

L<sup>1</sup> Stability for scalar balance laws.  
Control of the continuity equation with a non-local flow.

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Parma, 15th February 2010

## Introduction

Scalar balance laws:

$$\begin{cases} \partial_t u + \operatorname{Div} f(t, x, u) = F(t, x, u) & (t, x) \in \mathbb{R}_+^* \times \mathbb{R}^N \\ u(0, x) = u_0(x) \in \mathbf{L}^1 \cap \mathbf{L}^\infty \cap \mathbf{BV} & x \in \mathbb{R}^N, \end{cases}$$

where  $f \in \mathcal{C}^2([0, T] \times \mathbb{R}^N \times \mathbb{R}; \mathbb{R}^N)$ ,  $F \in \mathcal{C}^1([0, T] \times \mathbb{R}^N \times \mathbb{R}; \mathbb{R})$ .

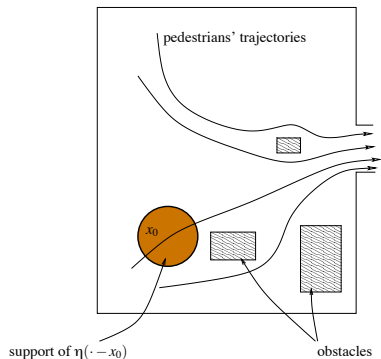
- Existence and uniqueness, dependence w.r.t. initial conditions: Kružkov Theorem;
- Dependence w.r.t. flow and source ?

Continuity equation:

$$\partial_t u + \operatorname{Div}(uV(u(t))) = 0, \quad u(0, \cdot) = u_0 \in \mathbf{L}^1 \cap \mathbf{L}^\infty \cap \mathbf{BV},$$

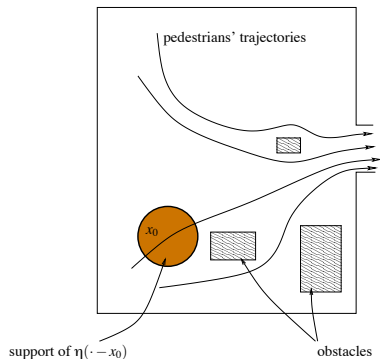
where  $V : \mathbf{L}^1(\mathbb{R}^N; \mathbb{R}) \rightarrow \mathcal{C}^2(\mathbb{R}^N; \mathbb{R})$  is a non-local averaging functional, for example, if  $v : \mathbb{R} \rightarrow \mathbb{R}$  is a regular function:

- $V(u) = v\left(\int_{\mathbb{R}} u \, dx\right)$  for a supply-chain
- $V(u) = v(\eta *_{x} u)w(x)$ , for pedestrian traffic.



Goal :

- Existence and uniqueness of an entropy solution ?
- Gâteaux differentiability of the semi-group w.r.t. initial conditions ?



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# Plan

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## Theorem (Kružkov (1970))

Let us denote  $\Omega_A = [0, T] \times \mathbb{R}^N \times [-A, A]$  for all  $A \geq 0$ . If

$$\text{(K)} \quad \forall A > 0, \quad \partial_u f \in \mathbf{L}^\infty(\Omega_A), \quad \partial_u(F - \operatorname{div} f) \in \mathbf{L}^\infty(\Omega_A) \\ \text{and } F - \operatorname{div} f \in \mathbf{L}^\infty(\Omega_A)$$

then for all  $u_0 \in (\mathbf{L}^\infty \cap \mathbf{L}^1)(\mathbb{R}^N; \mathbb{R})$  such that  $\|u_0\|_{\mathbf{L}^\infty} \leq M_0$ , there exists a unique weak entropy solution  $u \in \mathbf{L}^\infty([0, T]; \mathbf{L}^1(\mathbb{R}^N; \mathbb{R}))$  continuous from the right in time and there exists  $M > 0$  such that  $\|u\|_{\mathbf{L}^\infty} \leq M$ .

Let  $v_0 \in (\mathbf{L}^1 \cap \mathbf{L}^\infty)(\mathbb{R}^N; \mathbb{R})$  be such that  $\|v_0\|_{\mathbf{L}^\infty} \leq M_0$ , then

$$\|(u - v)(t)\|_{\mathbf{L}^1} \leq e^{\gamma t} \|u_0 - v_0\|_{\mathbf{L}^1},$$

where  $\gamma = \|\partial_u(F - \operatorname{div} f)\|_{\mathbf{L}^\infty(\Omega_M)}$ .



