

In this Maple file, we compute the evolution equations for the Painlevé 3 equations using the compatibility equation of the Lax system. We also obtain the expression of the Lax matrices in the geometric gauge without apparent singularities.

Lax matrices in the oper gauge from previous Maple files

Summary of previous files: We have the expression for some coefficients of the Lax matrix L and of A.

The deformation operator is $\mathcal{L} = \hbar (\alpha_{11} \partial_t^1 + \alpha_{21} \partial_t^2 + \alpha_{01} \partial_t^0 + \alpha_{02} \partial_t^0)$

```
> restart:
with(LinearAlgebra):
P042 := t011*t021;
P032 := t010*t021+t011*t020;
P012 := -1/2*(t010+t020)*(tinfy11+tinfy21)-1/2*(tinfy10-
tinfy20)*(-tinfy21+tinfy11);
P021 := t011+t021;
P011 := t010+t020;
Pinfty01 := -tinfy11-tinfy21;
Pinfty02 := tinfy11*tinfy21;
CoherenceEquation1 := tinfy10+tinfy20+t010+t020;

P1:=lambda-> P021/lambda^2+P011/lambda+Pinfty01;
P2:=lambda-> P042/lambda^4+P032/lambda^3+P022/lambda^2+
P012/lambda+Pinfty02;
dP1dlambda:=unapply(diff(P1(lambda),lambda),lambda):
dP2dlambda:=unapply(diff(P2(lambda),lambda),lambda):

tdP2:=unapply(P2(lambda)-P022/lambda^2-P012/lambda,lambda);

L:=Matrix(2,2,0):
L[1,1]:=0:
L[1,2]:=1:
L[2,1]:=-t011*t021/lambda^4 -(t010*t021+t020*t011)/lambda^3-
H/lambda^2- tinfy11*tinfy21 - (tinfy11*tinfy20+tinfy21*
tinfy10+h*tinfy11-h*p)/lambda- p*h/(lambda-q):
L[2,2]:= (t011+t021)/lambda^2+ (t010+t020-2*h)/lambda -
(tinfy11+tinfy21) +h/(lambda-q):

C01:=residue(L[2,1],lambda=0);
C02:=residue(L[2,1]*lambda,lambda=0);

A:=Matrix(2,2,0):
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A[1,1]:=(alphainf11*tinfty21-alphainf21*tinfty11)/(tinfty11-
tinfty21)*lambda+ C+rho/(lambda-q)-(t011*alpha021-
t021*alpha011)/(t011-t021)/lambda:
A[1,2]:=(alphainf11-alphainf21)/(tinfty11-tinfty21)*lambda+nu+
mu/(lambda-q):
A[2,1]:=AA21(lambda):
A[2,2]:=AA22(lambda):
dAdlambda:=Matrix(2,2,0):
for i from 1 to 2 do for j from 1 to 2 do dAdlambda[i,j]:=diff
(A[i,j],lambda): od: od:

L;
A;

nuMinus1:=factor(-residue(A[1,2]/lambda^2,lambda=infinity));
nu0:=factor(-residue(A[1,2]/lambda,lambda=infinity));
cinfy1:=factor(-residue(A[1,1]/lambda^2,lambda=infinity));
c01:=factor(residue(A[1,1],lambda=0));

Q2:=unapply(-p*(q-0)^2,lambda):
J:=Matrix(2,2,0):
J[1,1]:=1:
J[1,2]:=0:
J[2,1]:=Q2(lambda)/(lambda-q):
J[2,2]:=(lambda-0)^2/(lambda-q):
dJdlambda:=Matrix(2,2,0):
for i from 1 to 2 do for j from 1 to 2 do dJdlambda[i,j]:=diff
(J[i,j],lambda): od: od:
J:

LJ:=Matrix(2,2,0):
LJ[1,1]:=0:
LJ[1,2]:=0:
LJ[2,2]:=diff(J[2,2],q)*Lq+diff(J[2,2],p)*Lp+h*diff(J[2,2],t):
LJ[2,1]:=diff(J[2,1],q)*Lq+diff(J[2,1],p)*Lp+h*diff(J[2,1],t):
LJ:

checkL:=simplify(Multiply(Multiply(J,L),J^(-1))+h*Multiply
(dJdlambda,J^(-1))):
checkA:=simplify(Multiply(Multiply(J,A),J^(-1))+Multiply(LJ,J^
(-1))):
```

$$\begin{aligned}
P042 &:= t011 \ t021 \\
P032 &:= t010 \ t021 + t011 \ t020 \\
P012 &:= -\frac{1}{2} (t010 + t020) (tinfy11 + tinfy21) - \frac{1}{2} (tinfy10 - tinfy20) (-tinfy21 \\
&\quad + tinfy11) \\
P021 &:= t011 + t021 \\
P011 &:= t010 + t020 \\
Pinfty01 &:= -tinfy11 - tinfy21 \\
Pinfty02 &:= tinfy11 tinfy21 \\
CoherenceEquation1 &:= tinfy10 + tinfy20 + t010 + t020 \\
P1 &:= \lambda \rightarrow \frac{P021}{\lambda^2} + \frac{P011}{\lambda} + Pinfty01 \\
P2 &:= \lambda \rightarrow \frac{P042}{\lambda^4} + \frac{P032}{\lambda^3} + \frac{P022}{\lambda^2} + \frac{P012}{\lambda} + Pinfty02 \\
tdP2 &:= \lambda \rightarrow \frac{t011 \ t021}{\lambda^4} + \frac{t010 \ t021 + t011 \ t020}{\lambda^3} + tinfy11 tinfy21 \\
C01 &:= -\frac{-h \ p \ q + h \ q \ tinfy11 + q \ tinfy10 \ tinfy21 + q \ tinfy11 \ tinfy20}{q} \\
C02 &:= -H \\
\left[\left[0, 1 \right], \right. & \\
&\left[-\frac{t011 \ t021}{\lambda^4} - \frac{t010 \ t021 + t011 \ t020}{\lambda^3} - \frac{H}{\lambda^2} - tinfy11 tinfy21 \right. \\
&\quad - \frac{-h \ p + h \ tinfy11 + tinfy10 \ tinfy21 + tinfy11 \ tinfy20}{\lambda} - \frac{p \ h}{\lambda - q}, \frac{t011 + t021}{\lambda^2} \\
&\quad + \frac{t010 + t020 - 2 \ h}{\lambda} - tinfy11 - tinfy21 + \frac{h}{\lambda - q} \left. \right] \\
\left[\left[\frac{(alphainf11 \ tinfy21 - alphainf21 \ tinfy11) \ \lambda}{-tinfy21 + tinfy11} + C + \frac{\rho}{\lambda - q} \right. \right. & \\
&\quad \left. \left. - \frac{t011 \ o021 - t021 \ o011}{(t011 - t021) \ \lambda}, \frac{(alphainf11 - alphainf21) \ \lambda}{-tinfy21 + tinfy11} + v + \frac{\mu}{\lambda - q} \right], \right. \\
&\left[AA21(\lambda), AA22(\lambda) \right] \\
nuMinus1 &:= \frac{alphainf11 - alphainf21}{-tinfy21 + tinfy11} \\
v0 &:= v \\
cinfy1 &:= \frac{alphainf11 \ tinfy21 - alphainf21 \ tinfy11}{-tinfy21 + tinfy11} \\
c01 &:= -\frac{t011 \ o021 - t021 \ o011}{t011 - t021}
\end{aligned}$$

Solving the compatibility equations to obtain the Hamiltonian evolutions.

