{infty}1$$

Expression of the Lax matrix in the coordinates (Q,R).

```
> tdL11QPfunction := unapply( tdL11QP, Pinfty0, Pinfty1 );
```

(7)

```

tdL11QR:=simplify( tdL11QPfunction(Pinfty0sol2,Pinfty1sol2));
tdL12QPfunction:=unapply( tdL12QP,Pinfty0,Pinfty1);
tdL12QR:=simplify( tdL12QPfunction(Pinfty0sol2,Pinfty1sol2));
tdL21QPfunction:=unapply( tdL21QP,Pinfty0,Pinfty1);
tdL21QR:=simplify( tdL21QPfunction(Pinfty0sol2,Pinfty1sol2));

```

$$tdL11QR := -\lambda^3 + Rinfy1 \lambda + Rinfy0$$

$$tdL12QR := Qinfy1 \lambda + \lambda^2 + Qinfy0$$

$$tdL21QR := (2 t2 + 2 Rinfy1) Qinfy1^2 + ((-2 t2 - 2 Rinfy1) \lambda - 2 t1 - 2 Rinfy0) Qinfy1 + (2 t2 + 2 Rinfy1) \lambda^2 + (2 t1 + 2 Rinfy0) \lambda + t2^2 - 2 Qinfy0 t2 - 2 Qinfy0 Rinfy1 - Rinfy1^2 + 2 tinfy10$$

(8)

Computation of the evolutions of Rinfy0 and Rinfy1.

```

> dRinfy1dtlinter:=unapply( simplify( diff(Rinfy1sol,Qinfy1)
*dQinfy1dt1+ diff(Rinfy1sol,Qinfy0)*dQinfy0dt1+diff
(Rinfy1sol,Pinfty1)*dPinfty1dt1+diff(Rinfy1sol,Pinfty0)
*dPinfty0dt1+diff(Rinfy1sol,t1) ),Pinfty0,Pinfty1);
dRinfy0dtlinter:=unapply(simplify( diff(Rinfy0sol,Qinfy1)*
dQinfy1dt1+ diff(Rinfy0sol,Qinfy0)*dQinfy0dt1+diff
(Rinfy0sol,Pinfty1)*dPinfty1dt1+diff(Rinfy0sol,Pinfty0)*
dPinfty0dt1+diff(Rinfy0sol,t1) ),Pinfty0,Pinfty1);
dQinfy1dtlinter:=unapply(dQinfy1dt1 ,Pinfty0,Pinfty1);
dQinfy0dtlinter:=unapply(dQinfy0dt1 ,Pinfty0,Pinfty1);

```

```

dRinfy1dt1:=simplify(dRinfy1dtlinter(Pinfty0sol2,Pinfty1sol2));
dRinfy0dt1:=simplify(dRinfy0dtlinter(Pinfty0sol2,Pinfty1sol2));
dQinfy1QRdt1:=simplify(dQinfy1dtlinter(Pinfty0sol2,Pinfty1sol2)
);

```

```

dQinfy0QRdt1:=simplify(dQinfy0dtlinter(Pinfty0sol2,Pinfty1sol2)
);

```

$$dRinfy1dt1 := (-4 t2 - 4 Rinfy1) Qinfy1 + 2 t1 + 2 Rinfy0$$

$$dRinfy0dt1 := (2 t2 + 2 Rinfy1) Qinfy1^2 + (-2 t1 - 2 Rinfy0) Qinfy1 + t2^2 - 4 Qinfy0 t2 - 4 Qinfy0 Rinfy1 - Rinfy1^2 + 2 tinfy10 - 1$$

$$dQinfy1QRdt1 := 2 Qinfy1^2 - 2 Qinfy0 - 2 Rinfy1$$

$$dQinfy0QRdt1 := 2 Qinfy0 Qinfy1 - 2 Rinfy0$$

(9)

Rewriting of the quantities in terms of the coordinates (Q,R)

```

> tdA1function11:=unapply(tdA1[1,1],p1,p2):
tdA1function12:=unapply(tdA1[1,2],p1,p2):
tdA1function21:=unapply(tdA1[2,1],p1,p2):
tdA1function22:=unapply(tdA1[2,2],p1,p2):
tdA1QPintermediate11:=unapply(tdA1function11(p1sol,p2sol),q1,q2):
tdA1QPintermediate12:=unapply(tdA1function12(p1sol,p2sol),q1,q2):
tdA1QPintermediate21:=unapply(tdA1function21(p1sol,p2sol),q1,q2):
tdA1QPintermediate22:=unapply(tdA1function22(p1sol,p2sol),q1,q2):

