

Calculus of Variations and Elliptic Equations

5th class

From local to global regularity – reflections

Let $\Omega \subset \mathbb{R}^d$ be a compact domain, closure of an open set, with a flat part in $\partial\Omega$ and $R : \mathbb{R}^d \rightarrow \mathbb{R}^d$ a reflection which fixes this part. For instance, if $\Omega = [0, 1]^d$, we can consider $R(x_1, \dots, x_d) = (-x_1, \dots, x_d)$. The map R is linear, self-adjoint, with determinant equal to -1 , and $R^2 = id$.

Suppose that $u \in H_0^1(\Omega)$ solves in the weak sense $\Delta u = f$. Define $\tilde{\Omega} := \Omega \cup R(\Omega)$ and

$$\tilde{u}(x) = \begin{cases} u(x) & \text{if } x \in \Omega, \\ -u(Rx) & \text{if } x \in R(\Omega), \end{cases}$$

We define in analogous way \tilde{f} . Note that the condition $u \in H_0^1$ (i.e., zero on the boundary) makes \tilde{u} well-defined on $\Omega \cap R(\Omega)$ and we have $\tilde{u} \in H_0^1(\tilde{\Omega})$. This is not the case for f if we do not suppose any boundary condition on it, but $f \in L^p(\Omega)$ clearly implies $\tilde{f} \in L^p(\tilde{\Omega})$.

We want to prove that we also have $\Delta \tilde{u} = \tilde{f}$ in $\tilde{\Omega}$. To do so, we take a test function $\varphi \in H_0^1(\tilde{\Omega})$ and we compute

$$\int_{\tilde{\Omega}} \nabla \tilde{u} \cdot \nabla \varphi = \int_{\Omega} \nabla u \cdot \nabla \varphi + \int_{R(\Omega)} -R \nabla u \circ R \cdot \nabla \varphi.$$

Now, we have

$$\int_{R(\Omega)} R \nabla u \circ R \cdot \nabla \varphi = \int_{R(\Omega)} \nabla u \circ R \cdot R \nabla \varphi = \int_{\Omega} \nabla u \cdot R \nabla \varphi \circ R = \int_{\Omega} \nabla u \cdot \nabla(\varphi \circ R),$$

where the first equality comes from R being self-adjoint and the second is a change-of-variable. If we now set $\hat{\varphi} := \varphi - \varphi \circ R$ we have

$$\int_{\tilde{\Omega}} \nabla \tilde{u} \cdot \nabla \varphi = \int_{\Omega} \nabla u \cdot \nabla \hat{\varphi}.$$

We just need to observe that we have $\hat{\varphi} \in h_0^1(\Omega)$ since it vanishes both on $\partial\Omega \setminus R(\Omega)$ (as a consequence of $\varphi \in H_0^1(\tilde{\Omega})$) and on $\partial\Omega \cap R(\Omega)$ (because here R is the identity). We then have

$$\int_{\tilde{\Omega}} \nabla \tilde{u} \cdot \nabla \varphi = \int_{\Omega} \nabla u \cdot \nabla \hat{\varphi} = - \int_{\Omega} f \hat{\varphi} = - \int_{\Omega} f \varphi + \int_{\Omega} f \varphi \circ R.$$

In the very last integral we can use a change of variable and obtain $\int_{\Omega} f \varphi \circ R = \int_{R(\Omega)} f \circ R \varphi$, so that we finally have

$$\int_{\tilde{\Omega}} \nabla \tilde{u} \cdot \nabla \varphi = - \int_{\tilde{\Omega}} \tilde{f} \varphi,$$

which means $\Delta \tilde{u} = \tilde{f}$.

In the case of Neumann boundary conditions instead of Dirichlet ones it is possible to use a different symmetrization, namely

$$\tilde{u}(x) = \begin{cases} u(x) & \text{if } x \in \Omega, \\ u(Rx) & \text{if } x \in R(\Omega), \end{cases}$$

and the same for \tilde{f} (no change of sign in $R(\Omega)$). This is useful because if u does not vanish on the boundary the extension with the change of sign does not belong to H^1 . On the other hand, the function $\hat{\varphi}$ will be now defined as $\hat{\varphi} := \varphi + \varphi \circ R$ and does not vanish anymore on $\partial\Omega \cap R(\Omega)$, but since u solves $\Delta u = f$ with Neumann boundary conditions, the relation $\int \nabla u \cdot \nabla \phi = - \int f \phi$ is true for any $\phi \in H^1(\Omega)$, with no conditions on the values on the boundary.

Proposition 1. *Suppose that $u \in H_0^1(\Omega)$ is a weak solution of $\Delta u = f$ (i.e. $\int \nabla u \cdot \nabla \phi = -\int f \phi$ for every $\phi \in C_c^1(\Omega)$) with $f \in L^p(\Omega)$ and Ω is a cube. Then $u \in W^{2,p}(\Omega)$.*

Suppose that $u \in H^1(\Omega)$ is weak solution of $\Delta u = f$ with Neumann boundary conditions (i.e. $\int \nabla u \cdot \nabla \phi = -\int f \phi$ for every $\phi \in C^1(\Omega)$) with $f \in L^p(\Omega)$ and Ω is a cube. Then $u \in W^{2,p}(\Omega)$. If moreover $f \in W^{1,p}(\Omega)$ then $u \in W^{3,p}(\Omega)$.

Proof. Both for the Dirichlet and for the Neumann case we can iterate reflections R_k so that we iterately extend u into functions u_k , defined on $\Omega_k := \Omega_{k-1} \cup R_{k-1}(\Omega_{k-1})$, with $\Omega_0 = \Omega$, and extending f to f_k on the same domains, with $\Delta u_k = f_k$, according to the construction that we previously detailed. After a suitable number of iterations if the reflections are well-chosen then Ω is compactly contained in Ω_k and the local regularity result coming from the L^p theory for the Laplacian (see [1]) implies $u \in W^{2,p}$ if $f_k \in W^{2,p}$. Since reflections preserve the L^p summability, we do have $f_k \in L^p(\Omega_k)$ and we can apply this to $u \in W^{2,p}(\Omega)$ in both cases. Should we have $f_k \in W^{1,p}$, by differentiating the equation we would also have $u \in W^{3,p}(\Omega)$ (note that we need to first reflect and then differentiate, since if we first differentiate the equation we lose the boundary data). On the other hand, the reflection defined with a minus sign in the Dirichlet case in general destroy the $W^{1,p}$ behavior as they create discontinuities at the common boundary between Ω and $R(\Omega)$, so we cannot conclude the $W^{3,p}$ regularity in the Dirichlet case. Yet, this can be done in the Neumann case as the reflection without changing the sign preserves the $W^{1,p}$ behavior. \square

References

- [1] D. GILBARG, N. TRUDINGER, *Elliptic Partial Differential Equations of Second Order*, Springer Verlag, Berlin, 1977.