The compatibility equation is $\mathcal{L} \cdot L = h \partial_\lambda A + [A, L]$
 Since the first line of L is trivial, we may easily obtain $A[2,1]$ et $A[2,2]$ to obtain the full expression for A

```
> LL:=h*dAdlambda+ (Multiply(A,L)-Multiply(L,A)) :
Entry11:=LL[1,1]:
Entry12:=LL[1,2]:

AA21:=unapply(solve(Entry11=0,AA21(lambda)),lambda):
AA21bis:=h*dAdlambda[1,1]+A[1,2]*L[2,1]:

simplify(AA21(lambda)-AA21bis);
AA22:=unapply(solve(Entry12=0,AA22(lambda)),lambda):
AA22bis:=h*dAdlambda[1,2]+A[1,1]+A[1,2]*L[2,2]:

simplify(AA22(lambda)-AA22bis);
simplify(Entry11);
simplify(Entry12);
LL:=h*dAdlambda+ (Multiply(A,L)-Multiply(L,A)) :
```

$$\begin{matrix} 0 \\ 0 \\ 0 \\ 0 \end{matrix} \tag{2.1}$$

We now compute the action of \mathcal{L} on $L[2,2]$ et $L[2,1]$ to obtain the evolution equations
 Evolution of entry $L_{2,2}$

```
> Entry22:=simplify(LL[2,2]):
Entry22TermLambdaMinusqCube:=factor(residue(Entry22*(lambda-q)
^2,lambda=q));
Entry22TermLambdaMinusqSquare:=factor(residue(Entry22*(lambda-
q),lambda=q));
Entry22TermLambdaMinusq:=factor(residue(Entry22,lambda=q));
Entry22TermLambdaZeroMinus4:=factor(residue(Entry22*lambda^3,
lambda=0));
Entry22TermLambdaZeroMinus3:=factor(residue(Entry22*lambda^2,
lambda=0));
Entry22TermLambdaZeroMinus2:=factor(residue(Entry22*lambda,
lambda=0));
Entry22TermLambdaZeroMinus1:=factor(residue(Entry22,lambda=0));
Entry22TermLambdaInfy2:=factor(-residue(Entry22/lambda^3,
lambda=infinity));
Entry22TermLambdaInfy1:=factor(-residue(Entry22/lambda^2,
lambda=infinity));
```

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Entry22TermLambdaInfty0:=factor(-residue(Entry22/lambda,lambda=
infinity));

simplify( Entry22-(Entry22TermLambdaMinusqSquare/(lambda-q)^2+
Entry22TermLambdaMinusq/(lambda-q)
+Entry22TermLambdaZeroMinus4/lambda^4+
Entry22TermLambdaZeroMinus3/lambda^3+
Entry22TermLambdaZeroMinus2/lambda^2+
Entry22TermLambdaZeroMinus1/lambda
+Entry22TermLambdaInfty0+Entry22TermLambdaInfty1*lambda+
Entry22TermLambdaInfty2*lambda^2) );
L[2,2];

```

$$\begin{aligned}
& \text{Entry22TermLambdaMinusqCube} := 0 && (2.2) \\
& \text{Entry22TermLambdaMinusqSquare} := \frac{1}{q^2 (-tinfy21 + tinfy11)} ((-h \vee q^2 tinfy11 \\
& + h \vee q^2 tinfy21 - h q^3 alphainf11 + h q^3 alphainf21 + \mu q^2 tinfy11^2 - \mu q^2 tinfy21^2 \\
& + 2 h \mu q tinfy11 - 2 h \mu q tinfy21 - \mu q t010 tinfy11 + \mu q t010 tinfy21 \\
& - \mu q t020 tinfy11 + \mu q t020 tinfy21 - 2 q^2 \rho tinfy11 + 2 q^2 \rho tinfy21 \\
& - \mu t011 tinfy11 + \mu t011 tinfy21 - \mu t021 tinfy11 + \mu t021 tinfy21) h) \\
& \quad \text{Entry22TermLambdaMinusq} := 0 \\
& \quad \text{Entry22TermLambdaZeroMinus4} := 0 \\
& \quad \text{Entry22TermLambdaZeroMinus3} := \frac{2 (t011 + t021) (-\nu q + \mu) h}{q} \\
& \text{Entry22TermLambdaZeroMinus2} := -\frac{1}{q^2 (-tinfy21 + tinfy11) (t011 - t021)} (h (\\
& -2 h \vee q^2 t011 tinfy11 + 2 h \vee q^2 t011 tinfy21 + 2 h \vee q^2 t021 tinfy11 \\
& - 2 h \vee q^2 t021 tinfy21 + \nu q^2 t010 t011 tinfy11 - \nu q^2 t010 t011 tinfy21 \\
& - \nu q^2 t010 t021 tinfy11 + \nu q^2 t010 t021 tinfy21 + \nu q^2 t011 t020 tinfy11 \\
& - \nu q^2 t011 t020 tinfy21 - \nu q^2 t020 t021 tinfy11 + \nu q^2 t020 t021 tinfy21 \\
& + 2 h \mu q t011 tinfy11 - 2 h \mu q t011 tinfy21 - 2 h \mu q t021 tinfy11 \\
& + 2 h \mu q t021 tinfy21 - \mu q t010 t011 tinfy11 + \mu q t010 t011 tinfy21 \\
& + \mu q t010 t021 tinfy11 - \mu q t010 t021 tinfy21 - \mu q t011 t020 tinfy11 \\
& + \mu q t011 t020 tinfy21 + \mu q t020 t021 tinfy11 - \mu q t020 t021 tinfy21 \\
& + q^2 t011^2 alphainf11 - q^2 t011^2 alphainf21 - 2 q^2 t011 \alpha021 tinfy11 \\
& + 2 q^2 t011 \alpha021 tinfy21 - q^2 t021^2 alphainf11 + q^2 t021^2 alphainf21 \\
& + 2 q^2 t021 \alpha011 tinfy11 - 2 q^2 t021 \alpha011 tinfy21 - \mu t011^2 tinfy11 + \mu t011^2 tinfy21 \\
& + \mu t021^2 tinfy11 - \mu t021^2 tinfy21)) \\
& \quad \text{Entry22TermLambdaZeroMinus1} := 0 \\
& \quad \text{Entry22TermLambdaInfty2} := 0 \\
& \quad \text{Entry22TermLambdaInfty1} := 0
\end{aligned}$$

$$\begin{aligned} \text{Entry22TermLambdaInfty0} := & -h (\alpha_{\text{phainf11}} + \alpha_{\text{phainf21}}) \\ & \frac{t_{011} + t_{021}}{\lambda^2} + \frac{t_{010} + t_{020} - 2h}{\lambda} - t_{\text{infty11}} - t_{\text{infty21}} + \frac{h}{\lambda - q} \end{aligned}$$

Since the deformation operator is $\mathcal{L} = \hbar^{-1} (\alpha_{\text{phainf11}} \partial_t + \alpha_{\text{phainf21}} \partial_t + \alpha_{011} \partial_t + \alpha_{021} \partial_t)$, the double pole at $\lambda=0$ is $h^*(\alpha_{011} + \alpha_{021})$

