

Computation of the Lax matrix L in the oper gauge from a general Lax matrix \td{L} and application to the gl_3 case of one pole at infinity

```

> restart:
with(LinearAlgebra):
with(algcurves):
> L:=Matrix(3,3,0):
L[1,2]:=1:
L[2,3]:=1:
L[3,1]:=L31(lambda):
L[3,2]:=L32(lambda):
L[3,3]:=L33(lambda):
L;

```

$$\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ L31(\lambda) & L32(\lambda) & L33(\lambda) \end{bmatrix} \quad (1.1)$$

```

> tdL:=Matrix(3,3,0):
tdL[1,1]:=tdL11(lambda):
tdL[1,2]:=tdL12(lambda):
tdL[1,3]:=tdL13(lambda):
tdL[2,1]:=tdL21(lambda):
tdL[2,2]:=tdL22(lambda):
tdL[2,3]:=tdL23(lambda):
tdL[3,1]:=tdL31(lambda):
tdL[3,2]:=tdL32(lambda):
tdL[3,3]:=tdL33(lambda):
tdL;

```

$$\begin{bmatrix} tdL11(\lambda) & tdL12(\lambda) & tdL13(\lambda) \\ tdL21(\lambda) & tdL22(\lambda) & tdL23(\lambda) \\ tdL31(\lambda) & tdL32(\lambda) & tdL33(\lambda) \end{bmatrix} \quad (1.2)$$

```

> G:=Matrix(3,3,0):
G[1,1]:=G11(lambda):
G[1,2]:=G12(lambda):
G[1,3]:=G13(lambda):
G[2,1]:=G21(lambda):
G[2,2]:=G22(lambda):
G[2,3]:=G23(lambda):

```

```

G[3,1]:=G31(lambda):
G[3,2]:=G32(lambda):
G[3,3]:=G33(lambda):
G;
dGdlambda:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do dGdlambda[i,j]:=diff
(G[i,j],lambda): od: od:
dGdlambda;


$$\begin{bmatrix} G11(\lambda) & G12(\lambda) & G13(\lambda) \\ G21(\lambda) & G22(\lambda) & G23(\lambda) \\ G31(\lambda) & G32(\lambda) & G33(\lambda) \end{bmatrix} \quad (1.3)$$



$$\begin{bmatrix} \frac{d}{d\lambda} G11(\lambda) & \frac{d}{d\lambda} G12(\lambda) & \frac{d}{d\lambda} G13(\lambda) \\ \frac{d}{d\lambda} G21(\lambda) & \frac{d}{d\lambda} G22(\lambda) & \frac{d}{d\lambda} G23(\lambda) \\ \frac{d}{d\lambda} G31(\lambda) & \frac{d}{d\lambda} G32(\lambda) & \frac{d}{d\lambda} G33(\lambda) \end{bmatrix}$$


> ToCancel:=simplify(L-Multiply(Multiply(G,tdL),G^(-1))-h*
Multiply(dGdlambda,G^(-1))):
> G11:=unapply(1,lambda):
G12:=unapply(0,lambda):
G13:=unapply(0,lambda):
G23:=unapply(tdL13(lambda),lambda):
G22:=unapply(tdL12(lambda),lambda):
G21:=unapply(tdL11(lambda),lambda):
G31:=unapply(tdL12(lambda)*tdL21(lambda)+tdL13(lambda)*tdL31
(lambda)+tdL11(lambda)^2+h*diff(tdL11(lambda),lambda),lambda):
G32:=unapply(tdL12(lambda)*tdL22(lambda)+tdL11(lambda)*tdL12
(lambda)+tdL13(lambda)*tdL32(lambda)+h*diff(tdL12(lambda),
lambda),lambda):
G33:=unapply(tdL12(lambda)*tdL23(lambda)+tdL13(lambda)*tdL33
(lambda)+tdL11(lambda)*tdL13(lambda)+h*diff(tdL13(lambda),
lambda),lambda):
L32:=unapply((-2*(diff(tdL11(lambda),lambda))*tdL13(lambda)*
tdL33(lambda)*tdL12(lambda)*h+2*(diff(tdL11(lambda),lambda))**
tdL13(lambda)*tdL12(lambda)*tdL22(lambda)*h-tdL11(lambda)*(diff
(tdL22(lambda),lambda))*tdL12(lambda)*tdL13(lambda)*h+tdL11
(lambda)*(diff(tdL33(lambda),lambda))*tdL12(lambda)*tdL13
(lambda)*h-2*tdL11(lambda)*tdL22(lambda)*(diff(tdL12(lambda),

```

```

lambda) *tdL13(lambda) *h+2*tdL11(lambda) *tdL12(lambda) *tdL33
(lambda) * (diff(tdL13(lambda), lambda)) *h- (diff(tdL22(lambda),
lambda)) *tdL12(lambda) *tdL13(lambda) *tdL33(lambda) *h+ (diff
(tdL23(lambda), lambda)) *tdL32(lambda) *tdL12(lambda) *tdL13
(lambda) *h- (diff(tdL32(lambda), lambda)) *tdL12(lambda) *tdL23
(lambda) *tdL13(lambda) *h+ (diff(tdL33(lambda), lambda)) *tdL22
(lambda) *tdL12(lambda) *tdL13(lambda) *h+tdL22(lambda) *tdL32
(lambda) *tdL12(lambda) *tdL23(lambda) *tdL13(lambda) -tdL22
(lambda) *tdL32(lambda) *tdL13(lambda) * (diff(tdL13(lambda),
lambda)) *h+tdL22(lambda) * (diff(tdL12(lambda), lambda)) *tdL12
(lambda) *tdL23(lambda) *h-2*tdL22(lambda) * (diff(tdL12(lambda),
lambda)) *tdL13(lambda) *tdL33(lambda) *h+2*tdL22(lambda) *tdL12
(lambda) *tdL33(lambda) * (diff(tdL13(lambda), lambda)) *h+3*tdL32
(lambda) * (diff(tdL12(lambda), lambda)) *tdL23(lambda) *tdL13
(lambda) *h-tdL32(lambda) *tdL12(lambda) *tdL23(lambda) *tdL13
(lambda) *tdL33(lambda) -3*tdL32(lambda) *tdL12(lambda) *tdL23
(lambda) * (diff(tdL13(lambda), lambda)) *h-tdL32(lambda) *tdL13
(lambda) *tdL33(lambda) * (diff(tdL13(lambda), lambda)) *h+ (diff
(tdL12(lambda), lambda)) *tdL12(lambda) *tdL23(lambda) *tdL33
(lambda) *h+ (diff(tdL13(lambda), lambda, lambda)) * (diff(tdL12
(lambda), lambda)) *h^3- (diff(tdL12(lambda), lambda, lambda)) *
(diff(tdL13(lambda), lambda)) *h^3-tdL21(lambda) *tdL12(lambda)
^3*tdL23(lambda)-tdL32(lambda) *tdL12(lambda)^2*tdL23(lambda)^2+
tdL32(lambda)^2*tdL23(lambda)*tdL13(lambda)^2-2*tdL32(lambda) *
(diff(tdL13(lambda), lambda)) ^2*h^2+tdL31(lambda) *tdL32(lambda)
*tdL13(lambda)^3+2*(diff(tdL12(lambda), lambda)) ^2*tdL23
(lambda)*h^2+(diff(tdL12(lambda), lambda)) *tdL13(lambda) *tdL33
(lambda)^2*h+2*(diff(tdL12(lambda), lambda)) *tdL33(lambda) *
(diff(tdL13(lambda), lambda)) *h^2+2*(diff(tdL11(lambda),
lambda)) *(diff(tdL12(lambda), lambda)) *tdL13(lambda) *h^2-2*
(diff(tdL11(lambda), lambda)) *tdL12(lambda) * (diff(tdL13
(lambda), lambda)) *h^2+tdL21(lambda) *tdL22(lambda) *tdL12
(lambda)^2*tdL13(lambda)+tdL21(lambda) *tdL32(lambda) *tdL12
(lambda) *tdL13(lambda)^2-tdL21(lambda) *tdL12(lambda)^2*tdL13
(lambda) *tdL33(lambda)+tdL31(lambda) *tdL22(lambda) *tdL12
(lambda) *tdL13(lambda)^2-tdL31(lambda) *tdL12(lambda)^2*tdL23
(lambda) *tdL13(lambda)-tdL31(lambda) *tdL12(lambda) *tdL13
(lambda)^2*tdL33(lambda)+tdL11(lambda) * (diff(tdL23(lambda),
lambda)) *tdL12(lambda)^2*h-tdL11(lambda) * (diff(tdL32(lambda),
lambda)) *tdL13(lambda)^2*h-tdL11(lambda) *tdL22(lambda)^2*tdL12
(lambda) *tdL13(lambda)-tdL11(lambda) *tdL22(lambda) *tdL32
(lambda) *tdL13(lambda)^2+tdL11(lambda) *tdL22(lambda) *tdL12

```

```

(lambda) ^2*tdL23(lambda)-tdL11(lambda)*tdL32(lambda)*tdL13
(lambda) ^2*tdL33(lambda)+tdL11(lambda)*tdL12(lambda)^2*tdL23
(lambda)*tdL33(lambda)+tdL11(lambda)*tdL12(lambda)*tdL13
(lambda)*tdL33(lambda)^2-(diff(tdL22(lambda), lambda))*tdL12
(lambda)^2*tdL23(lambda)*h-(diff(tdL22(lambda), lambda))*tdL12
(lambda)*(diff(tdL13(lambda), lambda))*h^2+(diff(tdL23(lambda),
lambda))*tdL22(lambda)*tdL12(lambda)^2*h+(diff(tdL23(lambda),
lambda))*tdL12(lambda)*h^2-(diff(tdL32(lambda), lambda))*tdL13(lambda)^2*tdL33(lambda)*h-(diff(tdL32(lambda), lambda))*tdL13(lambda)*(diff(tdL13(lambda),
lambda))*h^2+(diff(tdL33(lambda), lambda))*tdL32(lambda)*tdL13
(lambda)^2*h+(diff(tdL33(lambda), lambda))*(diff(tdL12(lambda),
lambda))*tdL13(lambda)*h^2-tdL22(lambda)^2*tdL12(lambda)*tdL13
(lambda)*tdL33(lambda)-tdL22(lambda)^2*tdL12(lambda)*(diff(tdL13(lambda),
lambda))*h-tdL22(lambda)*tdL32(lambda)*tdL13
(lambda)^2*tdL33(lambda)-2*tdL22(lambda)*(diff(tdL12(lambda),
lambda))*h^2+tdL22(lambda)*tdL12
(lambda)^2*tdL23(lambda)*tdL33(lambda)+tdL22(lambda)*tdL12
(lambda)*tdL13(lambda)*tdL33(lambda)^2+(diff(tdL12(lambda),
lambda))*tdL13(lambda)*tdL12(lambda)*tdL21(lambda)*h+2*(diff(tdL12(lambda),
lambda))*tdL23(lambda)*tdL12(lambda)*tdL11
(lambda)*h-(diff(tdL13(lambda), lambda))*tdL13(lambda)*tdL12
(lambda)*tdL31(lambda)*h-2*(diff(tdL13(lambda), lambda))*tdL13
(lambda)*tdL32(lambda)*tdL11(lambda)*h+(diff(tdL12(lambda),
lambda))*tdL13(lambda)^2*tdL31(lambda)*h-(diff(tdL13(lambda),
lambda))*tdL12(lambda)^2*tdL21(lambda)*h+2*(diff(tdL11(lambda),
lambda))*tdL13(lambda)^2*tdL32(lambda)*h-2*(diff(tdL11(lambda),
lambda))*tdL23(lambda)*tdL12(lambda)^2*h+(diff(tdL13(lambda),
lambda))*tdL32(lambda)*tdL13(lambda)*h^2-(diff(tdL12(lambda),
lambda, lambda))*tdL11(lambda)*tdL13(lambda)*h^2-
(diff(tdL12(lambda), lambda, lambda))*tdL12(lambda)*tdL23
(lambda)*h^2-(diff(tdL12(lambda), lambda, lambda))*tdL13
(lambda)*tdL33(lambda)*h^2+(diff(tdL13(lambda), lambda, lambda))*tdL11(lambda)*tdL12
(lambda)*tdL22(lambda)*tdL12(lambda)*h^2/(tdL13(lambda)*tdL12
(lambda)*tdL22(lambda)+tdL13(lambda)^2*tdL32(lambda)+h*tdL13
(lambda)*(diff(tdL12(lambda), lambda))-tdL23(lambda)*tdL12
(lambda)^2-tdL13(lambda)*tdL33(lambda)*tdL12(lambda)-h*tdL12
(lambda)*(diff(tdL13(lambda), lambda))),lambda):
L33:=unapply(((diff(tdL12(lambda), lambda, lambda))*tdL13
(lambda)*h^2-(diff(tdL13(lambda), lambda, lambda))*tdL12
(lambda)*h^2+tdL13(lambda)*tdL12(lambda)*tdL22(lambda)*tdL11

```

```

(lambda)+tdL13(lambda)^2*tdL32(lambda)*tdL11(lambda)+(diff
(tdL12(lambda), lambda))*tdL13(lambda)*tdL11(lambda)*h-tdL23
(lambda)*tdL12(lambda)^2*tdL11(lambda)-tdL13(lambda)*tdL33
(lambda)*tdL12(lambda)*tdL11(lambda)-(diff(tdL13(lambda),
lambda))*tdL12(lambda)*tdL11(lambda)*h+(diff(tdL22(lambda),
lambda))*tdL13(lambda)*tdL12(lambda)*h-(diff(tdL23(lambda),
lambda))*tdL12(lambda)^2*h+(diff(tdL32(lambda), lambda))*tdL13
(lambda)^2*h-(diff(tdL33(lambda), lambda))*tdL13(lambda)*tdL12
(lambda)*h+tdL13(lambda)*tdL12(lambda)*tdL22(lambda)^2+tdL13
(lambda)^2*tdL22(lambda)*tdL32(lambda)+2*(diff(tdL12(lambda),
lambda))*tdL13(lambda)*tdL22(lambda)*h-tdL23(lambda)*tdL12
(lambda)^2*tdL22(lambda)+tdL13(lambda)^2*tdL33(lambda)*tdL32
(lambda)+2*(diff(tdL13(lambda), lambda))*tdL13(lambda)*tdL32
(lambda)*h-2*(diff(tdL12(lambda), lambda))*tdL23(lambda)*tdL12
(lambda)*h-tdL23(lambda)*tdL33(lambda)*tdL12(lambda)^2-tdL13
(lambda)*tdL33(lambda)^2*tdL12(lambda)-2*(diff(tdL13(lambda),
lambda))*tdL33(lambda)*tdL12(lambda)*h/(tdL13(lambda)*tdL12
(lambda)*tdL22(lambda)+tdL13(lambda)^2*tdL32(lambda)+h*tdL13
(lambda)*(diff(tdL12(lambda), lambda))-tdL23(lambda)*tdL12
(lambda)^2-tdL13(lambda)*tdL33(lambda)*tdL12(lambda)-h*tdL12
(lambda)*(diff(tdL13(lambda), lambda))),lambda):
L31:=unapply(-(-(diff(tdL11(lambda), lambda))*(diff(tdL23
(lambda), lambda)*tdL12(lambda)^2*h^2+(diff(tdL11(lambda),
lambda)*(diff(tdL32(lambda), lambda))*tdL13(lambda)^2*h^2-
tdL21(lambda)*(diff(tdL23(lambda), lambda))*tdL12(lambda)^3*
h-2*tdL21(lambda)*(diff(tdL12(lambda), lambda))^2*tdL13(lambda)
*h^2-tdL21(lambda)*tdL12(lambda)^3*tdL23(lambda)*tdL33(lambda)-
tdL21(lambda)*tdL12(lambda)^2*tdL13(lambda)*tdL33(lambda)^2+
tdL31(lambda)*(diff(tdL32(lambda), lambda))*tdL13(lambda)^3*h+
tdL31(lambda)*tdL22(lambda)^2*tdL12(lambda)*tdL13(lambda)^2+
tdL31(lambda)*tdL22(lambda)*tdL32(lambda)*tdL13(lambda)^3+2*
tdL31(lambda)*tdL12(lambda)*(diff(tdL13(lambda), lambda))^2*
h^2+tdL11(lambda)*tdL32(lambda)^2*tdL23(lambda)*tdL13(lambda)^2-
tdL11(lambda)*tdL32(lambda)*(diff(tdL13(lambda), lambda))^2*2*
tdL11(lambda)*tdL32(lambda)*(diff(tdL13(lambda), lambda))^2*h^2+
2*tdL11(lambda)*(diff(tdL12(lambda), lambda))^2*tdL23
(lambda)*h^2+(diff(tdL21(lambda), lambda))*tdL12(lambda)^3*
tdL23(lambda)*h+(diff(tdL21(lambda), lambda))*tdL12(lambda)^2*
(diff(tdL13(lambda), lambda))*h^2-(diff(tdL31(lambda), lambda))*
tdL32(lambda)*tdL13(lambda)^3*h-(diff(tdL31(lambda), lambda))*
(diff(tdL12(lambda), lambda))*tdL13(lambda)^2*h^2-(diff(tdL11
(lambda), lambda))*tdL32(lambda)*tdL13(lambda)^2*h^2+

```

```

(diff(tdL13(lambda), lambda, lambda))*tdL11(lambda)*(diff(tdL12
(lambda), lambda))*h^3+tdL31(lambda)*(diff(tdL12(lambda),
lambda, lambda))*tdL13(lambda)^2*h^2-(diff(tdL12(lambda),
lambda, lambda))*tdL11(lambda)*(diff(tdL13(lambda), lambda))*h^3-tdL21
(lambda)*(diff(tdL13(lambda), lambda, lambda))*tdL12(lambda)^2*h^2-(diff
(tdL11(lambda), lambda))*tdL13(lambda, lambda)*tdL12(lambda)*h^3+(diff
(tdL11(lambda), lambda))*tdL13(lambda)^2*h^2-(diff(tdL12(lambda),
lambda, lambda))*tdL11(lambda)*tdL13(lambda)*h^3+tdL21(lambda)*(diff
(tdL12(lambda), lambda, lambda))*tdL12(lambda)*h^3+(diff(tdL11
(lambda), lambda))*tdL13(lambda)^2*h^2-(diff(tdL12(lambda),
lambda, lambda))*tdL11(lambda)*tdL13(lambda)*h^3+(diff(tdL11
(lambda), lambda))*tdL13(lambda)^2*h^2-tdL21(lambda)*tdL23(lambda)*h^2+
tdL31(lambda)*tdL12(lambda)^3*tdL23(lambda)^2-tdL21(lambda)*tdL32
(lambda)^2*tdL13(lambda)^3-tdL21(lambda)*tdL22(lambda)*
(diff(tdL12(lambda), lambda))*tdL12(lambda)*tdL13(lambda)*h^3+
tdL21(lambda)*tdL32(lambda)*tdL12(lambda)*tdL13(lambda)*(diff
(tdL13(lambda), lambda))*h+2*tdL21(lambda)*(diff(tdL12(lambda),
lambda))*tdL12(lambda)*tdL13(lambda)*tdL33(lambda)*h-2*tdL31
(lambda)*tdL22(lambda)*tdL12(lambda)*tdL13(lambda)*(diff(tdL13
(lambda), lambda))*h-3*tdL31(lambda)*(diff(tdL12(lambda),
lambda))*tdL12(lambda)*tdL23(lambda)*tdL13(lambda)*h+tdL31
(lambda)*tdL12(lambda)*tdL13(lambda)*tdL33(lambda)*(diff(tdL13
(lambda), lambda))*h-tdL11(lambda)*(diff(tdL22(lambda), lambda))*tdL12
(lambda)*tdL13(lambda)*tdL33(lambda)*h+tdL11(lambda)*(diff
(tdL23(lambda), lambda))*tdL32(lambda)*tdL12(lambda)*tdL13
(lambda)*h-tdL11(lambda)*(diff(tdL32(lambda), lambda))*tdL12
(lambda)*tdL23(lambda)*tdL13(lambda)*h+tdL11(lambda)*(diff
(tdL33(lambda), lambda))*tdL22(lambda)*tdL12(lambda)*tdL13
(lambda)*h+tdL11(lambda)*tdL22(lambda)*(diff(tdL12(lambda),
lambda))*tdL12(lambda)*tdL23(lambda)*h-2*tdL11(lambda)*tdL22
(lambda)*(diff(tdL12(lambda), lambda))*tdL13(lambda)*tdL33
(lambda)*h+2*tdL11(lambda)*tdL22(lambda)*tdL12(lambda)*tdL33
(lambda)*(diff(tdL13(lambda), lambda))*h+3*tdL11(lambda)*tdL32
(lambda)*(diff(tdL12(lambda), lambda))*tdL23(lambda)*tdL13
(lambda)*h-tdL11(lambda)*tdL32(lambda)*tdL12(lambda)*tdL23
(lambda)*tdL13(lambda)*tdL33(lambda)-3*tdL11(lambda)*tdL32

```

```

(lambda)*tdL12(lambda)*tdL23(lambda)*(diff(tdL13(lambda),
lambda))*h-tdL11(lambda)*tdL32(lambda)*tdL13(lambda)*tdL33
(lambda)*(diff(tdL13(lambda), lambda))*h+tdL11(lambda)*(diff
(tdL12(lambda), lambda))*tdL12(lambda)*tdL23(lambda)*tdL33
(lambda)*h+(diff(tdL13(lambda), lambda, lambda))*tdL11(lambda)*
tdL32(lambda)*tdL13(lambda)*h^2-(diff(tdL11(lambda), lambda,
lambda))*tdL22(lambda)*tdL12(lambda)*tdL13(lambda)*h^2+(diff
(tdL11(lambda), lambda))*tdL22(lambda)*tdL13(lambda)*h^2-(diff(tdL11(lambda), lambda))*tdL12(lambda)*tdL33
(lambda), lambda))*tdL12(lambda)*tdL13(lambda)*h^2+(diff
(tdL11(lambda), lambda))*tdL22(lambda)^2*tdL12(lambda)*tdL13
(lambda)*h+(diff(tdL11(lambda), lambda))*tdL22(lambda)*tdL32
(lambda)*tdL13(lambda)^2*h+2*(diff(tdL11(lambda), lambda))*t
dL22(lambda)*(diff(tdL12(lambda), lambda))*tdL13(lambda)*h^2-
(diff(tdL11(lambda), lambda))*tdL22(lambda)*tdL12(lambda)^2*
tdL23(lambda)*h+(diff(tdL11(lambda), lambda))*tdL32(lambda)*
tdL13(lambda)^2*tdL33(lambda)*h+2*(diff(tdL11(lambda), lambda))
*tdL32(lambda)*tdL13(lambda)*(diff(tdL13(lambda), lambda))*h^2-
2*(diff(tdL11(lambda), lambda))*tdL12(lambda)*tdL23(lambda)*h^2-
(diff(tdL11(lambda), lambda))*tdL12(lambda)*tdL33(lambda)^2*
h-2*(diff(tdL11(lambda), lambda))*tdL12(lambda)*tdL33(lambda)*
(diff(tdL13(lambda), lambda))*h^2+tdL21(lambda)*(diff(tdL22
(lambda), lambda))*tdL12(lambda)^2*tdL13(lambda)*h+tdL21
(lambda)*(diff(tdL32(lambda), lambda))*tdL12(lambda)*tdL13
(lambda)^2*h-tdL21(lambda)*(diff(tdL33(lambda), lambda))*tdL12
(lambda)^2*tdL13(lambda)*h-tdL21(lambda)*tdL22(lambda)*tdL32
(lambda)*tdL12(lambda)*tdL13(lambda)^2+tdL21(lambda)*tdL22
(lambda)*tdL12(lambda)^2*tdL13(lambda)*tdL33(lambda)+tdL21
(lambda)*tdL22(lambda)*tdL12(lambda)^2*(diff(tdL13(lambda),
lambda))*h-3*tdL21(lambda)*tdL32(lambda)*(diff(tdL12(lambda),
lambda))*tdL13(lambda)^2*h+tdL21(lambda)*tdL32(lambda)*tdL12
(lambda)^2*tdL23(lambda)*tdL13(lambda)+2*tdL21(lambda)*tdL32
(lambda)*tdL12(lambda)*tdL13(lambda)^2*tdL33(lambda)+2*tdL21
(lambda)*(diff(tdL12(lambda), lambda))*tdL12(lambda)*(diff
(tdL13(lambda), lambda))*h^2-2*tdL21(lambda)*tdL12(lambda)^2*
tdL33(lambda)*(diff(tdL13(lambda), lambda))*h+tdL31(lambda)*
(diff(tdL22(lambda), lambda))*tdL12(lambda)*tdL13(lambda)^2*h-
tdL31(lambda)*(diff(tdL23(lambda), lambda))*tdL12(lambda)^2*
tdL13(lambda)*h-tdL31(lambda)*(diff(tdL33(lambda), lambda))*t
dL12(lambda)*tdL13(lambda)^2*h+2*tdL31(lambda)*tdL22(lambda)*

```

```

(diff(tdL12(lambda), lambda))*tdL13(lambda)^2*h-2*tdL31(lambda)
*tdL22(lambda)*tdL12(lambda)^2*tdL23(lambda)*tdL13(lambda)-
tdL31(lambda)*tdL22(lambda)*tdL12(lambda)*tdL13(lambda)^2*tdL33
(lambda)-tdL31(lambda)*tdL32(lambda)*tdL12(lambda)*tdL23
(lambda)*tdL13(lambda)^2-tdL31(lambda)*(diff(tdL12(lambda),
lambda))*tdL13(lambda)^2*tdL33(lambda)*h-2*tdL31(lambda)*(diff
(tdL12(lambda), lambda))*tdL13(lambda)*(diff(tdL13(lambda),
lambda))*h^2+tdL31(lambda)*tdL12(lambda)^2*tdL23(lambda)*tdL13
(lambda)*tdL33(lambda)+3*tdL31(lambda)*tdL12(lambda)^2*tdL23
(lambda)*(diff(tdL13(lambda), lambda))*h-tdL11(lambda)*(diff
(tdL22(lambda), lambda))*tdL12(lambda)^2*tdL23(lambda)*h-tdL11
(lambda)*(diff(tdL22(lambda), lambda))*tdL12(lambda)*(diff
(tdL13(lambda), lambda))*h^2+tdL11(lambda)*(diff(tdL23(lambda),
lambda))*tdL22(lambda)*tdL12(lambda)^2*h+tdL11(lambda)*(diff
(tdL23(lambda), lambda))*(diff(tdL12(lambda), lambda))*tdL12
(lambda)*h^2-tdL11(lambda)*(diff(tdL32(lambda), lambda))*tdL13
(lambda)^2*tdL33(lambda)*h-tdL11(lambda)*(diff(tdL32(lambda),
lambda))*tdL13(lambda)*(diff(tdL13(lambda), lambda))*h^2+tdL11
(lambda)*(diff(tdL33(lambda), lambda))*tdL32(lambda)*tdL13
(lambda)^2*h+tdL11(lambda)*(diff(tdL33(lambda), lambda))*tdL12
(lambda)*tdL13(lambda)*h^2-tdL11(lambda)*tdL22
(lambda)^2*tdL12(lambda)*tdL13(lambda)*tdL33(lambda)-tdL11
(lambda)*tdL22(lambda)^2*tdL12(lambda)*(diff(tdL13(lambda),
lambda))*h-tdL11(lambda)*tdL22(lambda)*tdL32(lambda)*tdL13
(lambda)^2*tdL33(lambda)-2*tdL11(lambda)*tdL22(lambda)*(diff
(tdL12(lambda), lambda))*tdL13(lambda)*h^2+
tdL11(lambda)*tdL22(lambda)*tdL12(lambda)^2*tdL23(lambda)*tdL33
(lambda)+tdL11(lambda)*tdL22(lambda)*tdL12(lambda)*tdL13
(lambda)*tdL33(lambda)^2+tdL11(lambda)*(diff(tdL12(lambda),
lambda))*tdL22(lambda)*tdL12(lambda)^2*tdL13(lambda)*h^2-
(diff(tdL21(lambda), lambda))*tdL22(lambda)*tdL12
(lambda)^2*tdL13(lambda)*h-(diff(tdL21(lambda), lambda))*tdL32
(lambda)*tdL12(lambda)*tdL13(lambda)^2*h-(diff(tdL21(lambda),
lambda))*tdL12(lambda)*tdL13(lambda)*h^2+(diff(tdL21(lambda),
lambda))*tdL12(lambda)^2*tdL13(lambda)*h-tdL31(lambda)*tdL12
(lambda)*tdL13(lambda)^2*h+(diff(tdL31(lambda), lambda))*tdL12
(lambda)*tdL13(lambda)^2*tdL33(lambda)*h+(diff(tdL31(lambda),
lambda))*tdL12(lambda)*tdL13(lambda)*h^2+tdL11

```

```

(lambda), lambda, lambda)*tdL12(lambda)*tdL13(lambda)*tdL33
(lambda)*h^2-(diff(tdL12(lambda), lambda, lambda))*tdL11
(lambda)*tdL12(lambda)*tdL23(lambda)*h^2-(diff(tdL12(lambda),
lambda, lambda))*tdL11(lambda)*tdL13(lambda)*tdL33(lambda)*h^2+
(diff(tdL13(lambda), lambda, lambda))*tdL11(lambda)*tdL22
(lambda)*tdL12(lambda)*h^2)/(tdL13(lambda)*tdL12(lambda)*tdL22
(lambda)+tdL13(lambda)^2*tdL32(lambda)+h*tdL13(lambda)*(diff
(tdL12(lambda), lambda))-tdL23(lambda)*tdL12(lambda)^2-tdL13
(lambda)*tdL33(lambda)*tdL12(lambda)-h*tdL12(lambda)*(diff
(tdL13(lambda), lambda))), lambda):

```

```

> simplify(ToCancel);
simplify(G);
factor(Determinant(G));

```

$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad (1.4)$$

$$\begin{aligned}
& \left[\begin{bmatrix} 1, 0, 0 \end{bmatrix}, \right. \\
& \left[\begin{bmatrix} tdL11(\lambda), tdL12(\lambda), tdL13(\lambda) \end{bmatrix}, \right. \\
& \left[\begin{bmatrix} tdL12(\lambda) tdL21(\lambda) + tdL13(\lambda) tdL31(\lambda) + tdL11(\lambda)^2 + h \left(\frac{d}{d\lambda} tdL11(\lambda) \right), \right. \\
& \left. h \left(\frac{d}{d\lambda} tdL12(\lambda) \right) + (tdL11(\lambda) + tdL22(\lambda)) tdL12(\lambda) + tdL13(\lambda) tdL32(\lambda), \right. \\
& \left. h \left(\frac{d}{d\lambda} tdL13(\lambda) \right) + (tdL11(\lambda) + tdL33(\lambda)) tdL13(\lambda) + tdL12(\lambda) tdL23(\lambda) \right] \\
& -tdL13(\lambda) tdL12(\lambda) tdL22(\lambda) - tdL13(\lambda)^2 tdL32(\lambda) - h tdL13(\lambda) \left(\frac{d}{d\lambda} tdL12(\lambda) \right) \\
& \quad + tdL23(\lambda) tdL12(\lambda)^2 + tdL13(\lambda) tdL33(\lambda) tdL12(\lambda) \\
& \quad \left. + h tdL12(\lambda) \left(\frac{d}{d\lambda} tdL13(\lambda) \right) \right]
\end{aligned}$$

Application to the case of $\text{td}\{\mathbf{L}\} = \mathbf{L}_1\lambda + \mathbf{L}_0$. We take $\mathbf{L}_1 = \text{diag}(t12, t22, t32)$ but \mathbf{L}_0 remains free. In particular, we keep $a_{1,2}$, $a_{1,3}$ as free parameters that shall not be determined since they belongs to the action by global conjugation of GL_3 .

```

> tdl11:=unapply(t12*lambda+a11,lambda):
tdl12:=unapply(a12,lambda):
tdl13:=unapply(a13,lambda):
tdl21:=unapply(a21,lambda):
tdl22:=unapply(t22*lambda+a22,lambda):

```

```

tdL23:=unapply(a23,lambda):
tdL31:=unapply(a31,lambda):
tdL32:=unapply(a32,lambda):
tdL33:=unapply(t32*lambda+a33,lambda):
simplify(tdL);
simplify(series(factor(Determinant(G)),lambda=0));
simplify(G);

tdLinfty1:=Matrix(3,3,0):
tdLinfty1[1,1]:=t12:
tdLinfty1[2,2]:=t22:
tdLinfty1[3,3]:=t32:

tdLinfty0:=Matrix(3,3,0):
tdLinfty0[1,1]:=a11:
tdLinfty0[1,2]:=a12:
tdLinfty0[1,3]:=a13:
tdLinfty0[2,1]:=a21:
tdLinfty0[2,2]:=a22:
tdLinfty0[2,3]:=a23:
tdLinfty0[3,1]:=a31:
tdLinfty0[3,2]:=a32:
tdLinfty0[3,3]:=a33:

simplify(tdL);
Trace(tdL);

```

$$\begin{bmatrix}
\lambda t12 + a11 & a12 & a13 \\
a21 & \lambda t22 + a22 & a23 \\
a31 & a32 & \lambda t32 + a33
\end{bmatrix} \quad (1.1.1)$$

$a12^2 a23 - a13 (a22 - a33) a12 - a13^2 a32 - a12 a13 (t22 - t32) \lambda$

$$\begin{bmatrix}
[1, 0, 0], \\
[\lambda t12 + a11, a12, a13], \\
[\lambda^2 t12^2 + (2 a11 \lambda + h) t12 + a11^2 + a12 a21 + a13 a31, ((t12 + t22) \lambda + a11 + a22) a12 + a13 a32, ((t12 + t32) \lambda + a11 + a33) a13 + a12 a23]
\end{bmatrix}$$

$$\begin{bmatrix}
\lambda t12 + a11 & a12 & a13 \\
a21 & \lambda t22 + a22 & a23 \\
a31 & a32 & \lambda t32 + a33
\end{bmatrix}$$

$$\lambda t12 + \lambda t22 + \lambda t32 + a11 + a22 + a33$$

Definition of the apparent singularity q

$$> Qsing:=(a12^2*a23-a12*a13*a22+a12*a13*a33-a13^2*a32) / (a12*a13*(t22-t32));$$

$$Qsing := \frac{a12^2 a23 - a12 a13 a22 + a12 a13 a33 - a13^2 a32}{a12 a13 (t22 - t32)} \quad (1.1.2)$$

$$> R31:=factor(residue(L31(lambda), lambda=Qsing)): \\ R32:=factor(residue(L32(lambda), lambda=Qsing)): \\ R33:=factor(residue(L33(lambda), lambda=Qsing)); \\ R33 := h \quad (1.1.3)$$

$$> L31bis:=(a11*a12*a13*a22*a33*t22-a11*a12*a13*a22*a33*t32-a11*a12*a13*a23*a32*t22+a11*a12*a13*a23*a32*t32-a12^2*a13*a21*a33*t22+a12^2*a13*a21*a33*t32+a12^2*a13*a23*a31*t22-a12^2*a13*a23*a31*t32+a12*a13^2*a22*a31*t22+a12*a13^2*a22*a31*t32+h*a12^2*a23*t12*t22-h*a12*a13*a22*t12*t22+h*a12*a13*a33*t12*t32-h*a13^2*a32*t12*t32) / (a12*a13*(t22-t32))+(a11*a22*t32+a11*a33*t22-a12*a21*t32-a13*a31*t22+a22*a33*t12-a23*a32*t12-h*t12*t22-h*t12*t32)*lambda+(a11*t22*t32+a22*t12*t32+a33*t12*t22)*lambda^2+t12*t22*t32*lambda^3+R31/(lambda-Qsing); \\ L32bis:=-a11*a22-a11*a33+a12*a21+a13*a31-a22*a33+a23*a32+h*t12+(-a11*t22-a11*t32-a22*t12-a22*t32-a33*t12-a33*t22)*lambda+(-t12*t22-t12*t32-t22*t32)*lambda^2+R32/(lambda-Qsing); \\ L33bis:=(t12+t22+t32)*lambda+a11+a22+a33+ h/(lambda-Qsing); \\ \\ simplify(L31(lambda)-L31bis); \\ simplify(L32(lambda)-L32bis); \\ simplify(L33(lambda)-L33bis); \\ \\ L:=simplify(L): \\ \\ L31:=unapply(L31bis,lambda): \\ L32:=unapply(L32bis,lambda): \\ L33:=unapply(L33bis,lambda): \\ \\ L31bis := \frac{1}{a12 a13 (t22 - t32)} (a11 a12 a13 a22 a33 t22 - a11 a12 a13 a22 a33 t32 - a11 a12 a13 a23 a32 t22 + a11 a12 a13 a23 a32 t32 - a12^2 a13 a21 a33 t22 + a12^2 a13 a23 a31 t22 - a12^2 a13 a23 a31 t32 + a12^2 a23 h t12 t22 + a12 a13^2 a21 a32 t22 - a12 a13^2 a21 a32 t32 - a12 a13^2 a22 a31 t22 + a12 a13^2 a22 a31 t32 - a12 a13 a22 h t12 t22 + a12 a13 a33 h t12 t32 - a13^2 a32 h t12 t32) + (a11 a22 t32 + a11 a33 t22 - a12 a21 t32 - a13 a31 t22 + a22 a33 t12 - a23 a32 t12 - h t12 t22 - h t12 t32)$$

$$\begin{aligned}
& \lambda + (a_{11} t_{22} t_{32} + a_{22} t_{12} t_{32} + a_{33} t_{12} t_{22}) \lambda^2 + t_{12} t_{22} t_{32} \lambda^3 \\
& + ((a_{11} a_{12}^3 a_{13} a_{23} t_{22}^2 - a_{11} a_{12}^3 a_{13} a_{23} t_{22} t_{32} - a_{11} a_{12}^2 a_{13}^2 a_{22} t_{22} t_{32} + a_{11} a_{12}^2 a_{13}^2 a_{23} t_{22} t_{32} \\
& + a_{12}^4 a_{23}^2 t_{12} t_{22} - a_{12}^3 a_{13}^2 a_{21} t_{22}^2 + 2 a_{12}^3 a_{13}^2 a_{21} t_{22} t_{32} \\
& - a_{12}^3 a_{13}^2 a_{21} t_{32}^2 - a_{12}^3 a_{13} a_{22} a_{23} t_{12} t_{22} - a_{12}^3 a_{13} a_{22} a_{23} t_{12} t_{32} \\
& + 2 a_{12}^3 a_{13} a_{23} a_{33} t_{12} t_{22} - a_{12}^2 a_{13}^3 a_{31} t_{22}^2 + 2 a_{12}^2 a_{13}^3 a_{31} t_{22} t_{32} \\
& - a_{12}^2 a_{13}^3 a_{31} t_{32}^2 + a_{12}^2 a_{13}^2 a_{22}^2 t_{12} t_{32} - a_{12}^2 a_{13}^2 a_{22} a_{33} t_{12} t_{22} \\
& - a_{12}^2 a_{13}^2 a_{22} a_{33} t_{12} t_{32} - a_{12}^2 a_{13}^2 a_{23} a_{32} t_{12} t_{22} \\
& - a_{12}^2 a_{13}^2 a_{23} a_{32} t_{12} t_{32} + a_{12}^2 a_{13}^2 a_{33} t_{12} t_{22} - a_{12}^2 a_{13}^2 h t_{12} t_{22}^2 \\
& + 2 a_{12}^2 a_{13}^2 h t_{12} t_{22} t_{32} - a_{12}^2 a_{13}^2 h t_{12} t_{32}^2 + 2 a_{12} a_{13}^3 a_{22} a_{32} t_{12} t_{32} \\
& - a_{12} a_{13}^3 a_{32} a_{33} t_{12} t_{22} - a_{12} a_{13}^3 a_{32} a_{33} t_{12} t_{32} + a_{13}^4 a_{32}^2 t_{12} t_{32}) h) /
\end{aligned}$$

$$\left(a_{12}^2 a_{13}^2 (t_{22} - t_{32})^2 \left(\lambda \right. \right. \\
\left. \left. - \frac{a_{12}^2 a_{23} - a_{12} a_{13} a_{22} + a_{12} a_{13} a_{33} - a_{13}^2 a_{32}}{a_{12} a_{13} (t_{22} - t_{32})} \right) \right)$$

$$\begin{aligned}
L32bis := & -a_{11} a_{22} - a_{11} a_{33} + a_{12} a_{21} + a_{13} a_{31} - a_{22} a_{33} + a_{23} a_{32} + h t_{12} + \\
& -a_{11} t_{22} - a_{11} t_{32} - a_{22} t_{12} - a_{22} t_{32} - a_{33} t_{12} - a_{33} t_{22}) \lambda + (-t_{12} t_{22} \\
& - t_{12} t_{32} - t_{22} t_{32}) \lambda^2 - ((a_{11} a_{12} a_{13} t_{22} - a_{11} a_{12} a_{13} t_{32} + a_{12}^2 a_{23} t_{12} \\
& + a_{12}^2 a_{23} t_{22} - a_{12} a_{13} a_{22} t_{12} - a_{12} a_{13} a_{22} t_{32} + a_{12} a_{13} a_{33} t_{12} \\
& + a_{12} a_{13} a_{33} t_{22} - a_{13}^2 a_{32} t_{12} - a_{13}^2 a_{32} t_{32}) h) / \left(a_{12} a_{13} (t_{22} - t_{32}) \left(\lambda \right. \right. \\
& \left. \left. - \frac{a_{12}^2 a_{23} - a_{12} a_{13} a_{22} + a_{12} a_{13} a_{33} - a_{13}^2 a_{32}}{a_{12} a_{13} (t_{22} - t_{32})} \right) \right)
\end{aligned}$$

$$\begin{aligned}
L33bis := & (t_{12} + t_{22} + t_{32}) \lambda + a_{11} + a_{22} + a_{33} \\
& + \frac{h}{\lambda - \frac{a_{12}^2 a_{23} - a_{12} a_{13} a_{22} + a_{12} a_{13} a_{33} - a_{13}^2 a_{32}}{a_{12} a_{13} (t_{22} - t_{32})}} \\
& \quad \quad \quad 0 \\
& \quad \quad \quad 0 \\
& \quad \quad \quad 0
\end{aligned}$$

