Transparent boundary conditions for the elastic waves in anisotropic media

Ivan L. Sofronov, Nickolai A. Zaitsev

Keldysh Institute of Applied Mathematics RAS, Moscow

Outline

- Problem formulation
- Generation of LRBC operator, main steps
- Numerical tests
- Conclusions

Motivation

Generation of low-reflecting boundary conditions on open boundaries for anisotropic elastodynamics is a challenging problem. The PML method is not stable in this case, see

- ÿ *Beaches E., Fauqueux S., Joly P.,* Stability of perfectly matched layers group velocities and anisotropic waves, *JCP, 188, 2003, 399 – 433;*
- ÿ *D. Appelö and G. Kreiss,* A New Absorbing Layer for Elastic Waves, *JCP, 215, 2006, 642 – 660.*

Figure 13: Some snapshots at different times for the orthotropic media (IV).

Low-reflecting boundary conditions (LRBC)

LRBC on "open boundaries" are needed for modeling of wave propagation using a bounded computational domain.

Typical setup:

Generation of LRBC on Γ is an additional problem which is set up by considering auxiliary external Initial Boundary Value Problems (IBVPs) outside *C*.

Remark: In the domain of interest the governing equations and geometry can be much more complex than outside *C*.

Anisotropic elasticity, 2D orthotropic media

We consider 2D elastodynamic equations:

$$
\rho \frac{\partial^2 v_1}{\partial t^2} = c^{11} \frac{\partial^2 v_1}{\partial x_1^2} + c^{33} \frac{\partial^2 v_1}{\partial x_2^2} + (c^{33} + c^{12}) \frac{\partial^2 v_2}{\partial x_1 \partial x_2},
$$

$$
\rho \frac{\partial^2 v_2}{\partial t^2} = c^{33} \frac{\partial^2 v_2}{\partial x_1^2} + c^{22} \frac{\partial^2 v_2}{\partial x_2^2} + (c^{33} + c^{12}) \frac{\partial^2 v_1}{\partial x_1 \partial x_2}.
$$

Here ρ is density; (v_1, v_2) is the Cartesian velocities; $\{c^{nm}\}$ are (constant) elastic coefficients of the Hook's law written in the matrix form, $\sigma^n = c^{nm} \varepsilon_m^{}$.

In polar coordinates for the velocity vector $f = (v_r, v_{\theta})$ the system reads:

$$
\frac{\partial^2 f}{\partial t^2} = A^{11} \frac{\partial^2 f}{\partial r^2} + A^{22} \frac{\partial^2 f}{\partial \theta^2} + A^{12} \frac{\partial^2 f}{\partial r \partial \theta} + A^1 \frac{\partial f}{\partial r} + A^2 \frac{\partial f}{\partial \theta} + A^0 f
$$

where $A^{ij}(r,\theta)$, $A^{i}(r,\theta)$ are 2x2 matrices

Generation of LRBC operator, main steps

Governing equation in 2D space: $f_{tt} - Lf = 0$

Main steps:

Stage 1: consider a set of auxiliary external IBVPs outside *C* (set wrt "*m*"):

$$
\left\{\begin{aligned}\n\mathcal{E}^{m}{}_{t} - L\mathcal{E}^{m} &= 0 \quad \text{in} \quad R^{2}/C \\
\mathcal{E}^{m}{}_{\vert_{\Gamma} = \boldsymbol{\delta}(t)\boldsymbol{\varphi}^{m}(\boldsymbol{\theta})} &= 0\n\end{aligned}\right.
$$
\n(1)

where $\delta(t)$ is Dirac's delta function;

 $\{\varphi^m(\theta)\}_{m=0}^{\infty}$ is a basis on Γ , i.e. (in 2D it is constructed, e.g., by using $\{\sin k\theta, \cos k\theta\}$) *m* $\sum_{m=0}^{\infty}$ is a basis on Γ , i.e. $f(t,\theta) = \sum c^{m}(t) \varphi^{m}(\theta)$ *m*