```
> solve({Entry22TermLambdaZeroMinus3, Entry22TermLambdaZeroMinus2-
h*(alpha011+alpha021)}, {nu, mu});
mu := q^2*(t011*alphainf11-t011*alphainf21-t021*alphainf11+
t021*alphainf21+alpha011*tinfty11-alpha011*tinfty21-alpha021*
tinfty11+alpha021*tinfty21)/(t011*tinfty11-t011*tinfty21-t021*
tinfty11+t021*tinfty21);
nu := q*(t011*alphainf11-t011*alphainf21-t021*alphainf11+t021*
alphainf21+alpha011*tinfty11-alpha011*tinfty21-alpha021*
tinfty11+alpha021*tinfty21)/(t011*tinfty11-t011*tinfty21-t021*
tinfty11+t021*tinfty21);
simplify(Entry22TermLambdaZeroMinus3);
simplify(Entry22TermLambdaZeroMinus2-h*(alpha011+alpha021));
```

$$\left\{ \begin{array}{l} \mu = ((t_{011} \alpha_{\text{phainf11}} - t_{011} \alpha_{\text{phainf21}} - t_{021} \alpha_{\text{phainf11}} + t_{021} \alpha_{\text{phainf21}} \right. \\ \left. + \alpha_{011} t_{\text{infty11}} - \alpha_{011} t_{\text{infty21}} - \alpha_{021} t_{\text{infty11}} + \alpha_{021} t_{\text{infty21}}) q^2) / (t_{011} t_{\text{infty11}} \right. \\ \left. - t_{011} t_{\text{infty21}} - t_{021} t_{\text{infty11}} + t_{021} t_{\text{infty21}}), v = ((t_{011} \alpha_{\text{phainf11}} \right. \\ \left. - t_{011} \alpha_{\text{phainf21}} - t_{021} \alpha_{\text{phainf11}} + t_{021} \alpha_{\text{phainf21}} + \alpha_{011} t_{\text{infty11}} \right. \\ \left. - \alpha_{011} t_{\text{infty21}} - \alpha_{021} t_{\text{infty11}} + \alpha_{021} t_{\text{infty21}}) q) / (t_{011} t_{\text{infty11}} - t_{011} t_{\text{infty21}} \right. \\ \left. - t_{021} t_{\text{infty11}} + t_{021} t_{\text{infty21}}) \} \end{array} \right. \quad (2.3)$$

$$\begin{aligned} \mu &:= ((t_{011} \alpha_{\text{phainf11}} - t_{011} \alpha_{\text{phainf21}} - t_{021} \alpha_{\text{phainf11}} + t_{021} \alpha_{\text{phainf21}} \right. \\ &\quad \left. + \alpha_{011} t_{\text{infty11}} - \alpha_{011} t_{\text{infty21}} - \alpha_{021} t_{\text{infty11}} + \alpha_{021} t_{\text{infty21}}) q^2) / (t_{011} t_{\text{infty11}} \right. \\ &\quad \left. - t_{011} t_{\text{infty21}} - t_{021} t_{\text{infty11}} + t_{021} t_{\text{infty21}}) \\ v &:= ((t_{011} \alpha_{\text{phainf11}} - t_{011} \alpha_{\text{phainf21}} - t_{021} \alpha_{\text{phainf11}} + t_{021} \alpha_{\text{phainf21}} \right. \\ &\quad \left. + \alpha_{011} t_{\text{infty11}} - \alpha_{011} t_{\text{infty21}} - \alpha_{021} t_{\text{infty11}} + \alpha_{021} t_{\text{infty21}}) q) / (t_{011} t_{\text{infty11}} \right. \\ &\quad \left. - t_{011} t_{\text{infty21}} - t_{021} t_{\text{infty11}} + t_{021} t_{\text{infty21}}) \right. \\ &\quad \left. \begin{array}{c} 0 \\ 0 \end{array} \right. \end{aligned}$$

```
> Lq:=factor(Entry22TermLambdaMinusqSquare/h):
Lqbis:=-2*rho-((alphainf11-alphainf21)/(tinfty11-tinfty21) +
(alpha011-alpha021)/(t011-t021))*q^2*p1(q)+(alpha011-alpha021)*
q/(t011-t021)*h;
factor(simplify(series(Lq-Lqbis,q=0)));
```

(2.4)

$$\begin{aligned}
Lqbis := -2 \rho - & \left(\frac{\alpha_{11} - \alpha_{21}}{-t_{11} + t_{21}} + \frac{\alpha_{11} - \alpha_{21}}{t_{11} - t_{21}} \right) q^2 \left(\frac{t_{11} + t_{21}}{q^2} \right. \\
& \left. + \frac{t_{10} + t_{20}}{q} - t_{11} - t_{21} \right) + \frac{(\alpha_{11} - \alpha_{21}) q h}{t_{11} - t_{21}} \\
& 0
\end{aligned} \tag{2.4}$$

= Evolution of $\text{L}[2,1]$

```

> Entry21:=simplify(LL[2,1]):
Entry21TermLambdaMinusqCube:=factor(residue(Entry21*(lambda-q)
^2,lambda=q));
Entry21TermLambdaMinusqSquare:=factor(residue(Entry21*(lambda-
q),lambda=q));
Entry21TermLambdaMinusq:=factor(residue(Entry21,lambda=q));
Entry21TermLambdaZeroMinus5:=factor(residue(Entry21*lambda^4,
lambda=0));
Entry21TermLambdaZeroMinus4:=factor(residue(Entry21*lambda^3,
lambda=0));
Entry21TermLambdaZeroMinus3:=factor(residue(Entry21*lambda^2,
lambda=0));
Entry21TermLambdaZeroMinus2:=factor(residue(Entry21*lambda,
lambda=0));
Entry21TermLambdaZeroMinus1:=factor(residue(Entry21,lambda=0));
Entry21TermLambdaInfty3:=factor(-residue(Entry21/lambda^4,
lambda=infinity));
Entry21TermLambdaInfty2:=factor(-residue(Entry21/lambda^3,
lambda=infinity));
Entry21TermLambdaInfty1:=factor(-residue(Entry21/lambda^2,
lambda=infinity));
Entry21TermLambdaInfty0:=factor(-residue(Entry21/lambda,lambda=
infinity));

