Intro duction

UNIVERSAL GEOMETRIC COEFFICIENTS FOR THE ONCE-PUNCTURED TORUS

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ABSTRACT. We construct universal geometric coefficients, over \mathbb{Z} , \mathbb{Q} , and \mathbb{R} , for cluster algebras arising from the once-punctured torus. We verify that the once-punctured torus has a property called the Null Tangle Property. The universal geometric coefficients over \mathbb{Z} and \mathbb{Q} are then given by the shear coordinates of certain "allowable" curves in the torus. The universal geometric coefficients over \mathbb{R} are given by the shear coordinates of allowable curves together with the normalized shear coordinates of certain other curves each of which is dense in the torus. We also construct the mutation fan for the once-punctured torus and recover a result of Nájera on **g**-vectors.

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1. INTRODUCTION

Given an exchange matrix B, a universal geometric cluster algebra for B is a cluster algebra that is universal, in the sense of coordinate specialization, among cluster algebras of geometric type (broadly defined in the sense of [14]) associated to B. A universal geometric cluster algebra is specified by an extended exchange matrix (again broadly defined) whose coefficient rows are called the universal geometric coefficients for B. The polyhedral geometry and "mutation-linear algebra" of these universal geometric coefficients is worked out in [14]. In the case where B arises from a marked surface, universal geometric coefficients and the closely related mutation fans can be approached through a variant of the laminations that appear

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in [8]. In [15], this approach yields a construction of the mutation fan for all marked surfaces except the once-punctured surfaces without boundary, and a construction of universal geometric coefficients for a smaller family of surfaces.

In this paper, we carry out the construction of universal geometric coefficients and the mutation fan for the simplest case not handled in [15]: the once-punctured torus. The essential step in the constructions of this paper is to establish the Null Tangle Property for the once-punctured torus. The Null Tangle Property implies that the universal geometric coefficients (over \mathbb{Z} or \mathbb{Q}) are given by the shear coordinates of certain curves. Universal geometric coefficients over \mathbb{Q} were already known to exist, by a non-constructive proof [14, Corollary 4.7], but even the existence of universal geometric coefficients over \mathbb{Z} was not previously known for the once-punctured torus. Our proof of the Null Tangle Property uses tools that are not surprising in the context of the once-punctured torus. Similar ideas have appeared, for example, in [4, 10, 11, 12, 16], and our treatment draws on ideas from these earlier works. We realize shear coordinates of curves in the once-punctured torus in terms of Farey triples.

We take the results for the once-punctured torus farther than the results for other surfaces in [15] by also computing universal geometric coefficients over \mathbb{R} . The universal geometric coefficients over \mathbb{R} are given by the (normalized) shear coordinates of a larger collection of curves, some of which are dense in the torus.

The following theorem gives the universal geometric coefficients explicitly.

Theorem 1.1. Let $B = \begin{bmatrix} 0 & 2 & -2 \\ -2 & 0 & 2 \\ 2 & -2 & 0 \end{bmatrix}$. A universal extended exchange matrix for B over \mathbb{Z} or \mathbb{Q} has the following coefficient rows:

- (1) The three cyclic permutations of [1 b, a + 1, b a 1], for all (possibly infinite) positive slopes with standard form b/a.
- (2) The three cyclic permutations of [-1 b, a 1, b a + 1], for all finite nonnegative slopes with standard form b/a.
- (3) All integer vectors [x, y, z] with x + y + z = 0 such that x, y, and z have no common factors.

A universal extended exchange matrix for B over \mathbb{R} has the coefficient rows described in (1.1) and (1.1) above, as well as

(3') Exactly one nonzero vector in ρ for each ray ρ contained in the plane given by x + y + z = 0.

The mutation fan for $B = \begin{bmatrix} 0 & 2 & -2 \\ -2 & 0 & 2 \\ 2 & -2 & 0 \end{bmatrix}$ is described in Theorem 7.1 and illustrated in Figure 1. The figure is interpreted as follows: Each cone of the mutation fan intersects the unit sphere about the origin in a point, circular arc, or spherical triangle. The figure pictures the images of these points, arcs, and triangles under a stereographic projection of the unit sphere to the plane. The projections of the standard basis vectors \mathbf{e}_1 , \mathbf{e}_2 , and \mathbf{e}_3 are indicated.