▼ Verification of the gauge formula with the formula

```

> J33:=unapply(j33/(lambda-Qsing),lambda):
J32:=unapply(j32/(lambda-Qsing),lambda):
J31:=unapply(j31/(lambda-Qsing),lambda):
j33:=1:

J:=Matrix(3,3,0):
J[1,1]:=1:
J[2,2]:=1:
J[3,1]:=J31(lambda):
J[3,2]:=J32(lambda):
J[3,3]:=J33(lambda):

```

```

J:=

Jprime:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do Jprime[i,j]:=diff(J
[i,j],lambda): od: od:
Jprime:

checkL:=simplify(Multiply(Multiply(J,L),J^(-1))+h*Multiply
(Jprime,J^(-1))):

> j31 :=factor( (a11*a12^3*a13*a23*t22^2-a11*a12^3*a13*a23*t22*
t32-a11*a12^2*a13^2*a22*t22*t32+a11*a12^2*a13^2*a22*t32^2+a11*
a12^2*a13^2*a33*t22^2-a11*a12^2*a13^2*a33*t22*t32-a11*a12*
a13^3*a32*t22*t32+a11*a12*a13^3*a32*t32^2+a12^4*a23^2*t12*t22-
a12^3*a13^2*a21*t22^2+2*a12^3*a13^2*a21*t22*t32-a12^3*a13^2*
a21*t32^2-a12^3*a13*a22*a23*t12*t22-a12^3*a13*a22*a23*t12*
t32+2*a12^3*a13*a33*t12*t22-a12^2*a13^3*a31*t22^2+2*a12^2*
a13^3*a31*t22*t32-a12^2*a13^3*a31*t32^2+a12^2*a13^2*a22^2*t12*
t32-a12^2*a13^2*a22*a33*t12*t22-a12^2*a13^2*a22*a33*t12*t32-
a12^2*a13^2*a23*a32*t12*t22-a12^2*a13^2*a23*a32*t12*t32+a12^2*
a13^2*a33^2*t12*t22+2*a12*a13^3*a22*a32*t12*t32-a12*a13^3*a32*
a33*t12*t22-a12*a13^3*a32*a33*t12*t32+a13^4*a32^2*t12*t32) /
(a12^2*a13^2*(t22-t32)^2))-h*t12;
j32 :=factor( -(a11*a12*a13*t22-a11*a12*a13*t32+a12^2*a23*t12+
a12^2*a23*t22-a12*a13*a22*t12-a12*a13*a22*t32+a12*a13*a33*t12+
a12*a13*a33*t22-a13^2*a32*t12-a13^2*a32*t32) / (a12*a13*(t22-t32)
));

factor(simplify(residue(checkL[3,1],lambda=Q)));
factor(simplify(residue(checkL[3,2],lambda=Q)));
factor(simplify(residue(checkL[3,3],lambda=Q)));

J:=simplify(J):
checkL:=simplify(checkL):

```

$$j31 := \frac{1}{a12^2 a13^2 (t22 - t32)^2} (a11 a12^3 a13 a23 t22^2 - a11 a12^3 a13 a23 t22 t32 - a11 a12^2 a13^2 a22 t22 t32 + a11 a12^2 a13^2 a22 t32^2 + a11 a12^2 a13^2 a33 t22^2 - a11 a12^2 a13^2 a33 t22 t32 - a11 a12 a13^3 a32 t22 t32 + a11 a12 a13^3 a32 t32^2 + a12^4 a23^2 t12 t22 - a12^3 a13^2 a21 t22^2 + 2 a12^3 a13^2 a21 t22 t32 - a12^3 a13^2 a21 t32^2 - a12^3 a13 a22 a23 t12 t22 - a12^3 a13 a22 a23 t12 t32 + 2 a12^3 a13 a23 a33 t12 t22 - a12^2 a13^3 a31 t32^2 + a12^2 a13^2 a22^2 t12 t32 - a12^2 a13^2 a22 a33 t12 t22 - a12^2 a13^2 a22 a33 t12 t32 - a12^2 a13^2 a22 a33 t12 t32 - a12^2 a13^2 a23 a32 t12 t32 - a12^2 a13^2 a23 a32 t12 t22 - a12^2 a13^2 a23 a32 t12 t32) \quad (2.1)$$

$$\begin{aligned}
& + a12^2 a13^2 a33^2 t12 t22 + 2 a12 a13^3 a22 a32 t12 t32 - a12 a13^3 a32 a33 t12 t22 \\
& - a12 a13^3 a32 a33 t12 t32 + a13^4 a32^2 t12 t32) - h t12 \\
j32 := & - \frac{1}{a12 a13 (t22 - t32)} (a11 a12 a13 t22 - a11 a12 a13 t32 + a12^2 a23 t12 \\
& + a12^2 a23 t22 - a12 a13 a22 t12 - a12 a13 a22 t32 + a12 a13 a33 t12 \\
& + a12 a13 a33 t22 - a13^2 a32 t12 - a13^2 a32 t32) \\
& \quad 0 \\
& \quad 0 \\
& \quad 0
\end{aligned}$$

> series(simplify(series(factor(series(series(checkL[2,1]-h*t12,lambda=infinity),lambda=infinity)),lambda=infinity));

series(simplify(series(factor(series(series(checkL[2,2],lambda=infinity),lambda=infinity)),lambda=infinity));

series(simplify(series(factor(series(series(checkL[2,3],lambda=infinity),lambda=infinity)),lambda=infinity));

series(simplify(series(factor(series(series(checkL[3,1]-h*t12^2,lambda=infinity),lambda=infinity)),lambda=infinity));

series(simplify(series(factor(series(series(checkL[3,2],lambda=infinity),lambda=infinity)),lambda=infinity));

series(simplify(series(factor(series(series(checkL[3,3],lambda=infinity),lambda=infinity)),lambda=infinity));

$$\frac{1}{a12^2 a13^2 (t22 - t32)^2} \left(-a12^4 a23^2 t12 t22 - (-a21 (t22 - t32)^2 a13 + a23 (t22^2 a11 - t32 a11 - t12 (-2 a33 + a22)) t22 - t12 t32 a22) a13 a12^3 - (-a31 (t22 - t32)^2 a13 + a11 t22^2 a33 + (-a11 (a33 + a22) t32 - t12 (a22 a33 + a23 a32 - a33^2)) t22 + (t32 a11 a22 + t12 (a22^2 - a22 a33 - a23 a32)) t32) a13^2 a12^2 + a32 a13^3 \left((a11 t32 + a33 t12) t22 - \left(t32 a11 + 2 \left(a22 - \frac{1}{2} a33 \right) t12 \right) t32 \right) a12 - a13^4 a32^2 t12 t32 \right) \quad (2.2)$$

$$\begin{aligned}
& \frac{1}{a12 a13 (-t22 + t32)} (-a23 (t12 + t22) a12^2 + (t12 (a22 - a33) + (-a11 - a33) t22 + t32 (a11 + a22)) a13 a12 + a13^2 a32 (t12 + t32)) \\
& \lambda + \frac{-a12^2 a23 + a13 (a22 - a33) a12 + a13^2 a32}{a12 a13 (t22 - t32)} \\
& - \frac{(-t22^3 t32 + 2 t22^2 t32^2 - t22 t32^3) t12 \lambda^2}{(t22 - t32)^2} + \frac{1}{a12^2 a13^2 (t22 - t32)^2} ((-a13 (-t22 t32 + t32^2) t22 t12 a23 a12^3 - ((a22 t22 t32^2 - a22 t32^3 - a33 t22^3 + a33 t22^2 t32) t12 - t22 t32 a11 (t22 - t32)^2) a13^2 a12^2 + a32 a13^3 t32 (-t22^2 + t22 t32) t12 a12) \lambda)
\end{aligned}$$

$$\begin{aligned}
& + \frac{1}{a12^2 a13^2 (t22 - t32)^2} \left(-t12 t22 a23^2 (t12 + t22) a12^4 - (-a21 (t22 - t32)^2 (t12 + t22) a13 + a23 ((-a22 + 2 a33) t22 - a22 t32) t12^2 + t22 ((a11 - a22 + a33) t22 - t32 (a11 + a22 - a33)) t12 + t22^2 a11 (t22 - t32))) a13 a12^3 \right. \\
& - (-a31 (t22 - t32)^2 (t12 + t32) a13 + ((-a22 a33 - a23 a32 + a33^2) t22 + t32 (a22^2 - a22 a33 - a23 a32)) t12^2 + (a33 (a11 - a22) t22^2 - (a11 (a33 + a22) - a22^2 + 2 a23 a32 - a33^2) t32 t22 + a22 t32^2 (a11 - a33)) t12 - t22 t32 a11 (t22 - t32) (a22 - a33)) a13^2 a12^2 + a32 \left(\left(a33 t22 - 2 \left(a22 - \frac{1}{2} a33 \right) t32 \right) t12^2 + ((a11 - a22 + a33) t22 - t32 (a11 + a22 - a33)) t32 t12 + t32^2 a11 (t22 - t32) \right) a13^3 a12 - t12 t32 a13^4 a32^2 (t12 + t32) \right) \\
& \left((t22^2 - t32^2) t12 - t32 t22 (-t22 + t32) \right) \lambda + \frac{1}{a12 a13 (-t22 + t32)} (-a23 (t12^2 + t12 t22 + t22^2) a12^2 + ((a22 - a33) t12^2 + ((-a11 + a22) t22 + t32 (a11 - a33)) t12 - t32 (a33 - a22) t22) a13 a12 + a13^2 a32 (t12^2 + t12 t32 + t32^2)) \\
& \left((t22 - t32) t12 + t22^2 - t32^2 \right) \lambda + \frac{1}{a12 a13 (t22 - t32)} (-a23 (t12 + t22) a12^2 + a13 (t12 (a22 - a33) + a22 t22 - a33 t32) a12 + a13^2 a32 (t12 + t32))
\end{aligned}$$

Computation of the additional gauge matrix to normalize properly at infinity

```

> Gnorm:=Matrix(3,3,0):
Gnorm[1,1]:=Gnorm111*lambda+Gnorm11:
Gnorm[1,2]:=Gnorm112*lambda+Gnorm12:
Gnorm[1,3]:=Gnorm113*lambda+Gnorm13:
Gnorm[2,1]:=Gnorm121*lambda+Gnorm21:
Gnorm[2,2]:=Gnorm122*lambda+Gnorm22:
Gnorm[2,3]:=Gnorm123*lambda+Gnorm23:
Gnorm[3,1]:=Gnorm131*lambda+Gnorm31:
Gnorm[3,2]:=Gnorm132*lambda+Gnorm32:
Gnorm[3,3]:=Gnorm133*lambda+Gnorm33:
Gnorm;

Gnormprime:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do Gnormprime[i,j]:=diff
(Gnorm[i,j],lambda): od: od:
Gnormprime;

```

(2.3)

$$\begin{bmatrix} \lambda Gnorm111 + Gnorm11 & \lambda Gnorm112 + Gnorm12 & \lambda Gnorm113 + Gnorm13 \\ \lambda Gnorm121 + Gnorm21 & \lambda Gnorm122 + Gnorm22 & \lambda Gnorm123 + Gnorm23 \\ \lambda Gnorm131 + Gnorm31 & \lambda Gnorm132 + Gnorm32 & \lambda Gnorm133 + Gnorm33 \end{bmatrix} \quad (2.3)$$

$$\begin{bmatrix} Gnorm111 & Gnorm112 & Gnorm113 \\ Gnorm121 & Gnorm122 & Gnorm123 \\ Gnorm131 & Gnorm132 & Gnorm133 \end{bmatrix}$$

```

> TdLtheo:=Matrix(3,3,0):
TdLtheo[1,1]:=t12*lambda+a11:
TdLtheo[1,2]:=a12:
TdLtheo[1,3]:=a13:
TdLtheo[2,1]:=a21:
TdLtheo[2,2]:=t22*lambda+a22:
TdLtheo[2,3]:=a23:
TdLtheo[3,1]:=a31:
TdLtheo[3,2]:=a32:
TdLtheo[3,3]:=t32*lambda+a33:
TdLtheo;

```

EquationToCancel:=simplify(Multiply(TdLtheo,Gnorm)-Multiply(Gnorm,checkL)-h*Gnormprime):

$$\begin{bmatrix} \lambda t12 + a11 & a12 & a13 \\ a21 & \lambda t22 + a22 & a23 \\ a31 & a32 & \lambda t32 + a33 \end{bmatrix} \quad (2.4)$$

```

> Gnorm113:=0:
factor(-residue(EquationToCancel[1,1]/lambda^4,lambda=infinity));
factor(-residue(EquationToCancel[1,2]/lambda^4,lambda=infinity));
factor(-residue(EquationToCancel[1,3]/lambda^4,lambda=infinity));
Gnorm123:=0:
factor(-residue(EquationToCancel[2,1]/lambda^4,lambda=infinity));
factor(-residue(EquationToCancel[2,2]/lambda^4,lambda=infinity));
factor(-residue(EquationToCancel[2,3]/lambda^4,lambda=infinity));
Gnorm133:=0:

```


$Gnorm121 := Gnorm23 t12 t32$
 0
 0
 0
 $Gnorm131 := Gnorm33 t12 t22$
 0
 0
 0

$Gnorm13 \lambda t22 t32 + Gnorm11$	$Gnorm12$	$Gnorm13$
$Gnorm23 \lambda t12 t32 + Gnorm21$	$Gnorm22$	$Gnorm23$
$Gnorm33 \lambda t12 t22 + Gnorm31$	$Gnorm32$	$Gnorm33$

```

> Gnorm12:=-Gnorm13*(t22+t32);
Gnorm13:=(Gnorm23*a12*t32+Gnorm33*a13*t22+Gnorm11)*a13*a12*(t22
-t32)/(a12^2*a23*t22*t32-a12*a13*a22*t32^2+a12*a13*a33*t22^2-
a13^2*a32*t22*t32);
factor(-residue(EquationToCancel[1,1]/lambda^2,lambda=infinity));
factor(-residue(EquationToCancel[1,2]/lambda^2,lambda=infinity));
factor(-residue(EquationToCancel[1,3]/lambda^2,lambda=infinity));
)

$$Gnorm12 := -Gnorm13 (t22 + t32) \quad (2.7)$$

Gnorm13 := 
$$\frac{(Gnorm23 a12 t32 + Gnorm33 a13 t22 + Gnorm11) a13 a12 (t22 - t32)}{a12^2 a23 t22 t32 - a12 a13 a22 t32^2 + a12 a13 a33 t22^2 - a13^2 a32 t22 t32}$$


$$0$$


$$0$$


$$0$$

=
> Gnorm22:=-Gnorm23*(t12+t32);
Gnorm23:=(Gnorm33*a12^2*a23^2*t12*t22*t32+Gnorm33*a12*a13^2*
a21*t22^2*t32-Gnorm33*a12*a13^2*a21*t22*t32^2-Gnorm33*a12*a13*
a22*a23*t12*t32^2+Gnorm33*a12*a13*a23*a33*t12*t22^2-Gnorm33*
a13^2*a23*a32*t12*t22*t32+Gnorm11*a12*a13*a21*t22*t32-Gnorm11*
a12*a13*a21*t32^2+Gnorm21*a12^2*a23*t22*t32-Gnorm21*a12*a13*
a22*t32^2+Gnorm21*a12*a13*a33*t22^2-Gnorm21*a13^2*a32*t22*t32)*
a12*a13*(t22-t32)/(a11*a12^3*a13*a23*t22^2*t32^2-a11*a12^3*a13*
a23*t22*t32^3-a11*a12^2*a13^2*a22*t22*t32^3+a11*a12^2*a13^2*
a22*t32^4+a11*a12^2*a13^2*a33*t22^3*t32-a11*a12^2*a13^2*a33*
t22^2*t32^2-a11*a12*a13^3*a32*t22^2*t32^2+a11*a12*a13^3*a32*
t22*t32^3+a12^4*a23^2*t12*t22*t32^2-a12^3*a13^2*a21*t22^2*
t32^2+2*a12^3*a13^2*a21*t22*t32^3-a12^3*a13^2*a21*t32^4-a12^3*
a13*a22*a23*t12*t22*t32^2-a12^3*a13*a22*a23*t12*t32^3+2*a12^3*
a13*a23*a33*t12*t22^2*t32+a12^2*a13^2*a22^2*t12*t32^3-a12^2*
a13^2*a22*a33*t12*t22^2*t32-a12^2*a13^2*a22*a33*t12*t22*t32^2
```

```

-2*a12^2*a13^2*a23*a32*t12*t22*t32^2+a12^2*a13^2*a33^2*t12*
t22^3+a12*a13^3*a22*a32*t12*t22*t32^2+a12*a13^3*a22*a32*t12*
t32^3-2*a12*a13^3*a32*a33*t12*t22^2*t32+a13^4*a32^2*t12*t22*
t32^2);
factor(-residue(EquationToCancel[2,1]/lambda^2,lambda=infinity));
factor(-residue(EquationToCancel[2,2]/lambda^2,lambda=infinity));
factor(-residue(EquationToCancel[2,3]/lambda^2,lambda=infinity));

```

$$Gnorm22 := -Gnorm23 (t12 + t32) \quad (2.8)$$

```

Gnorm23 := ((Gnorm33 a12^2 a23^2 t12 t22 t32 + Gnorm33 a12 a13^2 a21 t22^2 t32
- Gnorm33 a12 a13^2 a21 t22 t32^2 - Gnorm33 a12 a13 a22 a23 t12 t32^2
+ Gnorm33 a12 a13 a23 a33 t12 t22^2 - Gnorm33 a13^2 a23 a32 t12 t22 t32
+ Gnorm11 a12 a13 a21 t22 t32 - Gnorm11 a12 a13 a21 t32^2
+ Gnorm21 a12^2 a23 t22 t32 - Gnorm21 a12 a13 a22 t32^2
+ Gnorm21 a12 a13 a33 t22^2 - Gnorm21 a13^2 a32 t22 t32) a12 a13 (t22 - t32)) /
(a11 a12^3 a13 a23 t22^2 t32^2 - a11 a12^3 a13 a23 t22 t32^3 - a11 a12^2 a13^2 a22 t22 t32^3
+ a11 a12^2 a13^2 a22 t32^4 + a11 a12^2 a13^2 a33 t22^3 t32 - a11 a12^2 a13^2 a33 t22^2 t32^2
- a11 a12 a13^3 a32 t22^2 t32^2 + a11 a12 a13^3 a32 t22 t32^3 + a12^4 a23^2 t12 t22 t32^2
- a12^3 a13^2 a21 t22^2 t32^2 + 2 a12^3 a13^2 a21 t22 t32^3 - a12^3 a13^2 a21 t32^4
- a12^3 a13 a22 a23 t12 t22 t32^2 - a12^3 a13 a22 a23 t12 t32^3
+ 2 a12^3 a13 a23 a33 t12 t22^2 t32 + a12^2 a13^2 a22^2 t12 t32^3
- a12^2 a13^2 a22 a33 t12 t22^2 t32 - a12^2 a13^2 a22 a33 t12 t22 t32^2
- 2 a12^2 a13^2 a23 a32 t12 t22 t32^2 + a12^2 a13^2 a33^2 t12 t22^3
+ a12 a13^3 a22 a32 t12 t22 t32^2 + a12 a13^3 a22 a32 t12 t32^3
- 2 a12 a13^3 a32 a33 t12 t22^2 t32 + a13^4 a32^2 t12 t22 t32^2)

```

0
0
0

```

> Gnorm32:=-Gnorm33*(t12+t22);
Gnorm33:=factor(solve(factor(-residue(EquationToCancel[3,1]
/lambda^2,lambda=infinity)),Gnorm33));
factor(-residue(EquationToCancel[3,1]/lambda^2,lambda=infinity));
factor(-residue(EquationToCancel[3,2]/lambda^2,lambda=infinity));
factor(-residue(EquationToCancel[3,3]/lambda^2,lambda=infinity));
Gnorm:=simplify(Gnorm);

```

$$Gnorm32 := -Gnorm33 (t12 + t22) \quad (2.9)$$

0
0
0

```

> Gnorm31:=factor(solve(factor(-residue(EquationToCancel[3,3]
/lambda^1,lambda=infinity)),Gnorm31)):
factor(-residue(EquationToCancel[3,3]/lambda^1,lambda=infinity)
);
factor(-residue(EquationToCancel[3,2]/lambda^1,lambda=infinity)
);
0
0

```

(2.10)

```

> Gnorm11:=Gnorm21*a12^2*a13*(t22-t32)^2/(a11*a12*a13*t22*t32-
a11*a12*a13*t32^2+a12^2*a23*t12*t22-a12*a13*a22*t12*t32+a12*
a13*a33*t12*t22-a13^2*a32*t12*t32);

```

$$Gnorm11 := \frac{(Gnorm21 a12^2 a13 (t22 - t32)^2)}{(a11 a12 a13 t22 t32 - a11 a12 a13 t32^2 + a12^2 a23 t12 t22 - a12 a13 a22 t12 t32 + a12 a13 a33 t12 t22 - a13^2 a32 t12 t32)} \quad (2.11)$$

```

> factor(-residue(EquationToCancel[3,1]/lambda^1,lambda=infinity)
);
factor(-residue(EquationToCancel[2,1]/lambda^1,lambda=infinity)
);
factor(-residue(EquationToCancel[2,2]/lambda^1,lambda=infinity)
);
factor(-residue(EquationToCancel[2,3]/lambda^1,lambda=infinity)
);
factor(-residue(EquationToCancel[1,1]/lambda^1,lambda=infinity)
);
factor(-residue(EquationToCancel[1,2]/lambda^1,lambda=infinity)
);
factor(-residue(EquationToCancel[1,3]/lambda^1,lambda=infinity)
);
0
0
0
0
0
0
0
0

```

(2.12)

```

> Gnorm11:=factor(Gnorm11);
Gnorm12:=factor(Gnorm12);
Gnorm13:=factor(Gnorm13);
Gnorm21:=factor(Gnorm21);
Gnorm22:=factor(Gnorm22);
Gnorm23:=factor(Gnorm23);
Gnorm31:=factor(Gnorm31);
Gnorm32:=factor(Gnorm32);
Gnorm33:=factor(Gnorm33);

```

```

Gnorm21:=(a11*a12*a13*t22*t32-a11*a12*a13*t32^2+a12^2*a23*t12*t22-a12*a13*a22*t12*t32+a12*a13*a33*t12*t22-a13^2*a32*t12*t32)/
(a12^2*(t22-t32)^2*a13):
Gnorm:=simplify(Gnorm);

```

$$\begin{aligned}
Gnorm11 &:= \frac{(Gnorm21 a12^2 a13 (t22 - t32)^2)}{(a11 a12 a13 t22 t32 - a11 a12 a13 t32^2)} \quad (2.13) \\
&\quad + a12^2 a23 t12 t22 - a12 a13 a22 t12 t32 + a12 a13 a33 t12 t22 - a13^2 a32 t12 t32) \\
&\quad Gnorm12 := 0 \\
&\quad Gnorm13 := 0 \\
&\quad Gnorm21 := Gnorm21 \\
Gnorm22 &:= \frac{-((t12 + t32) (t22 - t32) a12 a13 Gnorm21)}{(a11 a12 a13 t22 t32 - a11 a12 a13 t32^2} \\
&\quad - a11 a12 a13 t32^2 + a12^2 a23 t12 t22 - a12 a13 a22 t12 t32 + a12 a13 a33 t12 t22 \\
&\quad - a13^2 a32 t12 t32) \\
Gnorm23 &:= \frac{((t22 - t32) a12 a13 Gnorm21)}{(a11 a12 a13 t22 t32 - a11 a12 a13 t32^2} \\
&\quad + a12^2 a23 t12 t22 - a12 a13 a22 t12 t32 + a12 a13 a33 t12 t22 - a13^2 a32 t12 t32) \\
Gnorm31 &:= \frac{-((a11 a12 a13 t22^2 - a11 a12 a13 t22 t32 + a12^2 a23 t12 t22} \\
&\quad - a12 a13 a22 t12 t32 + a12 a13 a33 t12 t22 - a13^2 a32 t12 t32) Gnorm21 a12) / \\
&\quad ((a11 a12 a13 t22 t32 - a11 a12 a13 t32^2 + a12^2 a23 t12 t22 - a12 a13 a22 t12 t32} \\
&\quad + a12 a13 a33 t12 t22 - a13^2 a32 t12 t32) a13) \\
Gnorm32 &:= \frac{((t12 + t22) (t22 - t32) a12^2 Gnorm21)}{(a11 a12 a13 t22 t32} \\
&\quad - a11 a12 a13 t32^2 + a12^2 a23 t12 t22 - a12 a13 a22 t12 t32 + a12 a13 a33 t12 t22} \\
&\quad - a13^2 a32 t12 t32) \\
Gnorm33 &:= \frac{-((t22 - t32) a12^2 Gnorm21)}{(a11 a12 a13 t22 t32 - a11 a12 a13 t32^2} \\
&\quad + a12^2 a23 t12 t22 - a12 a13 a22 t12 t32 + a12 a13 a33 t12 t22 - a13^2 a32 t12 t32) \\
&\quad \left[\begin{bmatrix} 1, 0, 0, \right. \right. \\
&\quad \left. \left. \left[\frac{1}{a13 a12^2 (-t22 + t32)^2} (a12^2 a23 t12 t22 - ((\lambda t12 + a11) t32^2 + ((-\lambda t22} \\
&\quad + a22) t12 - a11 t22) t32 - a33 t12 t22) a13 a12 - a13^2 a32 t12 t32), \right. \right. \\
&\quad \left. \left. \frac{-t12 - t32}{a12 (t22 - t32)}, \frac{1}{a12 (t22 - t32)} \right], \right. \\
&\quad \left. \left[\frac{1}{a12 (-t22 + t32)^2 a13^2} (-a12^2 a23 t12 t22 + a13 ((-\lambda t12 - a11) t22^2} \\
&\quad + ((\lambda t32 - a33) t12 + t32 a11) t22 + t12 t32 a22) a12 + a13^2 a32 t12 t32), \right. \right. \\
&\quad \left. \left. \frac{t12 + t22}{a13 (t22 - t32)}, -\frac{1}{a13 (t22 - t32)} \right] \right]
\end{aligned}$$

We verify that G is indeed equal to $G^{-1} J^{-1}$ and give the expression of $Gnorm$

```

> Gnormalisationinfini:=simplify(Multiply(G^(-1),J^(-1))):
dGnormalisationinfinidlambda:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do
dGnormalisationinfinidlambda[i,j]:=diff(Gnormalisationinfini[i,

```

```

j],lambda): od: od:
simplify(Gnorm-Gnormalisationinfini);
factor(-(residue(Gnorm[1,1]/lambda^2,lambda=infinity) ));
factor(-(residue(Gnorm[1,1]/lambda,lambda=infinity) ));

factor(-(residue(Gnorm[2,1]/lambda^2,lambda=infinity) ));
factor(-(residue(Gnorm[2,1]/lambda,lambda=infinity) ));

factor(-(residue(Gnorm[2,2]/lambda^2,lambda=infinity) ));
factor(-(residue(Gnorm[2,2]/lambda,lambda=infinity) ));

factor(-(residue(Gnorm[2,3]/lambda^2,lambda=infinity) ));
factor(-(residue(Gnorm[2,3]/lambda,lambda=infinity) ));

factor(-(residue(Gnorm[3,1]/lambda^2,lambda=infinity) ));
factor(-(residue(Gnorm[3,1]/lambda,lambda=infinity) ));

factor(-(residue(Gnorm[3,2]/lambda^2,lambda=infinity) ));
factor(-(residue(Gnorm[3,2]/lambda,lambda=infinity) ));

factor(-(residue(Gnorm[3,3]/lambda^2,lambda=infinity) ));
factor(-(residue(Gnorm[3,3]/lambda,lambda=infinity) ));

factor(Determinant(Gnorm));

```

$$\begin{aligned}
& \left[\begin{array}{ccc} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{array} \right] \\
& \frac{0}{a12 (t22 - t32)} \\
& \frac{1}{a12^2 (t22 - t32)^2 a13} (a11 a12 a13 t22 t32 - a11 a12 a13 t32^2 + a12^2 a23 t12 t22 \\
& \quad - a12 a13 a22 t12 t32 + a12 a13 a33 t12 t22 - a13^2 a32 t12 t32) \\
& \quad - \frac{0}{a12 (t22 - t32)} \\
& \quad - \frac{t12 + t32}{a12 (t22 - t32)} \\
& \quad - \frac{0}{a12 (t22 - t32)} \\
& \quad - \frac{1}{a13 (t22 - t32)} \\
& \quad - \frac{t12 t22}{a13 (t22 - t32)}
\end{aligned} \tag{2.14}$$

$$\begin{aligned}
& - \frac{1}{a_{12} (t_{22} - t_{32})^2 a_{13}^2} (a_{11} a_{12} a_{13} t_{22}^2 - a_{11} a_{12} a_{13} t_{22} t_{32} + a_{12}^2 a_{23} t_{12} t_{22} \\
& \quad - a_{12} a_{13} a_{22} t_{12} t_{32} + a_{12} a_{13} a_{33} t_{12} t_{22} - a_{13}^2 a_{32} t_{12} t_{32}) \\
& \quad \frac{0}{a_{13} (t_{22} - t_{32})} \\
& \quad \frac{0}{a_{13} (t_{22} - t_{32})} \\
& \quad - \frac{1}{a_{12} a_{13} (t_{22} - t_{32})}
\end{aligned}$$

Verification that TdLtheo is really the normalized version of \check{L}

$$> \text{simplify}(\text{TdLtheo-Multiply}(\text{Multiply}(\text{Gnorm}, \text{checkL}), \text{Gnorm}^{-1})) - h * \text{Multiply}(\text{Gnormprime}, \text{Gnorm}^{-1});$$

$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \tag{2.15}$$

Expression of the Lax matrices \td{L}, L and gauge matrices using irregular times after computing the local diagonalization of the singular part at infinity.

```

> Ginfinity:=Matrix(3,3,0):
Ginfinity[1,1]:=1+g111*lambda^(-1)+ g112*lambda^(-2)+E11*
lambda^(-3):
Ginfinity[1,2]:= g121*lambda^(-1)+ g122*lambda^(-2)+E12*
lambda^(-3):
Ginfinity[1,3]:= g131*lambda^(-1)+ g132*lambda^(-2)+E13*
lambda^(-3):
Ginfinity[2,1]:= g211*lambda^(-1)+ g212*lambda^(-2)+E21*
lambda^(-3):
Ginfinity[2,2]:=1+g221*lambda^(-1)+ g222*lambda^(-2)+E22*
lambda^(-3):
Ginfinity[2,3]:= g231*lambda^(-1)+ g231*lambda^(-2)+E23*
lambda^(-3):
Ginfinity[3,1]:= g311*lambda^(-1)+ g312*lambda^(-2)+E31*
lambda^(-3):
Ginfinity[3,2]:= g321*lambda^(-1)+ g322*lambda^(-2)+E32*
lambda^(-3):
Ginfinity[3,3]:=1+g331*lambda^(-1)+ g332*lambda^(-2)+E33*
lambda^(-3):
Ginfinity;

```

```

Ginfinityprime:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do Ginfinityprime[i,j]:=diff(Ginfinity[i,j],lambda): od: od:

Linfinity:=Matrix(3,3,0):
Linfinity[1,1]:=t12*lambda+t11+t10/lambda+u11/lambda^2+v11/lambda^3:
Linfinity[1,2]:=u12/lambda^2+v12/lambda^3:
Linfinity[1,3]:=u13/lambda^2+v13/lambda^3:
Linfinity[2,1]:=u21/lambda^2+v21/lambda^3:
Linfinity[2,2]:=t22*lambda+t21+t20/lambda+u22/lambda^2+v22/lambda^3:
Linfinity[2,3]:=u23/lambda^2+v23/lambda^3:
Linfinity[3,1]:=u31/lambda^2+v31/lambda^3:
Linfinity[3,2]:=u32/lambda^2+v32/lambda^3:
Linfinity[3,3]:=t32*lambda+t31+t30/lambda+u33/lambda^2+v33/lambda^3:
Linfinity,

$$\left[ \left[ 1 + \frac{g111}{\lambda} + \frac{g112}{\lambda^2} + \frac{E11}{\lambda^3}, \frac{g121}{\lambda} + \frac{g122}{\lambda^2} + \frac{E12}{\lambda^3}, \frac{g131}{\lambda} + \frac{g132}{\lambda^2} + \frac{E13}{\lambda^3} \right], \left[ \frac{g211}{\lambda} + \frac{g212}{\lambda^2} + \frac{E21}{\lambda^3}, 1 + \frac{g221}{\lambda} + \frac{g222}{\lambda^2} + \frac{E22}{\lambda^3}, \frac{g231}{\lambda} + \frac{g232}{\lambda^2} + \frac{E23}{\lambda^3} \right], \left[ \frac{g311}{\lambda} + \frac{g312}{\lambda^2} + \frac{E31}{\lambda^3}, \frac{g321}{\lambda} + \frac{g322}{\lambda^2} + \frac{E32}{\lambda^3}, 1 + \frac{g331}{\lambda} + \frac{g332}{\lambda^2} + \frac{E33}{\lambda^3} \right] \right], \left[ \left[ \lambda t12 + t11 + \frac{t10}{\lambda} + \frac{u11}{\lambda^2} + \frac{v11}{\lambda^3}, \frac{u12}{\lambda^2} + \frac{v12}{\lambda^3}, \frac{u13}{\lambda^2} + \frac{v13}{\lambda^3} \right], \left[ \frac{u21}{\lambda^2} + \frac{v21}{\lambda^3}, \lambda t22 + t21 + \frac{t20}{\lambda} + \frac{u22}{\lambda^2} + \frac{v22}{\lambda^3}, \frac{u23}{\lambda^2} + \frac{v23}{\lambda^3} \right], \left[ \frac{u31}{\lambda^2} + \frac{v31}{\lambda^3}, \frac{u32}{\lambda^2} + \frac{v32}{\lambda^3}, \lambda t32 + t31 + \frac{t30}{\lambda} + \frac{u33}{\lambda^2} + \frac{v33}{\lambda^3} \right] \right]$$

> tdL:=simplify(tdL):
ToCancel2:=simplify(simplify(tdL)-(Multiply(Multiply(Ginfinity,Linfinity),Ginfinity^(-1))+h*Multiply(Ginfinityprime,Ginfinity^(-1)))):
> g121:=-a12/(t12-t22);
residue(ToCancel2[1,2]/lambda^2,lambda=infinity);
residue(ToCancel2[1,2]/lambda,lambda=infinity);
g131:=-a13/(t12-t32);
residue(ToCancel2[1,3]/lambda^2,lambda=infinity);
residue(ToCancel2[1,3]/lambda,lambda=infinity);
g211:=-a21/(t22-t12);

```

```

residue(ToCancel2[2,1]/lambda^2,lambda=infinity);
residue(ToCancel2[2,1]/lambda,lambda=infinity);
a22:=t21;
residue(ToCancel2[2,2]/lambda^2,lambda=infinity);
residue(ToCancel2[2,2]/lambda,lambda=infinity);
g231:=-a23/(t22-t32);
residue(ToCancel2[2,3]/lambda^2,lambda=infinity);
residue(ToCancel2[2,3]/lambda,lambda=infinity);
g311:=-a31/(t32-t12);
residue(ToCancel2[3,1]/lambda^2,lambda=infinity);
residue(ToCancel2[3,1]/lambda,lambda=infinity);
g321:=a32/(t22-t32);
residue(ToCancel2[3,2]/lambda^2,lambda=infinity);
simplify(residue(ToCancel2[3,2]/lambda,lambda=infinity));
a33:=t31;
residue(ToCancel2[3,3]/lambda^2,lambda=infinity);
simplify(residue(ToCancel2[3,3]/lambda,lambda=infinity));
a11:=t11;
residue(ToCancel2[1,1]/lambda,lambda=infinity);


$$g121 := -\frac{a12}{t12 - t22} \quad (3.2)$$


$$\begin{matrix} 0 \\ 0 \end{matrix}$$


$$g131 := -\frac{a13}{t12 - t32}$$


$$\begin{matrix} 0 \\ 0 \end{matrix}$$


$$g211 := -\frac{a21}{-t12 + t22}$$


$$\begin{matrix} 0 \\ 0 \end{matrix}$$


$$a22 := t21$$


$$\begin{matrix} 0 \\ 0 \end{matrix}$$


$$g231 := -\frac{a23}{t22 - t32}$$


$$\begin{matrix} 0 \\ 0 \end{matrix}$$


$$g311 := -\frac{a31}{-t12 + t32}$$


$$\begin{matrix} 0 \\ 0 \end{matrix}$$


$$g321 := \frac{a32}{t22 - t32}$$


$$\begin{matrix} 0 \\ 0 \end{matrix}$$


$$a33 := t31$$


