

L¹ Stability for scalar balance laws. Control of the continuity equation with a non-local flow.

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Pedestrian traffic

We consider

$$\partial_t u + \operatorname{Div}(uV(x, u)) = 0; \quad u_0 \in (\mathbf{L}^1 \cap \mathbf{L}^\infty \cap \mathbf{BV})(\mathbb{R}^N; \mathbb{R})$$

whith $V(u) = v(\eta *_{x} u)w(x)$.

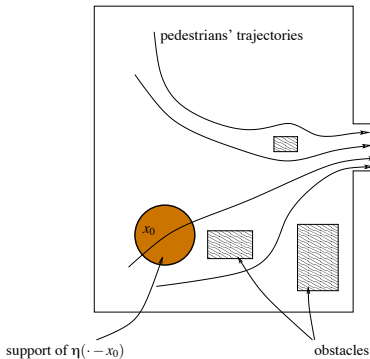


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Introduction of the problem

Scalar balance laws :

$$\begin{cases} \partial_t u + \operatorname{Div} f(t, x, u) = F(t, x, u) & (t, x) \in \mathbb{R}_+^* \times \mathbb{R}^N \\ u(0, x) = u_0(x) \in \mathbf{L}^1 \cap \mathbf{L}^\infty \cap \mathbf{BV} & x \in \mathbb{R}^N, \end{cases}$$

where $f \in \mathcal{C}^2([0, T] \times \mathbb{R}^N \times \mathbb{R}; \mathbb{R}^N)$, $F \in \mathcal{C}^1([0, T] \times \mathbb{R}^N \times \mathbb{R}; \mathbb{R})$.

- Existence and uniqueness, dependence w.r.t. initial conditions : Kruřkov Theorem (1970, Mat. Sb. (N.S.));
- Dependence w.r.t. flow and source ?

Previous Results

Theorem (Kružkov, 1970, Mat. Sb. (N.S.))

We consider the equation

$$\partial_t u + \operatorname{Div} f(t, x, u) = F(t, x, u),$$

with initial condition $u_0 \in \mathbf{L}^1 \cap \mathbf{L}^\infty(\mathbb{R}^N)$. Under the condition

$$\begin{aligned} \text{(K)} \quad & \forall A > 0, \partial_u f \in \mathbf{L}^\infty(\Omega_A), \partial_u(F - \operatorname{div} f) \in \mathbf{L}^\infty(\Omega_A) \\ & \text{and } F - \operatorname{div} f \in \mathbf{L}^\infty(\Omega_A) \end{aligned}$$

then there exists a unique weak entropy solution $u \in \mathbf{L}^\infty([0, T]; \mathbf{L}^1(\mathbb{R}^N; \mathbb{R}))$ continuous from the right in time.

Let $v_0 \in (\mathbf{L}^1 \cap \mathbf{L}^\infty)(\mathbb{R}^N; \mathbb{R})$, then

$$\|(u - v)(t)\|_{\mathbf{L}^1} \leq e^{\gamma t} \|u_0 - v_0\|_{\mathbf{L}^1},$$

where $\gamma = \|\partial_u F\|_{\mathbf{L}^\infty(\Omega_M)}$.

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where $\gamma = \|\partial_u F\|_{\mathbf{L}^\infty(\Omega_M)}$.



Theorem (Lucier, 1986, Math. Comp.)

If $f, g : \mathbb{R} \rightarrow \mathbb{R}^N$ are globally Lipschitz, then $\exists C > 0$ such that $\forall u_0, v_0 \in \mathbf{L}^1 \cap \mathbf{L}^\infty(\mathbb{R}^N; \mathbb{R})$ initial conditions for

$$\partial_t u + \operatorname{Div} f(u) = 0, \quad \partial_t v + \operatorname{Div} g(v) = 0.$$

with furthermore $v_0 \in \mathbf{BV}(\mathbb{R}^N; \mathbb{R})$, we have $\forall t \geq 0$,

$$\|(u - v)(t)\|_{\mathbf{L}^1} \leq \|u_0 - v_0\|_{\mathbf{L}^1} + C t \operatorname{TV}(v_0) \mathbf{Lip}(f - g).$$

Theorem (Chen & Karlsen, 2005, Commun. Pure Appl. Anal.)

