

April 30, 2024

- Exercises - Runge-Kutta method

$$\text{EX 5. (d)} \quad \begin{array}{c|cccc} 0 & 0 & 0 & 0 & 0 \\ \frac{1}{2} & \frac{1}{2} & 0 & 0 & 0 \\ \frac{1}{2} & 0 & \frac{1}{2} & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 \\ \hline & \frac{1}{6} & \frac{1}{3} & \frac{1}{3} & \frac{1}{6} \end{array}$$

Is developed as a R-K scheme as follows:

$$\text{Remark: } \begin{cases} X_i = x_n + h \sum_{j=1}^{i-1} a_{ij} f(t_n + c_j h, X_j) & i=1, \dots, s \\ x_{n+1} = x_n + h \sum_{i=1}^s b_i f(t_n + c_i h, X_i) & \text{with } \sum_{i=1}^s b_i = 1 \end{cases}$$

We have $S=4$

- As usual = $X_1 = x_n$
- $X_2 = x_n + h \sum_{j=1}^1 a_{2j} f(t_n + c_j h, X_j)$
- $X_2 = x_n + \frac{1}{2} h f(t_n, x_n)$

$$\bullet X_3 = x_n + h \sum_{j=1}^3 a_{3j} f(t_n + c_j h, x_j)$$

$$\boxed{X_3 = x_n + \frac{1}{2} h (f(t_n + 1/2 h, x_n) + 1/2 h f(t_n, x_n))}$$

$$\bullet X_4 = x_n + h \sum_{j=1}^3 a_{4j} f(t_n + c_j h, x_j)$$

$$\boxed{X_4 = x_n + h f(t_n + 1/2 h, x_n + 1/2 h (f(t_n + 1/2 h, x_n + 1/2 h f(t_n, x_n))))}$$

$$\bullet X_{n+1} = x_n + h \sum_{i=1}^4 b_i f(t_n + c_i h, x_i)$$

$$\boxed{X_{n+1} = x_n + 1/6 h f(t_n, x_n) + 1/3 h f(t_n + 1/2 h, x_2) + 1/3 h f(t_n + 1/2 h, x_3) + 1/6 h f(t_n, c_4, x_4)}$$

Question: is this scheme of order at least 1?

at least 2?

0	0	0	0	0
$\frac{1}{2}$	$\frac{1}{2}$	0	0	0
$\frac{1}{2}$	0	$\frac{1}{2}$	0	0
1	0	0	1	0
<hr/>				
	$\frac{1}{6}$	$\frac{1}{3}$	$\frac{1}{3}$	$\frac{1}{6}$

at least 1: $\sum_{i=1}^4 b_i = \frac{1}{6} + \frac{1}{3} + \frac{1}{3} + \frac{1}{6} = \frac{3}{3} = 1$ OK

at least 2

It is of order at least 2 if: $\sum_{i=1}^4 b_i c_i = \frac{1}{2}$ and $\sum_{i=1}^4 b_i \left(\sum_{j=1}^s a_{ij} \right) = \frac{1}{2}$

i) $\sum_{i=1}^4 b_i c_i = 0 \cdot \frac{1}{6} + \frac{1}{2} \cdot \frac{1}{3} + \frac{1}{2} \cdot \frac{1}{3} + 1 \cdot \frac{1}{6} = \frac{1}{2}$ (OK)

ii) $\sum_{i=1}^4 b_i \sum_{j=1}^{i-1} a_{ij} = b_2 a_{21} + b_3 a_{31} + b_3 a_{32} + b_4 a_{41} + b_4 a_{42} + b_4 a_{43}$
 $= \frac{1}{3} \cdot \frac{1}{2} + \frac{1}{3} \cdot \frac{1}{2} + \frac{1}{6} \cdot 1 = \frac{1}{2}$ (OK)

Note: this scheme is in fact of order 4, and is called RK4 (it is the one used in the matlab solver ode45)

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$$2. \quad (a) \quad \begin{array}{c|cc} 0 & 0 & 0 \\ 2/3 & 2/3 & 0 \\ \hline & \alpha & \alpha \end{array}$$

(a). Develop this scheme:

(b) Find α in order to get order at least 1

Is then possible to get order 2?

$$(a) \quad X_1 = x_n + h \sum_{j=1}^0 \dots = x_n$$

$$X_2 = x_n + h \sum_{j=1}^1 a_{ij} f(t_n + c_j h, X_j) = x_n + h \frac{2}{3} f(t_n + 0h, x_n) = x_n + h \frac{2}{3} f(t_n, x_n)$$

$$x_{n+1} = x_n + h \sum_{i=1}^2 b_i f(t_n + c_i h, X_i) \\ = x_n + h (\alpha f(t_n + 0h, X_1) + \alpha f(t_n + \frac{2}{3}h, X_2))$$

$$x_{n+1} = x_n + h\alpha f(t_n, X_1) + h\alpha f(t_n + \frac{2}{3}h, X_2)$$

$$(b) \text{ we want } \sum b_i = 1 \Rightarrow \alpha + \alpha = 1 \Rightarrow 2\alpha = 1 \Rightarrow \alpha = \frac{1}{2}$$

order at least 2:

$$\sum b_i c_i = \alpha \times 0 + \alpha \times \frac{2}{3} = \frac{1}{2} \times \frac{2}{3} = \frac{1}{3} \neq \frac{1}{2} \quad \text{it doesn't work}$$

$$\begin{array}{c|c} 0 & 0 \\ \gamma & 0 \end{array} \quad \text{we want } \sum_{i=1}^2 b_i c_i^2 = \frac{1}{2} \Rightarrow \frac{1}{2} \times 0 + \frac{1}{2} \times \beta = \frac{1}{2} \Rightarrow \beta = 1$$

$$\begin{array}{c|cc} \beta & \gamma & 0 \\ \hline & 1/2 & 1/2 \end{array}$$

we want $\sum_{i=1}^2 b_i c_i = \frac{1}{2} \Rightarrow \frac{1}{2} \times 0 + \frac{1}{2} \times \beta = \frac{1}{2} \Rightarrow \beta = 1$

$\sum_{i=1}^2 b_i \sum_{j=1}^1 a_{ij} = \frac{1}{2} \Rightarrow \frac{1}{2} \times \sum_{j=1}^1 \dots + \frac{1}{2} \times \sum_{j=1}^1 a_{ij} = \frac{1}{2}$

$\Rightarrow \frac{1}{2} \times \delta = \frac{1}{2} \Rightarrow \gamma = 1$

$$\begin{array}{c|cc} 0 & 0 & 0 \\ 1 & 1 & 0 \\ \hline & 1/2 & 1/2 \end{array}$$

Trapeze method

Implicit methods

1. Is the explicit Euler method A-stable?
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1. To answer the question, we need to apply the

1. To answer the question, we need to apply the STANDARD LINEAR TEST equation to the explicit Euler method:

Remember: the explicit Euler method is

$$\begin{cases} x_{n+1} = x_n + h f(t_n, x_n) & n=0, \dots, N-1 \\ x_0 \text{ given} \end{cases}$$

Applied to the (SLT): $\begin{cases} x' = -Lx, \text{ with } L > 0 \\ x(t_0) = x_0 \text{ given} \end{cases}$ $\begin{cases} x' = f(t, x) \\ x(t_0) = x_0 \end{cases}$

we set $f(t, x) = -Lx$

Applied to the explicit Euler method: (1) $x_{n+1} = x_n - h \cdot L x_n$ where $L > 0$
 $0 < h \leq T$

(1) $\Leftrightarrow \begin{cases} x_{n+1} = (1-hL) x_n, \quad n \in \mathcal{N} \quad (\text{SLT}) \rightarrow \text{we need } \underline{n \rightarrow +\infty} \\ x_0 \text{ given} \end{cases}$ $h = \frac{T}{N}$

this is a geometric sequence of the form $x_{n+1} = q \cdot x_n$

so $x_n = x_0 \cdot q^n$, for every $n \in \mathcal{N}$

here $x_n = x_0 \cdot (1-hL)^n$, $n \in \mathcal{N}$

And to satisfy A-stability we need to get $x_n \xrightarrow[n \rightarrow +\infty]{} 0$ for any $L > 0$ and $0 < h \leq T$
is it the case here?