simplify( Entry21-(Entry21TermLambdaMinusqCube/(lambda-q)^3+
Entry21TermLambdaMinusqSquare/(lambda-q)^2+
Entry21TermLambdaMinusq/(lambda-q)
+Entry21TermLambdaZeroMinus5/lambda^5+
Entry21TermLambdaZeroMinus4/lambda^4+
Entry21TermLambdaZeroMinus3/lambda^3+
Entry21TermLambdaZeroMinus2/lambda^2+
Entry21TermLambdaZeroMinus1/lambda
+Entry21TermLambdaInfty0+Entry21TermLambdaInfty1*lambda+
Entry21TermLambdaInfty2*lambda^2+Entry21TermLambdaInfty3*
lambda^3) );
L[2,1];

```

$$\begin{aligned}
Entry21TermLambdaMinusqCube &:= \frac{1}{(-tinfy21 + tinfy11) (t011 - t021)} (3 h^2 (p q^2 \\
&\quad t011 alphainf11 - p q^2 t011 alphainf21 - p q^2 t021 alphainf11 + p q^2 t021 alphainf21 \\
&\quad + p q^2 \alpha011 tinfy11 - p q^2 \alpha011 tinfy21 - p q^2 \alpha021 tinfy11 + p q^2 \alpha021 tinfy21 \\
&\quad + \rho t011 tinfy11 - \rho t011 tinfy21 - \rho t021 tinfy11 + \rho t021 tinfy21)) \quad (2.5) \\
Entry21TermLambdaMinusqSquare &:= \frac{1}{q^2 (-tinfy21 + tinfy11) (t011 - t021)} ((2 q^4 \\
&\quad t011 alphainf11 tinfy11 tinfy21 - 2 q^4 t011 alphainf21 tinfy11 tinfy21 \\
&\quad - 2 q^4 t021 alphainf11 tinfy11 tinfy21 + 2 q^4 t021 alphainf21 tinfy11 tinfy21 \\
&\quad + 2 q^4 \alpha011 tinfy11^2 tinfy21 - 2 q^4 \alpha011 tinfy11 tinfy21^2 \\
&\quad - 2 q^4 \alpha021 tinfy11^2 tinfy21 + 2 q^4 \alpha021 tinfy11 tinfy21^2 - h p q^3 \alpha011 tinfy11 \\
&\quad + h p q^3 \alpha011 tinfy21 + h p q^3 \alpha021 tinfy11 - h p q^3 \alpha021 tinfy21 \\
&\quad + 2 h q^3 t011 alphainf11 tinfy11 - 2 h q^3 t011 alphainf21 tinfy11 \\
&\quad - 2 h q^3 t021 alphainf11 tinfy11 + 2 h q^3 t021 alphainf21 tinfy11 \\
&\quad + 2 h q^3 \alpha011 tinfy11^2 - 2 h q^3 \alpha011 tinfy11 tinfy21 - 2 h q^3 \alpha021 tinfy11^2 \\
&\quad + 2 h q^3 \alpha021 tinfy11 tinfy21 + 2 q^3 t011 alphainf11 tinfy10 tinfy21 \\
&\quad + 2 q^3 t011 alphainf11 tinfy11 tinfy20 - 2 q^3 t011 alphainf21 tinfy10 tinfy21 \\
&\quad - 2 q^3 t011 alphainf21 tinfy11 tinfy20 - 2 q^3 t021 alphainf11 tinfy10 tinfy21 \\
&\quad - 2 q^3 t021 alphainf11 tinfy11 tinfy20 + 2 q^3 t021 alphainf21 tinfy10 tinfy21 \\
&\quad + 2 q^3 t021 alphainf21 tinfy11 tinfy20 + 2 q^3 \alpha011 tinfy10 tinfy11 tinfy21 \\
&\quad - 2 q^3 \alpha011 tinfy10 tinfy21^2 + 2 q^3 \alpha011 tinfy11^2 tinfy20 \\
&\quad - 2 q^3 \alpha011 tinfy11 tinfy20 tinfy21 - 2 q^3 \alpha021 tinfy10 tinfy11 tinfy21 \\
&\quad + 2 q^3 \alpha021 tinfy10 tinfy21^2 - 2 q^3 \alpha021 tinfy11^2 tinfy20 \\
&\quad + 2 q^3 \alpha021 tinfy11 tinfy20 tinfy21 - q^2 \rho t011 tinfy11^2 + q^2 \rho t011 tinfy21^2 \\
&\quad + q^2 \rho t021 tinfy11^2 - q^2 \rho t021 tinfy21^2 + 2 H q^2 t011 alphainf11 \\
&\quad - 2 H q^2 t011 alphainf21 - 2 H q^2 t021 alphainf11 + 2 H q^2 t021 alphainf21 \\
&\quad + 2 H q^2 \alpha011 tinfy11 - 2 H q^2 \alpha011 tinfy21 - 2 H q^2 \alpha021 tinfy11 \\
&\quad + 2 H q^2 \alpha021 tinfy21 - 2 h q \rho t011 tinfy11 + 2 h q \rho t011 tinfy21 \\
&\quad + 2 h q \rho t021 tinfy11 - 2 h q \rho t021 tinfy21 + q \rho t010 t011 tinfy11 \\
&\quad - q \rho t010 t011 tinfy21 - q \rho t010 t021 tinfy11 + q \rho t010 t021 tinfy21 \\
&\quad + q \rho t011 t020 tinfy11 - q \rho t011 t020 tinfy21 - q \rho t020 t021 tinfy11 \\
&\quad + q \rho t020 t021 tinfy21 + 2 q t010 t011 t021 alphainf11 \\
&\quad - 2 q t010 t011 t021 alphainf21 - 2 q t010 t021^2 alphainf11 \\
&\quad + 2 q t010 t021^2 alphainf21 + 2 q t010 t021 \alpha011 tinfy11 - 2 q t010 t021 \alpha011 tinfy21 \\
&\quad - 2 q t010 t021 \alpha021 tinfy11 + 2 q t010 t021 \alpha021 tinfy21 + 2 q t011^2 t020 alphainf11 \\
&\quad - 2 q t011^2 t020 alphainf21 - 2 q t011 t020 t021 alphainf11 \\
&\quad + 2 q t011 t020 t021 alphainf21 + 2 q t011 t020 \alpha011 tinfy11 \\
&\quad - 2 q t011 t020 \alpha011 tinfy21 - 2 q t011 t020 \alpha021 tinfy11 \\
&\quad + 2 q t011 t020 \alpha021 tinfy21 + \rho t011^2 tinfy11 - \rho t011^2 tinfy21 - \rho t021^2 tinfy11 \\
&\quad + \rho t021^2 tinfy21 + 2 t011^2 t021 alphainf11 - 2 t011^2 t021 alphainf21
\end{aligned}$$

$$\begin{aligned}
& -2 t011 t021^2 \alpha011 \text{tinfy11} + 2 t011 t021^2 \alpha011 \text{tinfy21} + 2 t011 t021 \alpha011 \text{tinfy11} \\
& - 2 t011 t021 \alpha011 \text{tinfy21} - 2 t011 t021 \alpha021 \text{tinfy11} + 2 t011 t021 \alpha021 \text{tinfy21}) \\
& h
\end{aligned}$$

$$\begin{aligned}
\text{Entry21TermLambdaMinusq} := & -\frac{1}{q^3 (-\text{tinfy21} + \text{tinfy11}) (t011 - t021)} ((\\
& -h p q^3 \alpha011 \text{tinfy11} + h p q^3 \alpha011 \text{tinfy21} + h p q^3 \alpha021 \text{tinfy11} \\
& -h p q^3 \alpha021 \text{tinfy21} + h q^3 t011 \alpha011 \text{tinfy11} + h q^3 t011 \alpha011 \text{tinfy21} \\
& -2 h q^3 t011 \alpha011 \text{tinfy21} - h q^3 t021 \alpha011 \text{tinfy11} \\
& -h q^3 t021 \alpha011 \text{tinfy21} + 2 h q^3 t021 \alpha011 \text{tinfy11} + h q^3 \alpha011 \text{tinfy11}^2 \\
& -h q^3 \alpha011 \text{tinfy11} \text{tinfy21} - h q^3 \alpha021 \text{tinfy11}^2 + h q^3 \alpha021 \text{tinfy11} \text{tinfy21} \\
& + q^3 t011 \alpha011 \text{tinfy10} \text{tinfy21} + q^3 t011 \alpha011 \text{tinfy11} \text{tinfy20} \\