With $f(t, x, u) = \lambda(x) l(u)$, $g(t, x, v) = \mu(x) m(v)$, no source $F = G = 0$,

$$\|(u - v)(t)\|_{\mathbf{L}^1} \leq \|u_0 - v_0\|_{\mathbf{L}^1} + C_1 t (\|\lambda - \mu\|_{\mathbf{L}^\infty} + \|\lambda - \mu\|_{\mathbf{W}^{1,1}} + \|l - m\|_{\mathbf{L}^\infty} + \|l - m\|_{\mathbf{W}^{1,\infty}})$$

where $C_1 = C \sup_{[0, \tau]} (\operatorname{TV}(u(t)), \operatorname{TV}(v(t)))$.



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Total Variation

Definition : For $u \in \mathbf{L}_{\text{loc}}^1(\mathbb{R}^N; \mathbb{R})$ we denote

$$\text{TV}(u) = \sup \left\{ \int_{\mathbb{R}^N} u \operatorname{div} \Psi; \quad \Psi \in \mathcal{C}_c^1(\mathbb{R}^N; \mathbb{R}^N), \quad \|\Psi\|_{\mathbf{L}^\infty} \leq 1 \right\};$$

and

$$\mathbf{BV}(\mathbb{R}^N; \mathbb{R}) = \left\{ u \in \mathbf{L}_{\text{loc}}^1; \text{TV}(u) < \infty \right\}.$$

When f and F depend only on u we have

$$u_0 \in \mathbf{L}^\infty \cap \mathbf{BV} \Rightarrow \forall t \geq 0, \quad u(t) \in \mathbf{L}^\infty \cap \mathbf{BV}$$

and, denoting $\gamma = \|\partial_u F\|_{\mathbf{L}^\infty(\Omega_M)}$,

$$\text{TV}(u(t)) \leq \text{TV}(u_0) e^{\gamma t}.$$

Goal : we want a more general estimate on the total variation.



Estimate on the total variation

Theorem (TV — Colombo, Mercier, Rosini, 2009, Comm. Math. Sciences)

Assume (f, F) satisfies **(K)** + **(H1)**. Let

$\kappa_0 = (2N + 1) \|\nabla_x \partial_u f\|_{L^\infty(\Omega_M)} + \|\partial_u F\|_{L^\infty(\Omega_M)}$. If $u_0 \in (L^\infty \cap \mathbf{BV})(\mathbb{R}^N; \mathbb{R})$, then $\forall t \in [0, T]$, $u(t) \in (L^\infty \cap \mathbf{BV})(\mathbb{R}^N; \mathbb{R})$ and

$$\begin{aligned} \text{TV}(u(t)) &\leq \text{TV}(u_0) e^{\kappa_0 t} \\ &\quad + NW_N \int_0^t e^{\kappa_0(t-\tau)} \int_{\mathbb{R}^N} \|\nabla_x (F - \text{div} f)(\tau, x, \cdot)\|_{L^\infty(du)} dx d\tau. \end{aligned}$$

(H1) : $\int_0^T \int_{\mathbb{R}^N} \|\nabla_x (F - \text{div} f)\|_{L^\infty(du)} dx dt < \infty$ and $\nabla_x \partial_u f \in L^\infty(\Omega_M)$

Remark : In some particular cases, we re-obtain optimal known estimates :

- f, F depending only on u ,
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L¹ Stability of the solution

Theorem (Flow/Source... — Colombo, Mercier, Rosini, 2009)

Assume $(f, F), (g, G)$ satisfy **(K)**, (f, F) satisfies **(H1)** and $(f - g, F - G)$ satisfies **(H2)**. Let $u_0, v_0 \in (\mathbf{L}^1 \cap \mathbf{L}^\infty \cap \mathbf{BV})(\mathbb{R}^N; \mathbb{R})$. We denote

$$\kappa = 2N \|\nabla_x \partial_u f\|_{\mathbf{L}^\infty(\Omega_M)} + \|\partial_u F\|_{\mathbf{L}^\infty(\Omega_M)} + \|\partial_u(F - G)\|_{\mathbf{L}^\infty(\Omega_M)}.$$

Let u and v be the solutions associated to (f, F) and (g, G) respectively and with initial conditions u_0 and v_0 .

(H2) : $\partial_u(F - G) \in \mathbf{L}^\infty(\Omega_M)$, $\partial_u(f - g) \in \mathbf{L}^\infty(\Omega_M)$ and $\int_0^T \int_{\mathbb{R}^N} \|F - G - \operatorname{div}(f - g)\|_{\mathbf{L}^\infty(\mathrm{d}u)} \mathrm{d}x \mathrm{d}t < \infty$.