Then $x_n \xrightarrow[n \rightarrow +\infty]{} 0$ if and only if $|1-hL| < 1$

$\Leftrightarrow -1 < 1-hL < 1$

$\Leftrightarrow -2 < -hL < 0$

$\Leftrightarrow 0 < hL < 2 \quad \Leftrightarrow$

$L < \frac{2}{h}$ or $h < \frac{2}{L}$

21

$$\begin{cases} x_{n+1} = x_n - hL x_{n+1} \\ x_0 \text{ given} \end{cases}$$

$$x_{n+1} (1 + hL) = x_n$$

$$x_{n+1} = \frac{1}{1+hL} x_n \Rightarrow x_n = \left(\frac{1}{1+hL} \right)^n x_0$$

$$0 < q < 1$$

↓
q

because: $h > 0$, $L > 0$

$$q^n \xrightarrow{n \rightarrow \infty} 0$$

so $x_n \xrightarrow{n \rightarrow \infty} 0$ for any h and $L > 0$ unconditionally!

Conclusion: the implicit Euler method is A-stable

Exercise 6. (S₁) $\begin{cases} u'(t) = -100u(t) + 25 \\ u(0) = 1 \end{cases}$

$$x'' + x' + 3x = g(t)$$

↑
order 2

1. PART: exact solution

a. order of the equation: 1. (highest derivative) here: x'

linearity: yes, because it is of the form $a(t)u'(t) + b(t)u(t) = g(t)$

with $a(t) = 1$, $b(t) = 100$ and $g(t) = 25$

autonomous. (it is not explicitly dependent)

b. yes it is globally unique because the problem is linear

c. Remember:
$$\begin{cases} x' + a(t)x = f(t) \\ x(t_0) = x_0 \end{cases}, t \in I$$

multiply the ODE by $e^{\int_{t_0}^t a(s) ds}$ and you get:

$$(x(t) e^{\int_{t_0}^t a(s) ds})' = e^{\int_{t_0}^t a(s) ds} \cdot f(t)$$

we integrate between t_0 and t :

$$\int_{t_0}^t (x(z) e^{\int_{t_0}^z a(s) ds})' dz = \int_{t_0}^t e^{\int_{t_0}^z a(s) ds} f(z) dz$$

$$\Leftrightarrow x(t) e^{\int_{t_0}^t a(s) ds} - \underbrace{x(t_0)}_{x_0} \underbrace{e^{\int_{t_0}^{t_0} a(s) ds}}_{=1} = \dots$$

$$\Leftrightarrow x(t) e^{\int_{t_0}^t a(s) ds} - x_0 = \dots$$

$$\Leftrightarrow x(t) = e^{-\int_{t_0}^t a(s) ds} \left(x_0 + \int_{t_0}^t e^{\int_{t_0}^z a(s) ds} f(z) dz \right)$$

Here: we have
$$\begin{cases} u' + 100u = 25 \quad (*) \\ u(0) = 1 \end{cases}$$

we multiply (*) by $e^{\int_0^t 100 ds} = e^{100t}$

we get $(u(t) e^{100t})' = 25 e^{100t}$

we integrate between 0 and t : and we get
$$u(t) e^{100t} - \underbrace{u(0)}_{=1} = \int_0^t 25 e^{100s} ds$$

$$\text{Finally, } u(t) = e^{-100t} \left[1 + \frac{1}{4} e^{100t} - \frac{1}{4} \right]$$

$$= \frac{3}{4} e^{-100t} + \frac{1}{4} = \frac{1}{4} (3e^{-100t} + 1)$$

d.
$$\lim_{t \rightarrow +\infty} u(t) = \lim_{t \rightarrow +\infty} \frac{1}{4} (3e^{-100t} + 1) = \boxed{\frac{1}{4}}$$