As a corollary (Corollary 7.3) to Theorem 7.1, we recover a result of Nájera [12] describing the **g**-vectors of cluster variables for B^T . Nájera's result was the starting point for our investigation of the mutation fan for the once-punctured torus. In two short sections at the end of the paper, we briefly discuss denominator vectors, and then briefly discuss how the results of this paper have been extended to the



FIGURE 1. The mutation fan for the once-punctured torus

four-punctured sphere [1] and might extend to other tubular cluster algebras in the sense of [2, 3].

2. Universal geometric coefficients

In this section, we briefly review background on universal geometric cluster algebras. Rather than give complete details, we move quickly to reframe the problem of constructing universal geometric coefficients as the problem of finding a basis, and then quote results that describe how to find a basis in the case of surfaces. We also introduce the closely related notion of the mutation fan. Details can be found in [14]. Additional background on geometric cluster algebras is found for example in [9], but we work with the broader definition originated in [14].

We choose an **underlying ring** R to be \mathbb{Z} , \mathbb{Q} , or \mathbb{R} , fix an integer n > 0, and let I be an indexing set of arbitrary cardinality. An **extended exchange matrix** \tilde{B} is a collection of vectors in \mathbb{R}^n called the **rows** of \tilde{B} , indexed by the disjoint union $[n] \cup I$. We think of \tilde{B} as an " $(n + |I|) \times n$ matrix," although since I may be infinite or even uncountable, it may not be a matrix in the usual sense. However, the rows of \tilde{B} indexed by [n] constitute an $n \times n$ matrix denoted by B. This **exchange matrix**

B is in general required to have integer entries and to be skew-symmetrizable, but the matrix under consideration in this paper has a stronger property than skewsymmetrizability: it is skew-symmetric in the usual sense. The rows of \tilde{B} indexed by I are called **coefficient rows**.

An extended exchange matrix defines a *cluster algebra of geometric type*, denoted by $\mathcal{A}_R(\tilde{B})$. The details of the definition are in [14]; we briefly sketch it here. One takes the coefficient semifield to be a tropical semifield over tropical variables indexed by I, with exponents on the tropical variables taking values in R, rather than only in \mathbb{Z} . One then uses \tilde{B} to define initial coefficients just as in the *geometric type* construction from [9] and takes B and these coefficients as the input to the general construction of cluster algebras. The cluster algebra $\mathcal{A}_R(\tilde{B})$ may not be of geometric type in the sense of [9], for two reasons: First, there may be infinitely many coefficient rows of \tilde{B} (or equivalently infinitely many tropical variables), and second, the coefficient rows of \tilde{B} may have non-integer entries. In [14, Definition 2.8], the definition of cluster algebras of geometric type is broadened to include exactly the cluster algebras of the form $\mathcal{A}_R(\tilde{B})$ as described here.

For those less familiar with cluster algebras: A **seed** is a pair (\hat{B}, \mathbf{x}) consisting of an extended exchange matrix \tilde{B} and an *n*-tuple $\mathbf{x} = (x_1, \ldots, x_n)$, called a **cluster**. The x_i are rational functions called **cluster variables**. Given a seed and an index $k \in [n]$, there is a notion of **seed mutation** that exchanges (\tilde{B}, \mathbf{x}) for a new seed $\mu_k(\tilde{B}, \mathbf{x}) = (\tilde{B}', \mathbf{x}')$. The matrix \tilde{B}' is obtained from \tilde{B} by matrix mutation, which we define below. Writing x'_1, \ldots, x'_n for the cluster variables in the new cluster, we have $x'_j = x_j$ for each $j \neq k$, while x'_k and x_k are related by an **exchange relation** which writes x'_k as a rational function of the cluster variables in \mathbf{x} , with coefficients given by the coefficient rows of \tilde{B} . We perform all possible sequences of mutations to obtain a (typically infinite) collection of seeds. Each cluster variables x_1, \ldots, x_n . The cluster algebra $\mathcal{A}_R(\tilde{B})$ is the algebra (i.e., the subalgebra of the field of rational functions) generated by all of the cluster variables in all of the seeds.

Matrix mutation is defined as follows. Given an extended exchange matrix B, we write b_{ij} for the j^{th} entry in the row of \tilde{B} indexed by i. Thus i is in the disjoint union $[n] \cup I$ and j is in [n]. For $k \in [n]$, the mutation of \tilde{B} at index k is the matrix $\mu_k(\tilde{B}) = \tilde{B}'$ with entries b'_{ij} given by

(2.1)
$$b'_{ij} = \begin{cases} -b_{ij}, & \text{if } i = k \text{ or } j = k; \\ b_{ij} + \operatorname{sgn}(b_{kj}) [b_{ik}b_{kj}]_+, & \text{otherwise}, \end{cases}$$

where $\operatorname{sgn}(0) = 0$ and $\operatorname{sgn}(a) = a/|a|$ for $a \neq 0$. We are interested in sequences of mutations, and we establish notation for such sequences. Given a sequence $\mathbf{k} = k_q, \ldots, k_1$ of integers in [n], the notation $\mu_{\mathbf{k}}$ stands for $\mu_{k_q} \circ \mu_{k_{q-1}} \circ \cdots \circ \mu_{k_1}$.