& -q^3 t011 \alpha011 \text{tinfy21} \text{tinfy10} \text{tinfy21} - q^3 t011 \alpha011 \text{tinfy21} \text{tinfy11} \text{tinfy20} \\
& -q^3 t021 \alpha011 \text{tinfy10} \text{tinfy21} - q^3 t021 \alpha011 \text{tinfy11} \text{tinfy20} \\
& + q^3 t021 \alpha011 \text{tinfy21} \text{tinfy10} \text{tinfy21} + q^3 t021 \alpha011 \text{tinfy21} \text{tinfy11} \text{tinfy20} \\
& + q^3 \alpha011 \text{tinfy10} \text{tinfy11} \text{tinfy21} - q^3 \alpha011 \text{tinfy10} \text{tinfy21}^2 \\
& + q^3 \alpha011 \text{tinfy11}^2 \text{tinfy20} - q^3 \alpha011 \text{tinfy11} \text{tinfy20} \text{tinfy21} \\
& -q^3 \alpha021 \text{tinfy10} \text{tinfy11} \text{tinfy21} + q^3 \alpha021 \text{tinfy10} \text{tinfy21}^2 \\
& -q^3 \alpha021 \text{tinfy11}^2 \text{tinfy20} + q^3 \alpha021 \text{tinfy11} \text{tinfy20} \text{tinfy21} + 2 H q^2 t011 \alpha011 \\
& -2 H q^2 t011 \alpha011 \text{tinfy21} - 2 H q^2 t021 \alpha011 \text{tinfy11} + 2 H q^2 t021 \alpha011 \\
& + 2 H q^2 \alpha011 \text{tinfy11} - 2 H q^2 \alpha011 \text{tinfy21} - 2 H q^2 \alpha021 \text{tinfy11} \\
& + 2 H q^2 \alpha021 \text{tinfy21} - 2 h q \rho t011 \text{tinfy11} + 2 h q \rho t011 \text{tinfy21} \\
& + 2 h q \rho t021 \text{tinfy11} - 2 h q \rho t021 \text{tinfy21} + h q t011 \alpha021 \text{tinfy11} \\
& -h q t011 \alpha021 \text{tinfy21} - h q t021 \alpha011 \text{tinfy11} + h q t021 \alpha011 \text{tinfy21} \\
& + q \rho t010 t011 \text{tinfy11} - q \rho t010 t011 \text{tinfy21} - q \rho t010 t021 \text{tinfy11} \\
& + q \rho t010 t021 \text{tinfy21} + q \rho t011 t020 \text{tinfy11} - q \rho t011 t020 \text{tinfy21} \\
& -q \rho t020 t021 \text{tinfy11} + q \rho t020 t021 \text{tinfy21} + 3 q t010 t011 t021 \alpha011 \\
& -3 q t010 t011 t021 \alpha011 \text{tinfy21} - 3 q t010 t021 \alpha011 \\
& + 3 q t010 t021^2 \alpha011 \text{tinfy21} + 3 q t010 t021 \alpha011 \text{tinfy11} - 3 q t010 t021 \alpha011 \text{tinfy21} \\
& -3 q t010 t021 \alpha021 \text{tinfy11} + 3 q t010 t021 \alpha021 \text{tinfy21} + 3 q t011^2 t020 \alpha011 \\
& -3 q t011^2 t020 \alpha011 \text{tinfy21} - 3 q t011 t020 t021 \alpha011 \\
& + 3 q t011 t020 t021 \alpha011 \text{tinfy21} + 3 q t011 t020 \alpha011 \text{tinfy11} \\
& -3 q t011 t020 \alpha011 \text{tinfy21} - 3 q t011 t020 \alpha021 \text{tinfy11} \\
& + 3 q t011 t020 \alpha021 \text{tinfy21} + 2 \rho t011^2 \text{tinfy11} - 2 \rho t011^2 \text{tinfy21} \\
& -2 \rho t021^2 \text{tinfy11} + 2 \rho t021^2 \text{tinfy21} + 4 t011^2 t021 \alpha011 \\
& -4 t011^2 t021 \alpha011 \text{tinfy21} - 4 t011 t021^2 \alpha011 \text{tinfy11} + 4 t011 t021^2 \alpha011 \\
& + 4 t011 t021 \alpha011 \text{tinfy11} - 4 t011 t021 \alpha011 \text{tinfy21} - 4 t011 t021 \alpha021 \text{tinfy11} \\
& + 4 t011 t021 \alpha021 \text{tinfy21}) h
\end{aligned}$$

$$\text{Entry21TermLambdaZeroMinus5} := 0$$

$$\text{Entry21TermLambdaZeroMinus4} := -(t011 \alpha021 + t021 \alpha011) h$$

$$\text{Entry21TermLambdaZeroMinus3} := -(t010 \alpha021 + t020 \alpha011) h$$

$$\begin{aligned}
Entry21TermLambdaZeroMinus2 := & \frac{1}{q^2 (-tinfy21 + tinfy11) (t011 - t021)} (h (\\
& -q^2 t011^2 alphainf11 tinfy21 + q^2 t011^2 alphainf21 tinfy11 + q^2 t011 \alpha021 tinfy11 \\
& -q^2 t011 \alpha021 tinfy21^2 + q^2 t021^2 alphainf11 tinfy21 - q^2 t021^2 alphainf21 tinfy11 \\
& -q^2 t021 \alpha011 tinfy11^2 + q^2 t021 \alpha011 tinfy21^2 + h q t011 \alpha021 tinfy11 \\
& -h q t011 \alpha021 tinfy21 - h q t021 \alpha011 tinfy11 + h q t021 \alpha011 tinfy21 \\
& + q t010 t011 t021 alphainf11 - q t010 t011 t021 alphainf21 - q t010 t021^2 alphainf11 \\
& + q t010 t021^2 alphainf21 + q t010 t021 \alpha011 tinfy11 - q t010 t021 \alpha011 tinfy21 \\
& -q t010 t021 \alpha021 tinfy11 + q t010 t021 \alpha021 tinfy21 + q t011^2 t020 alphainf11 \\
& -q t011^2 t020 alphainf21 - q t011 t020 t021 alphainf11 + q t011 t020 t021 alphainf21 \\
& + q t011 t020 \alpha011 tinfy11 - q t011 t020 \alpha011 tinfy21 - q t011 t020 \alpha021 tinfy11 \\
& + q t011 t020 \alpha021 tinfy21 + \rho t011^2 tinfy11 - \rho t011^2 tinfy21 - \rho t021^2 tinfy11 \\
& + \rho t021^2 tinfy21 + 2 t011^2 t021 alphainf11 - 2 t011^2 t021 alphainf21 \\
& -2 t011 t021^2 alphainf11 + 2 t011 t021^2 alphainf21 + 2 t011 t021 \alpha011 tinfy11 \\
& -2 t011 t021 \alpha011 tinfy21 - 2 t011 t021 \alpha021 tinfy11 + 2 t011 t021 \alpha021 tinfy21)) \\
Entry21TermLambdaZeroMinus1 := & \frac{1}{q^3 (-tinfy21 + tinfy11) (t011 - t021)} ((\\
& -h p q^3 \alpha011 tinfy11 + h p q^3 \alpha011 tinfy21 + h p q^3 \alpha021 tinfy11 \\
& -h p q^3 \alpha021 tinfy21 + 2 h q^3 t011 alphainf11 tinfy21 \\
& -2 h q^3 t011 alphainf21 tinfy11 - 2 h q^3 t021 alphainf11 tinfy21 \\
& + 2 h q^3 t021 alphainf21 tinfy11 + h q^3 \alpha011 tinfy11^2 - h q^3 \alpha011 tinfy11 tinfy21 \\
& -h q^3 \alpha021 tinfy11^2 + h q^3 \alpha021 tinfy11 tinfy21 - q^3 t010 t011 alphainf11 tinfy21 \\
& + q^3 t010 t011 alphainf21 tinfy11 + q^3 t010 t021 alphainf11 tinfy21 \\
& -q^3 t010 t021 alphainf21 tinfy11 - q^3 t011 t020 alphainf11 tinfy21 \\
& + q^3 t011 t020 alphainf21 tinfy11 + q^3 t020 t021 alphainf11 tinfy21 \\
& -q^3 t020 t021 alphainf21 tinfy11 + q^3 \alpha011 tinfy10 tinfy11 tinfy21 \\