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then $\forall t \in [0, T]$:

$$\begin{aligned} \|(u - v)(t)\|_{L^1} &\leq e^{\kappa t} \|u_0 - v_0\|_{L^1} + \frac{e^{\kappa_0 t} - e^{\kappa t}}{\kappa_0 - \kappa} \text{TV}(u_0) \|\partial_u(f - g)\|_{L^\infty} \\ &+ \int_0^t \frac{e^{\kappa_0(t-\tau)} - e^{\kappa(t-\tau)}}{\kappa_0 - \kappa} \int_{\mathbb{R}^N} \|\nabla_x(F - \text{div}f)(\tau, x, \cdot)\|_{L^\infty(\text{d}u)} \text{d}x \text{d}\tau \\ &\quad \times \text{NW}_N \|\partial_u(f - g)\|_{L^\infty} \\ &+ \int_0^t e^{\kappa(t-\tau)} \int_{\mathbb{R}^N} \|((F - G) - \text{div}(f - g))(\tau, x, \cdot)\|_{L^\infty(\text{d}u)} \text{d}x \text{d}\tau . \end{aligned}$$

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Introduction of the problem

Continuity equation :

$$\partial_t u + \text{Div}(uV(x, u(t))) = 0, \quad u(0, \cdot) = u_0 \in \mathbf{L}^1 \cap \mathbf{L}^\infty \cap \mathbf{BV},$$

where $V : \mathbb{R}^N \times \mathbf{L}^1(\mathbb{R}^N; \mathbb{R}) \rightarrow \mathcal{C}^2(\mathbb{R}^N; \mathbb{R})$ is a non-local averaging functional, for example, if $v : \mathbb{R} \rightarrow \mathbb{R}$ is a regular function :

- $V(u) = v\left(\int_{\mathbb{R}} u \, dx\right)$ for a supply-chain [Armbuster et al.]
- $V(u) = v(\eta *_x u)w(x)$ for pedestrian traffic [Colombo et al.].

Goal :

- Existence and uniqueness of an entropy solution ?
- Gâteaux differentiability of the semi-group w.r.t. initial conditions ?



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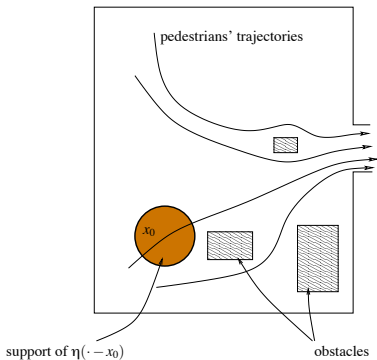


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whith $V(u) = v(\eta *_{x} u)w(x)$.





Existence of a solution

Theorem (Traffic — Colombo, Herty, Mercier, 2010, ESAIM-Control Opt. Calc. Var.)

If V satisfies **(V1)**, then there exists a time $T_{\text{ex}} > 0$ and a unique entropy solution

$$u \in C^0([0, T_{\text{ex}}[; \mathbf{L}^1 \cap \mathbf{L}^\infty \cap \mathbf{BV})$$

and we denote $S_t u_0 = u(t, \cdot)$.

We can bound below the time of existence by

$$T_{\text{ex}} \geq \sup \left\{ \sum_n \frac{\ln(\alpha_{n+1}/\alpha_n)}{C(\alpha_{n+1})}; (\alpha_n)_n \text{ strict. increasing, } \alpha_0 = \|u_0\|_{\mathbf{L}^\infty} \right\}.$$

If furthermore, V satisfies **(V2)** then

$$u_0 \in \mathbf{W}^{2,1} \cap \mathbf{L}^\infty \Rightarrow \forall t \in [0, T_{\text{ex}}[, \quad u(t) \in \mathbf{W}^{2,1}.$$



