

FINAL EXAM
DECEMBER 13, 2023 – 3 HOURS

PART I. SOLVING THE LAPLACE EQUATION WITH DIVERGENCE FORM DATUM. The purpose of this part is to partially prove the following

Theorem. Let Ω be a bounded domain in \mathbb{R}^N , of class C^2 , and let $1 < p < \infty$. For $F \in L^p(\Omega; \mathbb{R}^N)$, the equation

$$-\Delta u = \operatorname{div} F \text{ in } \mathcal{D}'(\Omega) \quad (1)$$

has a unique solution $u \in W_0^{1,p}(\Omega; \mathbb{R})$. In addition, with some finite constant C independent of F (but possibly depending on p and Ω), we have the estimate $\|u\|_{W^{1,p}} \leq C\|F\|_p$.

Preliminaries. a) The following identity may be useful. If $\omega, \Omega \subset \mathbb{R}^N$ are open sets and $\Phi \in C^1(\omega; \Omega)$, then

$$\nabla(u \circ \Phi) = {}^t J\Phi[(\nabla u) \circ \Phi], \quad \forall u \in C^1(\Omega; \mathbb{R}).$$

b) We set $\mathbb{R}_+^N = \mathbb{R}^{N-1} \times (0, \infty)$, $B_+ = \{x \in \mathbb{R}_+^N; |x| < 1\}$, and $B_0 = \{(x', 0); x' \in \mathbb{R}^{N-1}, |x'| \leq 1\}$.

c) In what follows, C denotes a constant depending possibly on p and Ω , but not on F , u , or the other scalar functions, matrix-valued functions, or vector fields appearing in the equations. This constant may change from a line to another.

d) We always suppose that $1 < p < \infty$. We take for granted the L^p -regularity theory for the equation $-\Delta u = f \in W^{k,p}(\Omega; \mathbb{R})$ and the following variant of the crucial lemma of the L^p -regularity theory.

Crucial lemma. There exist some $\varepsilon_0 > 0$ and $C < \infty$, possibly depending on $1 < p < \infty$ and on N , but not on B , H , h , or w below, such that, for: (a) $w \in W^{2,p}(B_+; \mathbb{R})$ satisfying: (i) there exists some $0 < R < 1$ such that $w(x) = 0$ if $|x| > R$; (ii) $\operatorname{tr}_{|B_0} w = 0$; (b) $H \in L^p(B_+; \mathbb{R}^N)$; (c) $h \in L^p(B_+; \mathbb{R})$; (d) $B \in L^\infty(B_+; M_N(\mathbb{R}))$, satisfying the equation

$$-\Delta w = \operatorname{div}(B\nabla w) + \operatorname{div} H + h \text{ in } \mathcal{D}'(B_+)$$

and the smallness condition $\|B\|_\infty \leq \varepsilon_0$, we have

$$\|w\|_{W^{1,p}} \leq C\|H\|_p + C\|h\|_p.$$

Exercise A. If p, q are conjugated exponents, prove that

$$[u \in W_0^{1,p}(\Omega; \mathbb{R}), -\Delta u = 0, v \in W^{2,q}(\Omega; \mathbb{R}) \cap W_0^{1,q}(\Omega; \mathbb{R})] \implies \int_\Omega u(-\Delta v) = 0,$$

and derive the uniqueness, in $W_0^{1,p}(\Omega; \mathbb{R})$, of a solution of (1).

Exercise B. Assume that the following *a priori* estimate holds.

$$[F \in C_c^\infty(\Omega; \mathbb{R}^N), u \in W_0^{1,p}(\Omega; \mathbb{R}) \text{ solves (1)}] \implies \|u\|_{W^{1,p}} \leq C\|F\|_p + C\|u\|_p. \quad (2)$$

1. Prove that the estimate (2) implies the validity of the following *a priori* estimate.

$$[F \in C_c^\infty(\Omega; \mathbb{R}^N), u \in W_0^{1,p}(\Omega; \mathbb{R}) \text{ solves (1)}] \implies \|u\|_{W^{1,p}} \leq C\|F\|_p.$$

2. Prove that the estimate (2) (and possibly other ingredients, to be specified) implies the theorem.

Exercise C. Let $u \in W_{loc}^{1,1}(\Omega; \mathbb{R})$ and $F \in L_{loc}^1(\Omega; \mathbb{R}^N)$ satisfy (1). Let $\Phi : \omega \rightarrow \Omega$ be a C^1 -diffeomorphism. Set $v = u \circ \Phi$. Find (explicitly) a matrix-valued function $A \in C(\omega; M_N(\mathbb{R}))$ and a vector field $G \in L_{loc}^1(\omega; \mathbb{R}^N)$ such that

$$-\operatorname{div}(A\nabla v) = \operatorname{div} G \text{ in } \mathcal{D}'(\omega), \quad (3)$$

and carefully justify and give a precise meaning to (3).