```

```
tdA1QP:=Matrix(2,2,0):
tdA1QP[1,1]:=simplify(tdA1QPintermediate11(q1sol,q2sol)):
tdA1QP[1,2]:=simplify(tdA1QPintermediate12(q1sol,q2sol)):
tdA1QP[2,1]:=simplify(tdA1QPintermediate21(q1sol,q2sol)):
tdA1QP[2,2]:=simplify(tdA1QPintermediate22(q1sol,q2sol)):
tdA1QP;
```

```
tdA2function11:=unapply(tdA2[1,1],p1,p2):
tdA2function12:=unapply(tdA2[1,2],p1,p2):
tdA2function21:=unapply(tdA2[2,1],p1,p2):
tdA2function22:=unapply(tdA2[2,2],p1,p2):
tdA2QPintermediate11:=unapply(tdA2function11(p1sol,p2sol),q1,q2):
tdA2QPintermediate12:=unapply(tdA2function12(p1sol,p2sol),q1,q2):
tdA2QPintermediate21:=unapply(tdA2function21(p1sol,p2sol),q1,q2):
tdA2QPintermediate22:=unapply(tdA2function22(p1sol,p2sol),q1,q2):
tdA2QP:=Matrix(2,2,0):
tdA2QP[1,1]:=simplify(tdA2QPintermediate11(q1sol,q2sol)):
tdA2QP[1,2]:=simplify(tdA2QPintermediate12(q1sol,q2sol)):
tdA2QP[2,1]:=simplify(tdA2QPintermediate21(q1sol,q2sol)):
tdA2QP[2,2]:=simplify(tdA2QPintermediate22(q1sol,q2sol)):
tdA2QP;
```

```
tdA1QRfunction11:=unapply(tdA1QP[1,1],Pinfty0,Pinfty1):
tdA1QRfunction12:=unapply(tdA1QP[1,2],Pinfty0,Pinfty1):
tdA1QRfunction21:=unapply(tdA1QP[2,1],Pinfty0,Pinfty1):
tdA1QRfunction22:=unapply(tdA1QP[2,2],Pinfty0,Pinfty1):
```

```
tdA1QR:=Matrix(2,2,0):
tdA1QR[1,1]:=simplify(tdA1QRfunction11(Pinfty0sol2,Pinfty1sol2)):
tdA1QR[1,2]:=simplify(tdA1QRfunction12(Pinfty0sol2,Pinfty1sol2)):
tdA1QR[2,1]:=simplify(tdA1QRfunction21(Pinfty0sol2,Pinfty1sol2)):
tdA1QR[2,2]:=simplify(tdA1QRfunction22(Pinfty0sol2,Pinfty1sol2)):
tdA1QR;
```

```
tdA2QRfunction11:=unapply(tdA2QP[1,1],Pinfty0,Pinfty1):
tdA2QRfunction12:=unapply(tdA2QP[1,2],Pinfty0,Pinfty1):
tdA2QRfunction21:=unapply(tdA2QP[2,1],Pinfty0,Pinfty1):
tdA2QRfunction22:=unapply(tdA2QP[2,2],Pinfty0,Pinfty1):
```

```
tdA2QR:=Matrix(2,2,0):
tdA2QR[1,1]:=simplify(tdA2QRfunction11(Pinfty0sol2,Pinfty1sol2)):
tdA2QR[1,2]:=simplify(tdA2QRfunction12(Pinfty0sol2,Pinfty1sol2)):
```

```

tdA2QR[2,1]:=simplify(tdA2QRfunction21(Pinfy0sol2,Pinfy1sol2)):
tdA2QR[2,2]:=simplify(tdA2QRfunction22(Pinfy0sol2,Pinfy1sol2)):
tdA2QR;

```

```

tdLQR:=Matrix(2,2,0):
tdLQR[1,1]:=tdL11QR:
tdLQR[1,2]:=tdL12QR:
tdLQR[2,1]:=simplify(tdL21QR):
tdLQR[2,2]:=-tdLQR[1,1]:
tdLQR;