Suppose \tilde{B} and \tilde{B}' are extended exchange matrices having the same exchange matrix B. A **coefficient specialization** from $\mathcal{A}_R(\tilde{B})$ to $\mathcal{A}_R(\tilde{B}')$ is a ring homomorphism taking each cluster variable in $\mathcal{A}_R(\tilde{B})$ to the corresponding cluster variable in $\mathcal{A}_R(\tilde{B}')$, taking the coefficients in each exchange relation to the corresponding coefficients, and satisfying some additional technical requirements. A cluster algebra $\mathcal{A}_R(\tilde{B})$ is a **universal geometric cluster algebra** over R for the exchange matrix B if, for any other geometric cluster algebra $\mathcal{A}_R(\tilde{B}')$ with exchange matrix B, there is a unique coefficient specialization from $\mathcal{A}_R(\tilde{B})$ to $\mathcal{A}_R(\tilde{B}')$. In this case, \tilde{B} is called a **universal extended exchange matrix** over R and the coefficient rows of \tilde{B} are called **universal geometric coefficients** for B over R. Rather than give the details of the definition of coefficient specialization, we now explain how to understand universal geometric coefficients for B directly.

An exchange matrix B defines, by matrix mutation, a collection of maps $\eta_{\mathbf{k}}^{B}$: $\mathbb{R}^{n} \to \mathbb{R}^{n}$ that we call **mutation maps**. Given $\mathbf{a} = (a_{1}, \ldots, a_{n}) \in \mathbb{R}^{n}$, create an extended exchange matrix $\begin{bmatrix} B \\ \mathbf{a} \end{bmatrix}$ with exchange matrix B and a single coefficient row \mathbf{a} . Given a sequence \mathbf{k} of integers in [n], the vector $\eta_{\mathbf{k}}^{B}(\mathbf{a})$ is defined to be the coefficient row of the matrix $\mu_{\mathbf{k}}(\begin{bmatrix} B \\ \mathbf{a} \end{bmatrix})$, The map $\eta_{\mathbf{k}}^{B}$ is a piecewise-linear homeomorphism from \mathbb{R}^{n} to \mathbb{R}^{n} , with inverse $\eta_{k_{1},\ldots,k_{q}}^{\mu_{\mathbf{k}}(B)}$. When \mathbf{k} is the singleton sequence k, the vector $(a'_{1},\ldots,a'_{n}) = \eta_{k}^{B}(a_{1},\ldots,a_{n})$ is given by

(2.2)
$$a'_{j} = \begin{cases} -a_{k}, & \text{if } j = k; \\ a_{j} + a_{k}b_{kj}, & \text{if } j \neq k, a_{k} \ge 0 \text{ and } b_{kj} \ge 0; \\ a_{j} - a_{k}b_{kj}, & \text{if } j \neq k, a_{k} \le 0 \text{ and } b_{kj} \le 0; \\ a_{j}, & \text{otherwise.} \end{cases}$$

Given a collection of vectors $(\mathbf{v}_i : i \in S)$ in \mathbb{R}^n indexed by a finite set S, the formal expression $\sum_{i \in S} c_i \mathbf{v}_i$ is a *B*-coherent linear relation with coefficients in R if each c_i is in R and if the equalities

(2.3)
$$\sum_{i \in S} c_i \eta_{\mathbf{k}}^B(\mathbf{v}_i) = \mathbf{0}, \text{ and}$$

(2.4)
$$\sum_{i \in S} c_i \min(\eta^B_{\mathbf{k}}(\mathbf{v}_i), \mathbf{0}) = \mathbf{0}$$

hold for every finite sequence $\mathbf{k} = k_q, \ldots, k_1$ of integers in [n]. The symbol **min** stands for componentwise minimum. Since (2.3) is required also for the empty sequence \mathbf{k} , a *B*-coherent linear relation is also a linear relation in the usual sense.