& -q^3 \alpha011 tinfy10 tinfy21^2 + q^3 \alpha011 tinfy11^2 tinfy20 \\
& -q^3 \alpha011 tinfy11 tinfy20 tinfy21 - q^3 \alpha021 tinfy10 tinfy11 tinfy21 \\
& + q^3 \alpha021 tinfy10 tinfy21^2 - q^3 \alpha021 tinfy11^2 tinfy20 \\
& + q^3 \alpha021 tinfy11 tinfy20 tinfy21 + 2 H q^2 t011 alphainf11 - 2 H q^2 t011 alphainf21 \\
& -2 H q^2 t021 alphainf11 + 2 H q^2 t021 alphainf21 + 2 H q^2 \alpha011 tinfy11 \\
& -2 H q^2 \alpha011 tinfy21 - 2 H q^2 \alpha021 tinfy11 + 2 H q^2 \alpha021 tinfy21 \\
& -2 h q \rho t011 tinfy11 + 2 h q \rho t011 tinfy21 + 2 h q \rho t021 tinfy11 \\
& -2 h q \rho t021 tinfy21 + h q t011 \alpha021 tinfy11 - h q t011 \alpha021 tinfy21 \\
& -h q t021 \alpha011 tinfy11 + h q t021 \alpha011 tinfy21 + q \rho t010 t011 tinfy11 \\
& -q \rho t010 t011 tinfy21 - q \rho t010 t021 tinfy11 + q \rho t010 t021 tinfy21 \\
& + q \rho t011 t020 tinfy11 - q \rho t011 t020 tinfy21 - q \rho t020 t021 tinfy11 \\
& + q \rho t020 t021 tinfy21 + 3 q t010 t011 t021 alphainf11 \\
& -3 q t010 t011 t021 alphainf21 - 3 q t010 t021^2 alphainf11 \\
& + 3 q t010 t021^2 alphainf21 + 3 q t010 t021 \alpha011 tinfy11 - 3 q t010 t021 \alpha011 tinfy21
\end{aligned}$$

$$\begin{aligned}
& -3 q t010 t021 \alpha021 tinfy11 + 3 q t010 t021 \alpha021 tinfy21 + 3 q t011^2 t020 alphainf11 \\
& - 3 q t011^2 t020 alphainf21 - 3 q t011 t020 t021 alphainf11 \\
& + 3 q t011 t020 t021 alphainf21 + 3 q t011 t020 \alpha011 tinfy11 \\
& - 3 q t011 t020 \alpha011 tinfy21 - 3 q t011 t020 \alpha021 tinfy11 \\
& + 3 q t011 t020 \alpha021 tinfy21 + 2 p t011^2 tinfy11 - 2 p t011^2 tinfy21 \\
& - 2 p t021^2 tinfy11 + 2 p t021^2 tinfy21 + 4 t011^2 t021 alphainf11 \\
& - 4 t011^2 t021 alphainf21 - 4 t011 t021^2 alphainf11 + 4 t011 t021^2 alphainf21 \\
& + 4 t011 t021 \alpha011 tinfy11 - 4 t011 t021 \alpha011 tinfy21 - 4 t011 t021 \alpha021 tinfy11 \\
& + 4 t011 t021 \alpha021 tinfy21) h
\end{aligned}$$

Entry21TermLambdaInfty3 := 0

Entry21TermLambdaInfty2 := 0

Entry21TermLambdaInfty1 := 0

$$Entry21TermLambdaInfty0 := -(alphainf11 tinfy21 + alphainf21 tinfy11) h$$

$$-\frac{t011 t021}{\lambda^4} - \frac{t010 t021 + t011 t020}{\lambda^3} - \frac{H}{\lambda^2} - tinfy11 tinfy21$$

$$- \frac{-h p + h tinfy11 + tinfy10 tinfy21 + tinfy11 tinfy20}{\lambda} - \frac{p h}{\lambda - q}$$

> rho:=factor(solve(Entry21TermLambdaMinusqCube,rho));

simplify(rho+p*q*nu);

simplify(Entry21TermLambdaMinusqCube);

LH:=simplify(-Entry21TermLambdaZeroMinus1):

EquationPoleSimple:=simplify(-h*(alphainf11*tinfy20+alphainf21*tinfy10+h*alphainf11-Lp)-

Entry21TermLambdaZeroMinus1):

$$p := -\frac{1}{(-tinfy21 + tinfy11)(t011 - t021)} (p q^2 (t011 alphainf11 - t011 alphainf21 - t021 alphainf11 + t021 alphainf21 + \alpha011 tinfy11 - \alpha011 tinfy21 - \alpha021 tinfy11 + \alpha021 tinfy21)) \quad (2.6)$$

0

0

> LpFunction:=unapply(-Entry21TermLambdaMinusq/h,H):

> Equation1:=simplify(Entry21TermLambdaMinusqSquare-(-p*h*Lq)):

> Hsol:=solve(Equation1,H):

Hsolbis:=-q^2*p^2+q^2*p1(q)*p-q^2*(p2(q)-P022/q^2)-p*q*h-

tinfy11*q*h;

factor(series(Hsol-Hsolbis+(tinfy11+tinfy21)

/2*CoherenceEquation1*q,q=0));

$$Hsolbis := -q^2 p^2 + q^2 \left(\frac{t011 + t021}{q^2} + \frac{t010 + t020}{q} - tinfy11 - tinfy21 \right) p \quad (2.7)$$

$$\begin{aligned}
& -q^2 \left(\frac{t011 t021}{q^4} + \frac{t010 t021 + t011 t020}{q^3} \right. \\
& + \frac{1}{q} \left(-\frac{1}{2} (t010 + t020) (tinfy11 + tinfy21) - \frac{1}{2} (tinfy10 - tinfy20) \right. \\
& \left. \left. - tinfy21 + tinfy11 \right) + tinfy11 tinfy21 \right) - h p q - tinfy11 q h \\
& 0
\end{aligned}$$

> Lp:=factor(simplify(LpFunction(Hsol))):

Lpbis:=

$$\begin{aligned}
& ((alphainf11-alphainf21)/(tinfy11-tinfy21)+(alpha011- \\
& alpha021)/(t011-t021))*(-2*q*p^2+diff(q^2*p1(q),q)*p-diff(q^2* \\
& p2(q),q)) \\
& -alphainf11*h- (alpha011-alpha021)*h*p/(t011-t021)-h*(alpha011- \\
& alpha021)*tinfy11/(t011-t021)-(t021*alpha011-t011*alpha021)* \\
& h/q^2/(t011-t021):
\end{aligned}$$

Lpter:=((alphainf11-alphainf21)/(tinfy11-tinfy21)+(alpha011- \\
alpha021)/(t011-t021))*(
-2*q*p^2+((t010+t020)-2*(tinfy11+tinfy21)*q)*p+2*t011* \\
t021/q^3+(t010*t021+t011*t020)/q^2 +1/2*((t010+t020)*(tinfy11+ \\
tinfy21)+(tinfy10-tinfy20)*(tinfy11-tinfy21))-2*tinfy11* \\
tinfy21*q)
-alphainf11*h- (alpha011-alpha021)*h*p/(t011-t021)-h*(alpha011- \\
alpha021)*tinfy11/(t011-t021)-(t021*alpha011-t011*alpha021)* \\
h/q^2/(t011-t021):

factor(series(Lp-Lpbis+1/2*(tinfy11+tinfy21)*(-alphainf11+ \\
alphainf21)/(tinfy21-tinfy11)*CoherenceEquation1-1/2* \\
(tinfy11+tinfy21)*(alpha011-alpha021)/(t021-t011)* \\
CoherenceEquation1,p=0));

factor(Lp-Lpter-1/2*(tinfy11+tinfy21)*(alphainf11-alphainf21) \\
/(tinfy21-tinfy11)*CoherenceEquation1-1/2*(tinfy11+tinfy21) \\
*(alpha011-alpha021)/(t021-t011)*CoherenceEquation1);

(2.8)

> factor(Lqbis- ((alphainf11-alphainf21)/(tinfy11-tinfy21) \\
+(alpha011-alpha021)/(t011-t021))*(2*q^2*p-q^2*p1(q)) + \\
(alpha011-alpha021)*q*h/(t011-t021));
0

(2.9)

We get that

$L[q] = ((alphainf11-alphainf21)/(tinfy11-tinfy21)+(alpha011-alpha021)/(t011-t021))*(2*q^2*$