```

$$\begin{aligned}
& \begin{bmatrix} Q_{infy1} - \lambda & 1 \\ 2 Q_{infy1}^2 - 2 P_{infy0} - 2 Q_{infy0} + 2 t2 & -Q_{infy1} + \lambda \end{bmatrix} \\
& \left[ \left[ \frac{1}{2} Q_{infy1}^2 - \frac{1}{2} \lambda^2 - \frac{1}{2} P_{infy0}, \frac{1}{2} \lambda + \frac{1}{2} Q_{infy1} \right], \right. \\
& \left. \left[ -Q_{infy1}^3 + Q_{infy1}^2 \lambda + (-t2 + 2 Q_{infy0}) Q_{infy1} + (t2 - P_{infy0} - Q_{infy0}) \lambda + t1 \right. \right. \\
& \left. \left. - P_{infy1}, -\frac{1}{2} Q_{infy1}^2 + \frac{1}{2} \lambda^2 + \frac{1}{2} P_{infy0} \right] \right] \\
& \begin{bmatrix} Q_{infy1} - \lambda & 1 \\ 2 t2 + 2 R_{infy1} & -Q_{infy1} + \lambda \end{bmatrix} \\
& \left[ \left[ -\frac{1}{2} \lambda^2 + \frac{1}{2} Q_{infy0} + \frac{1}{2} R_{infy1}, \frac{1}{2} \lambda + \frac{1}{2} Q_{infy1} \right], \right. \\
& \left. \left[ (-t2 - R_{infy1}) Q_{infy1} + \lambda t2 + R_{infy1} \lambda + t1 + R_{infy0}, \frac{1}{2} \lambda^2 - \frac{1}{2} Q_{infy0} \right. \right. \\
& \left. \left. - \frac{1}{2} R_{infy1} \right] \right] \\
& \left[ \left[ -\lambda^3 + R_{infy1} \lambda + R_{infy0}, Q_{infy1} \lambda + \lambda^2 + Q_{infy0} \right], \right. \\
& \left. \left[ (2 t2 + 2 R_{infy1}) Q_{infy1}^2 + ((-2 t2 - 2 R_{infy1}) \lambda - 2 t1 - 2 R_{infy0}) Q_{infy1} + (2 t2 \right. \right. \\
& \left. \left. + 2 R_{infy1}) \lambda^2 + (2 t1 + 2 R_{infy0}) \lambda + t2^2 - 2 Q_{infy0} t2 - 2 Q_{infy0} R_{infy1} - R_{infy1}^2 \right. \right. \\
& \left. \left. + 2 tinfy10, \lambda^3 - R_{infy1} \lambda - R_{infy0} \right] \right]
\end{aligned} \tag{10}$$

```

> lambdaplusQR:=series(simplify(series(Eigenvalues(tdLQR)[1],
lambda=infinity)),lambda=infinity):
CoefflambdaplusLambda3QR:=simplify(-residue
(lambdaplusQR/lambda^4,lambda=infinity));
CoefflambdaplusLambda2QR:=simplify(-residue
(lambdaplusQR/lambda^3,lambda=infinity));
CoefflambdaplusLambda1QR:=simplify(-residue
(lambdaplusQR/lambda^2,lambda=infinity));
CoefflambdaplusLambda0QR:=simplify(-residue
(lambdaplusQR/lambda^1,lambda=infinity));
CoefflambdaplusLambdaMinus1QR:=simplify(-residue

```

```

(lambdaplusQR/lambda^0,lambda=infinity));
CoefflambdaplusLambdaMinus2QR:=simplify(-residue
(lambdaplusQR/lambda^(-1),lambda=infinity)):
CoefflambdaplusLambdaMinus3QR:=simplify(-residue
(lambdaplusQR/lambda^(-2),lambda=infinity)):

I1QR:=expand(CoefflambdaplusLambdaMinus2QR);
I2QR:=expand(1/2*CoefflambdaplusLambdaMinus3QR);
      CoefflambdaplusLambda3QR := 1
      CoefflambdaplusLambda2QR := 0
      CoefflambdaplusLambda1QR := t2
      CoefflambdaplusLambda0QR := t1
      CoefflambdaplusLambdaMinus1QR := tinfty10
IIQR := QinftyI^3 Rinfty1 + t2 QinftyI^3 - 2 Qinfty0 Qinfty1 Rinfty1 - 2 Qinfty0 Qinfty1 t2
      - QinftyI^2 Rinfty0 - t1 QinftyI^2 - 1/2 Qinfty1 RinftyI^2 + 1/2 t2^2 Qinfty1 + Qinfty0 Rinfty0
      + Qinfty0 t1 + tinfty10 Qinfty1 + Rinfty0 Rinfty1 - t2 t1
I2QR := -1/2 Qinfty0^2 Rinfty1 - 1/2 Qinfty0^2 t2 + 1/2 Qinfty0 QinftyI^2 Rinfty1
      + 1/2 Qinfty0 QinftyI^2 t2 - 1/2 Qinfty0 Qinfty1 Rinfty0 - 1/2 Qinfty0 Qinfty1 t1
      - 1/4 Qinfty0 RinftyI^2 + 1/4 Qinfty0 t2^2 + 1/2 Qinfty0 tinfty10 - 1/4 tI^2 - 1/2 tinfty10 t2
      + 1/4 Rinfty0^2

```

(11)

### Third change of Darboux coordinates: from (Q,R) to (u,v)

Definition of the isospectral coordinates

```

> Qinfty1:=uinfty1;
Qinfty0:=uinfty0+t2/2;
Rinfty1:=-t2+vinfty1;
Rinfty0:=-t1+vinfty0;
tdLuv:=simplify(tdLQR);
I1uv:=simplify(I1QR);
I2uv:=simplify(I2QR);
      Qinfty1 := uinfty1
      Qinfty0 := uinfty0 + 1/2 t2
      Rinfty1 := -t2 + vinfty1
      Rinfty0 := -t1 + vinfty0
[[ [-lambda^3 + (-t2 + vinfty1) lambda - t1 + vinfty0, uinfty1 lambda + lambda^2 + uinfty0 + 1/2 t2 ],
  [ -vinftyI^2 + (2 lambda^2 - 2 lambda uinfty1 + 2 uinftyI^2 + t2 - 2 uinfty0) vinfty1 + 2 vinfty0 lambda
    - 2 uinfty1 vinfty0 + 2 tinfty10, lambda^3 + (t2 - vinfty1) lambda + t1 - vinfty0 ] ]
I1uv := uinftyI^3 vinfty1 - uinftyI^2 vinfty0 + 1/2 (-4 uinfty0 vinfty1 - vinftyI^2