Hypotheses

(V1) There exists $C \in \mathbf{L}_{\text{loc}}^{\infty}(\mathbb{R}_+; \mathbb{R}_+)$ such that $\forall u \in \mathbf{L}^1(\mathbb{R}^N; \mathbb{R})$

$$\begin{aligned} V(u) &\in \mathbf{L}^{\infty}, & \|\nabla_x V(u)\|_{\mathbf{L}^{\infty}} &\leq C(\|u\|_{\mathbf{L}^{\infty}}), \\ \|\nabla_x V(u)\|_{\mathbf{L}^1} &\leq C(\|u\|_{\mathbf{L}^{\infty}}), & \|\nabla_x^2 V(u)\|_{\mathbf{L}^1} &\leq C(\|u\|_{\mathbf{L}^{\infty}}), \end{aligned}$$

and $\forall u_1, u_2 \in \mathbf{L}^1(\mathbb{R}^N; \mathbb{R})$

$$\begin{aligned} \|V(u_1) - V(u_2)\|_{\mathbf{L}^{\infty}} &\leq C(\|u_1\|_{\mathbf{L}^{\infty}}) \|u_1 - u_2\|_{\mathbf{L}^1}, \\ \|\nabla_x(V(u_1) - V(u_2))\|_{\mathbf{L}^1} &\leq C(\|u_1\|_{\mathbf{L}^{\infty}}) \|u_1 - u_2\|_{\mathbf{L}^1}. \end{aligned}$$

(V2) There exists $C \in \mathbf{L}_{\text{loc}}^{\infty}(\mathbb{R}_+; \mathbb{R}_+)$ such that $\|\nabla_x^3 V(u)\|_{\mathbf{L}^{\infty}} \leq C(\|u\|_{\mathbf{L}^{\infty}})$.



Idea of the proof :

Let us introduce the space $X_\alpha = \mathbf{L}^1 \cap \mathbf{BV}(\mathbb{R}^N; [0, \alpha])$ and the application \mathcal{Q} that associates to $w \in \mathcal{X}_\beta = \mathcal{C}^0([0, T[, X_\beta)$ the solution $u \in \mathcal{X}_\beta$ of the Cauchy problem

$$\partial_t u + \text{Div}(uV(w)) = 0, \quad u(0, \cdot) = u_0 \in X_\alpha$$

For w_1, w_2 , we obtain thanks to the estimate of Thm (Flow/Source)

$$\|\mathcal{Q}(w_1) - \mathcal{Q}(w_2)\|_{\mathbf{L}^\infty([0, T[, \mathbf{L}^1)} \leq f(T) \|w_1 - w_2\|_{\mathbf{L}^\infty([0, T[, \mathbf{L}^1)},$$

where f is increasing, $f(0) = 0$ and $f \rightarrow \infty$ when $T \rightarrow \infty$.

Then we apply the Banach Fixed Point Theorem.



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Gâteaux derivative of the semi-group

Classical case : semi-group Lipschitz, not differentiable. Shift differentiability [Bressan, Guerra, Bianchini,...].

Definition : The application $S : \mathbf{L}^1(\mathbb{R}^N; \mathbb{R}) \rightarrow \mathbf{L}^1(\mathbb{R}^N; \mathbb{R})$ is said to be \mathbf{L}^1 Gâteaux differentiable in $u_0 \in \mathbf{L}^1$ in the direction $r_0 \in \mathbf{L}^1$ if there exists a linear continuous application $DS(u_0) : \mathbf{L}^1 \rightarrow \mathbf{L}^1$ such that

$$\left\| \frac{S(u_0 + hr_0) - S(u_0)}{h} - DS(u_0)(r_0) \right\|_{\mathbf{L}^1} \rightarrow 0 \quad \text{when } h \rightarrow 0$$

Formally, we expect the Gâteaux derivative of the semi-group to be the solution of the linearized problem :

$$\partial_t r + \text{Div}(rV(u) + uDV(u)(r)) = 0, \quad r(0, \cdot) = r_0.$$



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We introduce the hypotheses :

(V3) $V : \mathbf{L}^1 \rightarrow \mathcal{C}^2$ is differentiable and there exists $C \in \mathbf{L}_{\text{loc}}^\infty$ such that $\forall u, r \in \mathbf{L}^1$,

$$\begin{aligned} \|V(u+r) - V(u) - DV(u)(r)\|_{\mathbf{W}^{2,\infty}} &\leq C (\|u\|_{\mathbf{L}^\infty} + \|u+r\|_{\mathbf{L}^\infty}) \|r\|_{\mathbf{L}^1}^2, \\ \|DV(u)(r)\|_{\mathbf{W}^{2,\infty}} &\leq C (\|u\|_{\mathbf{L}^\infty}) \|r\|_{\mathbf{L}^1}. \end{aligned}$$