```

p-q^2*P1(q)) -(alpha011-alpha021)*q*h/(t011-t021)
L[p] = ((alphainf11-alphainf21)/(tinfy11-tinfy21)+(alpha011-alpha021)/(t011-t021))*(-2*q*p^2+
diff(q^2*P1(q),q)*p-diff(q^2*P2(q),q)) -alphainf11*h - (alpha011-alpha021)*h*p/(t011-t021)-h*
(alpha011-alpha021)*tinfy11/(t011-t021)-(t021*alpha011-t011*alpha021)*h/q^2/(t011-t021)

> Hamiltonian:= ((alphainf11-alphainf21)/(tinfy11-tinfy21) +
(alpha011-alpha021)/(t011-t021))*(q^2*p^2-q^2*P1(q)*p+q^2*P2(q))
+alphainf11*q*h+(alpha011-alpha021)*p*q*h/(t011-t021)+h*
(alpha011-alpha021)*tinfy11/(t011-t021)*q-(t021*alpha011-t011*
alpha021)*h/q/(t011-t021);
factor(simplify(diff(Hamiltonian,p)-Lq));
factor(simplify(diff(Hamiltonian,q)+Lp+(tinfy11+tinfy21)*(-
alphainf11+alphainf21)/(tinfy21-tinfy11)
/2*CoherenceEquation1)
-1/2*(tinfy11+tinfy21)*(alpha011-alpha021)/(t021-t011)*
CoherenceEquation1);

Hamiltonianbis:= mu*(p^2-P1(q)*p+h*p*(2/q) +tdP2(q) )-h*nu0*p-
h*nuMinus1*q*p -h*c01/q- h*cinfy1*q
+nu0*(tinfy11*tinfy20+tinfy21*tinfy10+h*tinfy11) :

factor(simplify(Lp- (-diff(Hamiltonianbis,q)))); 
simplify(Lq- (diff(Hamiltonianbis,p)));

```

$$\begin{aligned}
& \text{Hamiltonian} := \left(\frac{\alpha_{011} - \alpha_{021}}{t_{011} - t_{021}} + \frac{\alpha_{011} - \alpha_{021}}{-t_{\text{infy21}} + t_{\text{infy11}}} \right) \left(q^2 p^2 - q^2 \left(\frac{t_{011} + t_{021}}{q^2} \right. \right. \\
& \left. \left. + \frac{t_{010} + t_{020}}{q} - t_{\text{infy11}} - t_{\text{infy21}} \right) p + q^2 \left(\frac{t_{011} t_{021}}{q^4} + \frac{t_{010} t_{021} + t_{011} t_{020}}{q^3} \right. \right. \\
& \left. \left. + \frac{P_{022}}{q^2} \right. \right. \\
& \left. \left. + \frac{1}{q} \left(-\frac{1}{2} (t_{010} + t_{020}) (t_{\text{infy11}} + t_{\text{infy21}}) - \frac{1}{2} (t_{\text{infy10}} - t_{\text{infy20}}) (-t_{\text{infy21}} + t_{\text{infy11}}) \right) + t_{\text{infy11}} t_{\text{infy21}} \right) \right) + \alpha_{011} q h + \frac{(\alpha_{011} - \alpha_{021}) p q h}{t_{011} - t_{021}} \\
& \left. + \frac{h (\alpha_{011} - \alpha_{021}) t_{\text{infy11}} q}{t_{011} - t_{021}} - \frac{(-t_{011} \alpha_{021} + t_{021} \alpha_{011}) h}{q (t_{011} - t_{021})} \right. \\
& \left. \left. \left. \left. \begin{matrix} 0 \\ 0 \\ 0 \\ 0 \end{matrix} \right. \right. \right. \right. \quad (2.10)
\end{aligned}$$

Decomposition of the tangent space

```
> tdp:=p-P1(q)/2:
```

```

Ltp:=Lp-1/2*diff(P1(q),q)*Lq-1/2*(h*alphainf11*diff(P1(q),
tinfy11)+h*alphainf21*diff(P1(q),tinfy21)+h*alpha011*diff(P1
(q),t011)+h*alpha021*diff(P1(q),t021)) :
Ltpbis:=-((alphainf11-alphainf21)/(tinfy11-tinfy21) +
(alpha011-alpha021)/(t011-t021))*(2*q*tdp^2+diff(q^2*(P2(q)-P1
(q))^2/4),q)
+h/2*(tinfy11-tinfy21))-(alpha011-alpha021)*h*tdp/(t011-t021)
:
factor(series(factor(simplify(Ltp-Ltpbis+(tinfy11+tinfy21)*
(alphainf11-alphainf21)/2/(tinfy11-tinfy21)
*CoherenceEquation1)
+(tinfy11+tinfy21)*(alpha011-alpha021)/2/(t011-t021)*
CoherenceEquation1),h=0));
0

```

(3.1)

```

> Lpfunction:=unapply(simplify(Lp),
alphainf11,alphainf21,alpha011,alpha021):
Ltpfunction:=unapply(simplify(Ltp),alphainf11,alphainf21,
alpha011,alpha021):
Lqfunction:=unapply(simplify(Lq),alphainf11,alphainf21,
alpha011,alpha021):
cinfy1function:=unapply(cinfy1,alphainf11,alphainf21,
alpha011,alpha021):
c01function:=unapply(c01,alphainf11,alphainf21,alpha011,
alpha021):
nuMinus1function:=unapply(nuMinus1,alphainf11,alphainf21,
alpha011,alpha021):
> factor(Ltpfunction(1,1,0,0));
factor(Lqfunction(1,1,0,0));
factor(cinfy1function(1,1,0,0));
factor(c01function(1,1,0,0));
factor(nuMinus1function(1,1,0,0));
0
0
-1
0
0

```

(3.2)