Stage 2: make Laplace transform and pass to elliptic BVPs (parameterized by *s*):

$$
\begin{cases}\n\sum_{r \to \infty} \mathbf{S}^2 \hat{\mathcal{E}}^m - L \hat{\mathcal{E}}^m = 0 & \text{in } \mathbb{R}^2 / C \\
\hat{\mathcal{E}}^m \big|_{r \to \infty} = 0 & (2)\n\end{cases}
$$

Stage 3: solve (numerically) the problems and evaluate $\frac{\partial}{\partial z} \hat{\mathcal{E}}^m(r,\theta)$ on ∂ $\overline{\Gamma}$ ∂ *m r n* $\mathcal{E}_{\mathcal{E}}$

Thus we obtain the Dirichlet-to-Neumann maps

$$
\varphi^{m}(\theta) \mapsto \psi^{m}(\theta)[s] \quad \left(\equiv \frac{\partial}{\partial n} \hat{\mathcal{E}}^{m}(\theta, r), r = R_{\Gamma} \right)
$$

Stage 4: form matrix of the Poincare-Steklov operator:

we take arbitrary data on Γ

$$
\hat{f}(s,\theta) = \sum_{m} \hat{c}^{m}(s)\varphi^{m}(\theta)
$$

and write the representation of its normal derivative on Γ

$$
\frac{\partial}{\partial n}\hat{f}(s,\theta) = \sum_{m}\hat{c}^{m}(s)\psi^{m}(\theta)[s] = \sum_{m}\hat{c}^{m}(s)\sum_{n}P_{n}^{m}(s)\varphi^{n}(\theta)
$$

Thus we obtain the Poincare-Steklov operator in space of Fourier coefficients:

$$
\hat{d}^n(s) = \sum_n \hat{P}_n^m(s) \hat{c}^m(s) \qquad \left(\frac{\partial}{\partial n} \hat{f}(s,\theta) = \sum_n \hat{d}^n(s) \varphi^n(\theta)\right)
$$

or, in matrix form:

$$
\hat{\mathbf{d}}(s) = \hat{\mathbf{P}}(s)\hat{\mathbf{c}}(s), \qquad \hat{\mathbf{c}} = \left\{\hat{c}^0, \hat{c}^1, \ldots\right\}^T
$$

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Stage 5: make inverse Laplace transform for the P-S operator.

First we represent matrix $\hat{\mathbf{P}}(s)$ by sum of three matrices to take into account asymptotic at $s\to\infty$:

 $\hat{\mathbf{P}}(s) = \mathbf{P}_1 s + \mathbf{P}_0 + \hat{\mathbf{K}}(s); \quad \mathbf{P}_1, \mathbf{P}_0 \text{ are const}, \quad \hat{\mathbf{K}}(s) = o(1)$

 $\frac{\textbf{Then}}{\textbf{K}(s)}$ we calculate rational approximations to each entry in $\hat{\textbf{K}}(s)$ such that all poles have negative real parts, i.e.

$$
\hat{K}_n^m(s) \approx \hat{\tilde{K}}_n^m(s) \equiv \sum_{l=1}^{L_n^m} \frac{\alpha_{n\,l}^m}{s - \beta_{n\,l}^m}, \quad \text{Re}(\beta_{n\,l}^m) \le \delta < 0
$$

Finally the inverse Laplace transform of $\hat{\mathbf{d}}(s) = \hat{\mathbf{P}}(s)\hat{\mathbf{c}}(s)$ gives:

$$
\mathbf{d}(t) = \mathbf{P}_1 \frac{\partial \mathbf{c}(t)}{\partial t} + \mathbf{P}_0 \mathbf{c}(t) + \tilde{\mathbf{K}}(t) * \mathbf{c}(t)
$$

Remark: the explicit form of kernels $\tilde{K}_n^m(t)$ is

$$
\tilde{K}_n^m(t) = \sum_{l=1}^{L_n^m} \alpha_{n\ l}^m \exp(\beta_{n\ l}^m t), \qquad \qquad \text{Re}(\beta_{n\ l}^m) \le \delta < 0
$$

that permits to treat convolutions by *stable recurrent* formulas.