(V4) There exists $C \in \mathbf{L}_{\text{loc}}^\infty(\mathbb{R}_+; \mathbb{R}_+)$ such that $\forall u, \tilde{u}, r \in \mathbf{L}^1$

$$\begin{aligned} \left\| \operatorname{div} (V(\tilde{u}) - V(u) - DV(u)(\tilde{u} - u)) \right\|_{\mathbf{L}^1} &\leq C (\|\tilde{u}\|_{\mathbf{L}^\infty} + \|u\|_{\mathbf{L}^\infty}) (\|\tilde{u} - u\|_{\mathbf{L}^1})^2 \\ \left\| \operatorname{div} (DV(u)(r)) \right\|_{\mathbf{L}^1} &\leq C (\|u\|_{\mathbf{L}^\infty}) \|r\|_{\mathbf{L}^1}. \end{aligned}$$

We show that the linearised problem has a unique entropy solution :

Theorem (Linearised — Colombo, Herty, Mercier, 2010)

Assume that V satisfies **(V1)**, **(V2)**, **(V3)**. Let $u \in \mathcal{C}^0([0, T_{\text{ex}}[; \mathbf{W}^{1,\infty} \cap \mathbf{W}^{1,1})$, $r_0 \in (\mathbf{L}^1 \cap \mathbf{L}^\infty)(\mathbb{R}^N; \mathbb{R})$. Then the linearised problem

$$\partial_t r + \text{Div}(rV(u) + uDV(u)(r)) = 0, \quad \text{with } r(0, x) = r_0$$

has a unique entropy solution $r \in \mathcal{C}^0([0, T_{\text{ex}}[; \mathbf{L}^1(\mathbb{R}^N; \mathbb{R}))$ and we denote $\Sigma_t^u r_0 = r(t, \cdot)$.

If furthermore $r_0 \in \mathbf{W}^{1,1}$, then $\forall t \in [0, T_{\text{ex}}[, r(t) \in \mathbf{W}^{1,1}$.

Theorem (Gâteaux Derivative — Colombo, Herty, Mercier, 2010)

Assume that V satisfies **(V1)**, **(V2)**, **(V3)**, **(V4)**. Let $u_0 \in \mathbf{W}^{1,\infty} \cap \mathbf{W}^{2,1}$, $r_0 \in \mathbf{W}^{1,1} \cap \mathbf{L}^\infty$ and let T_{ex} be the time of existence for the initial problem given by Thm (Trafic).

Then, for all $t \in [0, T_{\text{ex}}[$ the local semi-group of the pedestrian traffic problem is \mathbf{L}^1 Gâteaux differentiable in the direction r_0 and

$$DS_t(u_0)(r_0) = \Sigma_t^{S_t u_0} r_0.$$

Idea of the proof : Thm (Flow/Source) allows to compare the solution with initial condition $u_0 + hr_0$ to the solution $u + hr$.

Extrema of a Cost Functional

Let J be a cost functional such that

$$J(\rho_0) = \int_{\mathbb{R}^N} f(S_t \rho_0) \psi(t, x) dx.$$

Proposition (Colombo, Herty, Mercier, 2010)

Let $f \in C^{1,1}(\mathbb{R}; \mathbb{R}_+)$ and $\psi \in L^\infty(I_{\text{ex}} \times \mathbb{R}^N; \mathbb{R})$. Let us assume that $S: I \times (L^1 \cap L^\infty)(\mathbb{R}^N; \mathbb{R}) \rightarrow (L^1 \cap L^\infty)(\mathbb{R}^N; \mathbb{R})$ is L^1 Gâteaux differentiable. If $\rho_0 \in (L^1 \cap L^\infty)(\mathbb{R}^N; \mathbb{R})$ is solution of

$$\text{Find } \min_{\rho_0} J(\rho_0) \text{ s. t. } \{S_t \rho_0 \text{ is solution of (Traffic)}\}.$$







then, for all $r_0 \in (L^1 \cap L^\infty)(\mathbb{R}^N; \mathbb{R})$

$$\int_{\mathbb{R}^N} f'(S_t \rho_0) \Sigma_t^{\rho_0} r_0 \psi(t, x) dx = 0.$$

Perspectives

- Derivation with respect to the geometric parameter (speed law).
- Avoid blow-up of the L^∞ norm.

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