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## Theorem (Lucier)

If  $f, g : \mathbb{R} \rightarrow \mathbb{R}^N$  are globally Lipschitz, then  $\exists C > 0$  such that  $\forall u_0, v_0 \in \mathbf{L}^1 \cap \mathbf{L}^\infty(\mathbb{R}^N; \mathbb{R})$  initial conditions for

$$\partial_t u + \operatorname{Div} f(u) = 0, \quad \partial_t v + \operatorname{Div} g(v) = 0.$$

with furthermore  $v_0 \in \mathbf{BV}(\mathbb{R}^N; \mathbb{R})$ , we have  $\forall t \geq 0$ ,

$$\|(u - v)(t)\|_{\mathbf{L}^1} \leq \|u_0 - v_0\|_{\mathbf{L}^1} + Ct \operatorname{TV}(v_0) \operatorname{Lip}(f - g).$$

## Theorem (Chen &amp; Karlsen)

With  $f(t, x, u) = \lambda(x)l(u)$ ,  $g(t, x, v) = \mu(x)m(v)$ , no source  $F = G = 0$ ,

$$\|(u - v)(t)\|_{\mathbf{L}^1} \leq \|u_0 - v_0\|_{\mathbf{L}^1} + C_1 t (\|\lambda - \mu\|_{\mathbf{L}^\infty} + \|\lambda - \mu\|_{\mathbf{W}^{1,1}} + \|l - m\|_{\mathbf{L}^\infty} + \|l - m\|_{\mathbf{W}^{1,\infty}})$$

where  $C_1 = C \sup_{[0, T]} (\operatorname{TV}(u(t)), \operatorname{TV}(v(t)))$ .

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## Total Variation

**Definition:** For  $u \in \mathbf{L}_{\text{loc}}^1(\mathbb{R}^N; \mathbb{R})$  we denote

$$\text{TV}(u) = \sup \left\{ \int_{\mathbb{R}^N} u \operatorname{div} \Psi; \quad \Psi \in \mathcal{C}_c^1(\mathbb{R}^N; \mathbb{R}^N), \quad \|\Psi\|_{L^\infty} \leq 1 \right\};$$

and

$$\mathbf{BV}(\mathbb{R}^N; \mathbb{R}) = \left\{ u \in \mathbf{L}_{\text{loc}}^1; \text{TV}(u) < \infty \right\}.$$

**Remark :** When  $f$  and  $F$  depend only on  $u$  we have

$$u_0 \in \mathbf{L}^\infty \cap \mathbf{BV} \Rightarrow \forall t \geq 0, \quad u(t) \in \mathbf{L}^\infty \cap \mathbf{BV}$$

and, denoting  $\gamma = \|\partial_u F\|_{L^\infty(\Omega_M)}$ ,

$$\text{TV}(u(t)) \leq \text{TV}(u_0) e^{\gamma t}.$$

**Problem:** we do not have in general an estimate on the total variation !

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## Estimate on the total variation (Colombo, Mercier, Rosini)

### Theorem (TV)

Assume  $(f, F)$  satisfies **(K)** + **(H1)**. Let

$\kappa_0 = NW_N \left( (2N + 1) \|\nabla_x \partial_u f\|_{L^\infty(\Omega_M)} + \|\partial_u F\|_{L^\infty(\Omega_M)} \right)$ . If  $u_0 \in (\mathbf{L}^\infty \cap \mathbf{BV})(\mathbb{R}^N; \mathbb{R})$ , then  $\forall t \in [0, T]$ ,  $u(t) \in (\mathbf{L}^\infty \cap \mathbf{BV})(\mathbb{R}^N; \mathbb{R})$  and

$$\begin{aligned} \text{TV}(u(t)) &\leq \text{TV}(u_0) e^{\kappa_0 t} \\ &\quad + NW_N \int_0^t e^{\kappa_0(t-\tau)} \int_{\mathbb{R}^N} \|\nabla_x (F - \text{div} f)(\tau, x, \cdot)\|_{L^\infty(\text{d}u)} \text{d}x \text{d}\tau. \end{aligned}$$

**(H1)** :  $\int_0^T \int_{\mathbb{R}^N} \|\nabla_x (F - \text{div} f)\|_{L^\infty(\text{d}u)} \text{d}x \text{d}t < \infty$  et  $\nabla_x \partial_u f \in L^\infty(\Omega_M)$

Remark : In some particular cases, we re-obtain known estimates:

- $f, F$  depending only on  $u$ ,
- $f, F$  not depending on  $u$ .