```

```

0
0
a11 := t11
0

> NonTrivialRelation:=residue(ToCancel2[1,1],lambda=infinity);
tdL:=simplify(tdL);

g212:=(a21*t12^2*g111-a21*t12*t22*g111-a21*t12*t32*g111+a21*
t22*t32*g111-a21*t12*t11+a21*t12*t21+a21*t32*t11-a21*t32*t21+
a23*a31*t12-a23*a31*t22)/(t12-t22)^2/(t12-t32);
simplify(residue(ToCancel2[2,1],lambda=infinity));

NonTrivialRelation2:=simplify(residue(ToCancel2[2,2],lambda=
infinity));

g331:=(a13*a21*t22-a13*a21*t32+a23*t12*t22-a23*t12*t32+a23*t12*
t21-a23*t12*t31-a23*t22*t32+a23*t32^2-a23*t32*t21+a23*t32*t31)/
((t12-t32)*(t22-t32)*a23);
simplify(residue(ToCancel2[2,3],lambda=infinity));

g312:=(a31*t12^2*g111-a31*t12*t22*g111-a31*t12*t32*g111+a31*
t22*t32*g111+a21*a32*t12-a21*a32*t32-a31*t12*t11+a31*t12*t31+
a31*t22*t11-a31*t22*t31)/(t12-t32)^2/(t12-t22);
simplify(residue(ToCancel2[2,3],lambda=infinity));

g322:=-(-a32*t12*t22*g221+a32*t12*t32*g221+a32*t22^2*g221-a32*
t22*t32*g221+a12*a31*t22-a12*a31*t32+a32*t12*t21-a32*t12*t31-
a32*t22*t21+a32*t22*t31)/(t22-t32)^2/(t12-t22);
simplify(residue(ToCancel2[3,2],lambda=infinity));

NonTrivialRelation3:=simplify(residue(ToCancel2[3,3],lambda=
infinity));

```

$$NonTrivialRelation := \frac{a21\ a12}{-t12 + t22} + \frac{a31\ a13}{-t12 + t32} + t10 \quad (3.3)$$

$$\begin{bmatrix} \lambda t12 + t11 & a12 & a13 \\ a21 & \lambda t22 + t21 & a23 \\ a31 & a32 & \lambda t32 + t31 \end{bmatrix}$$

$$g212 := \frac{1}{(t12 - t22)^2 (t12 - t32)} (a21 g111 t12^2 - a21 g111 t12 t22 - a21 g111 t12 t32 + a21 g111 t22 t32 - a21 t11 t12 + a21 t11 t32 + a21 t12 t21 - a21 t21 t32 + a23 a31 t12 - a23 a31 t22)$$

0

```

NonTrivialRelation2 :=  $\frac{1}{(t12 - t22)(t22 - t32)} (-t20 t22^2 + (a12 a21 + a23 a32 t12 t20 + t20 t32) t22 + (-a23 a32 - t20 t32) t12 - a12 a21 t32)$ 
g331 :=  $\frac{1}{(t12 - t32)(t22 - t32)a23} (a13 a21 t22 - a13 a21 t32 + a23 t12 t21 + a23 t12 t22 - a23 t12 t31 - a23 t12 t32 - a23 t21 t32 - a23 t22 t32 + a23 t31 t32 + a23 t32^2)$ 
0
g312 :=  $\frac{1}{(t12 - t32)^2(t12 - t22)} (a31 g111 t12^2 - a31 g111 t12 t22 - a31 g111 t12 t32 + a31 g111 t22 t32 + a21 a32 t12 - a21 a32 t32 - a31 t11 t12 + a31 t11 t22 + a31 t12 t31 - a31 t22 t31)$ 
0
g322 :=  $-\frac{1}{(t22 - t32)^2(t12 - t22)} (-a32 g221 t12 t22 + a32 g221 t12 t32 + a32 g221 t22^2 - a32 g221 t22 t32 + a12 a31 t22 - a12 a31 t32 + a32 t12 t21 - a32 t12 t31 - a32 t21 t22 + a32 t22 t31)$ 
0
NonTrivialRelation3 :=  $\frac{1}{(t12 - t32)(t22 - t32)} (t30 t32^2 + (-a13 a31 - a23 a32 t12 t30 - t22 t30) t32 + (a23 a32 + t22 t30) t12 + a13 a31 t22)$ 
> NonTrivialRelation:=simplify(NonTrivialRelation);
NonTrivialRelation2;
NonTrivialRelation3;

t10:=-t20-t30;
a21 := (a23*a32*t12-a23*a32*t22-t12*t22*t20+t12*t32*t20+t22^2*t20-t22*t32*t20)/(a12*(t22-t32));
a31 := -(a23*a32*t12-a23*a32*t32+t12*t22*t30-t12*t32*t30-t22*t32*t30+t32^2*t30)/(a13*(t22-t32));
simplify(NonTrivialRelation);
simplify(NonTrivialRelation2);
simplify(NonTrivialRelation3);
tdL:=simplify(tdL);

NonTrivialRelation :=  $\frac{1}{(t12 - t22)(t12 - t32)} (t10 t12^2 + ((-t22 - t32) t10 - a12 a21 - a13 a31) t12 + a12 a21 t32 + a13 a31 t22 + t10 t22 t32)$  (3.4)
 $\frac{1}{(t12 - t22)(t22 - t32)} (-t20 t22^2 + (a12 a21 + a23 a32 + t12 t20 + t20 t32) t22 + (-a23 a32 - t20 t32) t12 - a12 a21 t32)$ 
 $\frac{1}{(t12 - t32)(t22 - t32)} (t30 t32^2 + (-a13 a31 - a23 a32 - t12 t30 - t22 t30) t32 + (a23 a32 + t22 t30) t12 + a13 a31 t22)$ 
t10 := -t20 - t30

```

$$a_{21} := \frac{a_{23} a_{32} t_{12} - a_{23} a_{32} t_{22} - t_{12} t_{20} t_{22} + t_{12} t_{20} t_{32} + t_{20} t_{22}^2 - t_{20} t_{22} t_{32}}{a_{12} (t_{22} - t_{32})}$$

$$a_{31} := -\frac{a_{23} a_{32} t_{12} - a_{23} a_{32} t_{32} + t_{12} t_{22} t_{30} - t_{12} t_{30} t_{32} - t_{22} t_{30} t_{32} + t_{30} t_{32}^2}{a_{13} (t_{22} - t_{32})}$$

$$\begin{bmatrix} 0 \\ 0 \\ 0 \\ \lambda t_{12} + t_{11} & a_{12} & a_{13} \\ \frac{(t_{12} - t_{22}) ((-t_{22} + t_{32}) t_{20} + a_{23} a_{32})}{a_{12} (t_{22} - t_{32})} & \lambda t_{22} + t_{21} & a_{23} \\ -\frac{(t_{12} - t_{32}) (t_{30} (t_{22} - t_{32}) + a_{23} a_{32})}{a_{13} (t_{22} - t_{32})} & a_{32} & \lambda t_{32} + t_{31} \end{bmatrix}$$

Definition of the Darboux coordinates to end the expression of the Lax matrices and gauge matrices.

The coordinate q was introduced earlier in the oper gauge transform as the apparent singularity

```
> Conditionp:=unapply(factor(Determinant(Psing*IdentityMatrix(3)-
tdL)),lambda):
> Psing:=(a12^2*a23*t32+a12*a13*t22*t31-a12*a13*t32*t21-a13^2*
a32*t22)/(a12*(t22-t32)*a13);
factor(Conditionp(Qsing));
Qsing=q;
Psing=p;
solve({Qsing-q,Psing-p},{a23,a32});

a23 := -a13*(-q*t22+p-t21)/a12;
a32 := -a12*(-q*t32+p-t31)/a13;
simplify(Qsing-q);
simplify(Psing-p);

Psing :=  $\frac{a_{12}^2 a_{23} t_{32} - a_{12} a_{13} t_{21} t_{32} + a_{12} a_{13} t_{22} t_{31} - a_{13}^2 a_{32} t_{22}}{a_{12} a_{13} (t_{22} - t_{32})}$  (3.5)
0
 $\frac{a_{12}^2 a_{23} - a_{12} a_{13} t_{21} + a_{12} a_{13} t_{31} - a_{13}^2 a_{32}}{a_{12} a_{13} (t_{22} - t_{32})} = q$ 
 $\frac{a_{12}^2 a_{23} t_{32} - a_{12} a_{13} t_{21} t_{32} + a_{12} a_{13} t_{22} t_{31} - a_{13}^2 a_{32} t_{22}}{a_{12} a_{13} (t_{22} - t_{32})} = p$ 
 $\left\{ a_{23} = -\frac{a_{13} (-q t_{22} + p - t_{21})}{a_{12}}, a_{32} = -\frac{a_{12} (-q t_{32} + p - t_{31})}{a_{13}} \right\}$ 
a23 := - $\frac{a_{13} (-q t_{22} + p - t_{21})}{a_{12}}$ 
a32 := - $\frac{a_{12} (-q t_{32} + p - t_{31})}{a_{13}}$ 
0
0
```

```

> g132:=solve(simplify(residue(ToCancel2[1,3]/lambda^0,lambda=
infinity)),g132);
g221:=solve(simplify(residue(ToCancel2[1,2]/lambda^0,lambda=
infinity)),g221);

simplify(residue(ToCancel2[1,1],lambda=infinity));
simplify(residue(ToCancel2[1,2],lambda=infinity));
simplify(residue(ToCancel2[1,3],lambda=infinity));
simplify(residue(ToCancel2[2,1],lambda=infinity));
simplify(residue(ToCancel2[2,2],lambda=infinity));
simplify(residue(ToCancel2[2,3],lambda=infinity));
simplify(residue(ToCancel2[3,1],lambda=infinity));
simplify(residue(ToCancel2[3,2],lambda=infinity));
simplify(residue(ToCancel2[3,3],lambda=infinity));

```

$$g132 := -\frac{1}{(t12 - t32)^2 (-q t22 + p - t21)} ((q^2 t12 t22 - p q t12 - p q t22 + q t11 t22 + q t12 t21 - q t12 t22 + q t22 t32 + p^2 - p t11 + p t12 - p t21 - p t32 + t11 t21 + t12 t20 - t12 t21 - t20 t22 + t21 t32) a13) \quad (3.6)$$

$$+ q t12 t21 - q t12 t22 + q t22 t32 + p^2 - p t11 + p t12 - p t21 - p t32 + t11 t21 + t12 t20 - t12 t21 - t20 t22 + t21 t32) a13)$$

$$g221 := \frac{1}{(t12 - t22) (t22 - t32) a12} (-a12 q t12 t32 + a12 q t22 t32 - g122 t12^2 t22 + g122 t12^2 t32 + 2 g122 t12 t22^2 - 2 g122 t12 t22 t32 - g122 t22^3 + g122 t22^2 t32 + a12 p t12 - a12 p t22 + a12 t11 t22 - a12 t11 t32 - a12 t12 t31 - a12 t21 t22 + a12 t21 t32 + a12 t22 t31)$$

$$0$$

$$0$$

$$0$$

$$0$$

$$0$$

$$0$$

$$0$$

$$0$$

$$0$$

$$0$$

$$> u11:=solve(simplify(residue(ToCancel2[1,1]*lambda,lambda=
infinity)),u11):
simplify(residue(ToCancel2[1,1]*lambda,lambda=infinity));
u22:=solve(simplify(residue(ToCancel2[2,2]*lambda,lambda=
infinity)),u22):
simplify(residue(ToCancel2[2,2]*lambda,lambda=infinity));
u33:=solve(simplify(residue(ToCancel2[3,3]*lambda,lambda=
infinity)),u33):
simplify(residue(ToCancel2[3,3]*lambda,lambda=infinity)); \quad (3.7)$$

Summary of the formulas for Lax matrices and gauge matrices

```

> tdL:=simplify(tdL):
tdL[1,1];
tdL[1,2];
tdL[1,3];
tdL[2,1];
tdL21bis:=(t12-t22)/a12/(t22-t32)*(p^2-(q*(t22+t32)+t21+t31)*p+
t32*t22*q^2+(t22*t31+t32*t21)*q+(t32-t22)*t20+t21*t31 );
factor(series(factor(tdL[2,1]-tdL21bis),q=0));
tdL[2,2];
tdL[2,3];
tdL[3,1];
tdL31bis:=(t12-t32)*(p^2-(q*(t22+t32)+t21+t31)*p+t22*t32*q^2+
(t22*t31+t32*t21)*q+((t22-t32)*t30+t21*t31))/a13/(t32-t22);
factor(series(factor(tdL[3,1]-tdL31bis),q=0));
tdL[3,2];
tdL[3,3];
tdL;

```

$$\frac{\lambda_{t12+t11}}{a12} \quad (3.8)$$

$$\frac{a12}{a13}$$

$$\frac{1}{a12(t22-t32)} \left((t12-t22) \left((q^2 t32 - p q + q t31 - t20) t22 + (-p q + q t21 + t20) t32 + (p - t31) (p - t21) \right) \right)$$

$$tdL21bis := \frac{1}{a12(t22-t32)} \left((t12-t22) \left(p^2 - (q (t22 + t32) + t21 + t31) p + q^2 t22 t32 + (t21 t32 + t22 t31) q + (-t22 + t32) t20 + t21 t31 \right) \right)$$

$$\frac{\lambda_{t22+t21}}{a12}$$

$$- \frac{1}{a13(t22-t32)} \left((t12-t32) \left((q^2 t22 - p q + q t21 - t30) t32 + (-p q + q t31 + t30) t22 + (p - t31) (p - t21) \right) \right)$$

$$tdL31bis := \frac{1}{a13(-t22+t32)} \left((t12-t32) \left(p^2 - (q (t22 + t32) + t21 + t31) p + q^2 t22 t32 + (t21 t32 + t22 t31) q + t30 (t22 - t32) + t21 t31 \right) \right)$$

$$\frac{a12 (-q t32 + p - t31)}{a13}$$

$$\lambda_{t32+t31}$$

$$\left[\left[\lambda_{t12+t11}, a12, a13 \right], \right.$$

$$\left. \left[\frac{1}{a12(t22-t32)} \left((t12-t22) \left((q^2 t32 - p q + q t31 - t20) t22 + (-p q + q t21 + t20) t32 + (-p q + q t31 + t30) t22 + (p - t31) (p - t21) \right) \right) \right]$$

```

+ q t21 + t20) t32 + (p - t31) (p - t21) ), λ t22 + t21, -  $\frac{a13 (-q t22 + p - t21)}{a12}$ 
],
 $-\frac{1}{a13 (t22 - t32)} ((t12 - t32) ((q^2 t22 - p q + q t21 - t30) t32 + (-p q$ 
+ q t31 + t30) t22 + (p - t31) (p - t21) ), -  $\frac{a12 (-q t32 + p - t31)}{a13}$ , λ t32 + t31
]
]

> L33ter:=h/(lambda-q)+(t12+t22+t32)*lambda+t11+t21+t31;
simplify(L33bis-L33ter);

L32ter:=h*(-(t12+t22+t32)*q+p-t11-t21-t31)/(lambda-q)-(t12*t22+
t12*t32+t22*t32)*lambda^2-(t12*(t21+t31)+t22*(t11+t31)+t32*
(t11+t21))*lambda+ t12*t10+t22*t20+t32*t30-t11*t21-t11*t31-t21*t31 +h*t12 ;
factor(series(simplify(L32bis-L32ter),lambda=0));

L31ter:=h*( p^2-(t11+t21+t31+q*(t12+t22+t32))*p+ (t12*t22+t12*t32+t22*t32)*q^2+(t12*(t21+t31)+t22*(t11+t31)+t32*(t11+t21))*q-
t12*t10 -t22*t20-t32*t30+t11*t31+t11*t21+t21*t31 -h*t12 )/
(lambda-q)
+t12*t22*t32*lambda^3+(t22*t12*t31+t12*t32*t21+t22*t32*t11)*
lambda^2
+((t30-h)*t22*t12+(t20-h)*t32*t12+t10*t22*t32 +t12*t21*t31+t22*t11*t31+t32*t11*lambda
+p^3-((t12+t22+t32)*q+t21+t31+t11)*p^2
+(q^2*(t12*t22+t12*t32+t22*t32)+(t12*(t21+t31)+t22*(t11+t31)+t32*(t11+t21))*q-(t10*t12+t20*t22+t30*t32)+t11*t21+t11*t31+t21*t31 -h*t12 )*p
-q^3*t12*t22*t32-(t22*t32*t11+t12*t32*t21+t12*t22*t31)*q^2
-(t21*t31*t12+t11*t31*t22+t11*t21*t32 +t10*t22*t32+t20*t12*t32+t30*t12*t22 -h*(t22+t32)*t12)*q;
series(simplify(series(simplify(L31bis-L31ter),q=0)),q=0);

L33ter :=  $\frac{h}{\lambda - q} + (t12 + t22 + t32) \lambda + t11 + t21 + t31$  (3.9)
 $L32ter := \frac{h ((- (t12 + t22 + t32) q + p - t11 - t21 - t31))}{\lambda - q} - (t12 t22 + t12 t32$ 
 $+ t22 t32) \lambda^2 - (t12 (t21 + t31) + t22 (t11 + t31) + t32 (t11 + t21)) \lambda + t12 (-t20$ 
 $- t30) + t20 t22 + t30 t32 - t11 t21 - t11 t31 - t21 t31 + h t12$ 
 $0$ 

```

$$\begin{aligned}
L3Iter &:= \frac{1}{\lambda - q} \left(h (p^2 - (t11 + t21 + t31 + (t12 + t22 + t32) q) p + (t12 t22 + t12 t32 + t22 t32) q^2 + (t12 (t21 + t31) + t22 (t11 + t31) + t32 (t11 + t21)) q - t12 (-t20 - t30) - t20 t22 - t30 t32 + t11 t31 + t11 t21 + t21 t31 - h t12) \right) + t12 t22 t32 \lambda^3 \\
&\quad + (t11 t22 t32 + t12 t21 t32 + t12 t22 t31) \lambda^2 + ((-h + t30) t22 t12 + (-h + t20) t32 t12 + (-t20 - t30) t22 t32 + t12 t21 t31 + t22 t11 t31 + t32 t11 t21) \lambda + p^3 \\
&\quad - (t11 + t21 + t31 + (t12 + t22 + t32) q) p^2 + ((t12 t22 + t12 t32 + t22 t32) q^2 + (t12 (t21 + t31) + t22 (t11 + t31) + t32 (t11 + t21)) q - t12 (-t20 - t30) - t20 t22 - t30 t32 + t11 t21 + t11 t31 + t21 t31 - h t12) p - q^3 t12 t22 t32 \\
&\quad - (t11 t22 t32 + t12 t21 t32 + t12 t22 t31) q^2 - (t12 t21 t31 + t22 t11 t31 + t32 t11 t21 + (-t20 - t30) t22 t32 + t12 t20 t32 + t12 t22 t30 - h (t22 + t32) t12) q \\
&\quad 0
\end{aligned}$$

> G:=simplify(G):

```

simplify(G[1,1]);
simplify(G[1,2]);
simplify(G[1,3]);
simplify(G[2,1]);
simplify(G[2,2]);
simplify(G[2,3]);
simplify(G[3,1]);
simplify(G[3,2]);
simplify(G[3,3]);
G31bis:=(t12*lambda+t11)^2-p^2+(q*(t22+t32)+t21+t31)*p- t22*t32*q^2-(t22*t31+t32*t21)*q- t21*t31+t10*t12+t20*t22+t30*t32+h*t12;
G33bis:=a13*( (t12+t32)*lambda-p+t22*q+t11+t21+t31);
simplify(G[3,3]-G33bis);
G32bis:=a12*( (t12+t22)*lambda-p+t32*q+t11+t21+t31);
simplify(G[3,2]-G32bis);
series(simplify(G[3,1]-G31bis),q=0);

```

$$\begin{aligned}
&\quad 1 \\
&\quad 0 \\
&\quad 0 \\
&\quad \lambda t12 + t11 \\
&\quad \frac{a12}{a13} \\
&\quad -a13 ((-t12 - t32) \lambda - q t22 + p - t11 - t21 - t31) \\
&\quad - ((-t12 - t22) \lambda - q t32 + p - t11 - t21 - t31) a12 \\
G31bis &:= (\lambda t12 + t11)^2 - p^2 + (q (t22 + t32) + t21 + t31) p - q^2 t22 t32 - (t21 t32 + t22 t31) q - t21 t31 + t12 (-t20 - t30) + t20 t22 + t30 t32 + h t12 \\
G33bis &:= a13 ((t12 + t32) \lambda - p + q t22 + t11 + t21 + t31) \\
&\quad 0 \\
G32bis &:= a12 ((t12 + t22) \lambda - p + q t32 + t11 + t21 + t31)
\end{aligned}$$
(3.10)

```

0
0
> Gnorm:=simplify(Gnorm);
J:=simplify(J);
simplify(Gnorm-Multiply(G^(-1),J^(-1)));
simplify(G^(-1)-Multiply(Gnorm,J));
J[3,3];
J[3,2];
J[3,1];
J31bis:=1/(lambda-q)*(p^2-p*((t12+t22+t32)*q+t31+t11+t21) +
(t12*t22+t12*t32+t22*t32)*q^2 + (t12*(t21+t31)+ t22*(t11+t31) +
t32*(t21+t11))*q -t12*t10-t22*t20-t32*t30+t11*t21+t11*t31+t21*t31-h*t12);
series(simplify((lambda-q)*(J[3,1]-J31bis)),q=0);


$$\left[ \begin{bmatrix} 1, 0, 0 \\ \frac{((\lambda+q)t32+q t22-p+t21+t31)t12+t11 t32}{a12 (t22-t32)}, \frac{-t12-t32}{a12 (t22-t32)}, \frac{1}{a12 (t22-t32)} \end{bmatrix}, \begin{bmatrix} \frac{((-\lambda-q)t22-q t32+p-t21-t31)t12-t11 t22}{a13 (t22-t32)}, \frac{t12+t22}{a13 (t22-t32)}, -\frac{1}{a13 (t22-t32)} \end{bmatrix} \right] \quad (3.11)$$


$$\left[ \begin{bmatrix} 1, 0, 0 \\ 0, 1, 0 \\ \frac{1}{\lambda-q} ((t22+t32)t12+t22 t32) q^2 + ((t31-p+t21)t12 + (-t22-t32)p + t22(t11+t31) + t32(t11+t21))q + (-h+t20+t30)t12 + p^2 + (-t31-t11-t21)p - t20t22 - t30t32 + t11(t21+t31) + t21t31 \end{bmatrix}, \begin{bmatrix} \frac{(t12+t22+t32)q-p+t11+t21+t31}{-\lambda+q}, \frac{1}{\lambda-q} \end{bmatrix} \right]$$


$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$


```

$$\begin{aligned}
& \left[\begin{array}{ccc} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{array} \right] \\
& \frac{1}{\lambda - q} \\
& \frac{(t12 + t22 + t32) q - p + t11 + t21 + t31}{-\lambda + q} \\
& \frac{1}{\lambda - q} \left(((t22 + t32) t12 + t22 t32) q^2 + ((t31 - p + t21) t12 + (-t22 - t32) p \right. \\
& \quad \left. + t22 (t11 + t31) + t32 (t11 + t21)) q + (-h + t20 + t30) t12 + p^2 + (-t31 - t11 \right. \\
& \quad \left. - t21) p - t20 t22 - t30 t32 + t11 (t21 + t31) + t21 t31 \right) \\
& \quad 0
\end{aligned}$$

Definition of P_1, P_2 and P_3 and math with the theoretical formulas for L

```

> P1:=unapply( (t12+t22+t32)*lambda+t11+t21+t31,lambda);
P2:=unapply( (t12*t22+t12*t32+t22*t32)*lambda^2+((t21+t31)*t12+
(t11+t31)*t22+t32*(t11+t21))*lambda-t10*t12-t20*t22-t30*t32+
t21*t11 +t31*t11+t21*t31,lambda);
P3:=unapply(t12*t22*t32*lambda^3+(t12*t22*t31+t12*t32*t21+t22*t32*t11)*lambda^2+
(t12*t22*t30+t12*t32*t20+t22*t32*t10 +t12*t21*t31+t22*t11*t31+t32*t11*t21)*lambda,lambda);
L:=simplify(L):
simplify(L[3,3]-h/(lambda-q)-P1(lambda));
simplify(L[3,2]-(h*(p-P1(q))/(lambda-q)-P2(lambda)+h*t12));
series( simplify(L[3,1]-(h*(p^2-P1(q)*p+P2(q)-h*t12)/(lambda-q)
+p^3-P1(q)*p^2+(P2(q)-h*t12)*p-P3(q)+P3(lambda)-h*(t22+t32)*
t12*(lambda-q))),lambda=0);
simplify(J31bis-(p^2-P1(q)*p+P2(q)-h*t12)/(lambda-q));

```

$$P1 := \lambda \rightarrow (t12 + t22 + t32) \lambda + t11 + t21 + t31 \quad (3.12)$$

$$P2 := \lambda \rightarrow (t12 t22 + t12 t32 + t22 t32) \lambda^2 + (t12 (t21 + t31) + t22 (t11 + t31) + t32 (t11 + t21)) \lambda - t12 (-t20 - t30) - t20 t22 - t30 t32 + t11 t21 + t11 t31 + t21 t31$$

$$P3 := \lambda \rightarrow t12 t22 t32 \lambda^3 + (t11 t22 t32 + t12 t21 t32 + t12 t22 t31) \lambda^2 + ((-t20 - t30) t22 t32 + t32 t11 t21 + t22 t11 t31 + t12 t20 t32 + t12 t21 t31 + t12 t22 t30) \lambda$$

$$\quad 0$$

$$\quad 0$$

$$\quad 0$$

$$\quad 0$$

```

> Gnormalized:=Matrix(3,3,0):
Gnormalized[1,1]:=1:
Gnormalized[2,2]:=1:
Gnormalized[3,3]:=1:
Gnormalized[3,1]:=(t12-t32)/a13*lambda:
Gnormalized;

```

```

dGnormalizeddlambda:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do dGnormalizeddlambda
[i,j]:=diff(Gnormalized[i,j],lambda): od: od:
LGnormalized:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do LGnormalized[i,j]:=simplify( h*diff(Gnormalized[i,j],t12)*dott12+h*diff(Gnormalized[i,j],t22)*dott22+h*diff(Gnormalized[i,j],t32)*dott32+h*diff(Gnormalized[i,j],t11)*dott11+h*diff(Gnormalized[i,j],t21)*dott21+h*diff(Gnormalized[i,j],t31)*dott31+h*diff(Gnormalized[i,j],a12)*dota12+h*diff(Gnormalized[i,j],a13)*dota13):
od: od:
Lnew:=simplify(Multiply(Multiply(Gnormalized,tdL),Gnormalized^(-1))+h*Multiply(dGnormalizeddlambda,Gnormalized^(-1))):

Multiply(dGnormalizeddlambda,Gnormalized^(-1));
Multiply(Gnormalized^(-1),dGnormalizeddlambda);
simplify(tdL[1,2]*tdL[2,3]-tdL[2,2]*tdL[1,3]);

```

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \frac{(t12 - t32) \lambda}{a13} & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ \frac{t12 - t32}{a13} & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ \frac{t12 - t32}{a13} & 0 & 0 \end{bmatrix}$$

$$-((\lambda - q) t22 + p) a13$$
(3.13)

> GeneralSpectralCurve:=Determinant(y*IdentityMatrix(3)-tdL);

$$\begin{aligned}
GeneralSpectralCurve := & -\lambda^3 t12 t22 t32 + q^3 t12 t22 t32 - \lambda^2 t11 t22 t32 - \lambda^2 t12 t21 t32 \\
& - \lambda^2 t12 t22 t31 + \lambda^2 t12 t22 y + \lambda^2 t12 t32 y + \lambda^2 t22 t32 y - p q^2 t12 t22 - p q^2 t12 t32 \\
& - p q^2 t22 t32 + q^2 t11 t22 t32 + q^2 t12 t21 t32 + q^2 t12 t22 t31 - \lambda t11 t21 t32 \\
& - \lambda t11 t22 t31 + \lambda t11 t22 y + \lambda t11 t32 y - \lambda t12 t20 t32 - \lambda t12 t21 t31 + \lambda t12 t21 y \\
& - \lambda t12 t22 t30 + \lambda t12 t31 y - \lambda t12 y^2 + \lambda t20 t22 t32 + \lambda t21 t32 y + \lambda t22 t30 t32 \\
& + \lambda t22 t31 y - \lambda t22 y^2 - \lambda t32 y^2 + p^2 q t12 + p^2 q t22 + p^2 q t32 - p q t11 t22 \\
& - p q t11 t32 - p q t12 t21 - p q t12 t31 - p q t21 t32 - p q t22 t31 + q t11 t21 t32 \\
& + q t11 t22 t31 + q t12 t20 t32 + q t12 t21 t31 + q t12 t22 t30 - q t20 t22 t32
\end{aligned}$$
(3.14)

$$\begin{aligned}
& -q t22 t30 t32 - p^3 + p^2 t11 + p^2 t21 + p^2 t31 - p t11 t21 - p t11 t31 - p t12 t20 \\
& - p t12 t30 + p t20 t22 - p t21 t31 + p t30 t32 + t11 t21 y + t11 t31 y - t11 y^2 \\
& + t12 t20 y + t12 t30 y - t20 t22 y + t21 t31 y - t21 y^2 - t30 t32 y - t31 y^2 + y^3
\end{aligned}$$

Jimbo-Miwa-Ueno tau function

```

> ExpLambdaInfinity:=Matrix(3,3,0):
ExpLambdaInfinity[1,1]:=exp((t11*lambda+t12/2*lambda^2)/h):
ExpLambdaInfinity[2,2]:=exp((t21*lambda+t22/2*lambda^2)/h):
ExpLambdaInfinity[3,3]:=exp((t31*lambda+t32/2*lambda^2)/h):
ExpLambdaInfinity;

LambdaInfinity:=Matrix(3,3,0):
LambdaInfinity[1,1]:=t11*lambda+t12/2*lambda^2:
LambdaInfinity[2,2]:=t21*lambda+t22/2*lambda^2:
LambdaInfinity[3,3]:=t31*lambda+t32/2*lambda^2:
LambdaInfinity;

dLambdaInfinitydlambda:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do
dLambdaInfinitydlambda[i,j]:=diff(LambdaInfinity[i,j],lambda):
od: od:
dLambdaInfinitydlambda;

ExpMonodromies:=Matrix(3,3,0):
ExpMonodromies[1,1]:=exp(t10*ln(lambda)/h):
ExpMonodromies[2,2]:=exp(t20*ln(lambda)/h):
ExpMonodromies[3,3]:=exp(t30*ln(lambda)/h):
ExpMonodromies;

Monodromies:=Matrix(3,3,0):
Monodromies[1,1]:=t10/lambda:
Monodromies[2,2]:=t20/lambda:
Monodromies[3,3]:=t30/lambda:
Monodromies;

F1:=Matrix(3,3,0):
F2:=Matrix(3,3,0):
F3:=Matrix(3,3,0):
F4:=Matrix(3,3,0):
FF5:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do F1[i,j]:=f1[i,j]:
F2[i,j]:=f2[i,j]:
F3[i,j]:=f3[i,j]:

```

```

F4[i,j]:=f4[i,j]:
FF5[i,j]:=ff5[i,j]:
od: od:

HatPsiReg:=IdentityMatrix(3)+F1/lambda+F2/lambda^2+F3/lambda^3+
F4/lambda^4+ FF5/lambda^5:
tdPsi:=Multiply(Multiply
(HatPsiReg,ExpLambdaInfinity),ExpMonodromies):

dHatPsiRegdlambda:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do dHatPsiRegdlambda[i,
j]:=diff(HatPsiReg[i,j],lambda): od: od:

dtdPsidlambda:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do dtdPsidlambda[i,j]:=diff(tdPsi[i,j],lambda): od: od:

dLambdaInfinitydt:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do dLambdaInfinitydt[i,
j]:= simplify(diff(LambdaInfinity[i,j],t11)*dt11+diff
(LambdaInfinity[i,j],t21)*dt21+diff(LambdaInfinity[i,j],t31)*
dt31+diff(LambdaInfinity[i,j],t12)*dt12+diff(LambdaInfinity[i,
j],t22)*dt22+diff(LambdaInfinity[i,j],t32)*dt32): od: od:
dLambdaInfinitydt:

omegaJMU:=-h*residue(Trace(Multiply(Multiply(HatPsiReg^
(-1),dHatPsiRegdlambda), dLambdaInfinitydt)),lambda=infinity);

```

$$\left[\begin{array}{ccc} e^{\frac{\lambda t_{11} + \frac{1}{2} t_{12} \lambda^2}{h}} & 0 & 0 \\ 0 & e^{\frac{t_{21} \lambda + \frac{1}{2} t_{22} \lambda^2}{h}} & 0 \\ 0 & 0 & e^{\frac{t_{31} \lambda + \frac{1}{2} \lambda^2 t_{32}}{h}} \end{array} \right] \quad (3.15)$$

$$\begin{bmatrix} e^{\frac{(-t20 - t30) \ln(\lambda)}{h}} & 0 & 0 \\ 0 & e^{\frac{t20 \ln(\lambda)}{h}} & 0 \\ 0 & 0 & e^{\frac{t30 \ln(\lambda)}{h}} \end{bmatrix}$$

$$\begin{aligned} omegaJMU := & -h \left(fI_{1,1} dt11 - \frac{1}{2} (fI_{1,1}^2 + fI_{1,2}fI_{2,1} + fI_{1,3}fI_{3,1} - 2f2_{1,1}) dt12 \right. \\ & + fI_{2,2} dt21 - \frac{1}{2} (fI_{1,2}fI_{2,1} + fI_{2,2}^2 + fI_{2,3}fI_{3,2} - 2f2_{2,2}) dt22 + fI_{3,3} dt31 \\ & \left. - \frac{1}{2} (fI_{1,3}fI_{3,1} + fI_{2,3}fI_{3,2} + fI_{3,3}^2 - 2f2_{3,3}) dt32 \right) \end{aligned}$$

```

> ToCancel0:=simplify(h*dtdPsidlambda-Multiply(tdL,tdPsi));
> Cancel11:=series(simplify(series( simplify( ToCancel0[1,1]*exp
  (-((-2*t20-2*t30)*ln(lambda)+t12*lambda^2+2*lambda*t11)/(2*h))
  ),lambda=infinity,10)),lambda=infinity);
f1[3,1]:=solve(residue(Cancel11 ,lambda=infinity),f1[3,1]);
f2[3,1]:=solve(residue(Cancel11*lambda ,lambda=infinity),f2[3,
1]);
f3[3,1]:=solve(residue(Cancel11*lambda^2 ,lambda=infinity),f3
[3,1]);
Cancel11 := 
$$\frac{-a12 fI_{2,1} - a13 fI_{3,1} - t20 - t30}{\lambda} + \frac{-a12 f2_{2,1} - a13 f2_{3,1} - h fI_{1,1} - t20 fI_{1,1} - t30 fI_{1,1}}{\lambda^2} + \frac{-a12 f3_{2,1} - a13 f3_{3,1} - 2 h f2_{1,1} - t20 f2_{1,1} - t30 f2_{1,1}}{\lambda^3} + \frac{-a12 f4_{2,1} - a13 f4_{3,1} - 3 h f3_{1,1} - t20 f3_{1,1} - t30 f3_{1,1}}{\lambda^4} + \frac{-a12 ff5_{2,1} - a13 ff5_{3,1} - 4 h f4_{1,1} - t20 f4_{1,1} - t30 f4_{1,1}}{\lambda^5} + O\left(\frac{1}{\lambda^6}\right)$$
 (3.16)
fI_{3,1} := 
$$-\frac{a12 fI_{2,1} + t20 + t30}{a13}$$

f2_{3,1} := 
$$-\frac{a12 f2_{2,1} + h fI_{1,1} + t20 fI_{1,1} + t30 fI_{1,1}}{a13}$$

f3_{3,1} := 
$$-\frac{a12 f3_{2,1} + 2 h f2_{1,1} + t20 f2_{1,1} + t30 f2_{1,1}}{a13}$$

> Cancel12:=series(simplify(series( simplify( ToCancel0[1,2]*exp
  (-(lambda^2*t22+2*t20*ln(lambda)+2*lambda*t21)/(2*h))
  ),lambda=infinity,10)),lambda=infinity):

```

```

f1[1,2]:=solve(residue(Cancel12/lambda,lambda=infinity),f1[1,2])
);
f2[1,2]:=solve(residue(Cancel12,lambda=infinity),f2[1,2]);
f3[1,2]:=solve(residue(Cancel12*lambda,lambda=infinity),f3[1,2])
);

$$fl_{1,2} := -\frac{a12}{t12 - t22} \quad (3.17)$$


$$f2_{1,2} := \frac{1}{(t12 - t22)^2} (-a12 t12 fl_{2,2} + a12 t22 fl_{2,2} - a13 t12 fl_{3,2} + a13 t22 fl_{3,2} + a12 t11 - a12 t21)$$


$$f3_{1,2} := \frac{1}{(t12 - t22)^3} (a12 t11 t12 fl_{2,2} - a12 t11 t22 fl_{2,2} - a12 t12^2 f2_{2,2} - a12 t12 t21 fl_{2,2} + 2 a12 t12 t22 f2_{2,2} + a12 t21 t22 fl_{2,2} - a12 t22^2 f2_{2,2} + a13 t11 t12 fl_{3,2} - a13 t11 t22 fl_{3,2} - a13 t12^2 f2_{3,2} - a13 t12 t21 fl_{3,2} + 2 a13 t12 t22 f2_{3,2} + a13 t21 t22 fl_{3,2} - a13 t22^2 f2_{3,2} + a12 h t12 - a12 h t22 - a12 t11^2 + 2 a12 t11 t21 - a12 t12 t20 + a12 t20 t22 - a12 t21^2)$$

> Cancel13:=series(simplify(series(simplify(ToCancel0[1,3]*exp(-(lambda^2*t32+2*t30*ln(lambda)+2*lambda*t31)/(2*h)),lambda=infinity,10)),lambda=infinity);
f1[1,3]:=solve(residue(Cancel13/lambda,lambda=infinity),f1[1,3])
);
f2[1,3]:=solve(residue(Cancel13,lambda=infinity),f2[1,3]);
f3[1,3]:=solve(residue(Cancel13*lambda,lambda=infinity),f3[1,3])
);
Cancel13 := (-t12 + t32) fl_{1,3} - a13

$$+ \frac{(-t11 + t31) fl_{1,3} + (-t12 + t32) f2_{1,3} - a12 fl_{2,3} - fl_{3,3} a13}{\lambda} \quad (3.18)$$


$$+ \frac{(-h + t30) fl_{1,3} + (-t11 + t31) f2_{1,3} + (-t12 + t32) f3_{1,3} - a12 f2_{2,3} - f2_{3,3} a13}{\lambda^2}$$


$$+ \frac{1}{\lambda^3} ((-2 h + t30) f2_{1,3} + (-t11 + t31) f3_{1,3} + (-t12 + t32) f4_{1,3} - a12 f3_{2,3} - f3_{3,3} a13)$$


$$+ \frac{1}{\lambda^4} ((-t12 + t32) ff5_{1,3} + (-3 h + t30) f3_{1,3} + (-t11 + t31) f4_{1,3} - a12 f4_{2,3} - f4_{3,3} a13) + \frac{(-t11 + t31) ff5_{1,3} + (-4 h + t30) f4_{1,3} - a12 ff5_{2,3} - a13 ff5_{3,3}}{\lambda^5}$$


$$+ O\left(\frac{1}{\lambda^6}\right)$$


$$fl_{1,3} := -\frac{a13}{t12 - t32}$$