\int_0^{∞}
0



Part 2:

a. Explicit Euler method:

$$\begin{cases} u_{n+1} = u_n + h f(t_n, u_n) \\ u_0 = 1 \end{cases}$$

$$\Leftrightarrow \begin{cases} u_{n+1} = u_n + h (-100u_n + 25) \\ u_0 = 1 \end{cases}$$

$$\Leftrightarrow \begin{cases} u_{n+1} = u_n (1 - 100h) + 25h \\ u_0 = 1 \end{cases}$$

b. $u_{n+1} = u_n (1 - 100h) + 25h$

c. We have: $f: x \mapsto x(1 - 100h) + 25h$
we need to find $f(\alpha) = \alpha$

$$\alpha(1 - 100h) + 25h = \alpha$$

$$\Leftrightarrow \alpha(1 - 100h) - \alpha + 25h = 0$$

$$\Leftrightarrow -100h\alpha = -25h$$

$$\Leftrightarrow \alpha = \frac{1}{4}$$

We note $v_n = u_n - \frac{1}{4}$ $\Leftrightarrow u_n = v_n + \frac{1}{4}$ and $v_0 = \frac{3}{4}$

$$\begin{aligned} v_{n+1} &= u_{n+1} - \frac{1}{4} \\ &= u_n (1 - 100h) + 25h - \frac{1}{4} \\ &= \left(v_n + \frac{1}{4}\right) (1 - 100h) + 25h - \frac{1}{4} \\ &= v_n - 100h v_n + \frac{1}{4} - 25h + 25h - \frac{1}{4} \\ &= v_n (1 - 100h) \end{aligned}$$

So $(v_n)_{n \in \mathbb{N}}$ is a geometric sequence

$$\begin{aligned} v_n &= v_0 (1 - 100h)^n \\ &= \frac{3}{4} (1 - 100h)^n \end{aligned}$$

$$u_n = \frac{3}{4} (1 - 100h)^n + \frac{1}{4}$$

d. $h = \frac{1}{25}$ then $u_n = \frac{3}{4} \left(1 - \frac{100}{25}\right)^n + \frac{1}{4}$
 $= \frac{3}{4} (-3)^n + \frac{1}{4}$

$$|u_n| \xrightarrow{n \rightarrow +\infty} +\infty$$

e. $u_n \not\rightarrow \frac{1}{4}$ so the problem isn't A-stable

f. $u_n \xrightarrow{n \rightarrow \infty} \frac{1}{4}$ if $|1 - 100h| < 1$

$$\Leftrightarrow -1 < 1 - 100h < 1$$

$$\Leftrightarrow -2 < -100h < 0$$

$$\Leftrightarrow 0 < 100h < 2$$

$$\Leftrightarrow h < \frac{1}{50}$$

Part 3: with the implicit Euler method

a. Remember: Implicit Euler method:
 $X_{n+1} = X_n + h f(t_{n+1}, X_{n+1})$

Here, applied to our problem:

$$\begin{cases} U_{n+1} = U_n + h f(t_{n+1}, U_{n+1}) \\ U_0 = 1 \end{cases}$$

$$\Leftrightarrow \begin{cases} U_{n+1} = U_n + h (-100U_{n+1} + 25) \\ U_0 = 1 \end{cases}$$

$$\Leftrightarrow \begin{cases} U_{n+1} = U_n - 100hU_{n+1} + 25h \\ U_0 = 1 \end{cases}$$

$$\Leftrightarrow \begin{cases} U_{n+1} = \frac{1}{1+100h} (U_n + 25h) \\ U_0 = 1 \end{cases}$$

b) $U_{n+1} = \frac{1}{1+100h} (U_n + 25h)$

c) As before, we're looking for an α ^{such} as $f(\alpha) = \alpha$,
with $f: X \mapsto \frac{1}{1+100h} (X + 25h)$

$$\frac{1}{1+100h} (\alpha + 25h) = \alpha$$

$$\Leftrightarrow \left(\frac{1}{1+100h} - 1\right) \alpha + \frac{25h}{1+100h} = 0$$

$$\Leftrightarrow \left(\frac{-100h}{1+100h}\right) \alpha = \frac{-25h}{1+100h}$$