```

(12)

$$\begin{aligned}
& + 2 \text{tiny}10) \text{uinfy}1 + \frac{1}{2} (-2 t1 + 2 \text{vinfy}0) \text{vinfy}1 - \frac{1}{2} \text{vinfy}0 (t2 - 2 \text{uinfy}0) \\
I2uv := & \frac{1}{8} (-t2 - 2 \text{uinfy}0) \text{vinfy}1^2 + \frac{1}{8} (t2 + 2 \text{uinfy}0) (2 \text{uinfy}1^2 + t2 \\
& - 2 \text{uinfy}0) \text{vinfy}1 + \frac{1}{8} (-4 \text{uinfy}1 \text{vinfy}0 + 4 \text{tiny}10) \text{uinfy}0 + \frac{1}{8} ( \\
& -2 \text{uinfy}1 \text{vinfy}0 - 2 \text{tiny}10) t2 - \frac{1}{2} t1 \text{vinfy}0 + \frac{1}{4} \text{vinfy}0^2
\end{aligned}$$

```

> tdA1uv:=simplify(tdA1QR);
tdA2uv:=simplify(tdA2QR);

dtdA1uvdlambda:=Matrix(2,2,0):
for i from 1 to 2 do for j from 1 to 2 do dtdA1uvdlambda[i,j]:=
diff(tdA1uv[i,j],lambda): od: od:
dtdA2uvdlambda:=Matrix(2,2,0):
for i from 1 to 2 do for j from 1 to 2 do dtdA2uvdlambda[i,j]:=
diff(tdA2uv[i,j],lambda): od: od:
dtdA1uvdlambda:
dtdA2uvdlambda:

dtdLuvdt1:=Matrix(2,2,0):
for i from 1 to 2 do for j from 1 to 2 do dtdLuvdt1[i,j]:=
simplify(
diff(tdLuv[i,j],uinfy0)*duinfy0dt1+diff(tdLuv[i,j],uinfy1)*
duinfy1dt1+diff(tdLuv[i,j],vinfy0)*dvinfy0dt1+diff(tdLuv[i,j],
vinfy1)*dvinfy1dt1 +diff(tdLuv[i,j],t1)
): od: od:

dtdLuvdt2:=Matrix(2,2,0):
for i from 1 to 2 do for j from 1 to 2 do dtdLuvdt2[i,j]:=
diff(tdLuv[i,j],uinfy0)*duinfy0dt2+diff(tdLuv[i,j],uinfy1)*
duinfy1dt2+diff(tdLuv[i,j],vinfy0)*dvinfy0dt2+diff(tdLuv[i,j],
vinfy1)*dvinfy1dt2 +diff(tdLuv[i,j],t2): od: od:

CompatibilityEquation1:=simplify(dtdLuvdt1-dtdA1uvdlambda+
Multiply(tdLuv,tdA1uv)-Multiply(tdA1uv,tdLuv)):
CompatibilityEquation2:=simplify(dtdLuvdt2-dtdA2uvdlambda+
Multiply(tdLuv,tdA2uv)-Multiply(tdA2uv,tdLuv)):

```

$$\begin{bmatrix} \text{uinfy}1 - \lambda & 1 \\ 2 \text{vinfy}1 & -\text{uinfy}1 + \lambda \end{bmatrix}$$

(13)

$$\begin{bmatrix} -\frac{1}{2}\lambda^2 + \frac{1}{2}u_{\infty 0} - \frac{1}{4}t^2 + \frac{1}{2}v_{\infty 1} & \frac{1}{2}\lambda + \frac{1}{2}u_{\infty 1} \\ (-u_{\infty 1} + \lambda)v_{\infty 1} + v_{\infty 0} & \frac{1}{2}\lambda^2 - \frac{1}{2}u_{\infty 0} + \frac{1}{4}t^2 - \frac{1}{2}v_{\infty 1} \end{bmatrix}$$

