

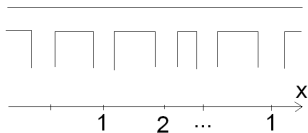
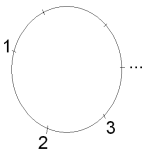
Riemann problem for traffic flow on a roundabout

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Modelization.



Model

- LWR model on each open segment: let v be a given (decreasing) speed law, then the total density r verifies

$$\partial_t r + \partial_x (rv(r)) = 0;$$

- Special boundary conditions:
 - bounds on the flows of exiting and entering vehicles,
 - conservation of the flow of the vehicles staying on the road.

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The one-T road.

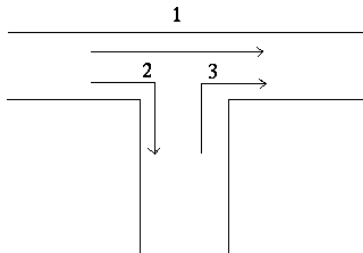


Figure: Road with an entry and an exit in $x = 0$.

ρ_1 : density of vehicles that go straight,

ρ_2 : density of vehicles that are to turn right,

ρ_3 : density of vehicles that are entering the road.

Equations:

We write the mass conservation of the vehicles with the same speed law v (multi-class extension of the LWR model):

$$\begin{cases} \partial_t \rho_1 + \partial_x (\rho_1 v(\rho_1 + \rho_2)) = 0 \\ \partial_t \rho_2 + \partial_x (\rho_2 v(\rho_1 + \rho_2)) = 0 \end{cases} \text{ for } x < 0, \\ \begin{cases} \partial_t \rho_1 + \partial_x (\rho_1 v(\rho_1 + \rho_3)) = 0 \\ \partial_t \rho_3 + \partial_x (\rho_3 v(\rho_1 + \rho_3)) = 0 \end{cases} \text{ for } x > 0. \end{cases} \quad (1)$$

We also add piecewise constant initial data (Riemann problem):

$$\begin{aligned} \rho_1(0, x) &= \rho_1^- & \text{for } x < 0 \\ \rho_1(0, x) &= \rho_1^+ & \text{for } x > 0 \\ \rho_2(0, x) &= \rho_2^- & \text{for } x < 0 \\ \rho_3(0, x) &= \rho_3^- & \text{for } x > 0, \end{aligned} \quad (2)$$

Special boundary conditions.

The boundary conditions give bounds on the flows of the vehicles:

$$\begin{aligned}
 \rho_1 v(\rho_1 + \rho_2)(t, 0-) &= \rho_1 v(\rho_1 + \rho_3)(t, 0+) && \text{max,} \\
 \rho_2 v(\rho_1 + \rho_2)(t, 0-) &\leq o(t) && \text{max,} \\
 \rho_3 v(\rho_1 + \rho_3)(t, 0+) &\leq i(t) && \text{max,}
 \end{aligned} \tag{3}$$

"max" means here that the flows of ρ_1 , ρ_2 and ρ_3 are maximised.

We also add a priority rule :

- we maximise first the flows of ρ_1 and ρ_2
- then the flow of ρ_3 .

We can obtain similar result with the other rule.

Result

Theorem

Under the hypotheses

- **(V)** : *the speed law v is $C^{0,1}$, decreasing and vanishes in 1.*
- **(R)** : *the flow $q(r) = rv(r)$ is strictly concave and attains its maximum in r_c ,*

the Riemann problem for the one T road admits a unique weak entropy solution.

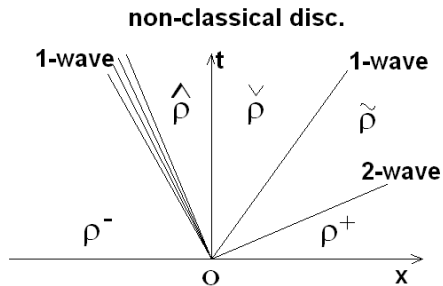
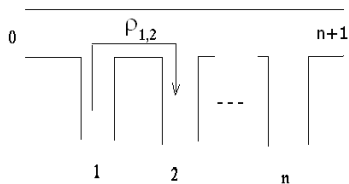


Figure: Solution.

The n -T road.



$\rho_{i,j}$: density of the vehicles which enter in i and exit in j .

(P) we know the numbers $\rho_{i,j}$ that represent the proportion of vehicles entering in i that are to exit in j .

(T) the vehicles are not authorized to do more than one turn !

This means: $\rho_{i,k}(x_k^+) = 0$, for $i \neq k$, $\rho_{k,j}(x_k^-) = 0$, for $j \neq k$.

Equations

We have:

$$\forall i \in \llbracket 0, n \rrbracket, \forall j \in \llbracket 1, n+1 \rrbracket, \quad \partial_t \rho_{i,j} + \partial_x \left(\rho_{i,j} v \left(\sum_{l,m} \rho_{l,m} \right) \right) = 0 \quad (4)$$

with boundary conditions in x_k :

$$\begin{aligned} \text{for } i, j \neq k, \quad \rho_{i,j} v \left(\sum_{l,m} \rho_{l,m} \right) (t, x_k^-) &= \rho_{i,j} v \left(\sum_{l,m} \rho_{l,m} \right) (t, x_k^+) && \text{max,} \\ \sum_{0 \leq i \leq n} \rho_{i,k} v \left(\sum_{l,m} \rho_{l,m} \right) (t, x_k^-) &\leq o_k(t) && \text{max,} \\ \sum_{1 \leq j \leq n+1} \rho_{k,j} v \left(\sum_{l,m} \rho_{l,m} \right) (t, x_k^+) &\leq i_k(t) && \text{max,} \end{aligned}$$

the flows being maximized first in x_k^- and then in x_k^+ because of the priority rule.