```

$$f2_{1,3} := \frac{a12 t12 f1_{2,3} - a12 t32 f1_{2,3} + a13 t12 f1_{3,3} - a13 t32 f1_{3,3} - a13 t11 + a13 t31}{(t12 - t32)^2}$$

$$f3_{1,3} := \frac{1}{(t12 - t32)^3} (a12 t11 t12 f1_{2,3} - a12 t11 t32 f1_{2,3} - a12 t12^2 f2_{2,3} - a12 t12 t31 f1_{2,3} + 2 a12 t12 t32 f2_{2,3} + a12 t31 t32 f1_{2,3} - a12 t32^2 f2_{2,3} + a13 t11 t12 f1_{3,3} - a13 t11 t32 f1_{3,3} - a13 t12^2 f2_{3,3} - a13 t12 t31 f1_{3,3} + 2 a13 t12 t32 f2_{3,3} + a13 t31 t32 f1_{3,3} - a13 t32^2 f2_{3,3} + a13 h t12 - a13 h t32 - a13 t11^2 + 2 a13 t11 t31 - a13 t12 t30 + a13 t30 t32 - a13 t31^2)$$

```

> Cancel21:=series(simplify(series( simplify( ToCancel0[2,1]*exp
(-((-2*t20-2*t30)*ln(lambda)+lambda^2*t12+2*lambda*t11)/(2*h)
)),lambda=infinity,10)),lambda=infinity):
f1[2,1]:=simplify(solve( residue(Cancel21/lambda,lambda=
infinity),f1[2,1]));
f2[2,1]:=simplify(solve( residue(Cancel21,lambda=infinity),f2
[2,1]));
f3[2,1]:=simplify(solve( residue(Cancel21*lambda,lambda=
infinity),f3[2,1]));

```

$$f1_{2,1} := \frac{1}{a12 (t22 - t32)} ((q^2 t32 - p q + q t31 - t20) t22 + (-p q + q t21 + t20) t32 + (p - t31) (p - t21)) \quad (3.19)$$

$$f2_{2,1} := \frac{1}{a12 (-t22 + t32) (t12 - t22)} ((-q (f1_{1,1} + q) p + t32 q^3 + (t32 f1_{1,1} + t31) q^2 + (t31 f1_{1,1} + t30) q - f1_{1,1} t20) t22^2 + ((f1_{1,1} + 2 q) p^2 + (-2 q^2 t32 + ((t12 - t32) f1_{1,1} - 2 t31 - t11 - t21) q + (-t31 - t21) f1_{1,1} - t30) p - t32 (t12 f1_{1,1} - t11 - t21) q^2 + ((-t12 t31 + t21 t32) f1_{1,1} - t30 t32 + t31 (t11 + t21)) q + (t12 t20 + t20 t32 + t21 t31) f1_{1,1} + t21 (t20 + t30) - t11 t20) t22 - p^3 + (q t32 - t12 f1_{1,1} + t11 + t21 + t31) p^2 + (t32 (t12 f1_{1,1} - t11 - t21) q + t12 (t21 + t31) f1_{1,1} + t30 t32 + (-t11 - t31) t21 - t11 t31) p - t21 t32 (t12 f1_{1,1} - t11) q - t12 (t20 t32 + t21 t31) f1_{1,1} + ((-t20 - t30) t21 + t11 t20) t32 + t11 t21 t31)$$

```

> Cancel22:=series(simplify(series( simplify( ToCancel0[2,2]*exp
(-(lambda^2*t22+2*t20*ln(lambda)+2*lambda*t21)/(2*h))
),lambda=infinity,10)),lambda=infinity):
f1[3,2]:=simplify(solve(residue(Cancel22,lambda=infinity),f1[3,
2]));
f2[3,2]:=simplify(solve(residue(Cancel22*lambda,lambda=
infinity),f2[3,2]));
f3[3,2]:=simplify(solve(residue(Cancel22*lambda^2,lambda=
infinity),f3[3,2]));

```

(3.20)

$$f_{l_{3,2}} := -\frac{a_{12}(-q t_{32} + p - t_{31})}{a_{13}(t_{22} - t_{32})} \quad (3.20)$$

$$\begin{aligned} f_{2_{3,2}} := & - \left(a_{12} \left(f_{l_{2,2}} (-q^2 t_{32} + (p - t_{31}) q + h) t_{22}^3 + (q^2 (f_{l_{2,2}} - q) t_{32}^2 \right. \right. \\ & + ((t_{12} f_{l_{2,2}} + 2p - t_{11} + t_{21} - 2t_{31}) q^2 + (-t_{21} f_{l_{2,2}} + t_{31} f_{l_{2,2}} + t_{20}) q \\ & - 2h f_{l_{2,2}}) t_{32} - (-p + t_{31}) (-t_{12} f_{l_{2,2}} - p + t_{11} - t_{21} + t_{31}) q - f_{l_{2,2}} p^2 \\ & + (t_{21} f_{l_{2,2}} + t_{31} f_{l_{2,2}} - t_{20}) p + (-t_{31} f_{l_{2,2}} - t_{20}) t_{21} - h f_{l_{2,2}} t_{12} + t_{20} (t_{11} \\ & + t_{31}) \right) t_{22}^2 + ((t_{12} q^3 + (-t_{12} f_{l_{2,2}} + p + t_{11} - 2t_{21}) q^2 + (-p f_{l_{2,2}} + t_{21} f_{l_{2,2}} \\ & - t_{20}) q + h f_{l_{2,2}}) t_{32}^2 + (2t_{12} (-p + t_{31}) q^2 + (-2p^2 + (2t_{31} + 2t_{21}) p + t_{21}^2 \\ & + (t_{12} f_{l_{2,2}} - t_{11} - 3t_{31}) t_{21} + (-t_{31} f_{l_{2,2}} - t_{20}) t_{12} + t_{11} t_{31}) q + f_{l_{2,2}} p^2 + (-t_{21} f_{l_{2,2}} - t_{31} f_{l_{2,2}} + t_{20}) p + (t_{31} f_{l_{2,2}} + 2t_{20}) t_{21} + 2h f_{l_{2,2}} t_{12} - t_{20} (t_{31} \\ & + 2t_{11}) \right) t_{32} + (-p + t_{31}) (t_{12} (-p + t_{31}) q - p^2 + (-t_{12} f_{l_{2,2}} + t_{11} + t_{31}) p \\ & + t_{21}^2 + (t_{12} f_{l_{2,2}} - t_{11} - t_{31}) t_{21} - t_{20} t_{12}) \right) t_{22} + \left(-(p - t_{21}) t_{12} q^2 \right. \\ & \left. + ((t_{12} f_{l_{2,2}} - t_{11} + t_{21}) p - t_{21}^2 + (-t_{12} f_{l_{2,2}} + t_{11}) t_{21} + t_{20} t_{12}) q \right. \\ & \left. - h f_{l_{2,2}} t_{12} + t_{11} t_{20} - t_{21} t_{20} \right) t_{32}^2 + (-p + t_{31}) (-2(p - t_{21}) t_{12} q + (t_{12} f_{l_{2,2}} \\ & - t_{11} + t_{21}) p - t_{21}^2 + (-t_{12} f_{l_{2,2}} + t_{11}) t_{21} + t_{20} t_{12}) t_{32} - t_{12} (-p + t_{31})^2 (p \\ & \left. - t_{21}) \right) \right) / ((t_{22} - t_{32})^2 (-t_{12} + t_{22}) a_{13} (q t_{22} - p + t_{21})) \end{aligned}$$

```
> Cancel23:=series(simplify(series( simplify( ToCancel0[2,3]*exp
  (- (lambda^2*t32+2*t30*ln(lambda)+2*lambda*t31)/(2*h))
  ),lambda=infinity,10)),lambda=infinity):
f1[2,3]:=simplify(solve( residue(Cancel23/lambda,lambda=
infinity),f1[2,3]));
f2[2,3]:=simplify(solve( residue(Cancel23,lambda=infinity),f2
[2,3]));
f3[2,3]:=simplify(solve( residue(Cancel23*lambda,lambda=
infinity),f3[2,3]));
```

$$f_{l_{2,3}} := \frac{a_{13}(-q t_{22} + p - t_{21})}{a_{12}(t_{22} - t_{32})} \quad (3.21)$$

$$\begin{aligned} f_{2_{2,3}} := & - \frac{1}{a_{12} (-t_{12} + t_{32}) (-t_{22} + t_{32})^2} \left(a_{13} \left((q (f_{l_{3,3}} - q) t_{32} - f_{l_{3,3}} q t_{12} + p q \right. \right. \\ & - q t_{31} + t_{20}) t_{22}^2 + (-t_{32}^2 f_{l_{3,3}} q + (q (f_{l_{3,3}} + q) t_{12} + (-f_{l_{3,3}} + q) p + (-2t_{21} + t_{31}) q + f_{l_{3,3}} t_{21} - t_{20}) t_{32} + ((f_{l_{3,3}} - q) p - f_{l_{3,3}} t_{21} + q t_{21} - t_{20}) t_{12} \right. \\ & \left. \left. - (p - t_{31}) (p - t_{21}) \right) t_{22} + f_{l_{3,3}} (p - t_{21}) t_{32}^2 + (((-f_{l_{3,3}} - q) p + f_{l_{3,3}} t_{21} + q t_{21} + t_{20}) t_{12} + (t_{21} - t_{31}) (p - t_{21}) \right) t_{32} + t_{12} (p - t_{21})^2 \right) \right) \end{aligned}$$

```
> Cancel31:=series(simplify(series( simplify( ToCancel0[3,1]*exp
  (-((-2*t20-2*t30)*ln(lambda)+lambda^2*t12+2*lambda*t11)/(2*h))
  ),lambda=infinity,10)),lambda=infinity):
f1[1,1]:=simplify(solve(simplify(residue(Cancel31,lambda=
infinity)),f1[1,1]));
```

```

f2[1,1]:=simplify(solve(simplify(residue(Cancel31*lambda,
lambda=infinity)),f2[1,1])):
f3[1,1]:=simplify(solve(simplify(residue(Cancel31*lambda^2,
lambda=infinity)),f3[1,1])):

$$f1_{1,1} := \frac{1}{(t12 - t22)(-t12 + t32)h} (p^3 + ((-t12 - t22 - t32)q - t31 - t11 - t21)p^2 + ((t22 + t32)t12 + t22t32)q^2 + (t12(t21 + t31) + t22(t11 + t31) + t32(t11 + t21))q + (t20 + t30)t12 - t20t22 - t30t32 + t11(t21 + t31) + t21t31)p - q^3t12t22t32 + ((-t21t32 - t22t31)t12 - t22t32t11)q^2 + ((-t20t32 - t21t31 - t22t30)t12 + ((t20 + t30)t32 - t11t31)t22 - t32t11t21)q - (t20 + t30)(t31 - t11 + t21)t12 + (-t11t30 + t31(t20 + t30))t22 + (t21(t20 + t30) - t11t20)t32 - t11t21t31) \quad (3.22)$$

> Cancel32:=series(simplify(series(simplify(ToCancel0[3,2]*exp(-(lambda^2*t22+2*t20*ln(lambda)+2*lambda*t21)/(2*h)),
lambda=infinity,10)),lambda=infinity):
f1[2,2]:=solve(simplify(residue(Cancel32,lambda=infinity)),f1[2,2]);
f2[2,2]:=solve(simplify(residue(Cancel32*lambda,lambda=infinity)),f2[2,2]):
f3[2,2]:=solve(simplify(residue(Cancel32*lambda^2,lambda=infinity)),f3[2,2]):

$$f1_{2,2} := \frac{1}{(t12 - t22)(t22 - t32)h} (-q^3t12t22t32 + p q^2 t12t22 + p q^2 t12t32 + p q^2 t22t32 - q^2 t11t22t32 - q^2 t12t21t32 - q^2 t12t22t31 - p^2 q t12 - p^2 q t22 - p^2 q t32 + p q t11t22 + p q t11t32 + p q t12t21 + p q t12t31 + p q t21t32 + p q t22t31 - q t11t21t32 - q t11t22t31 - q t12t20t32 - q t12t21t31 - q t12t22t30 + q t20t22t32 + q t22t30t32 + p^3 - p^2 t11 - p^2 t21 - p^2 t31 + p t11t21 + p t11t31 + p t12t20 + p t12t30 - p t20t22 + p t21t31 - p t30t32 + t11t20t22 - t11t20t32 - t11t21t31 - t12t20t31 - t12t21t30 - t20t21t22 + t20t21t32 + t20t22t31 + t21t30t32) \quad (3.23)$$

> Cancel33:=series(simplify(series(simplify(ToCancel0[3,3]*exp(-(lambda^2*t32+2*t30*ln(lambda)+2*lambda*t31)/(2*h)),
lambda=infinity,10)),lambda=infinity):
f1[3,3]:=solve(simplify(residue(Cancel33*lambda,lambda=infinity)),f1[3,3]);
f2[3,3]:=solve(simplify(residue(Cancel33*lambda^2,lambda=infinity)),f2[3,3]):
f3[3,3]:=solve(simplify(residue(Cancel33*lambda^3,lambda=infinity)),f3[3,3]):

$$f1_{3,3} := -\frac{1}{(t22 - t32)(t12 - t32)h} (-q^3t12t22t32 + p q^2 t12t22 + p q^2 t12t32 + p q^2 t22t32 - q^2 t11t22t32 - q^2 t12t21t32 - q^2 t12t22t31 - p^2 q t12 - p^2 q t22 - p^2 q t32 + p q t11t22 + p q t11t32 + p q t12t21 + p q t12t31 + p q t21t32) \quad (3.24)$$


```

```

+ p q t22 t31 - q t11 t21 t32 - q t11 t22 t31 - q t12 t20 t32 - q t12 t21 t31
- q t12 t22 t30 + q t20 t22 t32 + q t22 t30 t32 + p3 - p2 t11 - p2 t21 - p2 t31
+ p t11 t21 + p t11 t31 + p t12 t20 + p t12 t30 - p t20 t22 + p t21 t31 - p t30 t32
- t11 t21 t31 - t11 t22 t30 + t11 t30 t32 - t12 t20 t31 - t12 t21 t30 + t20 t22 t31
+ t21 t30 t32 + t22 t30 t31 - t30 t31 t32)

> omegaJMU:=simplify(omegaJMU):
> OmegaJMUdt11:=simplify(residue(omegaJMU/dt11^2,dt11=0)):
OmegaJMUdt21:=simplify(residue(omegaJMU/dt21^2,dt21=0)):
OmegaJMUdt31:=simplify(residue(omegaJMU/dt31^2,dt31=0)):

OmegaJMUdt12:=simplify(residue(omegaJMU/dt12^2,dt12=0)):
OmegaJMUdt22:=simplify(residue(omegaJMU/dt22^2,dt22=0)):
OmegaJMUdt32:=simplify(residue(omegaJMU/dt32^2,dt32=0)):

omegaJMUdt11:=1/((t12-t22)*(-t12+t32))*(-p^3+(t11+t21+t31+(t12+
t22+t32)*q)*p^2+((-t22-t32)*t12-t22*t32)*q^2+((-t31-t21)*t12+
(-t11-t31)*t22-t32*(t11+t21))*q+t12*(-t20-t30)+t22*t20+t30*t32+
(-t31-t21)*t11-t21*t31)*p+q^3*t12*t22*t32+((t21*t32+t22*t31)*
t12+t22*t32*t11)*q^2+((t20*t32+t21*t31+t22*t30)*t12+((-t20-t30)
*t32+t11*t31)*t22+t32*t11*t21)*q+(t20+t30)*(t31-t11+t21)*t12+
(t11*t30-t31*(t20+t30))*t22+(t11*t20-t21*(t20+t30))*t32+t11*
t21*t31);

omegaJMUdt21:=1/((t12-t22)*(-t22+t32))*(p^3+((-t12-t22-t32)*q-
t31-t11-t21)*p^2+((t12+t32)*t22+t12*t32)*q^2+(t12*(t21+t31) +
t22*(t11+t31)+t32*(t11+t21))*q-t22*t20-t30*t32+(t20+t30)*t12+
(t11+t31)*t21+t11*t31)*p-q^3*t12*t22*t32+((-t11*t32-t12*t31)*
t22-t32*t12*t21)*q^2+((t20+t30)*t32-t11*t31-t12*t30)*t22+(-
t11*t21-t12*t20)*t32-t12*t21*t31)*q+t20*(t31+t11-t21)*t22+(t21*
(t20+t30)-t11*t20)*t32+(-t20*t31-t21*t30)*t12-t11*t21*t31);

omegaJMUdt31:=1/((-t22+t32)*(-t12+t32))*(p^3+((-t12-t22-t32)*q-
t31-t11-t21)*p^2+((t12+t22)*t32+t12*t22)*q^2+(t12*(t21+t31) +
t22*(t11+t31)+t32*(t11+t21))*q-t30*t32-t22*t20+(t20+t30)*t12+
t31*(t11+t21)+t11*t21)*p-q^3*t12*t22*t32+((-t11*t22-t12*t21)*
t32-t31*t12*t22)*q^2+((t20+t30)*t22-t11*t21-t12*t20)*t32+(-
t11*t31-t12*t30)*t22-t12*t21*t31)*q-t30*(t31-t11-t21)*t32+(-
t11*t30+t31*(t20+t30))*t22+(-t20*t31-t21*t30)*t12-t11*t21*t31);

omegaJMUdt12:=1/(2*(t12-t22)^2*(-t12+t32)^2)*(-(t20+t30)^2*
t12^3+(-q^3*(t31-2*t11+t21)*t32+2*q*((-p+t31)*q+t30)*t11-(t21+

```

$t31) * (-p+t31) * q^2 - t30 * (t21+t31) * q + (t20+2*t30) * (t20+t30) * t22 +$
 $(-2*q*((p-t21)*q-t20)*t11+(p-t21)*(t21+t31)*q^2-t20*(t21+t31)*$
 $q+2*t20^2+3*t30*t20+t30^2)*t32+(-t20-t30)*t11^2+(-(2*(p-t21))*$
 $(-p+t31)*q+(2*(t20+t30))*(t31-p+t21))*t11+(p-t21)*(t21+t31)*(-$
 $p+t31)*q-(t20+t30)*((-t31-t21)*p+t31^2+t21*t31+t21^2))*t12^2+$
 $(q^3*(-t11+t31)*t32-q*((-p+t31)*q+t30)*t11+t31*(-p+t31)*q^2+$
 $t31*t30*q-t30*(t20+t30))*t22^2+(-q^3*(t11-t21)*t32^2+(2*q^2*$
 $t11^2-2*q*((t21+t31)*q+3*t20*(1/2)+3*t30*(1/2))*t11+2*q^2*t21*$
 $t31+((t20+2*t30)*t21+2*t31*(t20+(1/2)*t30))*q-2*(t20+t30)^2)*$
 $t32+((2*t31-2*p)*q+2*t30)*t11^2+(-(-p+t31)*(t31+2*t21+p)*q+$
 $(t30+3*t20)*p-t21*t30-(3*(t20+4*t30*(1/3)))*t31)*t11+(-p^2*t21+$
 $t21*t31^2)*q+(-t21*t20-2*t31*(t20+(1/2)*t30))*p+(2*(t20+t30))*$
 $t31*((1/2)*t21+t31))*t22+(q*((p-t21)*q-t20)*t11-(p-t21)*t21*$
 $q^2+t21*t20*q-t20*(t20+t30))*t32^2+(((2*p+2*t21)*q+2*t20)*$
 $t11^2+((2*(p-t21))*((1/2)*p+t31+(1/2)*t21)*q+(t20+3*t30)*p+(-4*$
 $t20-3*t30)*t21-t31*t20)*t11+(-p^2*t31+t21^2*t31)*q+((-t20-2*$
 $t30)*t21-t31*t30)*p+t21*(t20+t30)*(t31+2*t21))*t32-(p-t21)*(p-$
 $t11)*(t31-2*t11+t21)*(-p+t31))*t12+((-q^2*t11^2+q*((t31+p)*q+$
 $t20+t30)*t11-q^2*p*t31-(t20+t30)*t31*q+t30*(t20+t30))*t32-(-$
 $t11+t31)*(((p-t31)*q-t30)*t11+p*(-p+t31)*q-p*t20+t31*(t20+t30))$
 $)*t22^2+((-q^2*t11^2+((p+t21)*q+t20+t30)*q*t11-q^2*p*t21-t21*$
 $(t20+t30)*q+t20*(t20+t30))*t32^2+(-q*((t31-2*p+t21)*t11^2+((-2*$
 $p^2+2*t21*t31)*q+(-t20-t30)*p+t31*t20+t21*t30)*t11+((t21+t31)*$
 $p-2*t21*t31)*p*q+(t20*t21+t30*t31)*p-t31*t21*(t20+t30))*t32+(p-$
 $t11)*(-t11+t31)*(-p+t31)*(p-t21))*t22-((((p+t21)*q+t20)*t11+p*$
 $(p-t21)*q+p*t30-t21*(t20+t30))*t32+(p-t21)*(p-t11)*(-p+t31))*$
 $(t11-t21)*t32);$

$\text{omegaJMUdt22} := 1 / (2*(t12-t22)^2*(-t22+t32)^2)*(-t20^2*t22^3+(-$
 $q^3*(t31+t11-2*t21)*t12-2*q*((p-t11)*q+t20+t30)*t21+(p-t11)*$
 $(t11+t31)*q^2+(t20+t30)*(t11+t31)*q+2*t20^2+t30*t20)*t32+(2*q*(($
 $-p+t31)*q+t30)*t21-(t11+t31)*(-p+t31)*q^2-t30*(t11+t31)*q+t20*$
 $(t20-t30))*t12+t20*t21^2+(-(2*(p-t11))*(-p+t31)*q-2*t20*(t31-p+$
 $t11))*t21+(p-t11)*(t11+t31)*(-p+t31)*q+t20*((-t11-t31)*p+t31^2+$
 $t11*t31+t11^2))*t22^2+((q^3*(t11-t21)*t12+q*((p-t11)*q+t20+t30)$
 $*t21-(p-t11)*t11*q^2-t11*(t20+t30)*q-t20*(t20+t30))*t32^2+(q^3*$
 $(-t21+t31)*t12^2+(2*q^2*t21^2-2*((t11+t31)*q-3*t20*(1/2)))*q*$
 $t21+2*q^2*t11*t31+(t11*(-t20+t30)-2*t31*(t20+(1/2)*t30))*q-2*$
 $t20^2)*t12+((-2*p+2*t11)*q-2*t20-2*t30)*t21^2+((2*((1/2)*p+t31+$
 $(1/2)*t11))*(-p-t11)*q+(2*t30-t20)*p+(t30+4*t20)*t11+t31*(t20+$
 $t30))*t21+(-p^2*t31+t11^2*t31)*q+((t20-t30)*t11-t31*t30)*p-t11*$
 $t20*(t31+2*t11))*t32+(-q*((-p+t31)*q+t30)*t21+t31*(-p+t31)*q^2+$

```

t31*t30*q+t30*t20)*t12^2+((2*t31-2*p)*q+2*t30)*t21^2+(-(-p+
t31)*(t31+2*t11+p)*q+(-2*t30-3*t20)*p-t11*t30+3*t31*(t20-(1/3)*
t30))*t21+(-p^2*t11+t11*t31^2)*q+((t20+t30)*t11+2*t31*(t20+
(1/2)*t30))*p-(2*(t31+(1/2)*t11))*t31*t20)*t12-(p-t21)*(p-t11)*
(t31+t11-2*t21)*(-p+t31))*t22+((-q^2*t21^2+((p+t11)*q-t20)*q*
t21-q^2*p*t11+t20*t11*q+t20*(t20+t30))*t12+(t11-t21)*((( -p+t11)
*q-t20-t30)*t21+p*(p-t11)*q+p*t30+t11*t20))*t32^2+((-q^2*t21^2+
q*((t31+p)*q-t20)*t21-q^2*p*t31+t31*t20*q-t30*t20)*t12^2+(-q*
(-2*p+t31+t11)*t21^2+((-2*p^2+2*t11*t31)*q+p*t20+t11*t30-t31*
(t20+t30))*t21+((t11+t31)*p-2*t11*t31)*p*q+((-t20-t30)*t11+t31*
t30)*p+t31*t11*t20)*t12+(t11-t21)*(p-t21)*(p-t11)*(-p+t31))*t
32+t12*(((-p+t31)*q+t30)*t21-p*(-p+t31)*q+(-t20-t30)*p+t31*t20)*t12+(p-t21)*(p-t11)*(-p+t31)*(-t21+t31));

```

omegaJMUdt32:=

$$1 / (2 * (-t12+t32)^2 * (-t22+t32)^2) * (-t30^2 * t32^3 + (2 * q^3 * (t31 - (1/2) * t11 - (1/2) * t21) * t12 - 2 * q * ((p-t11) * q + t20 + t30) * t31 + (t11 + t21) * (p-t11) * q^2 + (t20 + t30) * (t11 + t21) * q + t30 * (t20 + 2 * t30)) * t22 - 2 * q * ((p-t21) * q - t20) * t31 + (t11 + t21) * (p-t21) * q^2 - t20 * (t11 + t21) * q - t30 * (t20 - t30)) * t12 + t30 * t31^2 + (2 * (p-t21)) * (p-t11) * q + 2 * t30 * (p-t11 - t21) * t31 - (t11 + t21) * (p-t21) * (p-t11) * q - t30 * ((t11 + t21) * p - t11^2 - t11 * t21 - t21^2)) * t32^2 + (-q^3 * (-t11 + t31) * t12 + q * ((p-t11) * q + t20 + t30) * t31 - (p-t11) * t11 * q^2 - t11 * (t20 + t30) * q - t30 * (t20 + t30)) * t22^2 + (-q^3 * (-t21 + t31) * t12 + 2 * q^2 * t31^2 - 2 * q * ((t11 + t21) * q - 3 * t30 * (1/2)) * t31 + 2 * q^2 * t11 * t21 + ((t20 - t30) * t11 - (t20 + 2 * t30) * t21) * q - 2 * t30^2) * t12 + ((-2 * p + 2 * t11) * q - 2 * t20 - 2 * t30) * t31^2 + ((p-t11) * (p + t11 + 2 * t21) * q + (-t30 + 2 * t20) * p + t11 * (4 * t30 + t20) + t21 * (t20 + t30)) * t31 + (-p^2 * t21 + t11^2 * t21) * q + (t11 * (-t20 + t30) - t21 * t20) * p - (2 * (t11 + (1/2) * t21)) * t11 * t30) * t22 + (q * ((p-t21) * q - t20) * t31 - (p-t21) * t21 * q^2 + t21 * t20 * q + t30 * t20) * t12 + 2 * ((-2 * p + 2 * t21) * q + 2 * t20) * t31^2 + ((p-t21) * (p + 2 * t11 + t21) * q + (-2 * t20 - 3 * t30) * p - t11 * t20 - t21 * (t20 - 3 * t30)) * t31 + (-p^2 * t11 + t11^2 * t21) * q + ((t20 + t30) * t11 + (t20 + 2 * t30) * t21) * p - t30 * t21 * (t11 + 2 * t21)) * t12 + (2 * (t31 - (1/2) * t11 - (1/2) * t21)) * (-p + t31) * (p - t21) * (p - t11) * t32 + ((-q^2 * t31^2 + q * ((p + t11) * q - t30) * t31 - q^2 * p * t11 + t30 * t11 * q + t30 * (t20 + t30)) * t12 + (-t11 + t31) * (((p - t11) * q + t20 + t30) * t31 - p * (p - t11) * q - p * t20 - t11 * t30)) * t22^2 + ((-q^2 * t31^2 + q * ((p + t21) * q - t30) * t31 - q^2 * p * t21 + t30 * t21 * q - t30 * t20) * t12 + 2 * q * (p - (1/2) * t11 - (1/2) * t21) * t31 + 2 * ((-2 * p^2 + 2 * t11 * t21) * q + p * t30 + t11 * t20 - t21 * (t20 + t30)) * t31 + ((t11 + t21) * p - 2 * t11 * t21) * p * q + ((-t20 - t30) * t11 + t21 * t20) * p + t21 * t11 * t30) * t12 - (p - t11) * (-t11 + t31) * (-p + t31) * (p - t21) * t22 - t12 * ((((-p + t21) * q + t20) * t31 + p * (p - t21) * q + (-t20 - t30) * p + t21 * t30) * t12 + (p - t21) * (p - t11) * (-p + t31)) * (-t21 + t31));$$

```

simplify(OmegaJMUdt11-omegaJMUdt11);
simplify(OmegaJMUdt21-omegaJMUdt21);
simplify(OmegaJMUdt31-omegaJMUdt31);
simplify(OmegaJMUdt12-omegaJMUdt12);
simplify(OmegaJMUdt22-omegaJMUdt22);
simplify(OmegaJMUdt32-omegaJMUdt32);

omegaJMUdt11 := 
$$\frac{1}{(t12 - t22)(-t12 + t32)} (-p^3 + (t11 + t21 + t31 + (t12 + t22 + t32)q)p^2 + (((-t22 - t32)t12 - t22t32)q^2 + ((-t31 - t21)t12 + (-t11 - t31)t22 - t32(t11 + t21))q + t12(-t20 - t30) + t20t22 + t30t32 + (-t31 - t21)t11 - t21t31)p + q^3t12t22t32 + ((t21t32 + t22t31)t12 + t22t32t11)q^2 + ((t20t32 + t21t31 + t22t30)t12 + ((-t20 - t30)t32 + t11t31)t22 + t32t11t21)q + (t20 + t30)(t31 - t11 + t21)t12 + (t11t30 - t31(t20 + t30))t22 + (t11t20 - t21(t20 + t30))t32 + t11t21t31)$$
 (3.25)

omegaJMUdt21 := 
$$\frac{1}{(t12 - t22)(-t22 + t32)} (p^3 + ((-t12 - t22 - t32)q - t31 - t11 - t21)p^2 + (((t12 + t32)t22 + t12t32)q^2 + (t12(t21 + t31) + t22(t11 + t31) + t32(t11 + t21))q - t20t22 - t30t32 + (t20 + t30)t12 + (t11 + t31)t21 + t11t31)p - q^3t12t22t32 + ((-t11t32 - t12t31)t22 - t12t21t32)q^2 + (((t20 + t30)t32 - t11t31 - t12t30)t22 + (-t11t21 - t12t20)t32 - t12t21t31)q + t20(t31 + t11 - t21)t22 + (t21(t20 + t30) - t11t20)t32 + (-t20t31 - t21t30)t12 - t11t21t31)$$


omegaJMUdt31 := 
$$\frac{1}{(-t22 + t32)(-t12 + t32)} (p^3 + ((-t12 - t22 - t32)q - t31 - t11 - t21)p^2 + (((t12 + t22)t32 + t12t22)q^2 + (t12(t21 + t31) + t22(t11 + t31) + t32(t11 + t21))q - t30t32 - t20t22 + (t20 + t30)t12 + t31(t11 + t21) + t11t21)p - q^3t12t22t32 + ((-t11t22 - t12t21)t32 - t31t12t22)q^2 + (((t20 + t30)t22 - t11t21 - t20t12)t32 + (-t11t31 - t12t30)t22 - t12t21t31)q - t30(t31 - t11 - t21)t32 + (-t11t30 + t31(t20 + t30))t22 + (-t20t31 - t21t30)t12 - t11t21t31)$$


omegaJMUdt12 := 
$$\frac{1}{2} \frac{1}{(t12 - t22)^2(-t12 + t32)^2} \left( -(t20 + t30)^2t12^3 + ((-q^3(t31 - 2t11 + t21)t32 + 2q((-p + t31)q + t30)t11 - (t21 + t31)(-p + t31)q^2 - t30(t21 + t31)q + (t20 + 2t30)(t20 + t30))t22 + (-2q((p - t21)q - t20)t11 + (t21 + t31)(p - t21)q^2 - (t21 + t31)t20q + 2t20^2 + 3t30t20 + t30^2)t32 + (-t20 - t30)t11^2 + (-2(p - t21)(-p + t31)q + 2(t20 + t30)(t31 - p + t21))t11 + (p - t21)(t21 + t31)(-p + t31)q - (t20 + t30)((-t31 - t21)p + t31^2 + t21t31 + t21^2))t12^2 + \left( (q^3(-t11 + t31)t32 - q((-p + t31)q + t30)t11 + t31(-p + t31)q^2 + t31t30q - t30(t20 + t30))t22^2 + (-q^3(t11 - t21)t32^2\right)\right)$$


```

$$\begin{aligned}
& + \left(2 t11^2 q^2 - 2 q \left((t21 + t31) q + \frac{3}{2} t20 + \frac{3}{2} t30 \right) t11 + 2 q^2 t21 t31 + \left((t20 \right. \right. \\
& + 2 t30) t21 + 2 t31 \left(t20 + \frac{1}{2} t30 \right) \left. \right) q - 2 (t20 + t30)^2 \left. \right) t32 + ((2 t31 - 2 p) q \\
& + 2 t30) t11^2 + \left(-(-p + t31) (p + 2 t21 + t31) q + (t30 + 3 t20) p - t21 t30 \right. \\
& - 3 t31 \left(t20 + \frac{4}{3} t30 \right) \left. \right) t11 + (-p^2 t21 + t21 t31^2) q + \left(-t21 t20 - 2 t31 \left(t20 \right. \right. \\
& + \frac{1}{2} t30) \left. \right) p + 2 (t20 + t30) t31 \left(t31 + \frac{1}{2} t21 \right) \left. \right) t22 + (q ((p - t21) q - t20) t11 \\
& - (p - t21) t21 q^2 + t21 t20 q - t20 (t20 + t30)) t32^2 + \left(((-2 p + 2 t21) q \right. \\
& + 2 t20) t11^2 + \left(2 (p - t21) \left(\frac{1}{2} p + t31 + \frac{1}{2} t21 \right) q + (t20 + 3 t30) p + (-4 t20 \right. \\
& - 3 t30) t21 - t31 t20 \left. \right) t11 + (-p^2 t31 + t21^2 t31) q + ((-t20 - 2 t30) t21 \\
& - t31 t30) p + t21 (t20 + t30) (t31 + 2 t21) \left. \right) t32 - (p - t21) (p - t11) (t31 - 2 t11 \\
& + t21) (-p + t31) \left. \right) t12 + ((-t11^2 q^2 + q ((p + t31) q + t20 + t30) t11 - t31 q^2 p \\
& - t31 (t20 + t30) q + t30 (t20 + t30)) t32 - (-t11 + t31) ((p - t31) q - t30) t11 \\
& + p (-p + t31) q - t20 p + t31 (t20 + t30)) t22^2 + ((-t11^2 q^2 + q ((p + t21) q \\
& + t20 + t30) t11 - t21 q^2 p - t21 (t20 + t30) q + t20 (t20 + t30)) t32^2 + (-q (t31 \\
& - 2 p + t21) t11^2 + ((-2 p^2 + 2 t21 t31) q + (-t20 - t30) p + t31 t20 + t21 t30) t11 \\
& + ((t21 + t31) p - 2 t21 t31) p q + (t20 t21 + t30 t31) p - t21 t31 (t20 + t30)) t32 \\
& + (p - t11) (-t11 + t31) (-p + t31) (p - t21) t22 - ((((-p + t21) q + t20) t11 \\
& + p (p - t21) q + p t30 - t21 (t20 + t30)) t32 + (p - t21) (p - t11) (-p + t31)) \\
& (t11 - t21) t32) \\
\omega_{JMU dt22} := & \frac{1}{2} \frac{1}{(t12 - t22)^2 (-t22 + t32)^2} \left(-t20^2 t22^3 + ((-q^3 (t11 - 2 t21 \right. \\
& + t31) t12 - 2 ((p - t11) q + t20 + t30) q t21 + (t11 + t31) (p - t11) q^2 + (t20 \\
& + t30) (t11 + t31) q + 2 t20^2 + t30 t20) t32 + (2 q ((-p + t31) q + t30) t21 - (t11 \\
& + t31) (-p + t31) q^2 - t30 (t11 + t31) q + t20 (t20 - t30)) t12 + t20 t21^2 + (-2 (p \\
& - t11) (-p + t31) q - 2 t20 (t31 - p + t11)) t21 + (p - t11) (t11 + t31) (-p \\
& + t31) q + t20 ((-t11 - t31) p + t31^2 + t11 t31 + t11^2)) t22^2 + \left((q^3 (t11 - t21) t12 \right. \\
& + ((p - t11) q + t20 + t30) q t21 - t11 (p - t11) q^2 - t11 (t20 + t30) q - t20 (t20 \\
& + t30)) t32^2 + \left(q^3 (-t21 + t31) t12^2 + \left(2 t21^2 q^2 - 2 q ((t11 + t31) q \right. \right. \\
& - \frac{3}{2} t20 \left. \right) t21 + 2 t31 t11 q^2 + \left(t11 (-t20 + t30) - 2 t31 \left(t20 + \frac{1}{2} t30 \right) \right) q
\end{aligned}$$

$$\begin{aligned}
& -2 t20^2 \Big) t12 + ((-2 p + 2 t11) q - 2 t20 - 2 t30) t21^2 + \left(2 \left(\frac{1}{2} p + t31 \right. \right. \\
& \left. \left. + \frac{1}{2} t11 \right) (p - t11) q + (2 t30 - t20) p + (t30 + 4 t20) t11 + t31 (t20 + t30) \right) t21 \\
& + (-p^2 t31 + t11^2 t31) q + ((t20 - t30) t11 - t31 t30) p - t11 t20 (t31 + 2 t11) \Big) t32 \\
& + (-q ((-p + t31) q + t30) t21 + t31 (-p + t31) q^2 + t31 t30 q + t30 t20) t12^2 \\
& + \left(((2 t31 - 2 p) q + 2 t30) t21^2 + \left(-(-p + t31) (p + 2 t11 + t31) q + (-2 t30 \right. \right. \\
& \left. \left. - 3 t20) p - t11 t30 + 3 t31 \left(t20 - \frac{1}{3} t30 \right) \right) t21 + (-p^2 t11 + t11 t31^2) q + \left((t20 \right. \right. \\
& \left. \left. + t30) t11 + 2 t31 \left(t20 + \frac{1}{2} t30 \right) \right) p - 2 t20 t31 \left(t31 + \frac{1}{2} t11 \right) \Big) t12 - (p \\
& - t21) (p - t11) (t11 - 2 t21 + t31) (-p + t31) \Big) t22 + ((-t21^2 q^2 + q ((p + t11) q \\
& - t20) t21 - t11 q^2 p + t20 t11 q + t20 (t20 + t30)) t12 + (((-p + t11) q - t20 \\
& - t30) t21 + p (p - t11) q + p t30 + t11 t20) (t11 - t21) \Big) t32^2 + ((-t21^2 q^2 + ((p \\
& + t31) q - t20) q t21 - t31 q^2 p + t31 t20 q - t30 t20) t12^2 + (-q (-2 p + t31 \\
& + t11) t21^2 + ((-2 p^2 + 2 t11 t31) q + t20 p + t11 t30 - t31 (t20 + t30)) t21 \\
& + p ((t11 + t31) p - 2 t11 t31) q + ((-t20 - t30) t11 + t31 t30) p + t31 t11 t20) t12 \\
& + (t11 - t21) (p - t21) (p - t11) (-p + t31) \Big) t32 + t12 ((((-p + t31) q + t30) t21 \\
& - p (-p + t31) q + (-t20 - t30) p + t31 t20) t12 + (p - t21) (p - t11) (-p \\
& + t31)) (-t21 + t31)) \\
omegaJMUdt32 := & \frac{1}{2} \frac{1}{(-t12 + t32)^2 (-t22 + t32)^2} \left(-t32^3 t30^2 + \left(\left(2 q^3 \left(t31 - \frac{1}{2} t11 \right. \right. \right. \right. \\
& \left. \left. \left. \left. - \frac{1}{2} t21 \right) t12 - 2 ((p - t11) q + t20 + t30) q t31 + (t11 + t21) (p - t11) q^2 + (t20 \right. \right. \\
& \left. \left. + t30) (t11 + t21) q + t30 (t20 + 2 t30) \right) t22 + (-2 q ((p - t21) q - t20) t31 \right. \right. \\
& \left. \left. + (t11 + t21) (p - t21) q^2 - t20 (t11 + t21) q - t30 (t20 - t30) \right) t12 + t31^2 t30 \right. \right. \\
& \left. \left. + (2 (p - t21) (p - t11) q + 2 t30 (p - t11 - t21)) t31 - (t11 + t21) (p - t21) (p \right. \right. \\
& \left. \left. - t11) q - ((t11 + t21) p - t11^2 - t11 t21 - t21^2) t30 \right) t32^2 + \left((-q^3 (-t11 \right. \right. \\
& \left. \left. + t31) t12 + ((p - t11) q + t20 + t30) q t31 - t11 (p - t11) q^2 - t11 (t20 + t30) q \right. \right. \\
& \left. \left. - t30 (t20 + t30) \right) t22^2 + (-q^3 (-t21 + t31) t12^2 + \left(2 t31^2 q^2 - 2 q \left((t11 + t21) q \right. \right. \right. \right. \\
& \left. \left. \left. \left. - \frac{3}{2} t30 \right) t31 + 2 t21 t11 q^2 + ((t20 - t30) t11 - (t20 + 2 t30) t21) q - 2 t30^2 \right) t12 \right. \right. \\
& \left. \left. + ((-2 p + 2 t11) q - 2 t20 - 2 t30) t31^2 + ((p - t11) (p + 2 t21 + t11) q + (-t30 \right. \right. \\
& \left. \left. + 2 t20) p + t11 (t20 + 4 t30) + t21 (t20 + t30)) t31 + (-p^2 t21 + t11^2 t21) q \right. \right. \\
\end{aligned}$$

$$\begin{aligned}
& + (t11 (-t20 + t30) - t21 t20) p - 2 t30 t11 \left(t11 + \frac{1}{2} t21 \right) t22 + (q ((p - t21) q \\
& - t20) t31 - (p - t21) t21 q^2 + t21 t20 q + t30 t20) t12^2 + ((-2 p + 2 t21) q \\
& + 2 t20) t31^2 + ((p - t21) (p + 2 t11 + t21) q + (-2 t20 - 3 t30) p - t11 t20 \\
& - t21 (t20 - 3 t30)) t31 + (-p^2 t11 + t11 t21^2) q + ((t20 + t30) t11 + (t20 \\
& + 2 t30) t21 (t11 + 2 t21)) t12 + 2 (p - t21) \left(t31 - \frac{1}{2} t11 \right. \\
& \left. - \frac{1}{2} t21 \right) (p - t11) (-p + t31) t32 + ((-t31^2 q^2 + q ((p + t11) q - t30) t31 \\
& - t11 q^2 p + t30 t11 q + t30 (t20 + t30)) t12 + (-t11 + t31) (((p - t11) q + t20 \\
& + t30) t31 - p (p - t11) q - t20 p - t11 t30) t22^2 + ((-t31^2 q^2 + ((p + t21) q \\
& - t30) q t31 - t21 q^2 p + t30 t21 q - t30 t20) t12^2 + \left(2 q \left(p - \frac{1}{2} t11 - \frac{1}{2} t21 \right) t31^2 \right. \\
& \left. + ((-2 p^2 + 2 t11 t21) q + p t30 + t11 t20 - t21 (t20 + t30)) t31 + p ((t11 + t21) p \\
& - 2 t11 t21) q + ((-t20 - t30) t11 + t21 t20) p + t21 t11 t30) t12 - (p - t11) (-t11 \\
& + t31) (-p + t31) (p - t21) t22 - t12 ((((-p + t21) q + t20) t31 + p (p - t21) q \\
& + (-t20 - t30) p + t21 t30) t12 + (p - t21) (p - t11) (-p + t31) (-t21 + t31)) \\
& 0 \\
& 0 \\
& 0 \\
& 0 \\
& 0 \\
& 0 \\
& > \text{simplify}(\text{Trace}(2 * \text{F2} - \text{F1}^2));
\end{aligned}$$