Computation of the evolutions of the Darboux coordinates (u,v)

```

> simplify(series(CompatibilityEquation1[1,1],lambda=0));
simplify(series(CompatibilityEquation1[1,2],lambda=0));
simplify(series(CompatibilityEquation1[2,1],lambda=0));
simplify(series(CompatibilityEquation1[2,2]
+CompatibilityEquation1[1,1],lambda=0));
dvinfty1dt1:=-4*uinfty1*viny1+2*viny0;
dvinfty0dt1:=-viny1^2+2*(uinfty1^2-2*uinfty0)*viny1-2*
uinfty1*viny0+2*tiny10;
duinfty1dt1:=2*uinfty1^2+t2-2*uinfty0-2*viny1;
duinfty0dt1:=(t2+2*uinfty0)*uinfty1+2*t1-2*viny0;
simplify(series(CompatibilityEquation1[1,1],lambda=0));
simplify(series(CompatibilityEquation1[1,2],lambda=0));
simplify(series(CompatibilityEquation1[2,1],lambda=0));
simplify(series(CompatibilityEquation1[2,2]+
CompatibilityEquation1[1,1],lambda=0));

simplify(series(CompatibilityEquation2[1,1],lambda=0));
simplify(series(CompatibilityEquation2[1,2],lambda=0));
simplify(series(CompatibilityEquation2[2,1],lambda=0));
simplify(series(CompatibilityEquation2[2,2]+
CompatibilityEquation2[1,1],lambda=0));

dvinfty1dt2:=viny1*uinfty1^2-uinfty1*viny0-(1/2)*viny1^2-2*
uinfty0*viny1+tiny10;
dvinfty0dt2:=uinfty1^3*viny1-uinfty1^2*viny0-(1/2)*(-2*t2*
viny1+viny1^2-2*tiny10)*uinfty1-(1/2)*(t2+2*uinfty0)*
viny0;
duinfty1dt2:=(1/2)*(t2+2*uinfty0)*uinfty1+t1-viny0;
duinfty0dt2:=(t1-viny0)*uinfty1-(1/4)*t2^2+(1/2)*t2*viny1+
uinfty0^2+uinfty0*viny1;

simplify(series(CompatibilityEquation2[1,1],lambda=0));
simplify(series(CompatibilityEquation2[1,2],lambda=0));
simplify(series(CompatibilityEquation2[2,1],lambda=0));
simplify(series(CompatibilityEquation2[2,2]+
CompatibilityEquation2[1,1],lambda=0));

```

$$\begin{aligned}
d\text{vinfty1dt1} &:= -4 \text{uinfty1 vinfty1} + 2 \text{vinfty0} \\
d\text{vinfty0dt1} &:= -\text{vinfty1}^2 + 2 (\text{uinfty1}^2 - 2 \text{uinfty0}) \text{vinfty1} - 2 \text{uinfty1 vinfty0} + 2 \text{tinfty10} \\
d\text{uinfty1dt1} &:= 2 \text{uinfty1}^2 + t2 - 2 \text{uinfty0} - 2 \text{vinfty1} \\
d\text{uinfty0dt1} &:= (t2 + 2 \text{uinfty0}) \text{uinfty1} + 2 t1 - 2 \text{vinfty0} \\
&0 \\
&0 \\
&0 \\
&0 \\
&0 \\
d\text{vinfty1dt2} &:= \text{vinfty1 uinfty1}^2 - \text{uinfty1 vinfty0} - \frac{1}{2} \text{vinfty1}^2 - 2 \text{uinfty0 vinfty1} + \text{tinfty10} \\
d\text{vinfty0dt2} &:= \text{uinfty1}^3 \text{vinfty1} - \text{uinfty1}^2 \text{vinfty0} - \frac{1}{2} (-2 t2 \text{vinfty1} + \text{vinfty1}^2 \\
&- 2 \text{tinfty10}) \text{uinfty1} - \frac{1}{2} (t2 + 2 \text{uinfty0}) \text{vinfty0} \\
d\text{uinfty1dt2} &:= \frac{1}{2} (t2 + 2 \text{uinfty0}) \text{uinfty1} + t1 - \text{vinfty0} \\
d\text{uinfty0dt2} &:= (t1 - \text{vinfty0}) \text{uinfty1} - \frac{1}{4} t2^2 + \frac{1}{2} t2 \text{vinfty1} + \text{uinfty0}^2 + \text{uinfty0 vinfty1} \\
&0 \\
&0 \\
&0 \\
&0
\end{aligned}$$

Verification of the isospectral condition  $\delta_t[\text{L}] = \partial_{\lambda} \text{td}\{A\}$

```

> diff(tdLuv[1,1],t1)-dtdA1uvdlambda[1,1];
diff(tdLuv[1,2],t1)-dtdA1uvdlambda[1,2];
diff(tdLuv[2,1],t1)-dtdA1uvdlambda[2,1];
diff(tdLuv[2,2],t1)-dtdA1uvdlambda[2,2];

diff(tdLuv[1,1],t2)-dtdA2uvdlambda[1,1];
diff(tdLuv[1,2],t2)-dtdA2uvdlambda[1,2];
diff(tdLuv[2,1],t2)-dtdA2uvdlambda[2,1];
diff(tdLuv[2,2],t2)-dtdA2uvdlambda[2,2];
0
0
0
0
0
0
0
0
0

```

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**Final change of coordinates to obtain a canonical set of isospectral coordinates  $(x_2, x_3, y_2, y_3)$  inspired by Appendix A of "Hamiltonian structure of rational isomonodromic deformation systems" by Bertola, Harnad and Hurtubise.**