Theorem

Under the hypotheses **(V)**, **(F)** and **(P)**, there exists $T > 0$ such that the Riemann problem for the n -T road admits a unique weak entropy solution for $t \in [0, T]$.

Furthermore, we can give a lower bound for the time of existence: let $L = \min(x_{k+1} - x_k) > 0$, then $T \geq \frac{L}{2V}$.

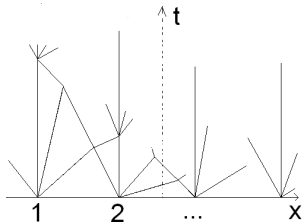


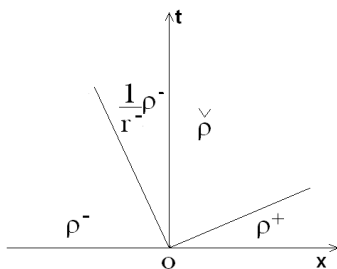
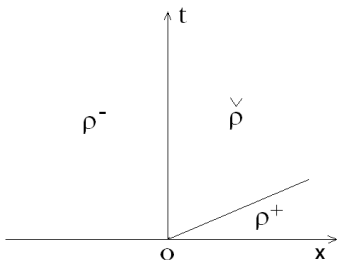
Figure: Solution with n points of entry and exit.

Discontinuity points.

We have some points of discontinuity for the Riemann solver :

- when $o, \rho_2^- \rightarrow 0$;
- when $r^+ = \rho_1^+ + \rho_3^+ \rightarrow 1$ and $\rho_1^- \rightarrow 0$,

For example, in the case: $o = 0$, i large, $\rho_1^- < r_c$, $r^+ \geq r_c$, we obtain



Invariant sets.

We have some invariant sets.

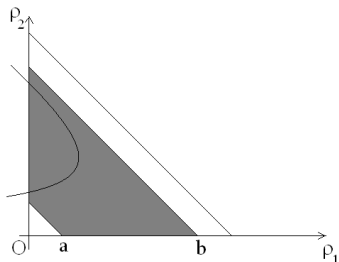


Figure: Invariant set.

On \mathcal{S} the Riemann solver for the considered problem is not continuous. However, it is continuous on some subset: for $\sigma \in [\varepsilon, 1]$ with $\varepsilon > 0$ and on $\rho \in T_{0,b}$, with $b < 1$ and $T_{0,b}$ invariant, the solution is obtained continuously.

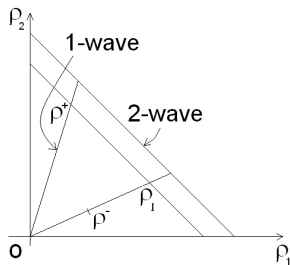


Figure: Waves curves.

We consider here a multi-class extension of the LWR model. The solution of the Riemann problem is obtained by following the Hugoniot loci.

- The 1- waves are shocks or rarefaction waves;
- the 2-waves are contact discontinuities.

We call $N(\rho^-)$ the set of states attainable in $x = 0$ by the left and $P(\rho^+)$ the set of states attainable in $x = 0$ by the right.

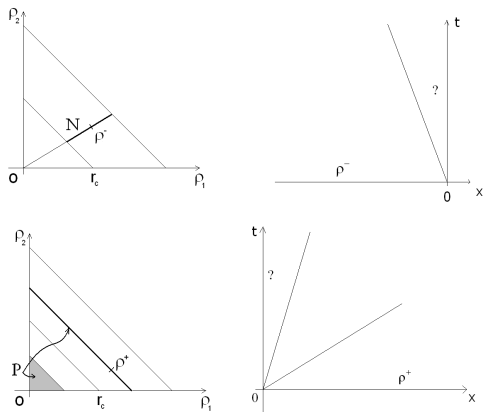


Figure: Left-Riemann problem(top), right-riemann problem (bottom).

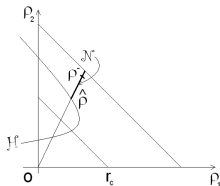
Authorized set.

Let d be a function such that $d(r) = q_c$ if $r \leq r_c$ and $d(r) = q(r)$ if $r \geq r_c$. Then, we introduce:




$$\mathcal{N}(\rho_1^-, \rho_2^-) = N(\rho_1^-, \rho_2^-) \cap \{(\rho_1, \rho_2), \rho_2 v(\rho_1 + \rho_2) \leq o\} \\ \cap \{(\rho_1, \rho_2), \rho_1 v(\rho_1 + \rho_2) \leq d(r^+)\},$$

$$\mathcal{P}(\rho_1^+, \rho_3^+) = P(\rho_1^+, \rho_3^+) \cap \{(\rho_1, \rho_3), \rho_1 v(\rho_1 + \rho_3) = M\} \\ \cap \{(\rho_1, \rho_3), \rho_3 v(\rho_1 + \rho_3) \leq i\}.$$

We maximise the flow of ρ_2 on $\mathcal{N}(\rho^-)$ and then the flow of ρ_3 on $\mathcal{P}(\rho^+)$.



Conclusion:

-  Benzoni-Gavage, S. and Colombo, R., An n -populations model for traffic flow, 2003
-  Colombo, Rinaldo M. and Goatin, Paola, A well posed conservation law with a variable unilateral constraint, J. Differential Equations, 2007,
-  Serre, D., Systèmes de lois de conservation. I, Diderot Editeur, Paris, 1996,