(3.26)

▼ Computation of the general auxiliary matrix \td{A} and of the Hamiltonian evolutions for (q,p)

The evolutions relatively to the irregular times are denoted dott12, dott22, dott32, dott11, dott21, dott31

```

> tdA:=Matrix(3,3,0):
tdA[1,1]:=tdA112*lambda^2+tdA111*lambda+tdA110:
tdA[1,2]:=tdA122*lambda^2+tdA121*lambda+tdA120:
tdA[1,3]:=tdA132*lambda^2+tdA131*lambda+tdA130:
tdA[2,1]:=tdA212*lambda^2+tdA211*lambda+tdA210:
tdA[2,2]:=tdA222*lambda^2+tdA221*lambda+tdA220:
tdA[2,3]:=tdA232*lambda^2+tdA231*lambda+tdA230:
tdA[3,1]:=tdA312*lambda^2+tdA311*lambda+tdA310:
tdA[3,2]:=tdA322*lambda^2+tdA321*lambda+tdA320:
tdA[3,3]:=tdA332*lambda^2+tdA331*lambda+tdA330:

```

```

tdA;

tdAdt:=Matrix(3,3,0):
tdAdt[1,1]:=tdAdt112*lambda^2+tdAdt111*lambda+tdAdt110:
tdAdt[1,2]:=tdAdt122*lambda^2+tdAdt121*lambda+tdAdt120:
tdAdt[1,3]:=tdAdt132*lambda^2+tdAdt131*lambda+tdAdt130:
tdAdt[2,1]:=tdAdt212*lambda^2+tdAdt211*lambda+tdAdt210:
tdAdt[2,2]:=tdAdt222*lambda^2+tdAdt221*lambda+tdAdt220:
tdAdt[2,3]:=tdAdt232*lambda^2+tdAdt231*lambda+tdAdt230:
tdAdt[3,1]:=tdAdt312*lambda^2+tdAdt311*lambda+tdAdt310:
tdAdt[3,2]:=tdAdt322*lambda^2+tdAdt321*lambda+tdAdt320:
tdAdt[3,3]:=tdAdt332*lambda^2+tdAdt331*lambda+tdAdt330:
tdAdt;

tdAdlambda:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do tdAdlambda[i,j]:=diff
(tdA[i,j],lambda): od: od:
tdAdlambda;

Anew:=simplify(Multiply(Multiply(Gnormalized,tdA),Gnormalized^
(-1))+Multiply(IGnormalized,Gnormalized^(-1))):

$$\begin{bmatrix} [\lambda^2 tdA112 + \lambda tdA111 + tdA110, \lambda^2 tdA122 + \lambda tdA121 + tdA120, \lambda^2 tdA132 + \lambda tdA131 \\ + tdA130], \\ [\lambda^2 tdA212 + \lambda tdA211 + tdA210, \lambda^2 tdA222 + \lambda tdA221 + tdA220, \lambda^2 tdA232 \\ + \lambda tdA231 + tdA230], \\ [\lambda^2 tdA312 + \lambda tdA311 + tdA310, \lambda^2 tdA322 + \lambda tdA321 + tdA320, \lambda^2 tdA332 \\ + \lambda tdA331 + tdA330] ] \quad (4.1)$$


$$\begin{bmatrix} [\lambda^2 tdAdt112 + \lambda tdAdt111 + tdAdt110, \lambda^2 tdAdt122 + \lambda tdAdt121 + tdAdt120, \lambda^2 tdAdt132 \\ + \lambda tdAdt131 + tdAdt130], \\ [\lambda^2 tdAdt212 + \lambda tdAdt211 + tdAdt210, \lambda^2 tdAdt222 + \lambda tdAdt221 + tdAdt220, \lambda^2 tdAdt232 \\ + \lambda tdAdt231 + tdAdt230], \\ [\lambda^2 tdAdt312 + \lambda tdAdt311 + tdAdt310, \lambda^2 tdAdt322 + \lambda tdAdt321 + tdAdt320, \lambda^2 tdAdt332 \\ + \lambda tdAdt331 + tdAdt330] ]$$


$$\begin{bmatrix} 2\lambda tdA112 + tdA111 & 2\lambda tdA122 + tdA121 & 2\lambda tdA132 + tdA131 \\ 2\lambda tdA212 + tdA211 & 2\lambda tdA222 + tdA221 & 2\lambda tdA232 + tdA231 \\ 2\lambda tdA312 + tdA311 & 2\lambda tdA322 + tdA321 & 2\lambda tdA332 + tdA331 \end{bmatrix}$$

> dtdLdt:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do dtdLdt[i,j]:=diff(tdL
[i,j],t12)*dott12+diff(tdL[i,j],t22)*dott22+ diff(tdL[i,j],t32)

```

```

*dott32+diff(tdL[i,j],a12)*dota12+diff(tdL[i,j],a13)*dota13
+diff(tdL[i,j],q)*dotq+ diff(tdL[i,j],p)*dotp
+diff(tdL[i,j],t11)*dott11+ diff(tdL[i,j],t21)*dott21+diff(tdL
[i,j],t31)*dott31: od: od:
dtdLdt:
Compatibilite:=simplify(h*tdAdlambda-h*dtdLdt+Multiply(tdA,tdL)
-Multiply(tdL,tdA));

```

Solving the compatibility equations to obtain \td{A} and the general evolutions for (q,p)

```

> residue(Compatibilite[1,1]*(lambda-q),lambda=q);
residue(Compatibilite[1,1],lambda=q);
factor(residue(Compatibilite[1,1]/lambda^4,lambda=infinity));
Eq1:= factor(residue(Compatibilite[1,1]/lambda^3,lambda=
infinity));
Eq2:= factor(residue(Compatibilite[1,1]/lambda^2,lambda=
infinity));
Eq3:= factor(residue(Compatibilite[1,1]/lambda^1,lambda=
infinity));
0
0
0

```

(4.2)

```

> residue(Compatibilite[1,2]*(lambda-q),lambda=q);
residue(Compatibilite[1,2],lambda=q);
factor(residue(Compatibilite[1,2]/lambda^5,lambda=infinity));
tdA122:=0;
factor(residue(Compatibilite[1,2]/lambda^4,lambda=infinity));
Eq4:= factor(residue(Compatibilite[1,2]/lambda^3,lambda=
infinity));
Eq5:= factor(residue(Compatibilite[1,2]/lambda^2,lambda=
infinity));
Eq6:= factor(residue(Compatibilite[1,2]/lambda^1,lambda=
infinity));
0
0
0

```

(4.3)

$$Eq4 := -\frac{1}{a13} (a12 q t32 tdA132 + a12 a13 tdA112 - a12 a13 tdA222 - a12 p tdA132 + a12 t31 tdA132 - a13^2 tdA322 - a13 t12 tdA121 + a13 t22 tdA121)$$

$$Eq5 := -\frac{1}{a13} (a12 q t32 tdA131 + a12 a13 tdA111 - a12 a13 tdA221 - a12 p tdA131 + a12 t31 tdA131 - a13^2 tdA321 - a13 t11 tdA121 - a13 t12 tdA120 + a13 t21 tdA121 + a13 t22 tdA120)$$

$$\begin{aligned}
Eq6 := & -\frac{1}{a13} (a12 q t32 tdA130 + a12 a13 tdA110 - a12 a13 tdA220 - a12 p tdA130 \\
& + a12 t31 tdA130 - a13^2 tdA320 - a13 dota12 h + a13 h tdA121 - a13 t11 tdA120 \\
& + a13 t21 tdA120) \\
> residue(Compatibilite[1,3]*(lambda-q), lambda=q); \\
& residue(Compatibilite[1,3], lambda=q); \\
& factor(residue(Compatibilite[1,3]/lambda^5, lambda=infinity)); \\
tdA132:=0; \\
& factor(residue(Compatibilite[1,3]/lambda^4, lambda=infinity)); \\
Eq7:= & factor(residue(Compatibilite[1,3]/lambda^3, lambda= \\
& infinity)); \\
Eq8:= & factor(residue(Compatibilite[1,3]/lambda^2, lambda= \\
& infinity)); \\
Eq9:= & factor(residue(Compatibilite[1,3]/lambda^1, lambda= \\
& infinity));
\end{aligned}
\tag{4.4}$$

$$\begin{aligned}
& 0 \\
& 0 \\
& 0 \\
tdA132:=0 & \\
& 0 \\
Eq7 := & a12 tdA232 - a13 tdA112 + a13 tdA332 + t12 tdA131 - t32 tdA131 \\
Eq8 := & \frac{1}{a12} (-a13 q t22 tdA121 + a12^2 tdA231 - a12 a13 tdA111 + a12 a13 tdA331 \\
& + a12 t11 tdA131 + a12 t12 tdA130 - a12 t31 tdA131 - a12 t32 tdA130 \\
& + a13 p tdA121 - a13 t21 tdA121) \\
Eq9 := & \frac{1}{a12} (-a13 q t22 tdA120 + a12^2 tdA230 - a12 a13 tdA110 + a12 a13 tdA330 \\
& + a12 dota13 h - a12 h tdA131 + a12 t11 tdA130 - a12 t31 tdA130 + a13 p tdA120 \\
& - a13 t21 tdA120) \\
> residue(Compatibilite[2,1]*(lambda-q), lambda=q); \\
& residue(Compatibilite[2,1], lambda=q); \\
& factor(residue(Compatibilite[2,1]/lambda^5, lambda=infinity)); \\
tdA212:=0; \\
& factor(residue(Compatibilite[2,1]/lambda^4, lambda=infinity)); \\
Eq10:= & factor(residue(Compatibilite[2,1]/lambda^3, lambda= \\
& infinity)); \\
Eq11:= & factor(residue(Compatibilite[2,1]/lambda^2, lambda= \\
& infinity)); \\
Eq12:= & factor(residue(Compatibilite[2,1]/lambda^1, lambda= \\
& infinity));
\end{aligned}
\tag{4.5}$$

```

> residue(Compatibilite[2,2]*(lambda-q),lambda=q);
residue(Compatibilite[2,2],lambda=q);
factor(residue(Compatibilite[2,2]/lambda^5,lambda=infinity));
factor(residue(Compatibilite[2,2]/lambda^4,lambda=infinity));
Eq13:= factor(residue(Compatibilite[2,2]/lambda^3,lambda=
infinity));
Eq14:= factor(residue(Compatibilite[2,2]/lambda^2,lambda=
infinity));
Eq15:= factor(residue(Compatibilite[2,2]/lambda^1,lambda=
infinity));

```

$$\begin{aligned}
& 0 \\
& 0 \\
& 0 \\
& 0
\end{aligned} \tag{4.6}$$

$$\begin{aligned}
Eq13 := & \frac{1}{a13 a12} (-a12^2 q t32 tdA232 + a13^2 q t22 tdA322 + a12^2 p tdA232 \\
& - a12^2 t31 tdA232 - a13^2 p tdA322 + a13^2 t21 tdA322)
\end{aligned}$$

$$\begin{aligned}
Eq14 := & -\frac{1}{a12 (t22 - t32) a13} (-a13 q^2 t12 t22 t32 tdA121 + a13 q^2 t22^2 t32 tdA121 \\
& + a12^2 q t22 t32 tdA231 - a12^2 q t32^2 tdA231 - a13^2 q t22^2 tdA321 \\
& + a13^2 q t22 t32 tdA321 + a13 p q t12 t22 tdA121 + a13 p q t12 t32 tdA121 \\
& - a13 p q t22^2 tdA121 - a13 p q t22 t32 tdA121 - a13 q t12 t21 t32 tdA121 \\
& - a13 q t12 t22 t31 tdA121 + a13 q t21 t22 t32 tdA121 + a13 q t22^2 t31 tdA121 \\
& + a12^2 a13 t22 tdA211 - a12^2 a13 t32 tdA211 - a12^2 p t22 tdA231 + a12^2 p t32 tdA231 \\
& + a12^2 t22 t31 tdA231 - a12^2 t31 t32 tdA231 - a12 a13 dott22 h t22 \\
& + a12 a13 dott22 h t32 + 2 a12 a13 h t22 tdA222 - 2 a12 a13 h t32 tdA222 \\
& + a13^2 p t22 tdA321 - a13^2 p t32 tdA321 - a13^2 t21 t22 tdA321 + a13^2 t21 t32 tdA321 \\
& - a13 p^2 t12 tdA121 + a13 p^2 t22 tdA121 + a13 p t12 t21 tdA121 \\
& + a13 p t12 t31 tdA121 - a13 p t21 t22 tdA121 - a13 p t22 t31 tdA121 \\
& + a13 t12 t20 t22 tdA121 - a13 t12 t20 t32 tdA121 - a13 t12 t21 t31 tdA121 \\
& - a13 t20 t22^2 tdA121 + a13 t20 t22 t32 tdA121 + a13 t21 t22 t31 tdA121)
\end{aligned}$$

$$\begin{aligned}
Eq15 := & -\frac{1}{a12 (t22 - t32) a13} (-a13 q^2 t12 t22 t32 tdA120 + a13 q^2 t22^2 t32 tdA120 \\
& + a12^2 q t22 t32 tdA230 - a12^2 q t32^2 tdA230 - a13^2 q t22^2 tdA320 \\
& + a13^2 q t22 t32 tdA320 + a13 p q t12 t22 tdA120 + a13 p q t12 t32 tdA120 \\
& - a13 p q t22^2 tdA120 - a13 p q t22 t32 tdA120 - a13 q t12 t21 t32 tdA120 \\
& - a13 q t12 t22 t31 tdA120 + a13 q t21 t22 t32 tdA120 + a13 q t22^2 t31 tdA120 \\
& + a12^2 a13 t22 tdA210 - a12^2 a13 t32 tdA210 - a12^2 p t22 tdA230 + a12^2 p t32 tdA230 \\
& + a12^2 t22 t31 tdA230 - a12^2 t31 t32 tdA230 - a12 a13 dott21 h t22 \\
& + a12 a13 dott21 h t32 + a12 a13 h t22 tdA221 - a12 a13 h t32 tdA221 \\
& + a13^2 p t22 tdA320 - a13^2 p t32 tdA320 - a13^2 t21 t22 tdA320 + a13^2 t21 t32 tdA320 \\
& - a13 p^2 t12 tdA120 + a13 p^2 t22 tdA120 + a13 p t12 t21 tdA120 \\
& + a13 p t12 t31 tdA120 - a13 p t21 t22 tdA120 - a13 p t22 t31 tdA120 \\
& + a13 t12 t20 t22 tdA120 - a13 t12 t20 t32 tdA120 - a13 t12 t21 t31 tdA120
\end{aligned}$$

```

    - a13 t20 t222 tdA120 + a13 t20 t22 t32 tdA120 + a13 t21 t22 t31 tdA120)
> residue(Compatibilite[2,3]*(lambda-q),lambda=q);
residue(Compatibilite[2,3],lambda=q);
factor(residue(Compatibilite[2,3]/lambda^5,lambda=infinity));
tdA232:=0;
factor(residue(Compatibilite[2,3]/lambda^4,lambda=infinity));
Eq16:= factor(residue(Compatibilite[2,3]/lambda^3,lambda=
infinity));
Eq17:= factor(residue(Compatibilite[2,3]/lambda^2,lambda=
infinity));
Eq18:= factor(residue(Compatibilite[2,3]/lambda^1,lambda=
infinity));
0
0
0
tdA232 := 0
0

```

(4.7)

$$Eq16 := \frac{1}{a12} (-a13 q t22 tdA222 + a13 q t22 tdA332 + a12 t22 tdA231 - a12 t32 tdA231 + a13 p tdA222 - a13 p tdA332 - a13 t21 tdA222 + a13 t21 tdA332)$$

```

> residue(Compatibilite[3,1]*(lambda-q),lambda=q);
residue(Compatibilite[3,1],lambda=q);
factor(residue(Compatibilite[3,1]/lambda^5,lambda=infinity));
tdA312:=0;
factor(residue(Compatibilite[3,1]/lambda^4,lambda=infinity));
Eq19:= factor(residue(Compatibilite[3,1]/lambda^3,lambda=
infinity));
Eq20:= factor(residue(Compatibilite[3,1]/lambda^2,lambda=
infinity));
Eq21:= factor(residue(Compatibilite[3,1]/lambda^1,lambda=
infinity));
0
0
0
tdA312 := 0
0

```

(4.8)

```

> residue(Compatibilite[3,2]*(lambda-q),lambda=q);
residue(Compatibilite[3,2],lambda=q);
factor(residue(Compatibilite[3,2]/lambda^5,lambda=infinity));
tdA322:=0;
factor(residue(Compatibilite[3,2]/lambda^4,lambda=infinity));
Eq22:= factor(residue(Compatibilite[3,2]/lambda^3,lambda=
infinity));
Eq23:= factor(residue(Compatibilite[3,2]/lambda^2,lambda=

```

```

infinity));
Eq24:= factor(residue(Compatibilite[3,2]/lambda^1,lambda=
infinity));
0
0
0
tdA322 := 0
0

```

(4.9)

```

Eq22 := -  $\frac{1}{a13}$  (-a12 q t32 tdA222 + a12 q t32 tdA332 + a12 p tdA222 - a12 p tdA332
- a12 t31 tdA222 + a12 t31 tdA332 + a13 t22 tdA321 - a13 t32 tdA321)
> residue(Compatibilite[3,3]*(lambda-q),lambda=q);
residue(Compatibilite[3,3],lambda=q);
factor(residue(Compatibilite[3,3]/lambda^5,lambda=infinity));

factor(residue(Compatibilite[3,3]/lambda^4,lambda=infinity));
factor(residue(Compatibilite[3,3]/lambda^3,lambda=infinity));
Eq25:= factor(residue(Compatibilite[3,3]/lambda^2,lambda=
infinity));
Eq26:= factor(residue(Compatibilite[3,3]/lambda^1,lambda=
infinity));

```

```

0
0
0
0
0

```

(4.10)

```

Eq25 := -  $\frac{1}{a12 (t22 - t32) a13}$  (a12 q2 t12 t22 t32 tdA131 - a12 q2 t22 t322 tdA131
- a122 q t22 t32 tdA231 + a122 q t322 tdA231 - a12 p q t12 t22 tdA131
- a12 p q t12 t32 tdA131 + a12 p q t22 t32 tdA131 + a12 p q t322 tdA131
+ a12 q t12 t21 t32 tdA131 + a12 q t12 t22 t31 tdA131 - a12 q t21 t322 tdA131
- a12 q t22 t31 t32 tdA131 + a132 q t222 tdA321 - a132 q t22 t32 tdA321
+ a122 p t22 tdA231 - a122 p t32 tdA231 - a122 t22 t31 tdA231 + a122 t31 t32 tdA231
+ a12 a132 t22 tdA311 - a12 a132 t32 tdA311 - a12 a13 dott32 h t22
+ a12 a13 dott32 h t32 + 2 a12 a13 h t22 tdA332 - 2 a12 a13 h t32 tdA332
+ a12 p2 t12 tdA131 - a12 p2 t32 tdA131 - a12 p t12 t21 tdA131
- a12 p t12 t31 tdA131 + a12 p t21 t32 tdA131 + a12 p t31 t32 tdA131
+ a12 t12 t21 t31 tdA131 + a12 t12 t22 t30 tdA131 - a12 t12 t30 t32 tdA131
- a12 t21 t31 t32 tdA131 - a12 t22 t30 t32 tdA131 + a12 t30 t322 tdA131
- a132 p t22 tdA321 + a132 p t32 tdA321 + a132 t21 t22 tdA321 - a132 t21 t32 tdA321)

```

```

Eq26 := -  $\frac{1}{a12 (t22 - t32) a13}$  (a12 q2 t12 t22 t32 tdA130 - a12 q2 t22 t322 tdA130
- a122 q t22 t32 tdA230 + a122 q t322 tdA230 - a12 p q t12 t22 tdA130
- a12 p q t12 t32 tdA130 + a12 p q t22 t32 tdA130 + a12 p q t322 tdA130
+ a12 q t12 t21 t32 tdA130 + a12 q t12 t22 t31 tdA130 - a12 q t21 t322 tdA130

```

```


$$\begin{aligned}
& -a12 q t22 t31 t32 tdA130 + a13^2 q t22^2 tdA320 - a13^2 q t22 t32 tdA320 \\
& + a12^2 p t22 tdA230 - a12^2 p t32 tdA230 - a12^2 t22 t31 tdA230 + a12^2 t31 t32 tdA230 \\
& + a12 a13^2 t22 tdA310 - a12 a13^2 t32 tdA310 - a12 a13 dott31 h t22 \\
& + a12 a13 dott31 h t32 + a12 a13 h t22 tdA331 - a12 a13 h t32 tdA331 \\
& + a12 p^2 t12 tdA130 - a12 p^2 t32 tdA130 - a12 p t12 t21 tdA130 \\
& - a12 p t12 t31 tdA130 + a12 p t21 t32 tdA130 + a12 p t31 t32 tdA130 \\
& + a12 t12 t21 t31 tdA130 + a12 t12 t22 t30 tdA130 - a12 t12 t30 t32 tdA130 \\
& - a12 t21 t31 t32 tdA130 - a12 t22 t30 t32 tdA130 + a12 t30 t32^2 tdA130 \\
& - a13^2 p t22 tdA320 + a13^2 p t32 tdA320 + a13^2 t21 t22 tdA320 - a13^2 t21 t32 tdA320
\end{aligned}$$


```

> Eq1:=simplify(Eq1) :

Eq2:=simplify(Eq2) :

Eq3:=simplify(Eq3) :

Eq4:=simplify(Eq4) :

Eq5:=simplify(Eq5) :

Eq6:=simplify(Eq6) :

Eq7:=simplify(Eq7) :

Eq8:=simplify(Eq8) :

Eq9:=simplify(Eq9) :

Eq10:=simplify(Eq10) :

Eq11:=simplify(Eq11) :

Eq12:=simplify(Eq12) :

Eq13:=simplify(Eq13) :

Eq14:=simplify(Eq14) :

Eq15:=simplify(Eq15) :

Eq16:=simplify(Eq16) :

Eq17:=simplify(Eq17) :

Eq18:=simplify(Eq18) :

Eq19:=simplify(Eq19) :

Eq20:=simplify(Eq20) :

Eq21:=simplify(Eq21) :

Eq22:=simplify(Eq22) :

Eq23:=simplify(Eq23) :

Eq24:=simplify(Eq24) :

Eq25:=simplify(Eq25) :

Eq26:=simplify(Eq26) :

> tdA131:=a13*(tdA112-tdA332)/(t12-t32) :

simplify(Eq7) ;

tdA130:=-(-q*a13*t12*t22*tdA121+q*a13*t22*t32*tdA121+p*a13*t12*
 tdA121-p*a13*t32*tdA121+a12^2*t12*tdA231-a12^2*t32*tdA231-a12*
 a13*t12*tdA111+a12*a13*t12*tdA331+a12*a13*t32*tdA111-a12*a13*
 t32*tdA331+a12*a13*t11*tdA112-a12*a13*t11*tdA332-a12*a13*t31*
 tdA112+a12*a13*t31*tdA332-a13*t12*t21*tdA121+a13*t32*t21*

```

tdA121)/((t12-t32)^2*a12) :
simplify(Eq8);
tdA321:=-(-q*a12*t32*tdA112+q*a12*t32*tdA332+p*a12*tdA112-p*
a12*tdA332-a12*t12*tdA111+a12*t12*tdA221+a12*t32*tdA111-a12*
t32*tdA221-a12*t31*tdA112+a12*t31*tdA332+t12^2*tdA120-t12*t22*
tdA120-t12*t32*tdA120+t12*t11*tdA121-t12*t21*tdA121+t22*t32*
tdA120-t32*t11*tdA121+t32*t21*tdA121)/((t12-t32)*a13) :
simplify(Eq5);
0
0
0

```

(4.11)

```

> tdA121:=a12*(tdA112-tdA222)/(t12-t22) :
simplify(Eq4);
tdA320:=(((tdA110-tdA220)*t12^3+((q*(tdA111-tdA331)-2*
tdA110+2*tdA220)*t32+(-tdA110+tdA220)*t22+(-tdA111+tdA331)*p+
(tdA111-tdA331)*t31+h*(tdA112-tdA222))*t12^2+(((tdA111+tdA331)-
q+tdA110-tdA220)*t32^2+(((tdA112-tdA222)*q^2+(-tdA111+tdA331)*
q+2*tdA110-2*tdA220)*t22+((-tdA112+tdA222)*q+tdA111-tdA331)*p+(*
tdA112-tdA332)*t31+(-t11+t21)*tdA112-tdA222*t21+tdA332*t11)*q+
(-tdA111+tdA331)*t31-2*h*(tdA112-tdA222))*t32+(((tdA112+
tdA222)*q+tdA111-tdA331)*t22+(tdA112-tdA222)*p+(-tdA112+tdA332)-
*t31+(t11-t21)*tdA112+tdA222*t21-tdA332*t11)*(p-t31))*t12+(((tdA112+
tdA222)*q^2+q*(tdA111-tdA331)-tdA110+tdA220)*t22+(tdA112-
tdA222)*(p*q-q*t21+h))*t32^2+(((tdA112-tdA222)*q-tdA111+
tdA331)*p+((-2*tdA112+tdA222+tdA332)*t31+t11*(tdA112-tdA332))*q+
(tdA111-tdA331)*t31)*t22-((tdA112-tdA222)*(p-t31)*(p-t21))*t32+
t22*(tdA112-tdA332)*(-t11+t31)*(p-t31)*a12+(t12-t32)^2*
(t12-t22)*(-dota12*h-t11*tdA120+t21*tdA120))*a13+tdA231*a12^2*
(t12-t32)*(t12-t22)*(-q*t32+p-t31))/((t12-t22)*(t12-t32)^2*
a13^2) :
simplify(Eq6);

```

```

tdA211:=((-q^2*(tdA222-tdA332)*t32+(p*q-q*t31+t20)*tdA222+(-p*
q+q*t31+t30)*tdA332+(-t30+2*h-t20)*tdA112-dott12*h-tdA311*a13)*
t22+((p*q-q*t21-t20)*tdA222+(-p*q+q*t21-t30)*tdA332+(t30-2*h+
t20)*tdA112+dott12*h+tdA311*a13)*t32-((tdA222-tdA332)*(p-t21)-
(p-t31))/((t22-t32)*a12) :
simplify(Eq2);
0
0
0

```

(4.12)

```

> tdA210:=(-tdA310*(t22-t32)*a13^2*(t12-t22)*(t12-t32)*a12+(((tdA112+
tdA222)*q+tdA111-tdA331)*q^2*t32-((-tdA112+tdA222)*q+
tdA111-tdA331)*q*p-t31*(tdA112-tdA222)*q^2+((tdA111-tdA331)*t31

```

$$\begin{aligned}
& -t30*(tdA112-tdA222))*q+t30*(tdA111-tdA331)+h*(dott11-tdA111))* \\
& t12-((-tdA112+tdA222)*q+tdA111-tdA331)*q^2*t32^2+((-tdA112+ \\
& tdA222)*q+tdA111-tdA331)*q*p+((2*tdA112-tdA222-tdA332)*t31-t11* \\
& (tdA112-tdA332))*q^2+((-tdA111+tdA331)*t31+t30*(tdA112-tdA222)) \\
& *q+(-tdA111+tdA331)*t30-h*(dott11-tdA111))*t32-(tdA112-tdA332)* \\
& (-t11+t31)*(p*q-q*t31-t30))*t22^2+((-q^2*(tdA111-tdA331)*t32+q* \\
& (tdA111-tdA331)*p-t31*(tdA111-tdA331)*q+(-tdA111+tdA331)*t30-h* \\
& (dott11-tdA111))*t12^2+(q^2*(tdA111-tdA331)*t32^2-2*q*((- \\
& tdA112+tdA222)*q+tdA111-tdA331)*p+((1/2)*tdA112-(1/2)*tdA332)* \\
& t31+(tdA112-tdA222)*t21-(1/2)*t11*(tdA112-tdA332))*q+(-(1/2)* \\
& tdA111+(1/2)*tdA331)*t31+(-(1/2)*tdA111+(1/2)*tdA331)*t21-(1/2) \\
& *t30*(tdA112-tdA222))*t32+((-2*tdA112+2*tdA222)*q+tdA111- \\
& tdA331)*p^2+((3*tdA112-2*tdA222-tdA332)*t31+(2*tdA112-2* \\
& tdA222)*t21-t11*(tdA112-tdA332))*q+(-tdA111+tdA331)*t31+(- \\
& tdA111+tdA331)*t21+t30*(tdA112-tdA222))*p-2*t31*((1/2)*tdA112- \\
& (1/2)*tdA332)*t31+(tdA112-tdA222)*t21-(1/2)*t11*(tdA112-tdA332) \\
&)*q+((tdA111-tdA331)*t21-t30*(tdA112-tdA332))*t31-t30*((tdA112- \\
& tdA222)*t21-t11*(tdA112-tdA332)))*t12+(q*((-2*tdA112+2*tdA222)* \\
& q+tdA111-tdA331)*p+(2*(tdA112-tdA222))*t21*q^2+((-tdA111+ \\
& tdA331)*t21-t30*(tdA112-tdA222))*q+t30*(tdA111-tdA331)+h* \\
& (dott11-tdA111))*t32^2+(((2*tdA112-2*tdA222)*q-tdA111+tdA331)* \\
& p^2+((-3*tdA112+2*tdA222+tdA332)*t31+(-2*tdA112+2*tdA222)*t21+ \\
& t11*(tdA112-tdA332))*q+(tdA111-tdA331)*t31+(tdA111-tdA331)*t21- \\
& t30*(tdA112-tdA222))*p+3*t21*((tdA112-2*tdA222*(1/3)-(1/3)* \\
& tdA332)*t31-(1/3)*t11*(tdA112-tdA332))*q+((-tdA111+tdA331)*t21- \\
& t30*(tdA112-tdA332))*t31+t30*((tdA112-tdA222)*t21+t11*(tdA112- \\
& tdA332))*t32+(tdA112-tdA332)*(-t11+t31)*(p-t31)*(p-t21))*t22+ \\
& ((q*(tdA111-tdA331)*p-t21*(tdA111-tdA331)*q+t30*(tdA111-tdA331)+ \\
& h*(dott11-tdA111))*t32-(tdA111-tdA331)*(p-t31)*(p-t21))*t12^2+ \\
& ((-q*(tdA111-tdA331)*p+t21*(tdA111-tdA331)*q+(-tdA111+tdA331)* \\
& t30-h*(dott11-tdA111))*t32^2+(((tdA112-2*tdA222)*q+tdA111- \\
& tdA331)*p^2+(((tdA112-tdA332)*t31+(2*tdA112-2*tdA222)*t21-t11* \\
& (tdA112-tdA332))*q+(-tdA111+tdA331)*t31+(-tdA111+tdA331)*t21- \\
& t30*(tdA112-tdA222))*p-((tdA112-tdA332)*t31+(tdA112-tdA222)*t21- \\
& t11*(tdA112-tdA332))*t21*q+((tdA111-tdA331)*t21+t30*(tdA112- \\
& tdA332))*t31+t30*((tdA112-tdA222)*t21-t11*(tdA112-tdA332)))* \\
& t32+(p-t21)*(p-t31)*((tdA112-tdA222)*p+(-tdA112+tdA332)*t31+(- \\
& tdA112+tdA222)*t21+t11*(tdA112-tdA332))*t12-(tdA112-tdA222)* \\
& ((-p*q+q*t21-t30)*t32+(p-t31)*(p-t21))*(p-t21)*t32*a12+((q^2* \\
& t32-p*q+q*t31-t20)*t22+(-p*q+q*t21+t20)*t32+(p-t31)*(p-t21))* \\
& (t12-t32)*(t12-t22)^2*tdA120)*a13+tdA231*a12^2*(t12-t32)*(t12- \\
& t22)*((q^2*t32-p*q+q*t31+t30)*t22+(-p*q+q*t21-t30))*t32+(p-t31)*
\end{aligned}$$

```

(p-t21)))/(a12^2*(t12-t22)*(t12-t32)*a13*(t22-t32)) :
simplify(Eq3);
simplify(Eq1);
0
0
(4.13)

> tdA230:=(((tdA110-tdA330)*t12^3+((-2*tdA110+2*tdA330)*t32+(-
tdA110+tdA330)*t22+(-tdA111+tdA331)*t11+(tdA111-tdA331)*t31+h*
(tdA112-tdA332))*t12^2+((tdA110-tdA330)*t32^2+((2*tdA110-2*
tdA330)*t22+(tdA111-tdA331)*t11+(-tdA111+tdA331)*t31-h*(tdA112-
tdA332))*t32+((-q*tdA112+q*tdA222+tdA111-tdA331)*t11+(q*tdA112-
q*tdA222-tdA111+tdA331)*t31-h*(tdA112-tdA332))*t22-(t11*(tdA112-
tdA332)+(-tdA112+tdA332)*t31+(tdA112-tdA222)*(p-t21))*(-t11+
t31))*t12-t22*(tdA110-tdA330)*t32^2+(((q*tdA112-q*tdA222-
tdA111+tdA331)*t11+(-q*tdA112+q*tdA222+tdA111-tdA331)*t31+h*
(tdA112-tdA332))*t22+(tdA112-tdA222)*(-t11+t31)*(p-t21))*t32-
t22*(-t11+t31)^2*(tdA112-tdA332))*a12-tdA120*(t12-t32)^2*(t12-
t22)*(-q*t22+p-t21))*a13-(t12-t32)*a12*(tdA231*(-t11+t31)*a12+
dota13*h*(t12-t32))*(t12-t22))/((t12-t22)*(t12-t32)^2*a12^2):
simplify(Eq9);

tdA311:=((-q^2*t32+p*q-q*t31+2*h-t30)*t22+(p*q-q*t21-2*h+t30)*
t32-(p-t31)*(p-t21))*tdA112+((q^2*t32-p*q+q*t31+t30)*t22+(-p*q+
q*t21-t30)*t32+(p-t31)*(p-t21))*tdA332-dott12*h*(t22-t32))/
(a13*(t22-t32)):
simplify(Eq10);

tdA231:=- (tdA222-tdA332)*(-q*t22+p-t21)*a13/(a12*(t22-t32)):
simplify(Eq16);

tdA112:=(1/2)*dott12:
simplify(Eq19);

tdA120:=- (((q*dott12-2*q*tdA222-2*tdA111+2*tdA221)*t12+(-q*
dott12+2*q*tdA222+2*tdA111-2*tdA221)*t22+(t11-t21)*(dott12-2*
tdA222))*t32^2+((2*q*tdA222-2*q*tdA332+2*tdA111-2*tdA221)*
t12^2+(-q*(dott12+2*tdA222-4*tdA332)*t22-(dott12-2*tdA222)*(p-
t31+t11-t21))*t12+((q*dott12-2*q*tdA332-2*tdA111+2*tdA221)*t22+
(dott12-2*tdA222)*(p-t31-t11+t21))*t22)*t32+((-2*tdA111+2*
tdA221)*t22-(2*(tdA222-tdA332)*(p-t31))*t12^2+((2*tdA111-2*
tdA221)*t22+(p-t31+t11-t21)*dott12+(2*p-2*t31-2*t11+2*t21)*
tdA222-4*tdA332*(p-t31))*t22*t12-t22^2*(dott12-2*tdA332)*(p-
t31))*a12)/(2*(t12-t22)^2*(t12-t32)*(t22-t32)):
simplify(Eq22);

tdA332:=(1/2)*dott32:
simplify(Eq25);

tdA222:=(1/2)*dott22:
simplify(Eq14);