A collection $(\mathbf{b}_i : i \in I)$ of vectors in \mathbb{R}^n , indexed by an arbitrary set I is an R-spanning set for B if for all $\mathbf{a} \in \mathbb{R}^n$, there exists a finite subset $S \subseteq I$ and elements $(c_i : i \in S)$ of R such that $\mathbf{a} - \sum_{i \in S} c_i \mathbf{b}_i$ is a B-coherent linear relation. The collection $(\mathbf{b}_i : i \in I)$ is an R-independent set for B if for every B-coherent linear relation $\sum_{i \in S} c_i \mathbf{b}_i$ with $S \subseteq I$, each c_i is zero. An R-basis for B is a collection $(\mathbf{b}_i : i \in I)$ that is both an R-independent set for B and an R-spanning set for B. The following theorem is [14, Theorem 4.4].

Theorem 2.1. Let \hat{B} be an extended exchange matrix with entries in R. Then \hat{B} is universal over R if and only if the coefficient rows of \tilde{B} are an R-basis for B.

For a vector $\mathbf{a} = (a_1, \ldots, a_n)$ in \mathbb{R}^n we define $\mathbf{sgn}(\mathbf{a})$ to be $(\mathrm{sgn}(a_1), \ldots, \mathrm{sgn}(a_n))$. Using mutation maps and the function \mathbf{sgn} , we define an equivalence relation on \mathbb{R}^n . Set $\mathbf{a}_1 \equiv^B \mathbf{a}_2$ if and only if $\mathbf{sgn}(\eta^B_{\mathbf{k}}(\mathbf{a}_1)) = \mathbf{sgn}(\eta^B_{\mathbf{k}}(\mathbf{a}_2))$ for every sequence \mathbf{k} of integers in [n]. The \equiv^B -equivalence classes are called *B*-classes and their closures are called *B*-cones. Each *B*-cone is a closed convex cone. The following proposition is [14, Proposition 5.3].

Proposition 2.2. Every mutation map $\eta^B_{\mathbf{k}}$ is linear on every *B*-cone.

The collection \mathcal{F}_B , consisting of all *B*-cones together with all their faces is called the *mutation fan* for *B*, in light of the following theorem [14, Theorem 5.13].

Theorem 2.3. The collection \mathcal{F}_B is a complete fan.

A **positive** R-**basis** for B is an R-independent set for B such that for any $\mathbf{a} \in R^n$, there is a B-coherent linear relation $\mathbf{a} - \sum_{i \in S} c_i \mathbf{b}_i$ with each c_i nonnegative. A positive R-basis for B is in particular an R-basis for B. For each B and R, there is at most one positive R-basis for B, up to scaling each basis element by a positive unit in R. (See [14, Proposition 6.2].) In the case $R = \mathbb{R}$, there is a direct connection between the mutation fan and the problem of constructing a positive R-basis for B, described in the following propositions, which are [14, Corollary 6.13] and [14, Proposition 6.14].

Proposition 2.4. If a positive \mathbb{R} -basis for B exists, then \mathcal{F}_B is simplicial. The basis consists of exactly one vector in each ray of \mathcal{F}_B .

Proposition 2.5. A collection consisting of exactly one nonzero vector in each ray of \mathcal{F}_B is a positive \mathbb{R} -basis for B if and only if it is an \mathbb{R} -independent set for B.

For $R \neq \mathbb{R}$, a similar statement can be made in terms of the *R*-part (e.g. the rational part) of \mathcal{F}_B . See [14, Definition 6.9] and [14, Corollary 6.12].

3. The once-punctured torus

The purpose of this section is to review background material on (universal) cluster algebras from surfaces. However, since this paper is focused on a particular surface, the once-punctured torus, we are able to simplify some definitions and results. For the general definitions and results, see [7, 8, 15].

In general, a marked surface is (\mathbf{S}, \mathbf{M}) , where **S** is a surface and **M** is some set of points on S, satisfying certain rules. Here we take S to be a torus and $\mathbf{M} = \{p\}$ where p is some point in S and write (S, p) rather than $(S, \{p\})$. The point p is referred to as a puncture, so that (\mathbf{S}, p) is the once-punctured torus. An **arc** in (\mathbf{S}, p) is a curve in \mathbf{S} , up to isotopy relative to $\{p\}$, with both endpoints at p, but otherwise not containing p and having no self-intersections. We exclude the arc that bounds an unpunctured monogon. Two arcs α and γ are **compatible** if (there is some isotopy representative of each such that) the two do not intersect except at p. The *arc complex* is the abstract simplicial complex whose vertices are the arcs and whose faces are the sets of pairwise compatible arcs. A *triangulation* of (\mathbf{S}, p) is a maximal face of the arc complex. A triangulation contains three arcs and cuts **S** into two triangles. Each arc in a triangulation is an edge of exactly two triangles in the triangulation. A *flip* is the operation of removing an arc from a triangulation and forming a new triangulation by inserting an arc that forms the other diagonal of the resulting quadrilateral. A *tagged arc* in (\mathbf{S}, p) is a arc in \mathbf{S} , either with both ends of the arc designated (or "tagged") **plain** or with both tagged **notched**. In general, one makes a suitable definition of compatibility of tagged arcs and works with the "tagged arc complex." For (\mathbf{S}, p) , however, we can (and indeed are forced to) work with the ordinary arc complex. (See [7, Proposition 7.10].)