$$\Leftrightarrow \alpha = \frac{1}{4}$$

Then we use an auxiliary sequence: $V_n = U_n - \alpha$

auxiliary sequence: $V_n = U_n - \alpha$

$$\begin{aligned}\text{So } V_{n+1} &= U_{n+1} - \alpha = U_{n+1} - \frac{1}{4} \\ &= \frac{1}{1+100h} (U_n + 25h) - \frac{1}{4} \\ &= \frac{1}{1+100h} \left(V_n + \frac{1}{4} + 25h \right) - \frac{1}{4} \\ &= V_n \times \frac{1}{1+100h} + \frac{1}{4+400h} + \frac{25h}{1+100h} - \frac{1}{4} \\ &= V_n \times \frac{1}{1+100h} + \frac{1}{4} \left(\frac{1}{1+100h} - 1 \right) + \frac{25h}{1+100h} \\ &= V_n \times \frac{1}{1+100h} + \frac{1}{4} \left(\frac{-100h}{1+100h} \right) + \frac{25h}{1+100h} \\ &= V_n \times \frac{1}{1+100h} + 0 \\ V_{n+1} &= V_n \times \frac{1}{1+100h}\end{aligned}$$

So $(V_n)_{n \in \mathbb{N}}$ is a geometric sequence.

$$\begin{aligned}V_n &= V_0 \left(\frac{1}{1+100h} \right)^n \\ &= \frac{3}{4} \left(\frac{1}{1+100h} \right)^n\end{aligned}$$

$$\begin{aligned}V_0 &= U_0 - \alpha \\ &= \frac{3}{4}\end{aligned}$$

$$\begin{aligned}\text{So: } U_n &= V_n + \alpha \\ &= \frac{3}{4} \left(\frac{1}{1+100h} \right)^n + \frac{1}{4}\end{aligned}$$

$0 < \frac{1}{1+100h} < 1$, which means that:

for every $h > 0$, $U_n \xrightarrow{n \rightarrow \infty} \frac{1}{4}$

This confirms that the implicit Euler method is A-stable.
The question is useless.

exercice sheet 2

II 1. Let us prove that a R.K method is order 1
if and only if $\sum_{i=1}^s b_i = 1$

Remember: the R-K scheme:

$$X_i = x_n + h \sum_{j=1}^{i-1} a_{ij} f(t+c_j h, X_j) \quad i=1, \dots, s$$

$$x_{n+1} = x_n + h \underbrace{\sum_{i=1}^s b_i f(t+c_i h, X_i)}_{\phi(t_n, x_n, h)} \quad x_{n+1} = x_n + h \phi(t_n, x_n, h)$$

.an explicit method is of order at least one if and only if $\phi(t, x, 0) = f(t, x)$

here, $\sum_{i=1}^s b_i f(t+c_i h, X_i) = f(t, x)$ with $X_i = x + 0$. $\dots = x$

$$\phi(t, x, 0) = \sum_{i=1}^s b_i f(t, x) = f(t, x) \Leftrightarrow f(t, x) \cdot \sum_{i=1}^s b_i$$

so $\phi(t, x, 0) = \sum_{i=1}^s b_i f(t, x) = f(t, x) \Leftrightarrow f(t, x) \cdot \sum_{i=1}^s b_i = f(t, x)$
independent of i $\Leftrightarrow \sum_{i=1}^s b_i = 1$

e. for order at least 2 we need to prove that $\frac{\partial^2 \phi(t, x, 0)}{\partial \eta^2} = \frac{1}{2} \partial^2 f = \frac{1}{2} \left(\frac{\partial^2 f}{\partial t^2} + 2 \frac{\partial f}{\partial t} \frac{\partial f}{\partial x} \right)$

hint: we can find that

$$\frac{\partial^2}{\partial \eta^2} \phi(t, x, 0) = \left(\sum_{i=1}^s b_i c_i \right) \frac{\partial^2 f}{\partial t^2}(t, x) + \left(\sum_{i=1}^s b_i \sum_{j=1}^{i-1} a_{ij} \right) \frac{\partial}{\partial x} f(t, x) \cdot f(t, x)$$

$$= \frac{1}{2} \frac{\partial^2 f}{\partial t^2} + 2 \frac{\partial f}{\partial t} \frac{\partial f}{\partial x}$$