```

```

tdA220:=simplify(solve(simplify(Eq23),tdA220)):
simplify(Eq23);
tdA310:=factor(solve(simplify(Eq20),tdA310)):
simplify(Eq20);
tdA111:=dott11:
simplify(Eq11);
tdA330:=factor(solve(simplify(Eq17),tdA330)):
simplify(Eq17);
tdA331:=dott31:
simplify(Eq26);
tdA221:=dott21:
simplify(Eq15);

```

(4.14)

0
0
0
0
0
0
0
0
0
0
0
0
0
0
0
0

```

> Eq1:=simplify(Eq1);
Eq2:=simplify(Eq2);
Eq3:=simplify(Eq3);
Eq4:=simplify(Eq4);
Eq5:=simplify(Eq5);
Eq6:=simplify(Eq6);
Eq7:=simplify(Eq7);
Eq8:=simplify(Eq8);
Eq9:=simplify(Eq9);
Eq10:=simplify(Eq10);
Eq11:=simplify(Eq11);

Eq13:=simplify(Eq13);
Eq14:=simplify(Eq14);
Eq15:=simplify(Eq15);
Eq16:=simplify(Eq16);
Eq17:=simplify(Eq17);

Eq19:=simplify(Eq19);
Eq20:=simplify(Eq20);

```

```

Eq22:=simplify(Eq22);
Eq23:=simplify(Eq23);

Eq25:=simplify(Eq25);
Eq26:=simplify(Eq26);
Eq1 := 0
Eq2 := 0
Eq3 := 0
Eq4 := 0
Eq5 := 0
Eq6 := 0
Eq7 := 0
Eq8 := 0
Eq9 := 0
Eq10 := 0
Eq11 := 0
Eq13 := 0
Eq14 := 0
Eq15 := 0
Eq16 := 0
Eq17 := 0
Eq19 := 0
Eq20 := 0
Eq22 := 0
Eq23 := 0
Eq25 := 0
Eq26 := 0
> Eq12:=simplify(Eq12):
Eq18:=simplify(Eq18):
Eq21:=simplify(Eq21):
Eq24:=simplify(Eq24):

```

There are only 4 remaining non trivial equations. Solving the first two gives the evolutions for (q,p) and we check that these evolutions are Hamiltonian

```

> dotq:=factor(solve(simplify(Eq12),dotq)):
simplify(Eq12);
dotp:=solve(simplify(Eq18),dotp):
simplify(Eq18);
simplify(Eq21);
simplify(Eq24);
dotq:=factor(simplify(dotq)):
0
0
0
0
> H:=unapply( int(h*dotq,p),q,p):
f:=unapply( factor(-simplify(int(simplify(diff(H(q,p),q)+h*
dotp),q))), q):

```

```

Hamiltonian:=unapply(simplify(H(q,p)+f(q)),q,p):
simplify(diff(Hamiltonian(q,p),p)-h*dotq);
simplify(diff(Hamiltonian(q,p),q)+h*dotp);
0
0
(4.17)

> dotqfunction:=unapply(dotq,t12,t22,t32,t11,t21,t31,dott12,
dott22,dott32,dott11,dott21,dott31):
dotpfunction:=unapply(dotp,t12,t22,t32,t11,t21,t31,dott12,
dott22,dott32,dott11,dott21,dott31):
P1function:=unapply(P1(lambda),lambda,t12,t22,t32,t11,t21,t31):
dP1function:=unapply(dP1(lambda),lambda,t12,t22,t32,t11,t21,
t31,dott12,dott22,dott32,dott11,dott21,dott31):

```

Expression of the Hamiltonian evolutions in the trivial directions

```

> factor(h*dotqfunction(t12,t22,t32,t11,t21,t31,0,0,0,1,1,1));
factor(h*dotpfunction(t12,t22,t32,t11,t21,t31,0,0,0,1,1,1));
Hamv1:=(q,p)->-h*q;
simplify(h*dotqfunction(t12,t22,t32,t11,t21,t31,0,0,0,1,1,1)-
diff(Hamv1(q,p),p));
simplify(h*dotpfunction(t12,t22,t32,t11,t21,t31,0,0,0,1,1,1)-
diff(Hamv1(q,p),q));
0
h
Hamv1 := (q, p) → - h q
0
0
(5.1)

```

```

> factor(h*dotqfunction(t12,t22,t32,t11,t21,t31,1,1,1,0,0,0));
factor(h*dotpfunction(t12,t22,t32,t11,t21,t31,1,1,1,0,0,0));
Hamv2:=(q,p)->-h*q^2/2;
simplify(h*dotqfunction(t12,t22,t32,t11,t21,t31,1,1,1,0,0,0)-
diff(Hamv2(q,p),p));
simplify(h*dotpfunction(t12,t22,t32,t11,t21,t31,1,1,1,0,0,0)-
diff(Hamv2(q,p),q));
0
h q
Hamv2 := (q, p) → -  $\frac{1}{2}$  h q2
0
0
(5.2)

```

```

> simplify(h*dotqfunction(t12,t22,t32,t11,t21,t31,0,0,0,t12,t22,
t32));
simplify(h*dotpfunction(t12,t22,t32,t11,t21,t31,0,0,0,t12,t22,

```

```

t32));
Hamu1:=(q,p) ->-h*p;
simplify(h*dotqfunction(t12,t22,t32,t11,t21,t31,0,0,0,t12,t22,
t32)- diff(Hamu1(q,p),p));
simplify(h*dotpfunction(t12,t22,t32,t11,t21,t31,0,0,0,t12,t22,
t32)+ diff(Hamu1(q,p),q));

$$Hamu1 := \begin{pmatrix} -h \\ 0 \\ 0 \end{pmatrix} \quad (5.3)$$


```

```

> simplify(h*dotqfunction(t12,t22,t32,t11,t21,t31,2*t12,2*t22,2*
t32,t11,t21,t31));
simplify(h*dotpfunction(t12,t22,t32,t11,t21,t31,2*t12,2*t22,2*
t32,t11,t21,t31));
Hamu2:=(q,p) ->-h*q*p;
simplify(h*dotqfunction(t12,t22,t32,t11,t21,t31,2*t12,2*t22,2*
t32,t11,t21,t31)- diff(Hamu2(q,p),p));
simplify(h*dotpfunction(t12,t22,t32,t11,t21,t31,2*t12,2*t22,2*
t32,t11,t21,t31)+ diff(Hamu2(q,p),q));

$$Hamu2 := \begin{pmatrix} -h q \\ p h \\ 0 \\ 0 \end{pmatrix} \quad (5.4)$$


```

```

> simplify(h*dotqfunction(t12,t22,t32,t11,t21,t31,2*(t12-t32)*
(t12-t22),0,0,t12*(3*t11-t21-t31)-(t12+t22+t32)*t11+ t22*t31+
t32*t21,0,0));
simplify(h*dotpfunction(t12,t22,t32,t11,t21,t31,2*(t12-t32)*
(t12-t22),0,0,t12*(3*t11-t21-t31)-(t12+t22+t32)*t11+ t22*t31+
t32*t21,0,0));
Hama1:=(q,p) ->h*( (t22+t32)*q*p-p^2+(t21+t31)*p -t32*t22*q^2 -
(t22*t31+t32*t21)*q);
simplify(h*dotqfunction(t12,t22,t32,t11,t21,t31,2*(t12-t32)*
(t12-t22),0,0,t12*(3*t11-t21-t31)-(t12+t22+t32)*t11+ t22*t31+
t32*t21,0,0)- diff(Hama1(q,p),p));
simplify(h*dotpfunction(t12,t22,t32,t11,t21,t31,2*(t12-t32)*
(t12-t22),0,0,t12*(3*t11-t21-t31)-(t12+t22+t32)*t11+ t22*t31+
t32*t21,0,0)+ diff(Hama1(q,p),q));

$$Hama1 := \begin{pmatrix} (t22 + t32) h q - (-t31 + 2 p - t21) h \\ -h ((-2 q t32 + p - t31) t22 + t32 (p - t21)) \\ 0 \\ 0 \end{pmatrix} \quad (5.5)$$


```

```

Hama1 := (q,p) ->h ((t22 + t32) q p - p^2 + (t21 + t31) p - t32 t22 q^2 - (t21 t32
+ t22 t31) q)

$$\begin{pmatrix} 0 \\ 0 \end{pmatrix}$$


```

```

> simplify(h*dotqfunction(t12,t22,t32,t11,t21,t31,0,2*(t22-t12)*
  (t22-t32),0,0,t22*(3*t21-t11-t31)-(t12+t22+t32)*t21+t12*t31+
  t32*t11,0));
simplify(h*dotpfunction(t12,t22,t32,t11,t21,t31,0,2*(t22-t12)*
  (t22-t32),0,0,t22*(3*t21-t11-t31)-(t12+t22+t32)*t21+t12*t31+
  t32*t11,0));
Hama2:=(q,p)->h*( (t12+t32)*q*p-p^2+(t11+t31)*p -t32*t12*q^2 -
  (t12*t31+t32*t11)*q);
simplify(h*dotqfunction(t12,t22,t32,t11,t21,t31,0,2*(t22-t12)*
  (t22-t32),0,0,t22*(3*t21-t11-t31)-(t12+t22+t32)*t21+t12*t31+
  t32*t11,0)- diff(Hama2(q,p),p));
simplify(h*dotpfunction(t12,t22,t32,t11,t21,t31,0,2*(t22-t12)*
  (t22-t32),0,0,t22*(3*t21-t11-t31)-(t12+t22+t32)*t21+t12*t31+
  t32*t11,0)+ diff(Hama2(q,p),q));
          
$$(t12 + t32) h q - (-t31 + 2 p - t11) h \\ -h ((-2 q t32 + p - t31) t12 + t32 (p - t11)) \quad (5.6)$$

Hama2 := (q, p) → h ((t12 + t32) q p - p2 + (t11 + t31) p - t32 t12 q2 - (t11 t32
  + t12 t31) q)
          0
          0

> simplify(h*dotqfunction(t12,t22,t32,t11,t21,t31,0,0,2*(t32-t12)*
  (t32-t22),0,0,t32*(3*t31-t11-t21)-(t12+t22+t32)*t31+t12*t21+
  t22*t11));
simplify(h*dotpfunction(t12,t22,t32,t11,t21,t31,0,0,2*(t32-t12)*
  (t32-t22),0,0,t32*(3*t31-t11-t21)-(t12+t22+t32)*t31+t12*t21+
  t22*t11));
Hama3:=(q,p)->h*( (t12+t22)*q*p-p^2+(t11+t21)*p -t22*t12*q^2 -
  (t12*t21+t22*t11)*q);
simplify(h*dotqfunction(t12,t22,t32,t11,t21,t31,0,0,2*(t32-t12)*
  (t32-t22),0,0,t32*(3*t31-t11-t21)-(t12+t22+t32)*t31+t12*t21+
  t22*t11)- diff(Hama3(q,p),p));
simplify(h*dotpfunction(t12,t22,t32,t11,t21,t31,0,0,2*(t32-t12)*
  (t32-t22),0,0,t32*(3*t31-t11-t21)-(t12+t22+t32)*t31+t12*t21+
  t22*t11)+ diff(Hama3(q,p),q));
          
$$(t12 + t22) h q - (2 p - t11 - t21) h \\ -h ((-2 q t22 + p - t21) t12 + t22 (p - t11)) \quad (5.7)$$

Hama3 := (q, p) → h ((t12 + t22) q p - p2 + (t11 + t21) p - t22 t12 q2 - (t11 t22
  + t12 t21) q)
          0
          0

> simplify(h*dotqfunction(t12,t22,t32,t11,t21,t31,0,0,0,1,0,0));
simplify(h*dotpfunction(t12,t22,t32,t11,t21,t31,0,0,0,1,0,0));
Hame11 := unapply( (-p3+((t12+t22+t32)*q+t11+t21+t31)*p2+((-t22-t32)*t12-t22*t32)*q2+((-t31-t21)*t12+(-t11-t31)*t22-t32*
```

```

(t11+t21))*q+t12*(-t20-t30)+t22*t20+t32*t30+(-t31-t21)*t11-t21*t31)*p+q*(q^2*t12*t22*t32+((t22*t31+t32*t21)*t12+t22*t32*t11)*q+(t22*t30+t32*t20+t21*t31)*t12+((-t20-t30)*t32+t11*t31)*t22+t32*t11*t21))/((t12-t32)*(t12-t22)),q,p);
simplify(h*dotqfunction(t12,t22,t32,t11,t21,t31,0,0,0,1,0,0)-diff(Hame11(q,p),p));
simplify(h*dotpfunction(t12,t22,t32,t11,t21,t31,0,0,0,1,0,0)+diff(Hame11(q,p),q));

simplify(Hame11(q,p)-1/((t32-t12)*(t22-t12))*(-p^3+P1(q)*p^2-P2(q)*p+P3(q)));

$$\frac{1}{(-t12+t32)(t12-t22)} \left( ((t22+t32)t12+t22t32)q^2 + \left( (t31-2p+t21)t12 + (-2p+t31+t11)t22 - 2\left(p-\frac{1}{2}t11-\frac{1}{2}t21\right)t32 \right)q + (t20+t30)t12 - t20t22 - t30t32 + 3p^2 + (-2t31-2t11-2t21)p + t11(t21+t31) + t21t31 \right) \quad (5.8)$$


$$\frac{1}{(-t12+t32)(t12-t22)} \left( ((3q^2t32-2pq+2qt31+t30)t22 + (-2pq+2qt11+t20)t32 + (p-t31)(p-t21)t12 + ((-2pq+2qt11-t20-t30)t32 + (p-t31)(p-t11)t22 + t32(p-t21)(p-t11)) \right)$$

Hame11 := (q, p) →  $\frac{1}{(t12-t32)(t12-t22)} \left( -p^3 + ((t12+t22+t32)q + t11+t21 + t31)p^2 + (((-t22-t32)t12-t22t32)q^2 + ((-t31-t21)t12 + (-t11-t31)t22 - t32(t11+t21))q + t12(-t20-t30) + t20t22 + t30t32 + (-t31-t21)t11 - t21t31)p + q(q^2t12t22t32 + ((t21t32+t22t31)t12 + t22t32t11)q + (t20t32 + t21t31 + t22t30)t12 + ((-t20-t30)t32 + t11t31)t22 + t32t11t21) \right)$ 

$$0$$


$$0$$


$$0$$

> simplify(h*dotqfunction(t12,t22,t32,t11,t21,t31,0,0,0,0,1,0));
simplify(h*dotpfunction(t12,t22,t32,t11,t21,t31,0,0,0,0,1,0));
Hame21 := unapply( (p^3+(-t12-t22-t32)*q-t31-t11-t21)*p^2+((t12+t32)*t22+t12*t32)*q^2+(t12*(t21+t31)+t22*(t11+t31)+t32*(t11+t21))*q+(h-t20)*t22+(t30-h+t20)*t12-t32*t30+t11*(t21+t31)+t21*t31)*p-q*(q^2*t12*t22*t32+((t12*t31+t32*t11)*t22+t12*t32*t21)*q+(t12*t30+(-t30+h-t20)*t32+t11*t31)*t22+((-h+t20)*t32+t21*t31)*t12+t32*t11*t21))/((t22-t32)*(t12-t22)),q,p);
simplify(h*dotqfunction(t12,t22,t32,t11,t21,t31,0,0,0,0,1,0)-diff(Hame21(q,p),p));
simplify(h*dotpfunction(t12,t22,t32,t11,t21,t31,0,0,0,0,1,0)+diff(Hame21(q,p),q));

simplify(Hame21(q,p) - (1/((t32-t22)*(t12-t22))*(-p^3+P1(q)*

```

$$\begin{aligned}
& \frac{1}{(-t22+t32)(t12-t22)} \left(((-t22-t32)t12 - t22t32)q^2 + \left((-t31+2p-t21)t12 \right. \right. \\
& \quad \left. \left. + (-t31+2p-t11)t22 + 2 \left(p - \frac{1}{2}t11 - \frac{1}{2}t21 \right) t32 \right) q + (h-t20-t30)t12 \right. \\
& \quad \left. + (-h+t20)t22 + t30t32 - 3p^2 + (2t31+2t11+2t21)p + (-t31-t21)t11 \right. \\
& \quad \left. - t21t31 \right) \\
& \frac{1}{(-t22+t32)(t12-t22)} \left(((-3q^2t12+2pq-2qt11-h+t20+t30)t32 + (2pq \right. \\
& \quad \left. - 2qt31-t30)t12 + (p-t11)(-p+t31))t22 + ((2pq-2qt21+h-t20)t12 \right. \\
& \quad \left. - (p-t21)(p-t11))t32 + t12(p-t21)(-p+t31) \right) \\
Hame21 := (q,p) \rightarrow & \frac{1}{(t22-t32)(t12-t22)} \left(p^3 + ((-t12-t22-t32)q - t31-t11 \right. \\
& \quad \left. - t21)p^2 + (((t12+t32)t22+t12t32)q^2 + (t12(t21+t31) + t22(t11+t31) \right. \\
& \quad \left. + t32(t11+t21))q + (h-t20)t22 + (-h+t20+t30)t12 - t30t32 + t11(t21 \right. \\
& \quad \left. + t31) + t21t31)p - q(q^2t12t22t32 + ((t11t32+t12t31)t22 + t12t21t32)q \right. \\
& \quad \left. + (t12t30 + (h-t20-t30)t32 + t11t31)t22 + ((-h+t20)t32 + t21t31)t12 \right. \\
& \quad \left. + t32t11t21) \right) \\
& \quad \quad \quad 0 \\
& \quad \quad \quad 0 \\
& \quad \quad \quad 0
\end{aligned}$$

> **simplify**(h*dotqfunction(t12,t22,t32,t11,t21,t31,0,0,0,0,0,1));
simplify(h*dotpfunction(t12,t22,t32,t11,t21,t31,0,0,0,0,0,1));
Hame31:=unapply((-p^3+(t11+t21+t31+(t12+t22+t32)*q)*p^2+((-t12
-t22)*t32-t12*t22)*q^2+((-t21-t11)*t32+(-t31-t21)*t12-t22*(t11+
t31))*q+(-h+t30)*t32+(-t30+h-t20)*t12+t22*t20+(-t31-t21)*t11-
t21*t31)*p+q*(t12*t22*t32*q^2+((t12*t21+t22*t11)*t32+t31*t12*
t22)*q+(t12*t20+(-t30+h-t20)*t22+t11*t21)*t32+((-h+t30)*t22+
t21*t31)*t12+t22*t11*t31))/((t22-t32)*(t12-t32)),q,p);
simplify(h*dotqfunction(t12,t22,t32,t11,t21,t31,0,0,0,0,0,1)-
diff(Hame31(q,p),p));
simplify(h*dotpfunction(t12,t22,t32,t11,t21,t31,0,0,0,0,0,1)+
diff(Hame31(q,p),q));

simplify(Hame31(q,p)- (1/((t22-t32)*(t12-t32))*(-p^3+ P1(q)*
p^2-P2(q)*p+P3(q)) - (p-q*t22)*h/(t32-t22)));
& \frac{1}{(-t22+t32)(-t12+t32)} \left(((-t22-t32)t12 - t22t32)q^2 + ((-t31+2p-t21)t12 \right. \\
& \quad \left. + t32(2p-t11-t21) - (-2p+t31+t11)t22)q + (h-t20-t30)t12 + (-h \right. \\
& \quad \left. + t30)t32 + t20t22 - 3p^2 + (2t31+2t11+2t21)p + (-t31-t21)t11 - t21t31 \right) \\
& \frac{1}{(-t22+t32)(-t12+t32)} \left(((-3q^2t12+2pq-2qt11-h+t20+t30)t32 + (2pq \right. \\
& \quad \left. - 2qt31+h-t30)t12 + (p-t11)(-p+t31))t22 + ((2pq-2qt21+h-t20)t12 \right)

```


$$- (p - t21) (p - t11)) t32 + t12 (p - t21) (-p + t31))$$


$$Hame31 := (q, p) \rightarrow \frac{1}{(t22 - t32) (t12 - t32)} (-p^3 + ((t12 + t22 + t32) q + t11 + t21$$


$$+ t31) p^2 + (((-t12 - t22) t32 - t12 t22) q^2 + ((-t21 - t11) t32 + (-t31 - t21) t12$$


$$- t22 (t11 + t31)) q + (-h + t30) t32 + (h - t20 - t30) t12 + t20 t22 + (-t31$$


$$- t21) t11 - t21 t31) p + q (q^2 t12 t22 t32 + ((t11 t22 + t12 t21) t32 + t31 t12 t22) q$$


$$+ (t20 t12 + (h - t20 - t30) t22 + t11 t21) t32 + ((-h + t30) t22 + t21 t31) t12$$


$$+ t22 t11 t31))$$


$$0$$


$$0$$


$$0$$


$$> \text{simplify}(Hame31(q, p) - (t12 / (t12 - t32) * Hamv1(q, p) + 1 / (t32 - t12) *$$


$$\text{Hamu1}(q, p) + (t22 - t12) / (t12 - t32) * Hame21(q, p)));$$


$$0 \quad (5.11)$$


$$> \text{simplify}(h * \text{dotqfunction}(t12, t22, t32, t11, t21, t31, 1, 0, 0, 0, 0, 0)) :$$


$$\text{simplify}(h * \text{dotpfunction}(t12, t22, t32, t11, t21, t31, 1, 0, 0, 0, 0, 0)) :$$


$$\text{Hame12} := \text{unapply}(((t32 * t22 * (t21 + t31 - 2 * t11)) * q^3 + (-t22 + t32) * (t21 +$$


$$t31 - 2 * t11) * p + (-h * t32 + t31 * (t21 + t31 - 2 * t11)) * t22 + t32 * t21 * (t21 + t31$$


$$- 2 * t11)) * q^2 + ((t21 + t31 - 2 * t11) * p^2 + (h * t22 + h * t32 - (t21 + t31) * (t21 +$$


$$t31 - 2 * t11)) * p + (-2 * t30 * t11 + t21 * t30 + (-h + t30) * t31) * t22 + (-2 * t11 *$$


$$t20 + (-h + t20) * t21 + t31 * t20) * t32 + t31 * t21 * (t21 + t31 - 2 * t11)) * q - (p * h +$$


$$(-2 * t30 - 2 * t20) * t11 + (t21 + t31) * (t30 - h + t20)) * p) * t12^2 + (-((-t11 +$$


$$t31) * t22 - t32 * (t11 - t21)) * t32 * t22 * q^3 + (((-t11 + t31) * t22^2 - t32^2 *$$


$$(t11 - t21)) * p + (h * t32 - t31 * (-t11 + t31)) * t22^2 + (2 * ((1/2) * h * t32 + (t11 -$$


$$t21) * (-t11 + t31))) * t32 * t22 + t21 * t32^2 * (t11 - t21)) * q^2 + (((-t11 + t21) *$$


$$* t22 + t32 * (-t11 + t31)) * p^2 + (-h * t22^2 + (-2 * h * t32 + 2 * t11 * (t11 - t21)) *$$


$$t22 - h * t32^2 - 2 * t11 * (-t11 + t31) * t32) * p + (t30 * t11 - (-h + t30) * t31) *$$


$$t22^2 + (((3 * t20 + 3 * t30) * t11 + (h - t20 - 2 * t30) * t21 - (-h + 2 * t20 + t30) * t31) *$$


$$* t32 + t31 * (t11 - t21) * (-2 * t11 + t31)) * t22 + (2 * ((1/2) * t11 * t20 + (1/2) *$$


$$(h - t20) * t21) * t32 + (-t11 + t31) * t21 * (-1/2 * t21 + t11))) * t32) * q - p * ($$


$$(t21 + t31 - 2 * t11) * p^2 + (-h * t22 - h * t32 - (t11 + t21 + t31) * (t21 + t31 - 2 * t11)) *$$


$$* p + ((3 * t20 + t30) * t11 + (h - t20) * t21 - (-h + 2 * t20 + t30) * t31) * t22 + (t11 *$$


$$(t20 + 3 * t30) + (h - t20 - 2 * t30) * t21 - (-h + t30) * t31) * t32 + (t21 + t31 - 2 * t11) *$$


$$* (t11 * (t21 + t31) + t21 * t31))) * t12 + t32 * ((((-t11 + t31) * t22 - t32 * (t11 -$$


$$t21)) * p + (-h * t32 - t11 * (-t11 + t31)) * t22 + t32 * t11 * (t11 - t21)) * t22 * q^2 +$$


$$(-((-t11 + t31) * t22 - t32 * (t11 - t21)) * (t22 + t32) * p^2 + ((t32 * h - t11^2 +$$


$$t31^2) * t22^2 + (h * t32^2 + (-2 * t11^2 + 2 * t21 * t31) * t32) * t22 + (-t11^2 +$$


$$t21^2) * t32^2) * p + ((((-t20 - t30) * t11 + (t30 - h + t20) * t31) * t32 - t11 * t31 *$$


$$(-t11 + t31)) * t22^2 - t32 * ((t11 * (t20 + t30) - (t30 - h + t20) * t21) * t32 -$$


$$(t11 * (t21 + t31) - 2 * t21 * t31) * t11) * t22 + t32^2 * t11 * t21 * (t11 - t21)) * q +$$


$$p * ((((-t11 + t31) * t22 - t32 * (t11 - t21)) * p^2 + (-h * t32 - (-t11 + t31) * (t11 +$$


$$t21 + t31)) * t22 + t32 * (t11 - t21) * (t11 + t21 + t31)) * p - t20 * (-t11 + t31) *$$


$$t22^2 + ((t11 * (t20 + t30) + (h - t20) * t21 - (-h + t30) * t31) * t32 + (-t11 + t31) *$$


```

```

(t11*(t21+t31)+t21*t31))*t22+t32*((-t31-t21)*t11+t32*t30-t21*
t31)*(t11-t21)))/(2*(t12-t32)^2*(t12-t22)^2)
,q,p);
simplify(h*dotqfunction(t12,t22,t32,t11,t21,t31,1,0,0,0,0,0)-
diff(Hame12(q,p),p));
simplify(h*dotpfunction(t12,t22,t32,t11,t21,t31,1,0,0,0,0,0)+
diff(Hame12(q,p),q));
Hame12 := (q,p)→
$$\frac{1}{2} \frac{1}{(t12 - t32)^2 (t12 - t22)^2} \left( (t32 t22 (t31 - 2 t11 + t21) q^3 + (-t22 + t32) (t31 - 2 t11 + t21) p + (-h t32 + t31 (t31 - 2 t11 + t21)) t22 + t32 t21 (t31 - 2 t11 + t21)) q^2 + ((t31 - 2 t11 + t21) p^2 + (h t22 + h t32 - (t21 + t31) (t31 - 2 t11 + t21)) p + (-2 t11 t30 + t21 t30 + (-h + t30) t31) t22 + (-2 t11 t20 + (-h + t20) t21 + t31 t20) t32 + t31 t21 (t31 - 2 t11 + t21)) q - (h p + (-2 t20 - 2 t30) t11 + (t21 + t31) (-h + t20 + t30)) p) t12^2 + \left( -(( -t11 + t31) t22 - t32 (t11 - t21)) t32 t22 q^3 + \left( (( -t11 + t31) t22^2 - t32^2 (t11 - t21)) p + (h t32 - t31 (-t11 + t31)) t22^2 + 2 \left( \frac{1}{2} h t32 + (t11 - t21) (-t11 + t31) \right) t32 t22 + t21 t32^2 (t11 - t21) \right) q^2 + \left( (( -t11 + t21) t22 + t32 (-t11 + t31)) p^2 + (-h t22^2 + (-2 h t32 + 2 t11 (t11 - t21)) t22 - h t32^2 - 2 t11 (-t11 + t31) t32) p + (t11 t30 - (-h + t30) t22^2 + (((3 t30 + 3 t20) t11 + t21 (h - t20 - 2 t30) - (-h + 2 t20 + t30) t31) t32 + t31 (t11 - t21) (t31 - 2 t11) t22 + 2 \left( \left( \frac{1}{2} t11 t20 + \frac{1}{2} (h - t20) t21 \right) t32 + (-t11 + t31) t21 \left( t11 - \frac{1}{2} t21 \right) \right) t32 \right) q - p ((t31 - 2 t11 + t21) p^2 + (-h t22 - h t32 - (t11 + t21 + t31) (t31 - 2 t11 + t21)) p + (t11 (t30 + 3 t20) + (h - t20) t21 - (-h + 2 t20 + t30) t31) t22 + (t11 (t20 + 3 t30) + t21 (h - t20 - 2 t30) - (-h + t30) t31) t32 + (t31 - 2 t11 + t21) (t11 (t21 + t31) + t21 t31))) t12 + t32 ((( -t11 + t31) t22 - t32 (t11 - t21)) p + (-h t32 - t11 (-t11 + t31)) t22 + t32 t11 (t11 - t21) t22 q^2 + (-(( -t11 + t31) t22 - t32 (t11 - t21)) (t22 + t32) p^2 + ((h t32 - t11^2 + t31^2) t22^2 + (h t32^2 + (-2 t11^2 + 2 t21 t31) t32) t22 + (-t11^2 + t21^2) t32^2) p + ((( -t20 - t30) t11 + (-h + t20 + t30) t31) t32 - t11 t31 (-t11 + t31)) t22^2 - t32 (((t20 + t30) t11 - (-h + t20 + t30) t21) t32 - (t11 (t21 + t31) - 2 t21 t31) t11) t22 + t32^2 t11 t21 (t11 - t21) q + p ((( -t11 + t31) t22 - t32 (t11 - t21)) p^2 + (-h t32 - (-t11 + t31) (t11 + t21 + t31)) t22 + t32 (t11 - t21) (t11 + t21 + t31)) p - t20 (-t11 + t31) t22^2 + (((t20 + t30) t11 + (h - t20) t21 - (-h + t30) t31) t32 + (-t11 + t31) (t11 (t21 + t31) + t21 t31)) t22 + t32 (( -t31 - t21) t11 + t30 t32$$
 (5.12)

```

```

- t21 t31) (t11 - t21)))
0
0
=> simplify(h*dotqfunction(t12,t22,t32,t11,t21,t31,0,1,0,0,0,0)):
simplify(h*dotpfunction(t12,t22,t32,t11,t21,t31,0,1,0,0,0,0)):
Hame22:=unapply( ((t12*t32*(t11-2*t21+t31)*q^3+(-(t12+t32)*(t11-2*t21+t31)*p+(-h*t12+t11*(t11-2*t21+t31))*t32+t12*t31*(t11-2*t21+t31))*q^2+((t11-2*t21+t31)*p^2+(h*t32+h*t12-(t11+t31)*(t11-2*t21+t31))*p+((2*t30-2*h+2*t20)*t21+(-t30+h-t20)*t31-t11*(t20+t30))*t32+(-2*t21*t30+(-h+t30)*t31+t30*t11)*t12+t11*t31*(t11-2*t21+t31))*q- (p*h+(-2*h+2*t20)*t21-t20*(t11+t31))*p)*t22^2+(-t12*t32*(t32*(t11-t21)+t12*(-t21+t31))*q^3+((t32^2*(t11-t21)+t12^2*(-t21+t31))*p+(h*t12-t11*(t11-t21))*t32^2-2*t12*(-(1/2)*h*t12+(t11-t21)*(-t21+t31))*t32-t31*(-t21+t31)*t12^2)*q^2+((-t21+t31)*t32+t12*(t11-t21))*p^2+(-h*t32^2+(-2*h*t12-2*t21*(-t21+t31))*t32-t12*(h*t12+2*t21*(t11-t21)))*p+((-t30+h-t20)*t21+t11*(t20+t30))*t32^2+((3*h-3*t20)*t21+(-h+2*t20+t30)*t31-(-t20+t30)*t11)*t12-t11*(-2*t21+t11)*(-t21+t31))*t32-t12*((-t21*t30+(-h+t30)*t31)*t12+t31*(t11-t21)*(t31-2*t21))*q- ((t11-2*t21+t31)*p^2+(-h*t32-h*t12-(t11+t21+t31)*(t11-2*t21+t31))*p+((2*t30+h-t20)*t21+(h-t30)*t31-(-t20+t30)*t11)*t32+((-2*t30+3*h-3*t20)*t21+(-h+2*t20+t30)*t31+t11*(t20+t30))*t12+(t11-2*t21+t31)*((t11+t31)*t21+t11*t31))*p)*t22+t12*((t32*(t11-t21)+t12*(-t21+t31))*p+(-h*t12-t21*(t11-t21))*t32-t12*t21*(-t21+t31))*t32*q^2+(-(t12+t32)*(t32*(t11-t21)+t12*(-t21+t31))*p^2+((t12*h+t11^2-t21^2)*t32^2+(h*t12^2+(2*t11*t31-2*t21^2)*t12)*t32+t12^2*(-t21^2+t31^2))*p+((-h*t20)*t21-t11*t20)*t12-t11*t21*(t11-t21))*t32^2-t12*((h-t20)*t21+t31*t20)*t12+(-t11-t31)*t21^2+2*t11*t21*t31)*t32-t31*t12^2*t21*(-t21+t31))*q+ ((t32*(t11-t21)+t12*(-t21+t31))*p^2+((-h*t12-(t11-t21)*(t11+t21+t31))*t32-t12*(-t21+t31)*(t11+t21+t31))*p-t30*(t11-t21)*t32^2+((h-t20)*t21+(h-t30)*t31+t11*(t20+t30))*t12+(t11-t21)*((t11+t31)*t21+t11*t31)*(-t21+t31))*p)/ (2*(t22-t32)^2*(t12-t22)^2),q,p);
simplify(h*dotqfunction(t12,t22,t32,t11,t21,t31,0,1,0,0,0,0)-diff(Hame22(q,p),p));
simplify(h*dotpfunction(t12,t22,t32,t11,t21,t31,0,1,0,0,0,0)+diff(Hame22(q,p),q));
Hame22 := (q,p)→
$$\frac{1}{2} \frac{1}{(t22-t32)^2 (t12-t22)^2} \left( (t12 t32 (t11-2 t21+t31) q^3 + (-t12+t32) (t11-2 t21+t31) p + (-h t12+t11 (t11-2 t21+t31)) t32 \right.$$
 (5.13)

```

$$\begin{aligned}
& + t12 t31 (t11 - 2 t21 + t31) q^2 + ((t11 - 2 t21 + t31) p^2 + (h t32 + h t12 - (t11 \\
& + t31) (t11 - 2 t21 + t31)) p + ((-2 h + 2 t30 + 2 t20) t21 + (h - t20 - t30) t31 \\
& - (t20 + t30) t11) t32 + (-2 t21 t30 + (-h + t30) t31 + t11 t30) t12 + t11 t31 (t11 \\
& - 2 t21 + t31)) q - (h p + (-2 h + 2 t20) t21 - t20 (t11 + t31)) p) t22^2 + \left(\right. \\
& - t12 t32 (t32 (t11 - t21) + t12 (-t21 + t31)) q^3 + \left((t32^2 (t11 - t21) + t12^2 (-t21 \\
& + t31)) p + (h t12 - t11 (t11 - t21)) t32^2 - 2 t12 \left(-\frac{1}{2} h t12 + (t11 - t21) (-t21 \\
& + t31) \right) t32 - t31 (-t21 + t31) t12^2 \right) q^2 + (((-t21 + t31) t32 + t12 (t11 - t21)) p^2 \\
& + (-h t32^2 + (-2 h t12 - 2 t21 (-t21 + t31)) t32 - t12 (h t12 + 2 t21 (t11 \\
& - t21))) p + (t21 (h - t20 - t30) + (t20 + t30) t11) t32^2 + (((3 h - 3 t20) t21 + \\
& - h + 2 t20 + t30) t31 - t11 (-t20 + t30)) t12 - t11 (t11 - 2 t21) (-t21 + t31)) t32 \\
& - t12 ((-t21 t30 + (-h + t30) t31) t12 + t31 (t11 - t21) (-2 t21 + t31))) q \\
& - ((t11 - 2 t21 + t31) p^2 + (-h t32 - h t12 - (t11 + t21 + t31) (t11 - 2 t21 \\
& + t31)) p + ((h + 2 t30 - t20) t21 + (h - t30) t31 - t11 (-t20 + t30)) t32 + ((\\
& - 2 t30 + 3 h - 3 t20) t21 + (-h + 2 t20 + t30) t31 + (t20 + t30) t11) t12 + (t11 \\
& - 2 t21 + t31) ((t11 + t31) t21 + t11 t31)) p) t22 + t12 ((t32 (t11 - t21) + t12 (\\
& - t21 + t31)) p + (-h t12 - t21 (t11 - t21)) t32 - t12 t21 (-t21 + t31)) t32 q^2 + \\
& - (t12 + t32) (t32 (t11 - t21) + t12 (-t21 + t31)) p^2 + ((h t12 + t11^2 - t21^2) t32^2 \\
& + (h t12^2 + (2 t11 t31 - 2 t21^2) t12) t32 + t12^2 (-t21^2 + t31^2)) p + (((-h \\
& + t20) t21 - t11 t20) t12 - t11 t21 (t11 - t21)) t32^2 - t12 (((h - t20) t21 \\
& + t31 t20) t12 + (-t11 - t31) t21^2 + 2 t11 t21 t31) t32 - t31 t12^2 t21 (-t21 + t31)) q \\
& + ((t32 (t11 - t21) + t12 (-t21 + t31)) p^2 + ((-h t12 - (t11 - t21) (t11 + t21 \\
& + t31)) t32 - t12 (-t21 + t31) (t11 + t21 + t31)) p - t30 (t11 - t21) t32^2 + (((h \\
& - t20) t21 + (h - t30) t31 + (t20 + t30) t11) t12 + (t11 - t21) ((t11 + t31) t21 \\
& + t11 t31)) t32 + t12 ((-h + t20 + t30) t12 + (t11 + t31) t21 + t11 t31) (-t21 \\
& + t31)) p) \\
& = 0 \\
& = 0
\end{aligned}$$

```

> simplify(h*dotqfunction(t12,t22,t32,t11,t21,t31,0,0,1,0,0,0)):
simplify(h*dotpfunction(t12,t22,t32,t11,t21,t31,0,0,1,0,0,0)):
Hame32:=unapply( ((-(2*(t31-(1/2)*t11-(1/2)*t21))*t12*t22*q^3+
((2*(t31-(1/2)*t11-(1/2)*t21))*t12+t22)*p+(-h*t12-(2*(t31-
(1/2)*t11-(1/2)*t21))*t11)*t22-(2*(t31-(1/2)*t11-(1/2)*t21))*t12*t21)*q^2+((t11+t21-2*t31)*p^2+(h*t22+h*t12+(2*(t31-(1/2)*
t11-(1/2)*t21))*t11)*t22+((2*t30-2*h+2*t20)*t31+(-t30+h-
t20)*t21-t11*(t20+t30))*t22+(-2*t31*t20+(-h+t20)*t21+t11*t20)*t12-2*t21*(t31-(1/2)*t11-(1/2)*t21)*t11)*q-p*(p*h+(2*t30-2*h)*
t31-t30*(t11+t21))*t32^2+(t12*((-t11+t31)*t22+t12*(-t21+t31))*t22*q^3+(((t11-t31)*t22^2-t12^2*(-t21+t31))*p+(h*t12+t11*(-t11+