Each triangulation T of (\mathbf{S}, p) has a **signed adjacency matrix** B(T), defined in [8, Definition 5.15]. This is a matrix indexed by the arcs in T. The entry $b_{\alpha\gamma}$ is the sum, over the two triangles of T, of a 1 if γ immediately follows α in a clockwise path around the triangle or -1 if γ immediately follows α in a counterclockwise path around the triangle. For the rest of the paper, the symbol B will stand for $\begin{bmatrix} -2 & 0 & 2 \\ -2 & 0 & 2 \end{bmatrix}$. For any triangulation T of (\mathbf{S}, p) , the matrix B(T) is $\pm B$.

An *allowable curve* in (\mathbf{S}, p) is a non-self-intersecting curve in $\mathbf{S} \setminus \{p\}$ that either

- is closed and not contractible in **S**, or
- spirals into p at both ends.

In the once-punctured torus, a non-closed allowable curve spirals into the same puncture at both ends, and therefore spirals in the same direction at both ends.

Two allowable curves are *compatible* if they do not intersect. In [15], the notions of allowable curves and compatibility refer to *quasi-laminations*, a modification of the *rational unbounded measured laminations* that figure in [8]. For the once-punctured torus, the two notions of laminations coincide.

Given an allowable curve λ and a triangulation T, the **shear coordinate vector** $\mathbf{b}(T,\lambda)$ of λ with respect to T is a vector with entries $b_{\gamma}(T,\lambda)$ indexed by arcs γ in T. The entry $b_{\gamma}(T,\lambda)$ is defined as follows. Up to isotopy, we can assume that λ does not cross any arc twice consecutively in opposite directions. The coordinate $b_{\gamma}(T,\lambda)$ is the sum, over the intersections of λ with γ , of a number in $\{-1,0,1\}$. This number is determined by how λ intersects the two triangles having γ as an edge. It is 1 or -1 if the intersection is as shown in Figure 2, and otherwise it is 0. The arc



FIGURE 2. Computing shear coordinates

 γ is the diagonal of the quadrilateral shown, and opposite sides of the quadrilateral coincide.

A (weighted) tangle (of curves) in (\mathbf{S}, p) is a finite collection of allowable curves λ , each having an integer weight w_{λ} , with no requirement of compatibility between curves. The shear coordinates $\mathbf{b}(T, \Xi)$ of a tangle Ξ are given by the sum $\sum_{\lambda \in \Xi} w_{\lambda} \mathbf{b}(T, \lambda)$. A null tangle is a tangle with $b(T, \Xi) = \mathbf{0}$ for all triangulations T. Proposition 3.1, below, is [15, Proposition 7.11], specialized to the once-punctured torus. We point out, however, an unfortunate typo in [15, Proposition 7.11]: It should begin "Let Ξ be a null tangle...," but the word "null" is omitted in [15]. The proposition itself is the specialization to surfaces of [14, Proposition 4.12]. See also [15, Proposition 7.9], quoted in this paper as Proposition 6.3.

Proposition 3.1. Let Ξ be a null tangle in (\mathbf{S}, p) . Suppose for some triangulation T, for some arc γ in T, and for some curve λ in Ξ that $b_{\gamma}(T, \lambda)$ is strictly

positive (respectively strictly negative) and that $b_{\gamma}(T,\nu)$ is nonpositive (respectively nonnegative) for every other $\nu \in \Xi$. Then $w_{\lambda} = 0$.

The *support* of a tangle is the set of curves having nonzero weight. A tangle is *trivial* if all weights are zero. A marked surface has the *Null Tangle Property* if every null tangle is trivial. In Section 6, we prove the following theorem.

Theorem 3.2. The once-punctured torus has the Null Tangle Property.

Both results quoted below in this section are obtained by combining Theorem 3.2 with results of [15] that are conditional on the Null Tangle Property. Although we do not prove Theorem 3.2 until Section 6, we do not use it or either of the results below until Section 7 and later.