Stage 6: compose azimuth modes:

Denote by Q the operator of Fourier decomposition for $f(t, \theta) = \sum_{n=0}^{\infty} c^m(t) \varphi^m(\theta)$ i.e. $\mathbf{Q}: f(t, \theta) \rightarrow \left\{ c^{m}(t) \right\}$. Consequently, $\mathbf{Q}^{-1}:\left\{ c^{m}(t) \right\}, \; \left\{ d^{m}(t) \right\}$. *m* $\{-1:\left\{c^m(t)\right\},\left\{d^m(t)\right\}\to f,\frac{\partial}{\partial t}$ ∂ $m_{(f)}$ $\left(\frac{1}{d}m_{(f)}\right)$ $\left(\frac{1}{d}m_{(f)}\right)$ $c^m(t)\langle, \ \{d^m(t)\}\rightarrow f$ *n* **Q**

The LRBC in the physical space reads:

$$
\mathbf{Q}^{-1}\mathbf{P}_{1}\mathbf{Q}\frac{\partial f}{\partial t} - \frac{\partial f}{\partial n} + \mathbf{Q}^{-1}\mathbf{P}_{0}\mathbf{Q}f + \mathbf{Q}^{-1}\left\{\tilde{\mathbf{K}}(t)*\right\}\mathbf{Q}f = 0
$$

Setup of the test problem

Governing equations are implemented in the polar system of coordinates. We consider the task in a circle:

- At $R_0 = 2$ we prescribe Dirichlet data (pulse) to initiate elastic waves;
- Γ with radius $R_{\Gamma} = 10$ is the external boundary where we put LRBC (with 36 azimuth harmonics).

The verification of LRBC is made by comparing with the *reference solution* of a second problem having *8x* bigger external radius (extended domain). Comparison of two solutions in *C*-norm is made at $r < R_{\Gamma}$.

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Test calculations

Parameters of anisotropic media are taken from

Beaches E., Fauqueux S., Joly P., Stability of perfectly matched layers group velocities and anisotropic waves, *JCP, 188, 2003, 399 – 433:*

anisotropic medium, case IV: $c_{11} = 4$, $c_{22} = 20$, $c_{33} = 2$, $c_{12} = 7.5$

Figure 13: Some snapshots at different times for the orthotropic media (IV).

Anisotropic case-IV, t=0.52

Anisotropic case-IV, t=1.92

Anisotropic case-IV, t=2.62

Anisotropic case-IV, t=3.32

Anisotropic case-IV, t=4.01

Anisotropic case-IV, t=4.71

Anisotropic case-IV, t=5.41

Anisotropic case-IV, t=6.11

Anisotropic case-IV, t=6.81

Anisotropic case-IV, t=7.50

Anisotropic case-IV, t=12.0

 U_r

Difference between LRBC and Reference solution

 $t=5.4$ 10 15 5

t=12.7 -10 -5 $\mathbf{0}$ $\overline{5}$ 10 15

LRBC stability at large times

Conclusions

• A novel approach to generate numerical LRBCs for anisotropic time-domain wave propagation problems is proposed and implemented in 2D

• LRBCs are efficient in both isotropic and anisotropic media, including the case where PML approach fails (case IV)

• LRBC operator does not depend on the meshing inside the computational domain

• LRBC efficiency (amplitude of reflected waves) can be automatically controlled during generation of the operator

• It is possible to generate in advance a library of LRBC matrices for given media parameters and geometry of computational domain

• The algorithm is highly parallelized

Further research

• The approach is still computationally expensive and must be revised and improved to enhance the performance

• Real*16 accuracy

• 3D problems

LRBC operator, numerical aspects

Main features of the algorithm for *discretized system:*

Stages 1–6: we take discrete azimuth basis $\{\sin k\theta, \cos k\theta\}$, $k = 0, 1, ..., M$; $(M = 20)$;

Stage 2 [Laplace image]: we take a finite interval $[0, S_{\text{max}}]$ and choose set of knots $\{s_j\} \in [0, S_{\text{max}}]$ which are representative enough to consider discrete counterparts of kernels $\hat{P}^m_n(s_j)$ for rational approximation (Stage 5).