```

```

t31)) * t22^2 - 2 * t12 * ((-1/2) * h * t12 + (-t21 + t31) * (-t11 + t31)) * t22 + t21 *
t12^2 * (-t21 + t31)) * q^2 + (((t21 - t31) * t22 - t12 * (-t11 + t31)) * p^2 + (-h *
t22^2 + (-2 * h * t12 + 2 * t31 * (-t21 + t31)) * t22 - h * t12^2 + 2 * t31 * (-t11 + t31) *
t12) * p + ((-t30 + h - t20) * t31 + t11 * (t20 + t30)) * t22^2 + (((-3 * t30 + 3 * h) *
t31 + (-h + t20 + 2 * t30) * t21 + (-t20 + t30) * t11) * t12 - (2 * (-t21 + t31)) * (-
(1/2) * t11 + t31) * t11) * t22 - 2 * t12 * ((-1/2) * t31 * t20 - (1/2) * (h - t20) *
t21) * t12 + (-t11 + t31) * t21 * (t31 - (1/2) * t21))) * q + (2 * ((t31 - (1/2) * t11 -
(1/2) * t21) * p^2 + ((1/2) * h * t22 + (1/2) * h * t12 - (t31 - (1/2) * t11 - (1/2) *
t21) * (t11 + t21 + t31)) * p + ((-1/2) * h - t20 + (1/2) * t30) * t31 + t21 * ((1/2) *
t20 - (1/2) * h) - (1/2) * (-t20 + t30) * t11) * t22 + ((t20 + 3 * t30 * (1/2) - 3 * h *
(1/2)) * t31 + (-t30 + (1/2) * h - (1/2) * t20) * t21 - (1/2) * t11 * (t20 + t30)) *
t12 + (t31 - (1/2) * t11 - (1/2) * t21) * ((t11 + t21) * t31 + t11 * t21))) * p) * t32 -
t12 * t22 * ((((-t11 + t31) * t22 + t12 * (-t21 + t31)) * p + (h * t12 - t31 * (-t11 +
t31)) * t22 - t12 * t31 * (-t21 + t31)) * q^2 + ((t12 + t22) * ((-t11 + t31) * t22 +
t12 * (-t21 + t31)) * p^2 + ((t12 * h + t11^2 - t31^2) * t22^2 + (h * t12^2 + (2 * t11 *
t21 - 2 * t31^2) * t12) * t22 + (t21^2 - t31^2) * t12^2) * p + (((-h + t30) * t31 -
t30 * t11) * t12 + t11 * t31 * (-t11 + t31)) * t22^2 + ((-t21 * t30 + (-h + t30) * t31) *
t12 + t31 * ((t11 + t21) * t31 - 2 * t11 * t21)) * t12 * t22 + t31 * t12^2 * t21 * (-
t21 + t31)) * q - (((-t11 + t31) * t22 + t12 * (-t21 + t31)) * p^2 + ((h * t12 - (-t11 +
t31) * (t11 + t21 + t31)) * t22 - t12 * (-t21 + t31) * (t11 + t21 + t31)) * p - t20 * (-
t11 + t31) * t22^2 + (((-h + t30) * t31 + (-h + t20) * t21 - t11 * (t20 + t30)) * t12 +
(-t11 + t31) * ((t11 + t21) * t31 + t11 * t21)) * t22 + t12 * ((t30 - h + t20) * t12 +
(t11 + t21) * t31 + t11 * t21) * (-t21 + t31)) * p) / (2 * (t22 - t32)^2 * (t12 - t32)
^2)

,q,p);

simplify(h*dotqfunction(t12,t22,t32,t11,t21,t31,0,0,1,0,0,0)-
diff(Hame32(q,p),p));
simplify(h*dotpfunction(t12,t22,t32,t11,t21,t31,0,0,1,0,0,0)-
diff(Hame32(q,p),q));

```

$$\begin{aligned}
Hame32 := (q, p) \rightarrow & \frac{1}{2} \frac{1}{(t22 - t32)^2 (t12 - t32)^2} \left(\left(-2 \left(t31 - \frac{1}{2} t11 \right. \right. \right. \\
& \left. \left. \left. - \frac{1}{2} t21 \right) t12 t22 q^3 + \left(2 \left(t31 - \frac{1}{2} t11 - \frac{1}{2} t21 \right) (t12 + t22) p + \left(-h t12 \right. \right. \right. \\
& \left. \left. \left. - 2 \left(t31 - \frac{1}{2} t11 - \frac{1}{2} t21 \right) t11 \right) t22 - 2 \left(t31 - \frac{1}{2} t11 - \frac{1}{2} t21 \right) t12 t21 \right) q^2 \right. \\
& \left. + \left((t11 + t21 - 2 t31) p^2 + \left(h t22 + h t12 + 2 \left(t31 - \frac{1}{2} t11 - \frac{1}{2} t21 \right) (t11 \right. \right. \right. \\
& \left. \left. \left. + t21) \right) p + ((-2 h + 2 t30 + 2 t20) t31 + t21 (h - t20 - t30) - (t20 + t30) t11) t22 \right. \\
& \left. + (-2 t31 t20 + (-h + t20) t21 + t11 t20) t12 - 2 t21 \left(t31 - \frac{1}{2} t11 - \frac{1}{2} t21 \right) t11 \right) \\
& q - p (h p + (-2 h + 2 t30) t31 - t30 (t11 + t21)) \right) t32^2 + \left(t12 ((-t11 + t31) t22 \right.
\end{aligned} \tag{5.14}$$

$$\begin{aligned}
& + t12 (-t21 + t31)) t22 q^3 + \left(((t11 - t31) t22^2 - t12^2 (-t21 + t31)) p + (h t12 \right. \\
& + t11 (-t11 + t31)) t22^2 - 2 t12 \left(-\frac{1}{2} h t12 + (-t21 + t31) (-t11 + t31) \right) t22 \\
& \left. + t21 t12^2 (-t21 + t31) \right) q^2 + \left(((t21 - t31) t22 - t12 (-t11 + t31)) p^2 + (-h t22^2 \right. \\
& + (-2 h t12 + 2 t31 (-t21 + t31)) t22 - h t12^2 + 2 t31 (-t11 + t31) t12) p + ((h \\
& - t20 - t30) t31 + (t20 + t30) t11) t22^2 + \left(((3 h - 3 t30) t31 + (-h + t20 \right. \\
& + 2 t30) t21 + t11 (-t20 + t30)) t12 - 2 (-t21 + t31) \left(t31 - \frac{1}{2} t11 \right) t11 \right) t22 \\
& - 2 t12 \left(\left(-\frac{1}{2} t31 t20 - \frac{1}{2} (h - t20) t21 \right) t12 + (-t11 + t31) t21 \left(t31 \right. \right. \\
& \left. \left. - \frac{1}{2} t21 \right) \right) q + 2 \left(\left(t31 - \frac{1}{2} t11 - \frac{1}{2} t21 \right) p^2 + \left(\frac{1}{2} h t22 + \frac{1}{2} h t12 - \left(t31 \right. \right. \right. \\
& \left. \left. \left. - \frac{1}{2} t11 - \frac{1}{2} t21 \right) (t11 + t21 + t31) \right) p + \left(\left(-t20 - \frac{1}{2} h + \frac{1}{2} t30 \right) t31 + t21 \left(\right. \right. \\
& \left. \left. - \frac{1}{2} h + \frac{1}{2} t20 \right) - \frac{1}{2} t11 (-t20 + t30) \right) t22 + \left(\left(t20 + \frac{3}{2} t30 - \frac{3}{2} h \right) t31 + \left(-t30 \right. \right. \\
& \left. \left. + \frac{1}{2} h - \frac{1}{2} t20 \right) t21 - \frac{1}{2} (t20 + t30) t11 \right) t12 + \left(t31 - \frac{1}{2} t11 \right. \\
& \left. - \frac{1}{2} t21 \right) (t31 (t11 + t21) + t11 t21) \right) p \Big) t32 - t12 t22 (((-t11 + t31) t22 + t12 (- \\
& t21 + t31)) p + (h t12 - t31 (-t11 + t31)) t22 - t12 t31 (-t21 + t31)) q^2 + ((t12 + t22) ((-t11 + t31) t22 + t12 (-t21 + t31)) p^2 + ((h t12 + t11^2 - t31^2) t22^2 \\
& + (h t12^2 + (2 t11 t21 - 2 t31^2) t12) t22 + (t21^2 - t31^2) t12^2) p + (((-h + t30) t31 - t11 t30) t12 + t11 t31 (-t11 + t31)) t22^2 + ((-t21 t30 + (-h + t30) t31) t12 \\
& + t31 (t31 (t11 + t21) - 2 t11 t21)) t12 t22 + t31 t12^2 t21 (-t21 + t31)) q - (((-t11 + t31) t22 + t12 (-t21 + t31)) p^2 + ((h t12 - (-t11 + t31) (t11 + t21 + t31)) t22 \\
& - t12 (-t21 + t31) (t11 + t21 + t31)) p - t20 (-t11 + t31) t22^2 + (((-h + t30) t31 + (-h + t20) t21 - (t20 + t30) t11) t12 + (-t11 + t31) (t31 (t11 + t21) + t11 t21)) \\
& t22 + t12 ((-h + t20 + t30) t12 + t31 (t11 + t21) + t11 t21) (-t21 + t31)) p) \\
& 0 \\
& 0
\end{aligned}$$

> **simplify(Hame21(q,p)-(1/((t32-t22)*(t12-t22))*(-p^3+ P1(q)*p^2-P2(q)*p+P3(q))+ (p-q*t32)*h/(t32-t22)))**;

0 (5.15)

Definition of the reduced Darboux coordiantes and Hamiltonian in the direction tau

```

> TT1:=unapply(t12+t22+t32,t11,t21,t31,t12,t22,t32);
TT2:=unapply(t11+t21+t31,t11,t21,t31,t12,t22,t32);
TT3:=unapply(t22,t11,t21,t31,t12,t22,t32);
TT4:=unapply(t11,t11,t21,t31,t12,t22,t32);

```

```

TT5:=unapply(t32,t11,t21,t31,t12,t22,t32);
taufunction:=unapply( ((t21-t31)*t12+(t31-t11)*t22+(t11-t21)*
t32)/(sqrt((t22-t12)*(t12-t32)*(t32-t22))) ,t11,t21,t31,t12,
t22,t32);
solve({TT1(t11,t21,t31,t12,t22,t32)=T1,TT2(t11,t21,t31,t12,t22,
t32)=T2,TT3(t11,t21,t31,t12,t22,t32)=T3,TT4(t11,t21,t31,t12,
t22,t32)=T4,TT5(t11,t21,t31,t12,t22,t32)=T5,taufunction(t11,
t21,t31,t12,t22,t32)=tau },{t11,t21,t31,t12,t22,t32});

t11function := T4;
t12function := -T3-T5+T1;
t21function := (tau*sqrt((-2*T3-T5+T1)*(-T3-2*T5+T1)*(T3-T5))+
T1*T2-T1*T4-2*T3*T2-T5*T2+3*T4*T3)/(2*T1-3*T3-3*T5);
t22function := T3;
t31function := -(tau*sqrt((-2*T3-T5+T1)*(-T3-2*T5+T1)*(T3-T5))-
T1*T2+T1*T4+T3*T2+2*T5*T2-3*T4*T5)/(2*T1-3*T3-3*T5);
t32function := T5;
simplify(TT1(t11function,t21function,t31function,t12function,
t22function,t32function));
simplify(TT2(t11function,t21function,t31function,t12function,
t22function,t32function));
simplify(TT3(t11function,t21function,t31function,t12function,
t22function,t32function));
simplify(TT4(t11function,t21function,t31function,t12function,
t22function,t32function));
simplify(TT5(t11function,t21function,t31function,t12function,
t22function,t32function));
simplify(taufunction(t11function,t21function,t31function,
t12function,t22function,t32function));

partialtaufunction:=unapply( diff(t11function,tau)*partialt11 +
diff(t21function,tau)*partialt21+diff(t31function,tau)*
partialt31+diff(t12function,tau)*partialt12+diff(t22function,
tau)*partialt22+diff(t32function,tau)*partialt32,T1,T2,T3,T4,
T5,tau):
partialtau:=partialtaufunction(TT1(t11,t21,t31,t12,t22,t32),TT2
(t11,t21,t31,t12,t22,t32),TT3(t11,t21,t31,t12,t22,t32),TT4(t11,
t21,t31,t12,t22,t32),TT5(t11,t21,t31,t12,t22,t32),taufunction
(t11,t21,t31,t12,t22,t32) ):

Coefft21:=residue(partialtau/partialt21^2,partialt21=0):
Coefft31:=residue(partialtau/partialt31^2,partialt31=0):

```

```

Hamtau:= unapply( simplify(Coefft21*Hame21(q,p)+Coefft31*Hame31
(q,p)),q,p):
Ltauq:=diff(Hamtau(q,p),p):
Ltaup:=-diff(Hamtau(q,p),q):

checkqfunction:=unapply( sqrt((t12-t32)/((t22-t12)*(t32-t22)))*
(-p+t22*q+t21),q,p);
checkpfunction:=unapply( sqrt((t32-t22)/((t12-t32)*(t22-t12)))*
(p-t12*q-t11),q,p);

SOLL:=solve({checkqfunction(q,p)=checkq,checkpfunction(q,p)=
checkp},{q,p}):
Solp:=simplify(rhs(SOLL[1])):
Solq:=simplify(rhs(SOLL[2])):
simplify(checkqfunction(Solq,Solp)-checkq);
simplify(checkpfunction(Solq,Solp)-checkp);

Ltauchekqfunction:=unapply( simplify( diff(checkqfunction(q,
p),q)*Ltauq+diff(checkqfunction(q,p),p)*Ltaup+Coefft21*h*diff
(checkqfunction(q,p),t21)+Coefft31*h*diff(checkqfunction(q,p),
t31)),q,p):
Ltauchekpfunction:=unapply(simplify( diff(checkpfunction(q,p),
q)*Ltauq+diff(checkpfunction(q,p),p)*Ltaup+Coefft21*h*diff
(checkpfunction(q,p),t21)+Coefft31*h*diff(checkpfunction(q,p),
t31)),q,p):
Ltauchekqfunction2:=unapply(simplify(Ltauchekqfunction(Solq,
Solp)),t11, t21, t31, t12, t22, t32):
Ltauchekpfunction2:=unapply(simplify(Ltauchekpfunction(Solq,
Solp)),t11, t21, t31, t12, t22, t32):
Ltauchekq:=simplify(Ltauchekqfunction2(t11function,
t21function ,t31function ,t12function ,t22function ,
t32function)):
Ltauchekp:=simplify(Ltauchekpfunction2(t11function,
t21function ,t31function ,t12function ,t22function ,
t32function)):
HamtauchekCoordinates:=unapply(simplify(int(Ltauchekq,checkp)
-int(simplify(diff(int(Ltauchekq,checkp),checkq)+Ltauchekp),
checkq),checkq,checkp)):
simplify(Ltauchekq-diff(HamtauchekCoordinates(checkq,checkp),
checkp));
simplify(Ltauchekp+diff(HamtauchekCoordinates(checkq,checkp),
checkq));

```

$$TT1 := (t11, t21, t31, t12, t22, t32) \rightarrow t12 + t22 + t32 \quad (5.16)$$

$$TT2 := (t11, t21, t31, t12, t22, t32) \rightarrow t11 + t21 + t31$$

$$TT3 := (t11, t21, t31, t12, t22, t32) \rightarrow t22$$

$$TT4 := (t11, t21, t31, t12, t22, t32) \rightarrow t11$$

$$TT5 := (t11, t21, t31, t12, t22, t32) \rightarrow t32$$

$$taufunction := (t11, t21, t31, t12, t22, t32)$$

$$\rightarrow \frac{(t21 - t31) t12 + (-t11 + t31) t22 + t32 (t11 - t21)}{\sqrt{(-t12 + t22) (t12 - t32) (-t22 + t32)}}$$

$$\left\{ t11 = T4, t12 = -T3 - T5 + T1, t21 \right.$$

$$= \frac{1}{2 T1 - 3 T3 - 3 T5} (\tau \sqrt{(-T3 - 2 T5 + T1) (T3 - T5) (-2 T3 - T5 + T1)} + T1 T2$$

$$- T1 T4 - 2 T3 T2 - T5 T2 + 3 T4 T3), t22 = T3, t31 =$$

$$- \frac{1}{2 T1 - 3 T3 - 3 T5} (\tau \sqrt{(-T3 - 2 T5 + T1) (T3 - T5) (-2 T3 - T5 + T1)} - T1 T2$$

$$+ T1 T4 + T3 T2 + 2 T5 T2 - 3 T4 T5), t32 = T5 \right\}$$

$$t11function := T4$$

$$t12function := -T3 - T5 + T1$$

$$t21function := \frac{1}{2 T1 - 3 T3 - 3 T5} (\tau$$

$$\sqrt{(-T3 - 2 T5 + T1) (T3 - T5) (-2 T3 - T5 + T1)} + T1 T2 - T1 T4 - 2 T3 T2$$

$$- T5 T2 + 3 T4 T3)$$

$$t22function := T3$$

$$t31function :=$$

$$- \frac{1}{2 T1 - 3 T3 - 3 T5} (\tau \sqrt{(-T3 - 2 T5 + T1) (T3 - T5) (-2 T3 - T5 + T1)} - T1 T2$$

$$+ T1 T4 + T3 T2 + 2 T5 T2 - 3 T4 T5)$$

$$t32function := T5$$

$$T1$$

$$T2$$

$$T3$$

$$T4$$

$$T5$$

$$\tau$$

$$checkqfunction := (q, p) \rightarrow \sqrt{\frac{t12 - t32}{(-t12 + t22) (-t22 + t32)}} (q t22 - p + t21)$$

$$checkpfunction := (q, p) \rightarrow \sqrt{\frac{-t22 + t32}{(-t12 + t22) (t12 - t32)}} (-q t12 + p - t11)$$

$$0$$

$$0$$

$$0$$

$$0$$

Verification that the reduced Darboux coordinates have trivial evolutions along the trivial directions

> hdotcheckqfunction := unapply(h*simplify(diff(checkqfunction(q,

```

p),q)*dotqfunction(t12,t22,t32,t11,t21,t31,dott12,dott22,
dott32,dott11,dott21,dott31)+ diff(checkqfunction(q,p),p)*
dotpfunction(t12,t22,t32,t11,t21,t31,dott12,dott22,dott32,
dott11,dott21,dott31)+ diff(checkqfunction(q,p),t12)
*dott12+diff(checkqfunction(q,p),t22)*dott22+diff
(checkqfunction(q,p),t32)*dott32+diff(checkqfunction(q,p),t11)*
dott11+diff(checkqfunction(q,p),t21)*dott21+diff(checkqfunction
(q,p),t31)*dott31),t12,t22,t32,t11,t21,t31,dott12,dott22,
dott32,dott11,dott21,dott31):
hdotcheckpfunction:= unapply(h*simplify(diff(checkpfunction(q,
p),q)*dotqfunction(t12,t22,t32,t11,t21,t31,dott12,dott22,
dott32,dott11,dott21,dott31)+ diff(checkpfunction(q,p),p)*
dotpfunction(t12,t22,t32,t11,t21,t31,dott12,dott22,dott32,
dott11,dott21,dott31)+ diff(checkpfunction(q,p),t12)*dott12+
diff(checkpfunction(q,p),t22)*dott22+diff(checkpfunction(q,p),
t32)*dott32+diff(checkpfunction(q,p),t11)*dott11+diff
(checkpfunction(q,p),t21)*dott21+diff(checkpfunction(q,p),t31)*
dott31),t12,t22,t32,t11,t21,t31,dott12,dott22,dott32,dott11,
dott21,dott31):

> simplify(hdotcheckqfunction(t12,t22,t32,t11,t21,t31,1,1,1,0,0,
0));
simplify(hdotcheckqfunction(t12,t22,t32,t11,t21,t31,0,0,0,1,1,
1));
simplify(hdotcheckqfunction(t12,t22,t32,t11,t21,t31,2*t12,2*
t22,2*t32,t11,t21,t31));
simplify(hdotcheckqfunction(t12,t22,t32,t11,t21,t31,0,0,0,t12,
t22,t32));
simplify(hdotcheckqfunction(t12,t22,t32,t11,t21,t31,2*(t12-t32)*
(t12-t22),0,0,t12*(3*t11-t21-t31)-(t12+t22+t32)*t11+ t22*t31+
t32*t21,0,0));
simplify(hdotcheckqfunction(t12,t22,t32,t11,t21,t31,0,2*(t22-
t12)*(t22-t32),0,0,t22*(3*t21-t11-t31)-(t12+t22+t32)*t21+t12*
t31+t32*t11,0));
simplify(hdotcheckqfunction(t12,t22,t32,t11,t21,t31,0,0,2*(t32-
t12)*(t32-t22),0,0,t32*(3*t31-t11-t21)-(t12+t22+t32)*t31+t12*
t21+t22*t11));
simplify(hdotcheckpfunction(t12,t22,t32,t11,t21,t31,1,1,1,0,0,
0));
simplify(hdotcheckpfunction(t12,t22,t32,t11,t21,t31,0,0,0,1,1,
1));
simplify(hdotcheckpfunction(t12,t22,t32,t11,t21,t31,2*t12,2*

```

```

t22,2*t32,t11,t21,t31));
simplify(hdotcheckpfunction(t12,t22,t32,t11,t21,t31,0,0,0,t12,
t22,t32));
simplify(hdotcheckpfunction(t12,t22,t32,t11,t21,t31,2*(t12-t32)
*(t12-t22),0,0,t12*(3*t11-t21-t31)-(t12+t22+t32)*t11+ t22*t31+
t32*t21,0,0));
simplify(hdotcheckpfunction(t12,t22,t32,t11,t21,t31,0,2*(t22-
t12)*(t22-t32),0,0,t22*(3*t21-t11-t31)-(t12+t22+t32)*t21+t12*
t31+t32*t11,0));
simplify(hdotcheckpfunction(t12,t22,t32,t11,t21,t31,0,0,2*(t32-
t12)*(t32-t22),0,0,t32*(3*t31-t11-t21)-(t12+t22+t32)*t31+t12*
t21+t22*t11));

```

(5.17)

```

> hdotcheckqtaufunction:=unapply(simplify(hdotcheckqfunction(t12,
t22,t32,t11,t21,t31,0,0,0,0,Coefft21,Coefft31)),q,p):
hdotcheckptaufunction:=unapply(simplify(hdotcheckpfunction(t12,
t22,t32,t11,t21,t31,0,0,0,0,Coefft21,Coefft31)),q,p):
hdotcheckqtaufunction2:=unapply(simplify(hdotcheckqtaufunction
(Solq,Solp)),t11,t21,t31,t12,t22,t32):
hdotcheckptaufunction2:=unapply(simplify(hdotcheckptaufunction
(Solq,Solp)),t11,t21,t31,t12,t22,t32):
hdotcheckqtau:=simplify(hdotcheckqtaufunction2(t11function,
t21function ,t31function ,t12function ,t22function ,
t32function));
hdotcheckptau:=simplify(hdotcheckptaufunction2(t11function,
t21function ,t31function ,t12function ,t22function ,
t32function));
simplify(hdotcheckqtau-Ltauchekq);

```

$$\begin{aligned}
& \text{simplify(hdotcheckptau-Ltauchekp)} ; \\
& \text{hdotcheckqtau} := \left(\sqrt{(-T3 - 2T5 + T1)(T3 - T5)(-2T3 - T5 + T1)} \left(\text{checkq} \left(\right. \right. \right. \right. \\
& \quad \left. \left. \left. \left. -2 \text{checkp} (-T3 - 2T5 + T1)(-2T3 - T5 \right. \right. \right. \right. \\
& \quad \left. \left. \left. \left. + T1) \sqrt{\frac{T3 - T5}{(-T3 - 2T5 + T1)(-2T3 - T5 + T1)}} \right. \right. \right. \right. \\
& \quad \left. \left. \left. \left. + \tau \sqrt{(-T3 - 2T5 + T1)(T3 - T5)(-2T3 - T5 + T1)} \right) \right. \right. \right. \right. \\
& \quad \left. \left. \left. \left. \sqrt{\frac{-T3 - 2T5 + T1}{(T3 - T5)(-2T3 - T5 + T1)}} + (-\text{checkq}^2 + t20)(-T3 - 2T5 + T1) \right) \right) \right) \Bigg) / \\
& \quad \left(\sqrt{\frac{-T3 - 2T5 + T1}{(T3 - T5)(-2T3 - T5 + T1)}} (-T3 - 2T5 + T1)(T3 - T5)(-2T3 - T5 \right. \\
& \quad \left. \left. \left. \left. + T1) \right) \right) \right. \\
& \text{hdotcheckptau} := \left(\left(2 \sqrt{\frac{T3 - T5}{(-T3 - 2T5 + T1)(-2T3 - T5 + T1)}} \text{checkp} \text{checkq} (T3 \right. \right. \right. \right. \\
& \quad \left. \left. \left. \left. - T5)(-2T3 - T5 + T1) \sqrt{\frac{-T3 - 2T5 + T1}{(T3 - T5)(-2T3 - T5 + T1)}} \right. \right. \right. \right. \\
& \quad \left. \left. \left. \left. - \sqrt{\frac{T3 - T5}{(-T3 - 2T5 + T1)(-2T3 - T5 + T1)}} \right. \right. \right. \right. \\
& \quad \left. \left. \left. \left. \sqrt{(-T3 - 2T5 + T1)(T3 - T5)(-2T3 - T5 + T1)} \text{checkp} \tau + (T3 - T5)(\text{checkp}^2 \right. \right. \right. \right. \\
& \quad \left. \left. \left. \left. + h - t20 - t30) \right) \sqrt{(-T3 - 2T5 + T1)(T3 - T5)(-2T3 - T5 + T1)} \right) \right) \Bigg) / \\
& \quad \left(\sqrt{\frac{T3 - T5}{(-T3 - 2T5 + T1)(-2T3 - T5 + T1)}} (-T3 - 2T5 + T1)(T3 - T5)(-2T3 \right. \\
& \quad \left. \left. \left. \left. - T5 + T1) \right) \right) \right. \\
& \quad \left. \left. \left. \left. 0 \right) \right. \right. \right. \right. \\
& \quad \left. \left. \left. \left. 0 \right) \right. \right. \right. \right.
\end{aligned}$$

```

> hdotcheckqtauValues:=unapply(hdotcheckqtau,T1,T2,T3,T4,T5):
hdotcheckptauValues:=unapply(hdotcheckptau,T1,T2,T3,T4,T5):
hdotcheckqtauFinal:=simplify(hdotcheckqtauValues(0,0,0,0,-1/2)):
;
hdotcheckptauFinal:=simplify(hdotcheckptauValues(0,0,0,0,-1/2)):
;
HamtaucheckCoordinatesTheo:=- (checkq*checkp^2+checkq^2*checkp-
tau*checkq*checkp-t20*checkp+(t10+h)*checkq);
simplify(hdotcheckqtauFinal-diff(HamtaucheckCoordinatesTheo,

```

```

checkp));
simplify(hdotcheckptauFinal+diff(HamtauchCoordinatesTheo,
checkq));

$$hdotcheckqtauFinal := -checkq^2 + (\tau - 2 checkp) checkq + t20 \quad (5.19)$$


$$hdotcheckptauFinal := checkp^2 + (-\tau + 2 checkq) checkp + h - t20 - t30$$


$$\begin{aligned} HamtauchCoordinatesTheo := & -checkq checkp^2 - checkq^2 checkp + \tau checkq checkp \\ & + t20 checkp - (h - t20 - t30) checkq \\ & 0 \\ & 0 \end{aligned}$$

=> S2:=1/sqrt(2)*sqrt(s12-s22);
S1:=1/sqrt(2)*(s11-s21)/sqrt(s12-s22);
tdX1function:=unapply(S2*X1+S1,s11,s21,s12,s22,X1);
RES:=unapply( simplify(series(simplify(tdX1function(t31/(t32-t22),t11/(t12-t22),-1/(t32-t22),-1/(t12-t22),t21) -1/sqrt(2)*taufunction(t11,t21,t31,t12,t22,t32)),t21)),t11,t21,t31,t12,t22,t32);
RES(2,4,3,-1,0,1);
RES(2,4,3,1,0,-1);
tdX1:=1/sqrt(2)*taufunction(t11,t21,t31,t12,t22,t32):

$$S2 := \frac{1}{2} \sqrt{2} \sqrt{s12 - s22} \quad (5.20)$$


$$S1 := \frac{1}{2} \frac{\sqrt{2} (s11 - s21)}{\sqrt{s12 - s22}}$$


$$tdX1function := (s11, s21, s12, s22, X1) \rightarrow \frac{1}{2} \sqrt{2} \sqrt{s12 - s22} X1 + \frac{1}{2} \frac{\sqrt{2} (s11 - s21)}{\sqrt{s12 - s22}}$$


$$\begin{aligned} RES := (t11, t21, t31, t12, t22, t32) \rightarrow & -\frac{1}{2} \left( \left( -(t22 - t32) (t12 - t22) \right. \right. \\ & - t22) \sqrt{\frac{t12 - t32}{(t22 - t32) (t12 - t22)}} + \sqrt{(t12 - t32) (t22 - t32) (t12 - t22)} \\ & \left. \left. (t22 (t11 - t31) + t31 t12 - t11 t32) \sqrt{2} \right) \right/ \\ & \left( \sqrt{\frac{t12 - t32}{(t22 - t32) (t12 - t22)}} \sqrt{(t12 - t32) (t22 - t32) (t12 - t22)} (t22 - t32) (t12 - t22) \right. \\ & \left. \left. - t22) \right) - \frac{1}{2} \left( (t12 - t32) \sqrt{2} \left( (t22 - t32) (t12 - t22) \right. \right. \\ & - t22) \sqrt{\frac{t12 - t32}{(t22 - t32) (t12 - t22)}} - \sqrt{(t12 - t32) (t22 - t32) (t12 - t22)} \right) \right) \right/ \\ & \left( \sqrt{\frac{t12 - t32}{(t22 - t32) (t12 - t22)}} \sqrt{(t12 - t32) (t22 - t32) (t12 - t22)} (t22 - t32) (t12 - t22) \right. \\ & \left. - t22) \right) t21 \\ & 0 \\ & 0 \end{aligned}$$


```

```

> R1:=unapply((sX10+sX20)/(xi-X1) -(s12+s22)*xi-s11-s21,xi);
checkqfunction(q,p);
checkqidfunction:=unapply(checkqfunction(p,q+t22*p),q,p):
checkqidfunction2:=unapply( checkqidfunction((checkq-S1)/S2,S2*
checkp+1/2*R1((checkq-S1)/S2)), s11,s21,s12,s22,X1,sX10,sX20):
simplify(series(checkqidfunction2(t31/(t32-t22),t11/(t12-t22),
-1/(t32-t22),-1/(t12-t22),t21,-s10-s20,0),checkq));
RES2:=unapply( simplify(series(checkqidfunction2(t31/(t32-t22),
t11/(t12-t22),-1/(t32-t22),-1/(t12-t22),t21,-s10-s20,0)-(-sqrt
(2)*(checkq-1/sqrt(2)*taufunction(t11,t21,t31,t12,t22,t32))),
checkq=0) ),t11,t21,t31,t12,t22,t32);
RES2(2,4,3,-1,0,1);
RES2(2,4,3,1,0,-1);

```

$$R1 := \xi \rightarrow \frac{sX10 + sX20}{\xi - X1} - (s12 + s22) \xi - s11 - s21 \quad (5.21)$$

$$\frac{\sqrt{\frac{t12 - t32}{(-t12 + t22)(-t22 + t32)}} (q t22 - p + t21)}{(t12 (-t21 + t31) + (-t11 + t21) t32 + t22 (t11 - t31)) \sqrt{\frac{t12 - t32}{(t22 - t32)(t12 - t22)}}}$$

$$-\sqrt{2} \, checkq$$

$$RES2 := (t11, t21, t31, t12, t22, t32) \rightarrow \left(\begin{array}{c} \left(\begin{array}{c} -\sqrt{\frac{t12 - t32}{(t22 - t32)(t12 - t22)}} \sqrt{(t12 - t32)(t22 - t32)(t12 - t22)} + t12 - t32 \\ (t12 (-t21 + t31) + (t21 - t11) t32 + t22 (t11 - t31)) \end{array} \right) \\ \left(\begin{array}{c} (\sqrt{(t12 - t32)(t22 - t32)(t12 - t22)} (t12 - t32)) \\ 0 \\ 0 \end{array} \right) \end{array} \right)$$

```

> checkqfunction(q,p);
checkpidfunction:=unapply(checkpfunction(p,q+t22*p),q,p):
checkpidfunction2:=unapply( checkpidfunction((checkq-S1)/S2,S2*
checkp+1/2*R1((checkq-S1)/S2)), s11,s21,s12,s22,X1,sX10,sX20):
checkpid:=simplify(series(checkpidfunction2(t31/(t32-t22),t11/
(t12-t22),-1/(t32-t22),-1/(t12-t22),t21,-s10-s20,0),checkp));

```

$$checkpidbis:=-1/sqrt(2)*(checkp- (s10+s20)/2/(checkq-tdX1)-
checkq);
simplify(series(simplify(series(simplify
(checkpid- checkpidbis),checkp),symbolic),checkq),symbolic);
\sqrt{\frac{t12 - t32}{(-t12 + t22)(-t22 + t32)}} (q t22 - p + t21) \quad (5.22)$$

$$\begin{aligned}
checkpidbis := & -\frac{1}{2} \sqrt{2} \left(checkp \right. \\
& - \frac{1}{2} \frac{s10 + s20}{checkq - \frac{1}{2} \frac{\sqrt{2} ((t21 - t31) t12 + (-t11 + t31) t22 + t32 (t11 - t21))}{\sqrt{(-t12 + t22) (t12 - t32) (-t22 + t32)}}} \\
& \left. - checkq \right) \\
& 0
\end{aligned}$$

We find that under the spectral identification:

$tdX1=1/sqrt(2)*tau$

$check\{q\}=-sqrt(2)*(check\{q\}-tdX1)$

$check\{p\}=-1/sqrt(2)*(checkp-(s10+s20)/2/(checkq-tdX1)-checkq)$

```

> HamtauchCoordinatesTheo:=unapply
  (HamtauchCoordinatesTheo,checkq,checkp,tau);
dtaufunction:=diff(taufunction(t11,t21,t31,t12,t22,t32),t11)*
dt11+diff(taufunction(t11,t21,t31,t12,t22,t32),t21)*dt21+diff
(taufunction(t11,t21,t31,t12,t22,t32),t31)*dt31+diff
(taufunction(t11,t21,t31,t12,t22,t32),t12)*dt12+diff
(taufunction(t11,t21,t31,t12,t22,t32),t22)*dt22+diff
(taufunction(t11,t21,t31,t12,t22,t32),t32)*dt32:
deltaHamtauchCoordinatesTheo:=unapply(diff
(HamtauchCoordinatesTheo,tau),checkq,checkp,tau):
OmegaHam:=unapply(HamtauchCoordinatesTheo(function(checkq,
checkp,tau)*dtaufunction,checkq,checkp,tau)):
OmegaR2:=unapply(-int(deltaHamtauchCoordinatesTheo(dtatau
(checkq(s),checkp(s),s),s=0..tau)*dtaufunction,checkq,checkp,
tau));
OmegaHambis:=simplify(OmegaHam(function(q,p),
checkpfunction(q,p),taufunction(t11,t21,t31,t12,t22,t32))):
OmegaHamNonReduced:=Hame11(q,p)*dt11+ Hame21(q,p)*dt21+Hame31
(q,p)*dt31+Hame12(q,p)*dt12+Hame22(q,p)*dt22+Hame32(q,p)*dt32:
HamtauchCoordinatesTheo:= (checkq,checkp,tau) → -checkq checkp2
- checkq2 checkp + checkq checkp τ + t20 checkp - (h - t20 - t30) checkq