The specialization of [15, Theorem 7.3] to the once-punctured torus says that the Null Tangle Property is equivalent to the following statement: The shear coordinates of allowable curves form a positive *R*-basis for B(T), where *T* is any triangulation and *R* is \mathbb{Z} or \mathbb{Q} . Thus Theorem 3.2 has the following corollary.

Corollary 3.3. If T is a triangulation of (\mathbf{S}, p) and R is \mathbb{Z} or \mathbb{Q} , then the shear coordinates $\mathbf{b}(T, \lambda)$ of allowable curves λ constitute a positive R-basis for B(T).

Fix a triangulation T of (\mathbf{S}, p) . For each set Λ of pairwise compatible allowable curves in (\mathbf{S}, p) , let C_{Λ} be the nonnegative \mathbb{R} -linear span of the vectors $\{\mathbf{b}(T, \lambda) :$ $\lambda \in \Lambda\}$. Let $\mathcal{F}_{\mathbb{Q}}(T)$ be the collection of all such cones C_{Λ} . In [15, Theorem 4.10], this collection is shown to be a fan and, more specifically, to be the rational part of \mathcal{F}_B in the sense of [15, Definition 4.9]. Rather than stating this definition, we summarize parts of [15, Theorem 4.10] and its corollary [15, Corollary 4.11] in the following proposition, which is stated in the special case of the once-punctured torus. The hypotheses of [15, Theorem 4.10] and [15, Corollary 4.11] include the assumption that the marked surface has a property called the Curve Separation Property. However, [15, Corollary 7.12] states that the Null Tangle Property implies the Curve Separation Property, so by Theorem 3.2, these results apply to the oncepunctured torus.

Proposition 3.4. Let T be a triangulation of (\mathbf{S}, p) . The collection $\mathcal{F}_{\mathbb{Q}}(T)$ is a rational, simplicial fan. Each cone in $\mathcal{F}_{\mathbb{Q}}(T)$ is contained in a cone of $\mathcal{F}_{B(T)}$. Each rational B(T)-cone is a cone in $\mathcal{F}_{\mathbb{Q}}(T)$. The full-dimensional B(T)-cones are exactly the full-dimensional cones in $\mathcal{F}_{\mathbb{Q}}(T)$.

4. ARCS AND ALLOWABLE CURVES

In this section, we prepare for the proof of Theorem 3.2 by classifying arcs and allowable curves in (\mathbf{S}, p) . Recall the usual construction of the torus as a quotient of its universal cover \mathbb{R}^2 : We identify points $[x_1, y_1]$ and $[x_2, y_2]$ in \mathbb{R}^2 if the fractional parts of x_1 and x_2 coincide and the fractional parts of y_1 and y_2 coincide. We assume that the marked point p is the image of [0, 0] under the covering map.

Proposition 4.1. The arcs in (\mathbf{S}, p) are the images, under the covering map, of straight line segments connecting the origin to nonzero integer points and containing no integer points in their interior. The map from segments to arcs is two-to-one, with antipodal pairs of segments mapping to the same arc.

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Proof. Arcs in (\mathbf{S}, p) are in particular elements of the fundamental group of \mathbf{S} based at the point p. A non-trivial element of the fundamental group represents an arc in \mathbf{S} if and only if (up to homotopy relative to p) it is non-self-intersecting except that the endpoints coincide. The fundamental group of the torus consists of the projections of curves connecting the origin to points in \mathbb{Z}^2 , and two fundamental group elements coincide if and only if they connect the origin to the same point. The images of straight line segments described in the proposition are thus all distinct up to homotopy and it is immediate that each image is non-self-intersecting, except that the endpoints coincide.