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## Idea of the proof

### Proposition

Let  $\mu \in \mathcal{C}_c^\infty(\mathbb{R}_+; \mathbb{R}_+)$  be such that  $\|\mu\|_{L^1} = 1$  and  $\mu' < 0$  on  $\mathbb{R}_+^*$ . We denote  $\mu_\lambda(x) = \frac{1}{\lambda^N} \mu\left(\frac{\|x\|}{\lambda}\right)$ . If there exists  $C_0 > 0$  such that  $\forall \lambda > 0$ ,

$$\frac{1}{\lambda} \int_{\mathbb{R}^N} \int_{\mathbb{R}^N} |u(x+y) - u(x)| \mu_\lambda(y) dx dy \leq C_0,$$

then  $u \in \mathbf{BV}$  and

$$\text{TV}(u) \int_{\mathbb{R}^N} |y_1| \mu(\|y\|) dy \leq C_0.$$

Let us introduce

$$\mathcal{F}(T, \lambda) = \int_0^T \int_{\mathbb{R}^N} \int_{B(x_0, R+M(T_0-t))} |u(x+y) - u(x)| \mu_\lambda(y) dx dy dt.$$

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The doubling variables method gives the estimate:

$$\partial_T \mathcal{F}(T, \lambda) \leq \partial_T \mathcal{F}(0, \lambda) + C\lambda \partial_\lambda \mathcal{F}(T, \lambda) + C' \mathcal{F}(T, \lambda) + \lambda \int_0^T A(t) dt,$$

where  $A(t) = \int_{\mathbb{R}^N} \|\nabla(F - \operatorname{div} f)(t, x \cdot)\|_{L^\infty(du)}$ .

We integrate in time and divide by  $CT\lambda$  :

$$0 \leq \frac{1}{C\lambda} \mathcal{F}(0, \lambda) + \partial_\lambda \mathcal{F}(T, \lambda) + \frac{\alpha(T)}{\lambda} \mathcal{F}(T, \lambda) + \frac{1}{C} \int_0^T A(t) dt,$$

where  $\alpha(T) = N + C'/C - 1/T \rightarrow -\infty$  when  $T \rightarrow 0$ . We choose  $T$  small enough and we integrate on  $[\lambda, +\infty[$ .

We obtain

$$\mathcal{F}(T, \lambda) \leq \frac{\lambda}{-\alpha - 1} KTV(u_0) + \frac{\lambda}{C(-\alpha - 1)} \int_0^T A(t) dt.$$

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## Dependence with respect to flow and source

### Theorem (Flow/Source...)

Assume  $(f, F), (g, G)$  satisfy **(K)**,  $(f, F)$  satisfies **(H1)** and  $(f - g, F - G)$  satisfies **(H2)**.  
Let  $u_0, v_0 \in (\mathbf{L}^1 \cap \mathbf{L}^\infty \cap \mathbf{BV})(\mathbb{R}^N; \mathbb{R})$ . We denote

$$\kappa = 2N \|\nabla_x \partial_u f\|_{\mathbf{L}^\infty(\Omega_M)} + \|\partial_u F\|_{\mathbf{L}^\infty(\Omega_M)} + \|\partial_u(F - G)\|_{\mathbf{L}^\infty(\Omega_M)}.$$

Let  $u$  and  $v$  be the solutions associated to  $(f, F)$  and  $(g, G)$  respectively and with initial conditions  $(u_0, v_0)$ .