Exercise D. Let $v \in W^{1,p}(B_+; \mathbb{R})$, $A \in C(B_+; M_N(\mathbb{R}))$, and $G \in L^p(B_+; \mathbb{R})$ satisfy (3) with $\omega = B_+$. Assume, moreover, that A is symmetric. (Is this requirement restrictive?)

1. Let $\zeta \in C^1(B_+; \mathbb{R})$ and set $w = \zeta v$. Carefully justify the equality

$$-\operatorname{div}(A\nabla w) = \operatorname{div}(\zeta G) - G \cdot \nabla \zeta - 2 \operatorname{div}(vA\nabla \zeta) + v \operatorname{div}(A\nabla \zeta) \text{ in } \mathcal{D}'(B_+). \quad (4)$$

2. Assume furthermore that: (i) for some $0 < R < 1$, we have $\zeta(x) = 0$ if $|x| \geq R$; (ii) $\zeta \in C^2(\overline{B_+})$; (iii) $v \in W^{2,p}(B_+)$; (iv) $\operatorname{tr}_{|B_0} v = 0$. Write $A = I_N + B$. Under an appropriate smallness condition on B , prove the *a priori* estimate

$$\|w\|_{W^{1,p}} \leq C\|G\|_p + C\|v\|_p. \quad (5)$$

3. Sketch the strategy for deriving (2) from (5) (and possibly other ingredients).

PART II. A UNIQUENESS RESULT. In what follows, B denotes the unit ball in \mathbb{R}^N . The purpose of this part is to establish the implication

$$[u \in W_0^{1,1}(B; \mathbb{R}), -\Delta u = 0] \implies u = 0. \quad (6)$$

Preliminaries. a) The following result (see, e.g., [1, Proposition 9.18]) may be useful. Let $\Omega \subset \mathbb{R}^N$ be an open set and let $u \in W_0^{1,1}(\Omega; \mathbb{R})$. Let \tilde{u} be the extension of u with the value 0 outside Ω . Then $\tilde{u} \in W^{1,1}(\mathbb{R}^N; \mathbb{R})$ and, in addition, $\nabla \tilde{u}$ is the extension of ∇u with the value 0 outside Ω .

b) We set, for $r > 0$, $B_r := \{x \in \mathbb{R}^N; |x| < r\}$, $S_r := \{x \in \mathbb{R}^N; |x| = r\}$.

Exercise A. Let $u \in C(B; \mathbb{R}) \cap W_0^{1,1}(B; \mathbb{R})$. For $0 < r < 1$, prove that

$$\int_{S_r} |u| \leq \int_{B \setminus B_r} |\nabla u|. \quad (7)$$

A possible approach consists of arguing by smoothing, by carefully justifying the limiting argument.

Exercise B. We now prove (6).

1. Let $g \in C_c^\infty(B; \mathbb{R})$ and let $v \in H_0^1(B; \mathbb{R})$ solve $-\Delta v = g$. For $0 < r < 1$, prove that

$$\begin{aligned} \left| \int_{B_r} u g \right| &\leq \|\nabla v\|_{L^\infty(B)} \int_{S_r} |u| + \|v\|_{L^\infty(S_r)} \int_{S_r} |\nabla u| \\ &\leq \|\nabla v\|_{L^\infty(B)} \int_{B \setminus B_r} |\nabla u| + (1-r) \|\nabla v\|_{L^\infty(B)} \int_{S_r} |\nabla u|. \end{aligned} \quad (8)$$

2. Conclude, using an appropriate sequence $r_j \rightarrow 1$.

References

- [1] Haim Brezis. *Functional analysis, Sobolev spaces and partial differential equations*. Universitext. Springer, New York, 2011.