Definition of the change of Darboux coordinates.



```

> y2sol:=alpha*vinfy1;
x3sol:=-beta*uinfy1;
x2sol:=delta*uinfy0+epsilon*vinfy1;
y3sol:=mu*vinfy0-nu*uinfy1*vinfy1;
solve({y2=y2sol,y3=y3sol,x2=x2sol,x3=x3sol},{uinfy0,uinfy1,
vinfy0,vinfy1});
uinfy0sol :=(alpha*x2-epsilon*y2)/(alpha*delta);
uinfy1sol :=-x3/beta;
vinfy0sol :=(alpha*beta*y3-nu*x3*y2)/(alpha*beta*mu);
vinfy1sol :=y2/alpha;

dy2dt1function:=unapply( simplify(diff(y2sol,uinfy0)*
duinfy0dt1+diff(y2sol,uinfy1)*duinfy1dt1+diff(y2sol,vinfy0)*
dvinfy0dt1+diff(y2sol,vinfy1)*dvinfy1dt1), uinfy0,uinfy1,
vinfy0,vinfy1):
dy3dt1function:=unapply( simplify(diff(y3sol,uinfy0)*
duinfy0dt1+diff(y3sol,uinfy1)*duinfy1dt1+diff(y3sol,vinfy0)*
dvinfy0dt1+diff(y3sol,vinfy1)*dvinfy1dt1), uinfy0,uinfy1,
vinfy0,vinfy1):
dx2dt1function:=unapply( simplify(diff(x2sol,uinfy0)*
duinfy0dt1+diff(x2sol,uinfy1)*duinfy1dt1+diff(x2sol,vinfy0)*
dvinfy0dt1+diff(x2sol,vinfy1)*dvinfy1dt1), uinfy0,uinfy1,
vinfy0,vinfy1):
dx3dt1function:=unapply( simplify(diff(x3sol,uinfy0)*
duinfy0dt1+diff(x3sol,uinfy1)*duinfy1dt1+diff(x3sol,vinfy0)*
dvinfy0dt1+diff(x3sol,vinfy1)*dvinfy1dt1), uinfy0,uinfy1,
vinfy0,vinfy1):

dy2dt1:=simplify(dy2dt1function(uinfy0sol,uinfy1sol,
vinfy0sol,vinfy1sol)):
dy3dt1:=simplify(dy3dt1function(uinfy0sol,uinfy1sol,vinfy0sol,
vinfy1sol)):
dx2dt1:=simplify(dx2dt1function(uinfy0sol,uinfy1sol,vinfy0sol,
vinfy1sol)):
dx3dt1:=simplify(dx3dt1function(uinfy0sol,uinfy1sol,vinfy0sol,
vinfy1sol)):

dy2dt2function:=unapply( simplify(diff(y2sol,uinfy0)*
duinfy0dt2+diff(y2sol,uinfy1)*duinfy1dt2+diff(y2sol,vinfy0)*
dvinfy0dt2+diff(y2sol,vinfy1)*dvinfy1dt2), uinfy0,uinfy1,
vinfy0,vinfy1):
dy3dt2function:=unapply( simplify(diff(y3sol,uinfy0)*

```

```

duinfty0dt2+diff(y3sol,uinfty1)*duinfty1dt2+diff(y3sol,vinfty0)*
dvinfty0dt2+diff(y3sol,vinfty1)*dvinfty1dt2), uinfty0,uinfty1,
vinfty0,vinfty1):
dx2dt2function:=unapply( simplify(diff(x2sol,uinfty0)*
duinfty0dt2+diff(x2sol,uinfty1)*duinfty1dt2+diff(x2sol,vinfty0)*
dvinfty0dt2+diff(x2sol,vinfty1)*dvinfty1dt2), uinfty0,uinfty1,
vinfty0,vinfty1):
dx3dt2function:=unapply( simplify(diff(x3sol,uinfty0)*
duinfty0dt2+diff(x3sol,uinfty1)*duinfty1dt2+diff(x3sol,vinfty0)*
dvinfty0dt2+diff(x3sol,vinfty1)*dvinfty1dt2), uinfty0,uinfty1,
vinfty0,vinfty1):

dy2dt2:=simplify(dy2dt2function(uinfty0sol,uinfty1sol,vinfty0sol,
vinfty1sol)):
dy3dt2:=simplify(dy3dt2function(uinfty0sol,uinfty1sol,vinfty0sol,
vinfty1sol)):
dx2dt2:=simplify(dx2dt2function(uinfty0sol,uinfty1sol,vinfty0sol,
vinfty1sol)):
dx3dt2:=simplify(dx3dt2function(uinfty0sol,uinfty1sol,vinfty0sol,
vinfty1sol)):

```

$$\begin{aligned}
 y2sol &:= \alpha \text{uinfty1} \\
 x3sol &:= -\beta \text{uinfty1} \\
 x2sol &:= \delta \text{uinfty0} + \epsilon \text{uinfty1} \\
 y3sol &:= -\nu \text{uinfty1} \text{uinfty1} + \mu \text{uinfty0} \\
 \left\{ \text{uinfty0} = \frac{\alpha x2 - \epsilon y2}{\alpha \delta}, \text{uinfty1} = -\frac{x3}{\beta}, \text{vinfty0} = \frac{\alpha \beta y3 - \nu x3 y2}{\alpha \beta \mu}, \text{vinfty1} = \frac{y2}{\alpha} \right\} \\
 \text{uinfty0sol} &:= \frac{\alpha x2 - \epsilon y2}{\alpha \delta} \\
 \text{uinfty1sol} &:= -\frac{x3}{\beta} \\
 \text{vinfty0sol} &:= \frac{\alpha \beta y3 - \nu x3 y2}{\alpha \beta \mu} \\
 \text{vinfty1sol} &:= \frac{y2}{\alpha}
 \end{aligned} \tag{16}$$