It remains to show that every arc is represented by the projection of a line segment. Let γ be an arc and consider a lift $\bar{\gamma}$ of γ having an endpoint at [0, 0]. Then $\bar{\gamma}$ is disjoint from all other lifts of γ (i.e., from all integer translates of $\bar{\gamma}$), except for coinciding endpoints. We break \mathbb{R}^2 into unit squares with integer vertices and describe $\bar{\gamma}$, up to homotopy in $\mathbb{R}^2 \setminus \mathbb{Z}^2$, by the sequence of squares it visits. We can assume that $\bar{\gamma}$ never enters a square and leaves through the same side. (Otherwise, we continuously deform $\bar{\gamma}$ so that it doesn't enter the square, and we can do this without losing the property that $\bar{\gamma}$ is disjoint from all of its integer translates.) Similarly, we can assume that after $\bar{\gamma}$ leaves [0, 0] and enters the interior of some square, it leaves that square through a side not containing [0, 0]. We can also assume the analogous condition at the other endpoint of $\bar{\gamma}$. By symmetry, we can assume that $\bar{\gamma}$ leaves [0, 0], enters the square shared by [0, 0] and [1, 1] and leaves this square through the top side or right side or terminates at one of the vertices of the square. In the latter case, we are done. If $\bar{\gamma}$ leaves the square through the top or right side, then it enters some other square. Because $\bar{\gamma}$ is disjoint from all its translates, we see that $\bar{\gamma}$ must either terminate at the top-right vertex of the new square or exit the new square through the top or right edge. The same is true each time $\bar{\gamma}$ enters a new square: it terminates in the top-right vertex or leaves through the top or right edge. Thus $\bar{\gamma}$ determines a word in the letters r and t, with r standing for exiting a square through the right and t standing for exiting through the right.

Let \mathbf{v} be the endpoint of $\bar{\gamma}$ other than [0, 0], and consider the straight line segment λ connecting [0, 0] to \mathbf{v} . This line segment determines a word in the same way, except that in addition to \mathbf{r} and \mathbf{t} we allow a third letter \mathbf{c} in the word for the case when λ leaves a square through its top-right corner without terminating there. If the words for $\bar{\gamma}$ and λ coincide, then there is a homeomorphism of the plane, homotopic to the identity, fixing the integer lattice, and commuting with integer translations, that takes $\bar{\gamma}$ to λ . Descending to the torus, we obtain an isotopy from γ to the projection of λ .

If the two words are different, then we can still continuously deform $\bar{\gamma}$ to a non-selfintersecting polygonal path composed of straight segments with finite positive slopes connecting different sides of squares. Concatenating $\bar{\gamma}$ with its translates by integer multiples of \mathbf{v} , we obtain the graph of a strictly increasing periodic piecewise-linear function. Doing the same with λ , we obtain a strictly increasing linear function. We reuse the symbols $\bar{\gamma}$ and λ for these functions. Since the two words disagree, either there is an integer point in the interior of λ or there is an integer point between the two graphs.

First, suppose there is an integer point in the interior of λ , and choose \mathbf{w} to be the integer point in the interior closest to [0,0]. There is some integer k > 1 such that $k\mathbf{w} = \mathbf{v}$. Since $\bar{\gamma}$ has the same endpoints as λ and has no integer points in its interior, we can assume by symmetry that $\bar{\gamma}$ passes above the point \mathbf{w} . Translating the graph of $\bar{\gamma}$ by \mathbf{w} , we obtain the graph of another strictly increasing function $\bar{\gamma}'$, and these two graphs are disjoint. Thus since $\bar{\gamma}$ passes above \mathbf{w} and $\bar{\gamma}'$ contains \mathbf{w} , we see that $\bar{\gamma}'$ passes above $2\mathbf{w}$. Thus $\bar{\gamma}$ passes above $2\mathbf{w}$, and thus $\bar{\gamma}'$ passes above $3\mathbf{w}$. Continuing in this manner, we conclude that the graph $\bar{\gamma}$ passes above $k\mathbf{w}$, contradicting the fact that $\mathbf{v} = k\mathbf{w}$ is on the curve $\bar{\gamma}$.

Now suppose there is an integer point \mathbf{w} between the two graphs. Among integer points between the two graphs, choose a point \mathbf{w} that maximizes the distance from \mathbf{w} to the line λ . By symmetry, we may as well assume that \mathbf{w} is above λ . Since \mathbf{w} is between the line λ and the graph of $\bar{\gamma}$, we see that $\bar{\gamma}$ is above $\bar{\gamma}'$ (for $\bar{\gamma}'$ as in the previous paragraph). Thus $\bar{\gamma}'$ is above the point $\mathbf{w} + \mathbf{w}$, so $\bar{\gamma}$ is above $\mathbf{w} + \mathbf{w}$, but the point $\mathbf{w} + \mathbf{w}$ is twice as far from λ as the point \mathbf{w} .

In either case, we have a contradiction, and we conclude that the two words must be the same. Thus γ is isotopic to the projection of λ . Furthermore, the word for λ avoids the letter c, so the line segment λ has no integer points in its interior.