**(H2)** :  $\partial_u(F - G) \in \mathbf{L}^\infty(\Omega_M)$ ,  $\partial_u(f - g) \in \mathbf{L}^\infty(\Omega_M)$  and  
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## Theorem (...Flow/Source)

then  $\forall t \in [0, T]$ :

$$\begin{aligned} \|(u - v)(t)\|_{L^1} &\leq e^{\kappa t} \|u_0 - v_0\|_{L^1} + \frac{e^{\kappa_0 t} - e^{\kappa t}}{\kappa_0 - \kappa} \text{TV}(u_0) \|\partial_u(f - g)\|_{L^\infty} \\ &\quad + \int_0^t \frac{e^{\kappa_0(t-\tau)} - e^{\kappa(t-\tau)}}{\kappa_0 - \kappa} \int_{\mathbb{R}^N} \|\nabla_x(F - \text{div}f)(\tau, x, \cdot)\|_{L^\infty(du)} dx d\tau \\ &\quad \quad \times \text{NW}_N \|\partial_u(f - g)\|_{L^\infty} \\ &\quad + \int_0^t e^{\kappa(t-\tau)} \int_{\mathbb{R}^N} \|((F - G) - \text{div}(f - g))(\tau, x, \cdot)\|_{L^\infty(du)} dx d\tau. \end{aligned}$$

Remark : As before, we re-obtain known estimates in some particular cases

- $f, g$  depend only on  $u$ ,  $F = G = 0$ ,
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## Pedestrian Traffic (Colombo, Herty, Mercier)

We now consider equations of the type

$$\partial_t u + \operatorname{Div}(uV(u)) = 0; \quad u_0 \in (\mathbf{L}^1 \cap \mathbf{L}^\infty \cap \mathbf{BV})(\mathbb{R}^N; \mathbb{R})$$

where  $V : \mathbf{L}^1 \rightarrow \mathcal{C}^2$  is a non-local functional.

## Existence of a solution

### Theorem (Traffic)

If  $V$  satisfies **(V1)**, then there exists a time  $T_{\text{ex}} > 0$  and a unique entropy solution

$$u \in \mathcal{C}^0([0, T_{\text{ex}}[; \mathbf{L}^1 \cap \mathbf{L}^\infty \cap \mathbf{BV})$$

and we denote  $S_t u_0 = u(t, \cdot)$ .

We can bound by below the time of existence by

$$T_{\text{ex}} \geq \sup \left\{ \sum_n \frac{\ln(\alpha_{n+1}/\alpha_n)}{C(\alpha_{n+1})}; (\alpha_n)_n \text{ strict. increasing, } \alpha_0 = \|u_0\|_{\mathbf{L}^\infty} \right\}.$$

If furthermore,  $V$  satisfies **(V2)** then

$$u_0 \in \mathbf{W}^{2,1} \cap \mathbf{L}^\infty \Rightarrow \forall t \in [0, T_{\text{ex}}[, \quad u(t) \in \mathbf{W}^{2,1}.$$

## Hypotheses

**(V1)** There exists  $C \in \mathbf{L}_{\text{loc}}^{\infty}(\mathbb{R}_+; \mathbb{R}_+)$  such that  $\forall u \in \mathbf{L}^1(\mathbb{R}^N; \mathbb{R})$

$$\begin{aligned} V(u) &\in \mathbf{L}^{\infty}, & \|\nabla_x V(u)\|_{\mathbf{L}^{\infty}} &\leq C(\|u\|_{\mathbf{L}^{\infty}}), \\ \|\nabla_x V(u)\|_{\mathbf{L}^1} &\leq C(\|u\|_{\mathbf{L}^{\infty}}), & \|\nabla_x^2 V(u)\|_{\mathbf{L}^1} &\leq C(\|u\|_{\mathbf{L}^{\infty}}), \end{aligned}$$

and  $\forall u_1, u_2 \in \mathbf{L}^1(\mathbb{R}^N; \mathbb{R})$

$$\begin{aligned} \|V(u_1) - V(u_2)\|_{\mathbf{L}^{\infty}} &\leq C(\|u_1\|_{\mathbf{L}^{\infty}})\|u_1 - u_2\|_{\mathbf{L}^1}, \\ \|\nabla_x(V(u_1) - V(u_2))\|_{\mathbf{L}^1} &\leq C(\|u_1\|_{\mathbf{L}^{\infty}})\|u_1 - u_2\|_{\mathbf{L}^1}. \end{aligned}$$

**(V2)** There exists  $C \in \mathbf{L}_{\text{loc}}^{\infty}(\mathbb{R}_+; \mathbb{R}_+)$  such that  $\|\nabla_x^3 V(u)\|_{\mathbf{L}^{\infty}} \leq C(\|u\|_{\mathbf{L}^{\infty}})$ .