Expression of the Hamiltonians in the coordinates (x<sub>i</sub>,y<sub>i</sub>).

```

> mu:=1;
beta:=-1;
epsilon:=0;
delta:=1;
nu:=mu;
alpha:=-beta*mu/delta;

```

```

Ham1xy:=((( -delta*t2-2*x2)*x3+2*delta*t1*beta)*mu-2*y3*beta*
(delta-epsilon))*alpha*y2+3*y2^2*(mu*epsilon+(1/3)*nu*(delta-
epsilon))*x3)/(alpha*beta*mu)-2*y3*alpha*x2/mu-(2*beta*mu*x3*
tinfty10+2*x3^2*y3)/beta-beta*t2*y3:
simplify(dx2dt1-diff(Ham1xy,y2));
simplify(series(simplify(dy2dt1+diff(Ham1xy,x2)),y2));
simplify(series(simplify(dy3dt1+diff(Ham1xy,x3)),y2));
simplify(series(simplify(dx3dt1-diff(Ham1xy,y3)),y2));

```

```

Ham2xy:=((-1/2)*x3^2+(1/4)*t2+(1/2)*x2)*y2+x3*(t1-y3)-(1/4)*
t2^2+x2^2)*y2+(x3*y3-tinfty10)*x2+(1/2)*t2*y3*x3+(1/2)*y3*(2*t1-
y3)+(1/2)*tinfty10*t2:
simplify(dx2dt2-diff(Ham2xy,y2));
simplify(series(simplify(dy2dt2+diff(Ham2xy,x2)),y2));
simplify(series(simplify(dy3dt2+diff(Ham2xy,x3)),y2));
simplify(series(simplify(dx3dt2-diff(Ham2xy,y3)),y2));

```

```

mu := 1
beta := -1
epsilon := 0
delta := 1
nu := 1
alpha := 1
0
0
0
0
0
0
0
0
0

```

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```

> Ham1xy:=simplify(Ham1xy);
x2sol:=x2sol;
x3sol:=x3sol;
y2sol:=y2sol;
y3sol:=y3sol;
Ham2xy:=expand(simplify(Ham2xy));

```

$Ham1xy := 2 x^3 y^3 + (-y^2 + (t^2 + 2 x^2) y^2 - 2 tinfty10) x^3 + (2 t1 - 2 y^3) y^2 + y^3 (t^2 - 2 x^2)$

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```

x2sol := uinfty0
x3sol := uinfty1
y2sol := vinfty1
y3sol := -uinfty1 vinfty1 + vinfty0

```

$$\begin{aligned}
Ham2xy := & -\frac{1}{2} x^3 y^2 + \frac{1}{4} y^2 t^2 + \frac{1}{2} x^2 y^2 + y^2 x^3 t - y^2 x^3 y^3 - \frac{1}{4} y^2 t^2 + y^2 x^2 \\
& + x^2 x^3 y^3 - x^2 t y^3 + \frac{1}{2} t^2 y^3 x^3 + y^3 t - \frac{1}{2} y^3 + \frac{1}{2} t y^3
\end{aligned}$$

Expression of the spectral invariants in the coordinates (x,y) and verification that they recover the Hamiltonians.

```

> I1uvfunction:=unapply(I1uv,uinfy0,uinfy1,vinfy0,vinfy1):
I1xy:=simplify(I1uvfunction(uinfy0sol,uinfy1sol,vinfy0sol,
vinfy1sol));
I2uvfunction:=unapply(I2uv,uinfy0,uinfy1,vinfy0,vinfy1):
I2xy:=simplify(I2uvfunction(uinfy0sol,uinfy1sol,vinfy0sol,
vinfy1sol));
simplify(Ham1xy-(-2)*I1xy);
simplify(Ham2xy-(-2)*I2xy);

```

$$\begin{aligned}
I1xy := & -x^3 y^3 + \frac{1}{2} (y^2 + (-t^2 - 2 x^2) y^2 + 2 t y^3) x^3 + \frac{1}{2} (-2 t + 2 y^3) y^2 \\
& - \frac{1}{2} y^3 (t - 2 x^2)
\end{aligned}$$

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$$\begin{aligned}
I2xy := & \frac{1}{8} (2 x^3 - t - 2 x^2) y^2 + \frac{1}{8} ((-4 t + 4 y^3) x^3 + t^2 - 4 x^2) y^2 - \frac{1}{4} y^3 (t \\
& + 2 x^2) x^3 + \frac{1}{4} y^3 - \frac{1}{2} y^3 t - \frac{1}{4} t y^3 (t - 2 x^2) \\
& \qquad \qquad \qquad 0 \\
& \qquad \qquad \qquad 0
\end{aligned}$$