```

> factor(Ltpfunction(0,0,1,1));
factor(Lqfunction(0,0,1,1));
factor(cinfy1function(0,0,1,1));
factor(c01function(0,0,1,1));
factor(nuMinus1function(0,0,1,1));
0
0
0

```

(3.3)

Expression of the Lax matrices in the geometric gauge after the symplectic reduction and the Painlevé 3 equation

Expression of the geometric Lax matrix in the gauge without apparent singularities after symplectic reduction

```
> tinfy21:=-tinfy11:  
  tinfy20:=-tinfy10:  
  t021:=-t011:  
  t020:=-t010:  
  tinfy11:=1:  
  t011:=t/2:  
  H:=Hsol:  
  C:=0:  
  q:=checkq:  
  p:=checkp:  
  dcheckqdt:=Lq/h:  
  dcheckpdt:=Lp/h:  
  
  alphainf11:=0:  
  alphainf21:=0:  
  alpha011:=1/2:  
  alpha021:=-1/2:  
> G1:=Matrix(2,2,0):  
  G1[1,1]:=1:  
  G1[2,2]:=1:  
  G1[1,2]:=0:  
  G1[2,1]:=g1*lambda+g0:  
  g1:=tinfy11;  
  g0:=checkq+tinfy10;  
  
  dG1dlambda:=Matrix(2,2,0):  
  for i from 1 to 2 do for j from 1 to 2 do dG1dlambda[i,j]:=diff(G1[i,j],lambda): od: od:  
  
  dG1dtau:=Matrix(2,2,0):  
  for i from 1 to 2 do for j from 1 to 2 do dG1dtau[i,j]:=diff(G1[i,j],t)+diff(G1[i,j],checkq)*dcheckqdt+diff(G1[i,j],checkp)  
  *dcheckpdt : od: od:
```

```

tdL:=simplify(Multiply(Multiply(G1,checkL),G1^(-1))+h*Multiply
(dG1dlambda,G1^(-1)));
tdA:=simplify(Multiply(Multiply(G1,checkA),G1^(-1))+h*Multiply
(dG1dtau,G1^(-1)));

checkL:=simplify(checkL);
checkA:=simplify(checkA);
tdL:=simplify(tdL);
tdA:=simplify(tdA);

```

$$\begin{aligned}
& \text{g1 := 1} \\
& g0 := \text{checkq} + \text{tinfy10} \\
& \left[\left[\frac{\text{checkp} \text{checkq}^2}{\lambda^2}, \frac{\lambda - \text{checkq}}{\lambda^2} \right], \right. \\
& \quad \left[\frac{1}{4} \frac{1}{\lambda^2 \text{checkq}^2} \left(4 \text{checkp}^2 \text{checkq}^5 + 4 \text{checkp}^2 \text{checkq}^4 \lambda + 4 \lambda^2 \text{checkq}^3 \right. \right. \\
& \quad \left. \left. - 4 \lambda^2 (h - \lambda - 2 \text{tinfy10}) \text{checkq}^2 + (-4 \lambda t \text{t010} - t^2) \text{checkq} - \lambda t^2 \right), \right. \\
& \quad \left. \left[- \frac{\text{checkp} \text{checkq}^2}{\lambda^2} \right] \right] \\
& \left[\left[- \frac{\text{checkp} \text{checkq}^2}{\lambda t}, \frac{\text{checkq}}{t \lambda} \right], \right. \\
& \quad \left[\frac{1}{4} \frac{-4 \text{checkp}^2 \text{checkq}^4 + 8 \lambda \text{checkq}^3 - 4 \lambda (h - \lambda - 2 \text{tinfy10}) \text{checkq}^2 + t^2}{\lambda \text{checkq} t}, \right. \\
& \quad \left. \left[\frac{\text{checkp} \text{checkq}^2}{\lambda t} \right] \right] \\
& \left[\left[\frac{(\text{checkp} + 1) \text{checkq}^2 + \text{tinfy10} \text{checkq} - \lambda (\lambda + \text{tinfy10})}{\lambda^2}, \frac{\lambda - \text{checkq}}{\lambda^2} \right], \right. \\
& \quad \left[\frac{1}{4} \frac{1}{\lambda^2 \text{checkq}^2} \left(4 (\text{checkp} + 1)^2 \text{checkq}^5 + 4 ((\text{checkp} + 1) \lambda \right. \right. \\
& \quad \left. \left. + 2 \text{tinfy10}) (\text{checkp} + 1) \text{checkq}^4 + 4 \text{tinfy10}^2 \text{checkq}^3 - 4 \lambda \text{tinfy10}^2 \text{checkq}^2 + (-4 \lambda t \text{t010} - t^2) \text{checkq} - \lambda t^2 \right), \right. \\
& \quad \left. \left[\frac{(-\text{checkp} - 1) \text{checkq}^2 - \text{tinfy10} \text{checkq} + \lambda (\lambda + \text{tinfy10})}{\lambda^2} \right] \right] \\
& \left[\left[- \frac{(\text{checkp} \text{checkq} + \text{checkq} + \lambda + \text{tinfy10}) \text{checkq}}{\lambda t}, \frac{\text{checkq}}{t \lambda} \right], \right]
\end{aligned} \tag{4.1}$$

$$\begin{aligned}
& \left[\frac{1}{4} \frac{1}{\lambda \text{checkq} t} \left(((2 \text{checkp} + 2) \text{checkq}^2 + 2 \text{tinfy10} \text{checkq} + t) \right. \right. \\
& \quad \left. \left. (-2 \text{checkp} - 2 \text{checkq}^2 - 2 \text{tinfy10} \text{checkq} + t) \right) \right. \\
& \quad \left. \frac{(\text{checkp} \text{checkq} + \text{checkq} + \lambda + \text{tinfy10}) \text{checkq}}{\lambda t} \right] \\
\Rightarrow & \text{series}(\text{tdL}[1,1], \text{lambda}=\text{infinity}); \\
& \text{series}(\text{tdL}[1,2], \text{lambda}=\text{infinity}); \\
& \text{residue}(\text{tdL}[2,1]/\text{lambda}, \text{lambda}=\text{infinity}); \\
& -1 - \frac{\text{tinfy10}}{\lambda} + \frac{(\text{checkp} + 1) \text{checkq}^2 + \text{tinfy10} \text{checkq}}{\lambda^2} \\
& \quad \frac{1}{\lambda} - \frac{\text{checkq}}{\lambda^2} \\
& \quad 0
\end{aligned} \tag{4.2}$$

Reduced Hamiltonian evolutions

$$\begin{aligned}
& \text{simplify}(\text{series}(\text{dcheckqdt}, \text{checkp}=0)); \\
& \text{simplify}(\text{series}(\text{dcheckpdt}, \text{checkp}=0));
& \quad \frac{\text{checkq}}{t} + \frac{2 \text{checkq}^2}{t h} \text{checkp} \\
& \frac{1}{2} \frac{4 \text{checkq}^4 + (-2 h + 4 \text{tinfy10}) \text{checkq}^3 - 2 \text{checkq} t010 t - t^2}{\text{checkq}^3 t h} - \frac{1}{t} \text{checkp} \\
& \quad - \frac{2 \text{checkq}}{t h} \text{checkp}^2
\end{aligned} \tag{4.3}$$