## Idea of the proof:

Let us introduce the space  $X_\alpha = \mathbf{L}^1 \cap \mathbf{BV}(\mathbb{R}^N; [0, \alpha])$  and the application  $\mathcal{Q}$  that associates to  $w \in \mathcal{X}_\beta = \mathcal{C}^0([0, T[, X_\beta)$  the solution  $u \in \mathcal{X}_\beta$  of the Cauchy problem

$$\partial_t u + \operatorname{Div}(uV(w)) = 0, \quad u(0, \cdot) = u_0 \in X_\alpha$$

For  $w_1, w_2$ , we obtain thanks to the estimate of Thm (Flow/Source)

$$\|\mathcal{Q}(w_1) - \mathcal{Q}(w_2)\|_{L^\infty([0, T[, L^1)} \leq f(T) \|w_1 - w_2\|_{L^\infty([0, T[, L^1)},$$

where  $f$  is increasing,  $f(0) = 0$  and  $f \rightarrow_{T \rightarrow \infty} \infty$ .

Then we apply the Banach Fixed Point Theorem.

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# Plan

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  - Previous Results
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**Definition :** The application  $S : \mathbf{L}^1(\mathbb{R}^N; \mathbb{R}) \rightarrow \mathbf{L}^1(\mathbb{R}^N; \mathbb{R})$  is said to be **L<sup>1</sup> Gâteaux differentiable** in  $u_0 \in \mathbf{L}^1$  in the direction  $r_0 \in \mathbf{L}^1$  if there exists a linear continuous application  $DS(u_0) : \mathbf{L}^1 \rightarrow \mathbf{L}^1$  such that

$$\left\| \frac{S(u_0 + hr_0) - S(u_0)}{h} - DS(u_0)(r_0) \right\|_{\mathbf{L}^1} \xrightarrow{h \rightarrow 0} 0.$$

Formally, we expect the Gâteaux derivative of the semi-group to be the solution of the linearized problem:

$$\partial_t r + \text{Div}(rV(u) + uDV(u)(r)) = 0, \quad r(0, \cdot) = r_0.$$

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We introduce the hypotheses:

**(V3)**  $V : \mathbf{L}^1 \rightarrow \mathcal{C}^2$  is differentiable and there exists  $C \in \mathbf{L}_{\text{loc}}^\infty$  such that  $\forall u, r \in \mathbf{L}^1$ ,

$$\begin{aligned} \|V(u+r) - V(u) - DV(u)(r)\|_{\mathbf{W}^{2,\infty}} &\leq C (\|u\|_{\mathbf{L}^\infty} + \|u+r\|_{\mathbf{L}^\infty}) \|r\|_{\mathbf{L}^1}^2, \\ \|DV(u)(r)\|_{\mathbf{W}^{2,\infty}} &\leq C (\|u\|_{\mathbf{L}^\infty}) \|r\|_{\mathbf{L}^1}. \end{aligned}$$

**(V4)** There exists  $C \in \mathbf{L}_{\text{loc}}^\infty(\mathbb{R}_+; \mathbb{R}_+)$  such that  $\forall u, \tilde{u}, r \in \mathbf{L}^1$

$$\begin{aligned} \left\| \operatorname{div} (V(\tilde{u}) - V(u) - DV(u)(\tilde{u} - u)) \right\|_{\mathbf{L}^1} &\leq C (\|\tilde{u}\|_{\mathbf{L}^\infty} + \|u\|_{\mathbf{L}^\infty}) (\|\tilde{u} - u\|_{\mathbf{L}^1})^2 \\ \left\| \operatorname{div} (DV(u)(r)) \right\|_{\mathbf{L}^1} &\leq C (\|u\|_{\mathbf{L}^\infty}) \|r\|_{\mathbf{L}^1}. \end{aligned}$$

We show that the linearised problem has a unique entropy solution:

### Theorem (Linearised)

Assume that  $V$  satisfies **(V1)**, **(V2)**, **(V3)**. Let  $u \in C^0([0, T_{\text{ex}}[; \mathbf{W}^{1,\infty} \cap \mathbf{W}^{1,1})$ ,  $r_0 \in (\mathbf{L}^1 \cap \mathbf{L}^\infty)(\mathbb{R}^N; \mathbb{R})$ . Then the linearised problem

$$\partial_t r + \text{Div}(rV(u) + uDV(u)(r)) = 0, \quad \text{with } r(0, x) = r_0$$

has a unique entropy solution  $r \in C^0([0, T_{\text{ex}}[; \mathbf{L}^1(\mathbb{R}^N; \mathbb{R}))$  and we denote  $\Sigma_t^u r_0 = r(t, \cdot)$ . If furthermore  $r_0 \in \mathbf{W}^{1,1}$ , then  $\forall t \in [0, T_{\text{ex}}[, r(t) \in \mathbf{W}^{1,1}$ .

## Theorem (Gâteaux Derivative)

Assume that  $V$  satisfies (V1),(V2),(V3),(V4). Let  $u_0 \in \mathbf{W}^{1,\infty} \cap \mathbf{W}^{2,1}$ ,  $r_0 \in \mathbf{W}^{1,1} \cap \mathbf{L}^\infty$  and let  $T_{\text{ex}}$  be the time of existence for the initial problem given by Thm (Trafic). Then, for all  $t \in [0, T_{\text{ex}}[$  the local semi-group of the pedestrian traffic problem is  $\mathbf{L}^1$  Gâteaux differentiable in the direction  $r_0$  and

$$DS_t(u_0)(r_0) = \sum_t^{S_t u_0} r_0.$$

**Idea of the proof:** Thm (Flow/Source) allows to compare the solution with initial condition  $u_0 + hr_0$  to the solution  $u + hr$ .

Let  $u, u_h$  be the solutions of the Cauchy problem  $\partial_t u + \text{Div}(uV(u)) = 0$  with initial conditions  $u_0, u_0 + hr_0$ . Let  $r$  be the solution of the Linearized equation  $\partial_t r + \text{Div}(rV(u) + uDV(u)(r)) = 0$ , with  $r(0) = r_0$ . We define then  $z_h = u + hr$  that satisfies

$$\partial_t z_h + \text{Div}(z_h(V(u) + hDV(u)(r))) = h^2 \text{Div}(rDV(u)(r)), \quad z_h(0) = u_0 + hr_0.$$

Next, we use Thm (Flow/Source) to compare  $u_h$  and  $z_h$ . We obtain

$$\begin{aligned} \frac{1}{h} \|u_h - z_h\|_{L^\infty([0, T], L^1)} \leq F(T) & \left( \frac{1}{h} \|u_h - u\|_{L^\infty(L^1)}^2 + \frac{1}{h} \|u_h - z_h\|_{L^\infty(L^1)} \right) \\ & + hC(\beta) Te^{C(\beta)T} \|r\|_{L^\infty(W^{1,1})} \|r\|_{L^\infty(L^1)}, \end{aligned}$$

where  $F$  is increasing and  $F(0) = 0$ .

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Let  $J$  be a cost functional such that

$$J(\rho_0) = \int_{\mathbb{R}^N} f(S_t \rho_0) \psi(t, x) dx.$$

### Proposition







Let  $f \in C^{1,1}(\mathbb{R}; \mathbb{R}_+)$  and  $\psi \in L^\infty(I_{\text{ex}} \times \mathbb{R}^N; \mathbb{R})$ . Let us assume that  $S: I \times (L^1 \cap L^\infty)(\mathbb{R}^N; \mathbb{R}) \rightarrow (L^1 \cap L^\infty)(\mathbb{R}^N; \mathbb{R})$  is  $L^1$  Gâteaux differentiable. If  $\rho_0 \in (L^1 \cap L^\infty)(\mathbb{R}^N; \mathbb{R})$  is solution of

$$\text{Find } \min_{\rho_0} J(\rho_0) \text{ s. t. } \{S_t \rho_0 \text{ is solution of (Traffic)}\}.$$

then, for all  $r_0 \in (L^1 \cap L^\infty)(\mathbb{R}^N; \mathbb{R})$

$$\int_{\mathbb{R}^N} f'(S_t \rho_0) \Sigma_t^{\rho_0} r_0 \psi(t, x) dx = 0.$$

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