Expression of the Lax matrices in the coordinates (x,y)

```

> tdLxy11function:=unapply(tdLuv[1,1],uinfy0,uinfy1,vinfy0,
vinfy1):
tdLxy12function:=unapply(tdLuv[1,2],uinfy0,uinfy1,vinfy0,
vinfy1):
tdLxy21function:=unapply(tdLuv[2,1],uinfy0,uinfy1,vinfy0,
vinfy1):
tdLxy22function:=unapply(tdLuv[2,2],uinfy0,uinfy1,vinfy0,
vinfy1):
tdLxy:=Matrix(2,2,0):
tdLxy[1,1]:=simplify(tdLxy11function(uinfy0sol,uinfy1sol,
vinfy0sol,vinfy1sol)):
tdLxy[1,2]:=simplify(tdLxy12function(uinfy0sol,uinfy1sol,
vinfy0sol,vinfy1sol)):
tdLxy[2,1]:=simplify(tdLxy21function(uinfy0sol,uinfy1sol,
vinfy0sol,vinfy1sol)):
tdLxy[2,2]:=simplify(tdLxy22function(uinfy0sol,uinfy1sol,
vinfy0sol,vinfy1sol)):
tdLxy;

```

```

tdA1xy1function:=unapply(tdA1uv[1,1],uinfty0,uinfty1,vinfty0,
vinfty1):
tdA1xy2function:=unapply(tdA1uv[1,2],uinfty0,uinfty1,vinfty0,
vinfty1):
tdA1xy21function:=unapply(tdA1uv[2,1],uinfty0,uinfty1,vinfty0,
vinfty1):
tdA1xy22function:=unapply(tdA1uv[2,2],uinfty0,uinfty1,vinfty0,
vinfty1):
tdA1xy:=Matrix(2,2,0):
tdA1xy[1,1]:=simplify(tdA1xy1function(uinfty0sol,uinfty1sol,
vinfty0sol,vinfty1sol)):
tdA1xy[1,2]:=simplify(tdA1xy2function(uinfty0sol,uinfty1sol,
vinfty0sol,vinfty1sol)):
tdA1xy[2,1]:=simplify(tdA1xy21function(uinfty0sol,uinfty1sol,
vinfty0sol,vinfty1sol)):
tdA1xy[2,2]:=simplify(tdA1xy22function(uinfty0sol,uinfty1sol,
vinfty0sol,vinfty1sol)):
tdA1xy;

```

```

tdA2xy1function:=unapply(tdA2uv[1,1],uinfty0,uinfty1,vinfty0,
vinfty1):
tdA2xy2function:=unapply(tdA2uv[1,2],uinfty0,uinfty1,vinfty0,
vinfty1):
tdA2xy21function:=unapply(tdA2uv[2,1],uinfty0,uinfty1,vinfty0,
vinfty1):
tdA2xy22function:=unapply(tdA2uv[2,2],uinfty0,uinfty1,vinfty0,
vinfty1):
tdA2xy:=Matrix(2,2,0):
tdA2xy[1,1]:=simplify(tdA2xy1function(uinfty0sol,uinfty1sol,
vinfty0sol,vinfty1sol)):
tdA2xy[1,2]:=simplify(tdA2xy2function(uinfty0sol,uinfty1sol,
vinfty0sol,vinfty1sol)):
tdA2xy[2,1]:=simplify(tdA2xy21function(uinfty0sol,uinfty1sol,
vinfty0sol,vinfty1sol)):
tdA2xy[2,2]:=simplify(tdA2xy22function(uinfty0sol,uinfty1sol,
vinfty0sol,vinfty1sol)):
tdA2xy;

```

$$\left[ \begin{array}{l}
-\lambda^3 + (-t2 + y2) \lambda - t1 + x3 y2 + y3, x3 \lambda + \lambda^2 + x2 + \frac{1}{2} t2 \\
[-y2^2 + (2 \lambda^2 + t2 - 2 x2) y2 - 2 x3 y3 + 2 \lambda y3 + 2 tinfy10, \lambda^3 + (t2 - y2) \lambda + t1 \\
-x3 y2 - y3]
\end{array} \right] \quad (20)$$

$$\left[ \begin{array}{cc}
 & \begin{bmatrix} x^3 - \lambda & 1 \\ 2y^2 & \lambda - x^3 \end{bmatrix} \\
 \begin{bmatrix} -\frac{1}{2}\lambda^2 + \frac{1}{2}x^2 - \frac{1}{4}t^2 + \frac{1}{2}y^2 & \frac{1}{2}\lambda + \frac{1}{2}x^3 \\ \lambda y^2 + y^3 & \frac{1}{2}\lambda^2 - \frac{1}{2}x^2 + \frac{1}{4}t^2 - \frac{1}{2}y^2 \end{bmatrix}
 \end{array} \right]$$