```

(5.23)

$$\begin{aligned}
OmegaR2 := & (checkq,checkp,τ) → - \left(\int_0^\tau checkp(s) checkq(s) \right. \\
& ds \left. \right) \left(\frac{(-t22 + t32) dt11}{\sqrt{(-t12 + t22) (t12 - t32) (-t22 + t32)}} \right. \\
& + \left. \frac{(t12 - t32) dt21}{\sqrt{(-t12 + t22) (t12 - t32) (-t22 + t32)}} \right)
\end{aligned}$$

$$\begin{aligned}
& + \frac{(-t12 + t22) dt31}{\sqrt{(-t12 + t22) (t12 - t32) (-t22 + t32)}} \\
& + \left(\frac{t21 - t31}{\sqrt{(-t12 + t22) (t12 - t32) (-t22 + t32)}} \right. \\
& - \frac{1}{2} \frac{1}{((-t12 + t22) (t12 - t32) (-t22 + t32))^{3/2}} (((t21 - t31) t12 + (-t11 \\
& + t31) t22 + t32 (t11 - t21)) (- (t12 - t32) (-t22 + t32) + (-t12 + t22) (-t22 \\
& + t32))) dt12 + \left(\frac{-t11 + t31}{\sqrt{(-t12 + t22) (t12 - t32) (-t22 + t32)}} \right. \\
& - \frac{1}{2} \frac{1}{((-t12 + t22) (t12 - t32) (-t22 + t32))^{3/2}} (((t21 - t31) t12 + (-t11 \\
& + t31) t22 + t32 (t11 - t21)) ((t12 - t32) (-t22 + t32) - (-t12 + t22) (t12 \\
& - t32))) dt22 + \left(\frac{t11 - t21}{\sqrt{(-t12 + t22) (t12 - t32) (-t22 + t32)}} \right. \\
& - \frac{1}{2} \frac{1}{((-t12 + t22) (t12 - t32) (-t22 + t32))^{3/2}} (((t21 - t31) t12 + (-t11 \\
& + t31) t22 + t32 (t11 - t21)) (- (-t12 + t22) (-t22 + t32) + (-t12 + t22) (t12 \\
& - t32))) dt32) \\
> & \text{simplify}(\text{residue}(\text{simplify}(\text{OmegaHambis})/\text{dt11}^2, \text{dt11}=0), \text{symbolic}) \\
& ; \\
& \text{simplify}(\text{Hame11}(q, p)); \\
& \text{simplify}(\text{series}(\text{simplify}(\text{simplify}(\text{residue}(\text{simplify}(\text{OmegaHambis}) \\
& /\text{dt11}^2, \text{dt11}=0), \text{symbolic}) - (-\text{Hame11}(q, p) - h*(p - t22*q)/(t12 - \\
& t22) + h*t21/(t12 - t22) - t11*t21*t31/((t12 - t32)*(t12 - t22)) + (-t12 * \\
& t21 + (-t11 + t21)*t32 + t11*t22)*t20/((t12 - t32)*(t12 - t22)) - t21* \\
& t30/(t12 - t22)), \text{t30}=0)); \\
& \frac{1}{(t12 - t22) (-t12 + t32)} (-p^3 + (t11 + t21 + t31 + (t12 + t22 + t32) q) p^2 + ((-t22 \\
& - t32) t12 - t22 t32) q^2 + ((-t21 - t11) t32 + (-t31 - t21) t12 - t22 (t11 + t31)) q \\
& + (h - t20 - t30) t12 + (-h + t30) t32 + t20 t22 + (-t11 - t31) t21 - t11 t31) p \\
& + q^3 t12 t22 t32 + ((t21 t32 + t22 t31) t12 + t22 t32 t11) q^2 + ((t20 t32 + (-h \\
& + t30) t22 + t21 t31) t12 + ((h - t20 - t30) t22 + t11 t21) t32 + t22 t11 t31) q \\
& - t21 (h - t20 - t30) t12 + (t21 (h - t20 - t30) + t11 t20) t32 + t11 (-t20 t22 \\
& + t21 t31)) \\
& \frac{1}{(-t12 + t32) (t12 - t22)} (p^3 + ((-t12 - t22 - t32) q - t31 - t11 - t21) p^2 + ((t22 \\
& + t32) t12 + t22 t32) q^2 + (t12 (t21 + t31) + t22 (t11 + t31) + t32 (t11 + t21)) q \\
& + (t20 + t30) t12 - t20 t22 - t30 t32 + t11 (t21 + t31) + t21 t31) p \\
& - q (q^2 t12 t22 t32 + ((t21 t32 + t22 t31) t12 + t22 t32 t11) q + (t20 t32 + t21 t31 \\
& + t22 t30) t12 + ((-t20 - t30) t32 + t11 t31) t22 + t32 t11 t21)) \\
& 0 \\
> & \text{simplify}(\text{residue}(\text{simplify}(\text{OmegaHambis})/\text{dt21}^2, \text{dt21}=0), \text{symbolic})
\end{aligned} \tag{5.24}$$

```

;
simplify(Hame21(q,p));
simplify(series(simplify(residue(simplify(OmegaHambis)/dt21^2,
dt21=0),symbolic) -( -Hame21(q,p) +h*(p-t12*q)/(t12-t22) ) ,q=0)
);

$$\frac{1}{(t12 - t22)(-t22 + t32)} \left( p^3 + ((-t12 - t22 - t32) q - t31 - t11 - t21) p^2 + (((t12 + t22) t32 + t12 t22) q^2 + (t12 (t21 + t31) + t22 (t11 + t31) + t32 (t11 + t21)) q + (h - t30) t32 + (-h + t20 + t30) t12 - t20 t22 + (t11 + t31) t21 + t11 t31) p - q^3 t12 t22 t32 + ((-t11 t22 - t12 t21) t32 - t31 t12 t22) q^2 + ((-t20 t12 + (-h + t20 + t30) t22 - t11 t21) t32 + ((h - t30) t22 - t21 t31) t12 - t22 t11 t31) q + ((-h + t20 + t30) t21 - t11 t20) t32 + t21 (h - t20 - t30) t12 - t11 (-t20 t22 + t21 t31)) \right) \quad (5.25)$$


$$\frac{1}{(t12 - t22)(-t22 + t32)} \left( -p^3 + (t11 + t21 + t31 + (t12 + t22 + t32) q) p^2 + (((-t12 - t32) t22 - t12 t32) q^2 + ((-t31 - t21) t12 + (-t11 - t31) t22 - t32 (t11 + t21)) q + (-h + t20) t22 + (h - t20 - t30) t12 + t30 t32 + (-t31 - t21) t11 - t21 t31) p - (-q^2 t12 t22 t32 + ((-t11 t32 - t12 t31) t22 - t12 t21 t32) q + (-t12 t30 + (-h + t20 + t30) t32 - t11 t31) t22 + ((h - t20) t32 - t21 t31) t12 - t32 t11 t21) q) \right) \frac{((h - t20 - t30) t32 + (-h + t20 + t30) t12 + t11 t31) t21 - t11 t20 (t22 - t32)}{(t22 - t32) (t12 - t22)}$$

> simplify(residue(simplify(OmegaHambis)/dt31^2,dt31=0),symbolic)
;
simplify(Hame31(q,p));
simplify(series(simplify(residue(simplify(simplify(OmegaHambis)/dt31^2,
dt31=0),symbolic) -( -Hame31(q,p) ) ,q=0));

$$\frac{1}{(-t22 + t32)(-t12 + t32)} \left( p^3 + ((-t12 - t22 - t32) q - t31 - t11 - t21) p^2 + (((t12 + t22) t32 + t12 t22) q^2 + (t12 (t21 + t31) + t22 (t11 + t31) + t32 (t11 + t21)) q + (h - t30) t32 + (-h + t20 + t30) t12 - t20 t22 + (t11 + t31) t21 + t11 t31) p - q^3 t12 t22 t32 + ((-t11 t22 - t12 t21) t32 - t31 t12 t22) q^2 + ((-t20 t12 + (-h + t20 + t30) t22 - t11 t21) t32 + ((h - t30) t22 - t21 t31) t12 - t22 t11 t31) q + ((-h + t20 + t30) t21 - t11 t20) t32 + t21 (h - t20 - t30) t12 - t11 (-t20 t22 + t21 t31)) \right) \quad (5.26)$$


$$\frac{1}{(-t22 + t32)(-t12 + t32)} \left( -p^3 + (t11 + t21 + t31 + (t12 + t22 + t32) q) p^2 + (((-t12 - t22) t32 - t12 t22) q^2 + ((-t21 - t11) t32 + (-t31 - t21) t12 - t22 (t11 + t31)) q + (-h + t30) t32 + (h - t20 - t30) t12 + t20 t22 + (-t31 - t21) t11 - t21 t31) p + q (q^2 t12 t22 t32 + ((t11 t22 + t12 t21) t32 + t31 t12 t22) q + (t20 t12 + (h - t20 - t30) t22 + t11 t21) t32 + ((-h + t30) t22 + t21 t31) t12 + t22 t11 t31) \right) \frac{((-h + t20 + t30) t32 + (h - t20 - t30) t12 - t11 t31) t21 + t11 t20 (t22 - t32)}{(t22 - t32) (t12 - t22)}$$

> simplify(residue(simplify(OmegaHambis)/dt12^2,dt12=0),symbolic)
:
simplify(Hame12(q,p));

```

```

simplify(series(simplify(residue(simplify(OmegaHambis)/dt12^2,
dt12=0),symbolic) - ( -Hame12(q,p) -(1/2)*h*p^2/((t12-t22)*(t12-
t32)) - (1/2)*(-q*t22^2+(q*t12-q*t32-t11-t21)*t22+(q*t32+2*
t11)*t12-t32*(t11-t21))*h/((t12-t22)^2*(t12-t32))*p +(1/2)*h*
t22*t32*q^2/((t12-t22)*(t12-t32)) +(((t11-(1/2)*t21)*t22+
(1/2)*t32*t21)*t12-(1/2)*t11*t22*(t22+t32))*h*q/((t12-t22)^2*
(t12-t32)),q=0));
- 
$$\frac{1}{(t12-t32)^2 (t12-t22)^2} \left( (((-h+t20+t30) t32 + (h-t20-t30) t12 - t11 t31) t21 \quad (5.27) \right. \\
\left. + t11 t20 (t22-t32)) \left( \left( -\frac{1}{2} t12 + \frac{1}{2} t32 \right) t21 + \left( t11 - \frac{1}{2} t31 \right) t12 - \frac{1}{2} t11 t32 \right. \\
\left. - \frac{1}{2} t22 (t11-t31) \right) \right)$$

> simplify(residue(simplify(OmegaHambis)/dt32^2,dt32=0),symbolic);
:
simplify(Hame32(q,p));
simplify(series(simplify(residue(simplify(OmegaHambis)/dt32^2,
dt32=0),symbolic) - ( -Hame32(q,p)
- (1/2)*h*p^2/((t22-t32)*(t12-t32))+(1/2)*((t12+t22)*q+t11+t21)*
h*p/((t22-t32)*(t12-t32))-(1/2)*h*t12*t22*q^2/((t22-t32)*(t12-
t32))-(1/2)*h*(t11*t22+t12*t21)*q/((t22-t32)*(t12-t32))
),q=0));
- 
$$\frac{1}{2} \frac{1}{(t22-t32)^2 (t12-t32)^2} (((t12-t32) t21 + (-t11+2 t31) t32 + (-t12 \quad (5.28) \right. \\
\left. - t22) t31 + t11 t22) (((-h+t20+t30) t32 + (h-t20-t30) t12 - t11 t31) t21 \right. \\
\left. + t11 t20 (t22-t32))) \right)$$


```

We do not care about the term only proportional to times. Thus, we find OmegaHambis= - Hame11 -h*(p-t22*q-t21)/(t12-t22) +times

```

> simplify(checkqfunction(q,p)*checkpfunction(q,p));
checkqcheckpbis:=-1/(t12-t22)*(p^2- ((t12+t22)*q+(t11+t21))*p
+(t12*q+t11)*(t22*q+t21));
series(simplify(simplify(checkqfunction(q,p)*checkpfunction(q,
p),symbolic)- checkqcheckpbis),q=0);
- 
$$\sqrt{\frac{t12-t32}{(t22-t32)(t12-t22)}} (-q t22+p-t21) \sqrt{\frac{t22-t32}{(t12-t32)(t12-t22)}} (-q t12 \quad (5.29) \right. \\
\left. +p-t11)
checkqcheckpbis := - \frac{p^2 - ((t12+t22) q + t11 + t21) p + (q t12 + t11) (q t22 + t21)}{t12 - t22}
0$$

> diff(checkqcheckpbis,t11);
diff(checkqcheckpbis,t21);
diff(checkqcheckpbis,t31);
- 
$$\frac{q t22 - p + t21}{t12 - t22} \quad (5.30)$$


```

$$-\frac{q t12 - p + t11}{t12 - t22}$$

0

Expression of the Lax matrix in the coordinates (checkq,checkp)

```

> tdL21functioninter:=unapply(tdL[2,1],q,p);
tdL21function:=unapply(simplify(tdL21functioninter(Solq,Solp)),
t11,t21,t31,t12,t22,t32):
tdL21check:=unapply(1/a12*(t22-t12)*(-checkq*checkp-checkq^2+
tau*checkq+t20),tau):
simplify(series(tdL21check(taufunction(t11,t21,t31,t12,t22,t32)
)-tdL21function(t11,t21,t31,t12,t22,t32),checkp=0),symbolic);

tdL23functioninter:=unapply(tdL[2,3],q,p);
tdL23function:=unapply(simplify(tdL23functioninter(Solq,Solp)),
t11,t21,t31,t12,t22,t32):
tdL23check:=unapply(-a13/a12*sqrt(t32-t22)*sqrt(t22-t12)/sqrt
(t12-t32)*checkq,tau):
simplify(series(tdL23check(taufunction(t11,t21,t31,t12,t22,t32)
)-tdL23function(t11,t21,t31,t12,t22,t32),checkp=0),symbolic);

tdL31functioninter:=unapply(tdL[3,1],q,p);
tdL31function:=unapply(simplify(tdL31functioninter(Solq,Solp)),
t11,t21,t31,t12,t22,t32):
tdL31check:=unapply( 1/a13*(t12-t32)*(-checkq*checkp-checkq^2+
tau*checkq-t30) ,tau):
simplify(series(tdL31check(taufunction(t11,t21,t31,t12,t22,t32)
)-tdL31function(t11,t21,t31,t12,t22,t32),checkp=0),symbolic);

tdL32functioninter:=unapply(tdL[3,2],q,p);
tdL32function:=unapply(simplify(tdL32functioninter(Solq,Solp)),
t11,t21,t31,t12,t22,t32):
tdL32check:=unapply( a12/a13*sqrt(t12-t32)*sqrt(t32-t22)/sqrt
(t22-t12)*(checkp+1*checkq+1*tau) ,tau):
simplify(series(simplify(series(tdL32check(taufunction(t11,t21,
t31,t12,t22,t32))-tdL32function(t11,t21,t31,t12,t22,t32),
checkp=0),symbolic),checkq=0),symbolic);

tdL21functioninter := (q,p) →  $\frac{1}{a12 (t22 - t32)} \left( (t12 - t22) ((q^2 t32 - p q + q t31) - t20) t22 + (-p q + q t21 + t20) t32 + (p - t31) (p - t21) \right)$  0 |

(5.31)

-\frac{a13 (-q t22 + p - t21)}{a12}
 0 |
```

$$\begin{aligned}
tdL31functioninter &:= (q, p) \rightarrow -\frac{1}{a_{13} (t_{22} - t_{32})} ((t_{12} - t_{32}) ((q^2 t_{22} - p q + q t_{21} \\
&\quad - t_{30}) t_{32} + (-p q + q t_{31} + t_{30}) t_{22} + (p - t_{31}) (p - t_{21})) \\
tdL32functioninter &:= (q, p) \rightarrow -\frac{a_{12} (-q t_{32} + p - t_{31})}{a_{13}} \\
&\quad - \frac{2 (t_{22} (t_{11} - t_{31}) + t_{12} (-t_{21} + t_{31}) - t_{32} (t_{11} - t_{21})) a_{12}}{a_{13} (t_{12} - t_{22})} \\
&\quad - \frac{2 a_{12} \sqrt{t_{12} - t_{32}} \sqrt{-t_{22} + t_{32}}}{a_{13} \sqrt{-t_{12} + t_{22}}} checkq
\end{aligned}$$

> GeneralSpectralCurve := simplify(Determinant(y*IdentityMatrix(3) - tdL)):
GeneralSpectralCurvebis := y^3 - P1(lambda)*y^2 + P2(lambda)*y - P3
(lambda) - (p^3 - P1(q)*p^2 + P2(q)*p - P3(q)):
simplify(series(simplify
(GeneralSpectralCurve - GeneralSpectralCurvebis), y=0));

0 (5.32)

▼ Definition of the auxiliary matrix A by gauge transformation of \td{A} and verification of the compatibility equation in the oper gauge. Verification of the gauge transformations

```

> LalphaG:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do
  LalphaG[i,j]:=simplify( h*diff(G[i,j],t12)*dott12+h*diff(G[i,
j],t22)*dott22+h*diff(G[i,j],t32)*dott32+h*diff(G[i,j],t11)*
dott11+h*diff(G[i,j],t21)*dott21+h*diff(G[i,j],t31)*dott31+h*
diff(G[i,j],a12)*dota12+h*diff(G[i,j],a13)*dota13+ h*diff(G[i,
j],q)*dotq+h*diff(G[i,j],p)*dotp): od: od:

LalphatdL:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do
  LalphatdL[i,j]:=simplify( h*diff(tdL[i,j],t12)*dott12+h*diff
(tdL[i,j],t22)*dott22+h*diff(tdL[i,j],t32)*dott32+h*diff(tdL[i,
j],t11)*dott11+h*diff(tdL[i,j],t21)*dott21+h*diff(tdL[i,j],t31)
*dott31+h*diff(tdL[i,j],a12)*dota12+h*diff(tdL[i,j],a13)*
dota13+ h*diff(tdL[i,j],q)*dotq+h*diff(tdL[i,j],p)*dotp): od:
od:

LalphaLnew:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do
  LalphaLnew[i,j]:=simplify( h*diff(Lnew[i,j],t12)*dott12+h*diff
(Lnew[i,j],t22)*dott22+h*diff(Lnew[i,j],t32)*dott32+h*diff

```



```

> A:=simplify( Multiply(Multiply(G,tdA),G^(-1))+Multiply(LalphaG,
G^(-1)) ):
dAdlambda:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do dAdlambda[i,j]:=diff
(A[i,j],lambda): od: od:
> Verification3:= simplify(A- ( Multiply(Multiply(G,tdA),G^(-1))
+Multiply(LalphaG,G^(-1)))):
Verification4:=simplify(h*dAdlambda-LalphaL- Multiply(L,A) +
Multiply(A,L)) ;
Verification4bis:=simplify( LalphaL-h*dAdlambda- (Multiply(A,L)) -
Multiply(L,A)) );

```

$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad (6.2)$$

```

> dAnewdlambda:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do dAnewdlambda[i,j]:=diff
(Anew[i,j],lambda): od: od:

Verification5:= simplify(Anew- ( Multiply(Multiply
(Gnormalized,tdA),Gnormalized^(-1))+Multiply(LGnormalized,
Gnormalized^(-1)))):
Verification6:=simplify(h*dAnewdlambda-LalphaLnew- Multiply
(Lnew,Anew)+Multiply(Anew,Lnew)) ;

```

$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad (6.3)$$

Expression of the auxiliary matrices in the various directions of deformations

```

> tdAfunction[1,1]:=unapply(tdA[1,1],dott12,dott22,dott32,dott11,
dott21,dott31):
tdAfunction[1,2]:=unapply(tdA[1,2],dott12,dott22,dott32,dott11,
dott21,dott31):
tdAfunction[1,3]:=unapply(tdA[1,3],dott12,dott22,dott32,dott11,
dott21,dott31):
tdAfunction[2,1]:=unapply(tdA[2,1],dott12,dott22,dott32,dott11,
dott21,dott31):
tdAfunction[2,2]:=unapply(tdA[2,2],dott12,dott22,dott32,dott11,
dott21,dott31):
tdAfunction[2,3]:=unapply(tdA[2,3],dott12,dott22,dott32,dott11,
dott21,dott31):
tdAfunction[3,1]:=unapply(tdA[3,1],dott12,dott22,dott32,dott11,
dott21,dott31):
tdAfunction[3,2]:=unapply(tdA[3,2],dott12,dott22,dott32,dott11,
dott21,dott31):
tdAfunction[3,3]:=unapply(tdA[3,3],dott12,dott22,dott32,dott11,
dott21,dott31):

Afunction[1,1]:=unapply(A[1,1],dott12,dott22,dott32,dott11,
dott21,dott31):
Afunction[1,2]:=unapply(A[1,2],dott12,dott22,dott32,dott11,
dott21,dott31):
Afunction[1,3]:=unapply(A[1,3],dott12,dott22,dott32,dott11,
dott21,dott31):
Afunction[2,1]:=unapply(A[2,1],dott12,dott22,dott32,dott11,
dott21,dott31):
Afunction[2,2]:=unapply(A[2,2],dott12,dott22,dott32,dott11,
dott21,dott31):
Afunction[2,3]:=unapply(A[2,3],dott12,dott22,dott32,dott11,
dott21,dott31):
Afunction[3,1]:=unapply(A[3,1],dott12,dott22,dott32,dott11,
dott21,dott31):
Afunction[3,2]:=unapply(A[3,2],dott12,dott22,dott32,dott11,
dott21,dott31):
Afunction[3,3]:=unapply(A[3,3],dott12,dott22,dott32,dott11,
dott21,dott31):

Anewfunction[1,1]:=unapply(Anew[1,1],dott12,dott22,dott32,
dott11,dott21,dott31):
Anewfunction[1,2]:=unapply(Anew[1,2],dott12,dott22,dott32,
dott11,dott21,dott31):

```

```

Anewfunction[1,3]:=unapply(Anew[1,3],dott12,dott22,dott32,
dott11,dott21,dott31):
Anewfunction[2,1]:=unapply(Anew[2,1],dott12,dott22,dott32,
dott11,dott21,dott31):
Anewfunction[2,2]:=unapply(Anew[2,2],dott12,dott22,dott32,
dott11,dott21,dott31):
Anewfunction[2,3]:=unapply(Anew[2,3],dott12,dott22,dott32,
dott11,dott21,dott31):
Anewfunction[3,1]:=unapply(Anew[3,1],dott12,dott22,dott32,
dott11,dott21,dott31):
Anewfunction[3,2]:=unapply(Anew[3,2],dott12,dott22,dott32,
dott11,dott21,dott31):
Anewfunction[3,3]:=unapply(Anew[3,3],dott12,dott22,dott32,
dott11,dott21,dott31):

```

Specialisation in different directions of the tangent space. We also assume from now on that $a_{\{1,2\}}$ and $a_{\{1,3\}}$ are independent to the irregular times

```

> tdA110:=0:
dota12:=0;
dota13:=0;

tdAvinfy1:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do tdAvinfy1[i,j]:=simplify(tdAfunction[i,j](0,0,0,1,1,1)): od: od:
tdAvinfy2:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do tdAvinfy2[i,j]:=simplify(tdAfunction[i,j](1,1,1,0,0,0)): od: od:
tdAuinfy1:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do tdAuinfy1[i,j]:=simplify(tdAfunction[i,j](0,0,0,t12,t22,t32)): od: od:
tdAuinfy2:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do tdAuinfy2[i,j]:=simplify(tdAfunction[i,j](2*t12,2*t22,2*t32,t11,t21,t31)): od: od:
tdAa1:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do tdAa1[i,j]:= simplify(tdAfunction[i,j](2*(t12-t32)*(t12-t22),0,0,t12*(3*t11-t21-t31)-(t12+t22+t32)*t11+ t22*t31+t32*t21,0,0)): od: od:
tdAa2:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do tdAa2[i,j]:= simplify(tdAfunction[i,j](0,2*(t22-t12)*(t22-t32),0,0,t22*(3*t21-t11-t31)- (t12+t22+t32)*t21+t12*t31+t32*t11,0)): od: od:

```

```

tdAa3:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do tdAa3[i,j]:= simplify
(tdAfunction[i,j](0,0,2*(t32-t12)*(t32-t22),0,0,t32*(3*t31-t11-
t21)- (t12+t22+t32)*t31+t12*t21+t22*t11)): od: od:
tdAe11:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do tdAe11[i,j]:= simplify(tdAfunction[i,j](0,0,0,1,0,0)): od: od:
tdAe21:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do tdAe21[i,j]:= simplify(tdAfunction[i,j](0,0,0,0,1,0)): od: od:
tdAe31:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do tdAe31[i,j]:= simplify(tdAfunction[i,j](0,0,0,0,0,1)): od: od:

tdAe12:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do tdAe12[i,j]:= simplify(tdAfunction[i,j](1,0,0,0,0,0)): od: od:
tdAe22:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do tdAe22[i,j]:= simplify(tdAfunction[i,j](0,1,0,0,0,0)): od: od:
tdAe32:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do tdAe32[i,j]:= simplify(tdAfunction[i,j](0,0,1,0,0,0)): od: od:

tdAtau:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do tdAtau[i,j]:= simplify(tdAfunction[i,j](0,0,0,0,Coefftau,-Coefftau)): od: od:

Anewe2:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do Anewe2[i,j]:= simplify(Anewfunction[i,j](0,0,0,0,1,0)): od: od:

dtdAtaudlambda:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do dtdAtaudlambda[i,j]:= diff(tdAtau[i,j],lambda): od: od:

dtdAe31dlambda:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do dtdAe31dlambda[i,j]:= diff(tdAe31[i,j],lambda): od: od:

dtdAe21dlambda:=Matrix(3,3,0):

```

```

for i from 1 to 3 do for j from 1 to 3 do dtdAe21dlambda[i,j]:=  

diff(tdAe21[i,j],lambda): od: od:

dtdAnewdlambda:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do dtdAnewdlambda[i,j]:=  

diff(Anewe2[i,j],lambda): od: od:

Avinfy1:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do Avinfy1[i,j]:=  

simplify(Afunction[i,j](0,0,0,1,1,1)): od: od:
Avinfy2:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do Avinfy2[i,j]:=  

simplify(Afunction[i,j](1,1,1,0,0,0)): od: od:
Auinfy1:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do Auinfy1[i,j]:=  

simplify(Afunction[i,j](0,0,0,t12,t22,t32)): od: od:
Auinfy2:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do Auinfy2[i,j]:=  

simplify(Afunction[i,j](2*t12,2*t22,2*t32,t11,t21,t31)): od:  

od:
Aa1:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do Aa1[i,j]:= simplify  

(Afunction[i,j](2*(t12-t32)*(t12-t22),0,0,t12*(3*t11-t21-t31)-  

(t12+t22+t32)*t11+ t22*t31+t32*t21,0,0)): od: od:
Aa2:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do Aa2[i,j]:= simplify  

(Afunction[i,j](0,2*(t22-t12)*(t22-t32),0,0,t22*(3*t21-t11-t31)  

- (t12+t22+t32)*t21+t12*t31+t32*t11,0)): od: od:
Aa3:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do Aa3[i,j]:= simplify  

(Afunction[i,j](0,0,2*(t32-t12)*(t32-t22),0,0,t32*(3*t31-t11-  

t21)- (t12+t22+t32)*t31+t12*t21+t22*t11)): od: od:
Ae11:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do Ae11[i,j]:= simplify  

(Afunction[i,j](0,0,0,1,0,0)): od: od:
Ae21:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do Ae21[i,j]:= simplify  

(Afunction[i,j](0,0,0,0,1,0)): od: od:
Ae31:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do Ae31[i,j]:= simplify  

(Afunction[i,j](0,0,0,0,0,1)): od: od:

```

```

Ae12:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do Ae12[i,j]:= simplify
(Afunction[i,j](1,0,0,0,0,0)): od: od:
Ae22:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do Ae22[i,j]:= simplify
(Afunction[i,j](0,1,0,0,0,0)): od: od:
Ae32:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do Ae32[i,j]:= simplify
(Afunction[i,j](0,0,1,0,0,0)): od: od:

Atau:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do Atau[i,j]:= simplify
(Afunction[i,j](0,0,0,0,Coefftau,-Coefftau)): od: od:

dAtaudlambd:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do dAtaudlambd[i,j]:=
diff(Atau[i,j],lambda): od: od:

dAe31dlambd:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do dAe31dlambd[i,j]:=
diff(Ae31[i,j],lambda): od: od:

dAe21dlambd:=Matrix(3,3,0):
for i from 1 to 3 do for j from 1 to 3 do dAe21dlambd[i,j]:=
diff(Ae21[i,j],lambda): od: od:

```

$$\begin{aligned} dotal2 &:= 0 \\ dotal3 &:= 0 \end{aligned} \tag{7.1}$$

```

> tdAvinfy1;
tdAvinfy2;
tdAuinfy1:
tdAuinfy2:
tdAe11:
tdAe21:
tdAe31:
tdAa1:
tdAa2:
tdAa3:

tdAtau:

```

$$\begin{bmatrix} \lambda & 0 & 0 \\ 0 & \lambda & 0 \\ 0 & 0 & \lambda \end{bmatrix} \quad (7.2)$$

$$\begin{bmatrix} \frac{1}{2} \lambda^2 & 0 & 0 \\ 0 & \frac{1}{2} \lambda^2 & 0 \\ 0 & 0 & \frac{1}{2} \lambda^2 \end{bmatrix}$$

```
> simplify(series(tdAa2[1,1],lambda)) :
simplify(series(tdAa2[1,2],lambda)) :
simplify(series(tdAa2[1,3],lambda)) :
simplify(series(tdAa2[2,1],lambda)) :
simplify(series(tdAa2[2,2],lambda)) :
simplify(series(tdAa2[2,3],lambda)) :
simplify(series(tdAa2[3,1],lambda)) :
simplify(series(tdAa2[3,2],lambda)) :
simplify(series(tdAa2[3,3],lambda)) :
```

Verification for direction ∂_{τ} and $\partial_{e_{31}}$ and $\partial_{e_{21}}$

```
> LalphatautdL:=Matrix(3,3,0) :
for i from 1 to 3 do for j from 1 to 3 do
LalphatdLfunction:=unapply(LalphatdL[i,j],dott12,dott22,dott32,
dott11,dott21,dott31) :
LalphatautdL[i,j]:=simplify(LalphatdLfunction(0,0,0,0,
Coefftau,-Coefftau)) : od: od:

Lalphe31tdL:=Matrix(3,3,0) :
for i from 1 to 3 do for j from 1 to 3 do
LalphatdLfunction:=unapply(LalphatdL[i,j],dott12,dott22,dott32,
dott11,dott21,dott31) :
Lalphe31tdL[i,j]:=simplify(LalphatdLfunction(0,0,0,0,0,1)) :
od: od:

Lalphe21tdL:=Matrix(3,3,0) :
for i from 1 to 3 do for j from 1 to 3 do
LalphatdLfunction:=unapply(LalphatdL[i,j],dott12,dott22,dott32,
dott11,dott21,dott31) :
Lalphe21tdL[i,j]:=simplify(LalphatdLfunction(0,0,0,0,1,0)) :
od: od:
```


$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Canonical choice of trivial times: $t12:=1/2$, $t22=0$, $t32=-1/2$, $t11=0$ and $t31=-t21$ and $t21=1/3*\tau$

```

> TT1(0,1/3*tau,-1/3*tau,1/2,0,-1/2);
TT2(0,1/3*tau,-1/3*tau,1/2,0,-1/2);
TT3(0,1/3*tau,-1/3*tau,1/2,0,-1/2);
TT4(0,1/3*tau,-1/3*tau,1/2,0,-1/2);
TT5(0,1/3*tau,-1/3*tau,1/2,0,-1/2);
simplify(taufunction(0,1/3*tau,-1/3*tau,1/2,0,-1/2));

partialtaufunction:=unapply(partialtau,t11,t21,t31,t12,t22,t32)
:
simplify(partialtaufunction(0,1/3*tau,-1/3*tau,1/2,0,-1/2));

checkqfunctionT:=unapply(checkqfunction(q,p),t11,t21,t31,t12,
t22,t32);
simplify(checkqfunctionT(0,1/3*tau,-1/3*tau,1/2,0,-1/2));
checkpfunctionT:=unapply(checkpfunction(q,p),t11,t21,t31,t12,
t22,t32);
simplify(checkpfunctionT(0,1/3*tau,-1/3*tau,1/2,0,-1/2));
solve({-2*p+2*tau*(1/3)=checkq,-(1/2)*q+p=checkp},{q,p});

```

(8.1)

$$\begin{aligned}
& 0 \\
& 0 \\
& 0 \\
& 0 \\
& -\frac{1}{2} \\
& \tau \\
& \frac{1}{3} \partial_{t21} - \frac{1}{3} \partial_{t31} \\
& \text{checkqfunctionT} := (t11, t21, t31, t12, t22, t32) \rightarrow \sqrt{\frac{t12 - t32}{(-t12 + t22)(-t22 + t32)}} (q t22 \\
& - p + t21) \\
& -2 p + \frac{2}{3} \tau \\
& \text{checkpfunctionT} := (t11, t21, t31, t12, t22, t32) \rightarrow \sqrt{\frac{-t22 + t32}{(-t12 + t22)(t12 - t32)}} (-q t12 \\
& + p - t11)
\end{aligned}$$

$$\begin{aligned}
 & -\frac{1}{2} q + p \\
 & \left\{ p = \frac{1}{3} \tau - \frac{1}{2} \text{check}_q, q = \frac{2}{3} \tau - \text{check}_q - 2 \text{check}_p \right\} \\
 > \text{a12:=1;} & a12 := 1 \\
 > \text{a13:=1;} & a13 := 1 \\
 > \text{t12:=1/2;} & t12 := \frac{1}{2} \\
 > \text{t22:=0;} & t22 := 0 \\
 > \text{t32:=-1/2;} & t32 := -\frac{1}{2} \\
 > \text{t11:=0;} & t11 := 0 \\
 > \text{t31:=-t21;} & t31 := -t21 \\
 > \text{t21:=1/3*tau;} & t21 := \frac{1}{3} \tau \tag{8.2} \\
 \\
 > \text{tdL[1,1];} & \frac{1}{2} \lambda \\
 > \text{tdL[2,2];} & \frac{1}{3} \tau \\
 > \text{tdL[3,3];} & -\frac{1}{2} \lambda - \frac{1}{3} \tau \\
 > \text{tdL21check(tau);} & \frac{1}{2} \text{check}_p \text{check}_q + \frac{1}{2} \text{check}_q^2 - \frac{1}{2} \text{check}_q \tau - \frac{1}{2} t20 \\
 > \text{tdL23check(tau);} & \frac{1}{2} \text{check}_q \\
 > \text{tdL31check(tau);} & -\text{check}_p \text{check}_q - \text{check}_q^2 + \text{check}_q \tau - t30 \\
 > \text{tdL32check(tau);} & \text{check}_p + \text{check}_q + \tau \tag{8.3} \\
 \\
 > \text{Coefftau:=simplify(Coefft21);} \\
 > \text{tdAtau:=simplify(tdAtau);} \\
 > \text{tdAtau1function:=unapply(tdAtau[1,1],q,p):}
 \end{aligned}$$

```

tdAtau11:=simplify(tdAtau11function(2*tau*(1/3)-checkq-2*
checkp,(1/3)*tau-(1/2)*checkq));
tdAtau12function:=unapply(tdAtau[1,2],q,p):
tdAtau12:=simplify(tdAtau12function(2*tau*(1/3)-checkq-2*
checkp,(1/3)*tau-(1/2)*checkq));
tdAtau13function:=unapply(tdAtau[1,3],q,p):
tdAtau13:=simplify(tdAtau13function(2*tau*(1/3)-checkq-2*
checkp,(1/3)*tau-(1/2)*checkq));
tdAtau21function:=unapply(tdAtau[2,1],q,p):
tdAtau21:=simplify(tdAtau21function(2*tau*(1/3)-checkq-2*
checkp,(1/3)*tau-(1/2)*checkq));
tdAtau22function:=unapply(tdAtau[2,2],q,p):
tdAtau22:=simplify(tdAtau22function(2*tau*(1/3)-checkq-2*
checkp,(1/3)*tau-(1/2)*checkq));
tdAtau23function:=unapply(tdAtau[2,3],q,p):
tdAtau23:=simplify(tdAtau23function(2*tau*(1/3)-checkq-2*
checkp,(1/3)*tau-(1/2)*checkq));
tdAtau31function:=unapply(tdAtau[3,1],q,p):
tdAtau31:=simplify(tdAtau31function(2*tau*(1/3)-checkq-2*
checkp,(1/3)*tau-(1/2)*checkq));
tdAtau32function:=unapply(tdAtau[3,2],q,p):
tdAtau32:=simplify(tdAtau32function(2*tau*(1/3)-checkq-2*
checkp,(1/3)*tau-(1/2)*checkq));
tdAtau33function:=unapply(tdAtau[3,3],q,p):
tdAtau33:=simplify(tdAtau33function(2*tau*(1/3)-checkq-2*
checkp,(1/3)*tau-(1/2)*checkq));

```

$$\begin{aligned}
\text{Coeff}_{tau} &:= \frac{1}{3} \\
tdAtau11 &:= 0 \\
tdAtau12 &:= -\frac{2}{3} \\
tdAtau13 &:= \frac{1}{3}
\end{aligned} \tag{8.4}$$

$$tdAtau21 := -\frac{1}{3} checkq^2 + \frac{1}{3} (\tau - checkp) checkq + \frac{1}{3} t20$$

$$tdAtau22 := \frac{7}{9} \tau - checkq - checkp + \frac{1}{3} \lambda$$

$$tdAtau23 := \frac{2}{3} checkq$$

$$tdAtau31 := -\frac{1}{3} checkq^2 + \frac{1}{3} (\tau - checkp) checkq - \frac{1}{3} t30$$

$$tdAtau32 := -\frac{4}{3} \tau + \frac{4}{3} checkq + \frac{4}{3} checkp$$

$$tdAtau33 := -\frac{1}{9} \tau - checkq - \frac{1}{3} \lambda$$

$$\begin{aligned}
 > P1(\lambda) ; \\
 P2(\lambda) ; \\
 P3(\lambda) ;
 \end{aligned} \quad (8.5)$$

$$\begin{aligned}
 & -\frac{1}{4} \lambda^2 - \frac{1}{6} \tau \lambda + t30 + \frac{1}{2} t20 - \frac{1}{9} \tau^2 \\
 & -\frac{1}{12} \tau \lambda^2 + \left(-\frac{1}{4} t20 - \frac{1}{18} \tau^2 \right) \lambda
 \end{aligned}$$

$$\begin{aligned}
 > L[3,3] ; \\
 \text{simplify}(L[3,2] - (h*p/(lambda-q) - P2(lambda)+h/2)) ; \\
 \text{simplify}(L[3,1] - (h*(p^2+P2(q)-h/2)/(lambda-q)+P3(lambda)+p^3+ \\
 (P2(q)-h/2)*p-P3(q)+h/4*(lambda-q))) ;
 \end{aligned} \quad (8.6)$$

$$\begin{aligned}
 & -\frac{h}{-\lambda + q} \\
 & 0 \\
 & 0
 \end{aligned}$$

$$\begin{aligned}
 > Atau := \text{simplify}(Atau) : \\
 \text{simplify}(Atau[1,1] - (-2*p^2-2*P2(q)+h)/(lambda-q)+1/3* \\
 lambda+p+1/2*q)) ; \\
 \text{simplify}(Atau[1,2] - (-2*p/(lambda-q)+1/3)) ; \\
 \text{simplify}(Atau[1,3] - (-2/(lambda-q))) ; \\
 \text{simplify}(Atau[2,1] - (p*(-2*p^2-2*P2(q)+h)/(lambda-q)+1/6*tau* \\
 lambda+tau/6*q +tau^2/9+t20/2-h/6)) ; \\
 \text{simplify}(Atau[2,2] - (-2*p^2/(lambda-q)-1/6*lambda)-p+1/3*tau \\
) ; \\
 \text{simplify}(Atau[2,3] - (-2*p/(lambda-q) +1/3)) ; \\
 \text{simplify}(Atau[3,1] - (-1/3*(6*p^2-h)*(p^2+P2(q)-1/2*h)/(lambda- \\
 q)-(1/36)*tau*lambda^2 \\
 +1/6*(tau*p-tau^2/9-t20/2+h/2)*lambda \\
 +1/6*(2*p^3-(q^2-4/3*tau*q-8/9*tau^2+8*h-8*t20-4*t30)*p/2+ \\
 tau^2/9*q+tau/6*q^2+h*tau -h/2*q+t20/2*q) \\
)) ; \\
 \text{simplify}(Atau[3,2] - (p*(-6*p^2+h)/3/(lambda-q)+(1/12)* \\
 lambda^2 +(-(1/2)*p+2*tau*(1/9))*lambda \\
 +1/6*(8/9*tau^2+(-2*p+q)*tau-3*p*q-h+2*t20-2*t30) \\
)) ; \\
 \text{simplify}(Atau[3,3] - ((-6*p^2+h)/3/(lambda-q) -lambda/6+p- \\
 tau/3)) ;
 \end{aligned} \quad (8.7)$$

$$\begin{aligned}
 & 0 \\
 & 0 \\
 & 0 \\
 & 0 \\
 & 0 \\
 & 0
 \end{aligned}$$

[[

0
0
0