> In particular, the Chebyshev's nodes are used:

$$
s_j = \frac{S_{\text{max}}}{2} \left(1 - \cos\left(\pi \frac{j - 0.5}{J}\right) \right), \ \ j = 1, ..., J
$$

$$
J \sim 100
$$

LRBC operator, numerical aspects (cont.)

Stages 3-4 [P-S operator]: we discretise governing equations by *pseudospectral* derivatives in azimuth direction (uniform grid) and *finite differences* in radial direction (exponential grid) and make massive calculations to evaluate each $\hat{P}^m_n(s_{\overline{j}})$ with a guarantied accuracy, ε_{PS} ~ 10^{-10} (controlled by mesh convergence). Number of separate tasks is $4*(M+1)*J;$

LRBC operator, numerical aspects (cont.)

Stage 5 [inverse Laplace transform]:

Constant matrices P_1 , P_0 are estimated from the rational approximations

$$
R_n^m(s_j) \approx \hat{P}_n^m(s_j)
$$

on the interval $[0, S_{\max}]$ $\;$ $(R_n^m(s)$ is calculated by Chebyshev-Pade algorithm), and the reminder matrix is formed:

$$
\hat{\mathbf{K}}(s_j) := \hat{\mathbf{P}}(s_j) - \mathbf{P}_1 s_j - \mathbf{P}_0
$$

 $\overline{\textbf{Rational approximations}}$ are calculated for each $\hat{K}^m_n(s_j):$

$$
\left\| \sum_{l=1}^{L} \frac{\alpha_{l}}{s_{j} - \beta_{l}} - \hat{K}(s_{j}) \right\|_{\{s_{j}\}}^{2} \to \min_{\alpha_{l}, \beta_{l}} , \text{ Re}(\beta_{l}) \le \delta < 0
$$

(indices $\frac{m}{n}$ at $\hat{K}, L, \alpha, \beta$ are omitted); $L = 8$.

The minimization is made by an optimization algorithm.

LRBC operator, numerical aspects (cont.)

As a result we obtain the rational functions $K_n^m(s)$ satisfying $\hat{\tilde{K}}_n^m(s)$

$$
|\hat{K}_n^m(s_j) - \hat{\tilde{K}}_n^m(s_j)| < \varepsilon_R \qquad (\varepsilon_R \sim 10^{-8})
$$

They are explicitly inverted from the Laplace space:

$$
\hat{\tilde{K}}_n^m(s) \mapsto \tilde{K}_n^m(t) \equiv \sum_{l=1}^{L_n^m} \alpha_{n\ l}^m \exp(\beta_{n\ l}^m t), \qquad \text{Re}(\beta_{n\ l}^m) \le \delta < 0
$$

 \mathbf{G} *kage* 6 *[discrete NRBC]:* introducing matrices $\mathbf{Q}_M^{-1}, \mathbf{Q}_M$ of the discrete Fourier transform for vector-functions $\,f = (v_r, v_\theta \,) \,$ in $\,$ *sin-cos* basis, we write out our discrete BC:

$$
\mathbf{Q}_M^{-1} \mathbf{P}_1 \mathbf{Q}_M \frac{\partial f}{\partial t} - \frac{\partial f}{\partial n} + \mathbf{Q}_M^{-1} \mathbf{P}_0 \mathbf{Q}_M f + \mathbf{Q}_M^{-1} {\{\tilde{\mathbf{K}}(t) * \} \mathbf{Q}_M f} = 0
$$

Remark: in isotropic case $P_1 = p_1 I$, $P_0 = p_0 I$, $\tilde{K}(t)$ is diagonal

LRBC matrix, amplitude $|P_1^m|$

LRBC matrix, entry $n = (14,1) \rightarrow m = (18,3)$