The arcs constructed in Proposition 4.1 are indexed by rational slopes, including the infinite slope. To specify these slopes, and thus these arcs, we introduce some (mostly standard) terminology. A **Farey point** is an integer vector [a, b] that is a closest nonzero integer point to the origin on the line through the origin with slope b/a. Taking the appropriate conventions for the gcd of not-necessarily-positive integers, this is the same as requiring that gcd(a, b) = 1. A **standard Farey point** satisfies the additional conditions that $a \ge 0$ and that b = 1 whenever a = 0. For each rational slope q (including ∞), there are exactly two Farey points [a, b] such that b/a = q. The **standard form** of a (possibly infinite) rational slope is an expression b/a such that [a, b] is a standard Farey point.

The **Farey ray** for a Farey point [a, b] is the set $\{c[a, b] : c \ge 1\}$. **Farey neighbors** are pairs of Farey points [a, b] and [c, d] satisfying the following three requirements: a and c have weakly the same sign, b and d have weakly the same sign, and $ad - bc = \pm 1$. A **Farey triangle** is the convex hull of three Farey points which are pairwise Farey neighbors. The following lemma justifies the name Farey triangle.

Lemma 4.2. If three Farey points are pairwise Farey neighbors, then they are not collinear.

Proof. If Farey points [a, b], [c, d] and [e, f] are collinear, then there exists a scalar λ such that $[e, f] = \lambda[a, b] + (1 - \lambda)[c, d]$. The equations $af - be = \pm 1$ and $cf - de = \pm 1$ are constraints on λ . Requiring also that $ad - bc = \pm 1$, the constraints become $1 - \lambda = \pm 1$ and $\lambda = \pm 1$, and this is a contradiction.

Figure 3 shows the Farey points, triangles, and rays close to the origin. Farey points are shown in blue and Farey rays are shown in red. The black dot marks the origin. (All lines in the figure are straight. The apparent curvature of some lines is due to a well-known optical illusion. See [17].)

Our interest in Farey neighbors stems from the following proposition.



FIGURE 3. Farey points, triangles, and rays

Proposition 4.3. Given two distinct arcs in (\mathbf{S}, p) , write the slopes of the corresponding line segments in standard forms b/a and d/c with $\frac{b}{a} < \frac{d}{c}$. Then the arcs are compatible if and only if ad - bc = 1.

Proof. The condition $\frac{b}{a} < \frac{d}{c}$ is equivalent to ad - bc > 0. Thus it is enough to show that for $b/a \neq d/c$, the condition $ad - bc = \pm 1$ is equivalent to the following condition: Given a line with slope b/a passing through an integer point and a line with slope d/c passing through another integer point, the intersection of the two lines is an integer point.

Given a line with slope b/a passing through the integer point $[m_1, p_1]$ and a line with slope d/c passing through the integer point $[m_2, p_2]$, the intersection of the two lines is the integer point [x, y] with

$$x = \frac{adm_2 - bcm_1 + ac(p_1 - p_2)}{ad - bc}, \quad y = \frac{adp_1 - bcp_2 + bd(m_2 - m_1)}{ad - bc}.$$

This is an integer point if $ad - bc = \pm 1$.

On the other hand, suppose $ad-bc \neq \pm 1$ and suppose for the sake of contradiction that all of the intersections of lines are integers. Choose $m_1 = 1$ and $m_2 = p_1 = p_2 = 0$ so that $x = \frac{bc}{bc-ad}$ and $y = \frac{bd}{bc-ad}$ are both integers. Then bc and bd are both

divisible by ad - bc, but since c and d have no common factor, we conclude that b is a multiple of ad - bc. Choosing $p_1 = 1$ and $m_1 = m_2 = p_2 = 0$, we see that a is also a multiple of ad - bc. This is a contradiction because b/a is in standard form. \Box

In light of Proposition 4.3, if we identify antipodal Farey points and Farey triangles in Figure 3, we obtain a representation of the arc complex of the punctured torus. A representation of the arc complex appears later in Figure 8.

Having classified arcs and determined the arc complex, we are able to describe the allowable curves in (\mathbf{S}, p) . First we find the allowable closed curves.

Proposition 4.4. The allowable closed curves in (\mathbf{S}, p) are the images, under the covering map, of straight lines in $\mathbb{R}^2 \setminus \mathbb{Z}^2$ with rational (or infinite) slope. Two such images are isotopic if and only if the corresponding lines have the same slope.

Proof. We first observe that for each arc α in (\mathbf{S}, p) , there is a unique closed allowable curve λ in (\mathbf{S}, p) such that α and λ do not intersect, and this correspondence is bijective. Indeed, given an arc α , the set $\mathbf{S} \setminus \alpha$ is a cylinder and admits exactly one non-contractible simple closed curve up to isotopy. Similarly, given a non-contractible simple closed curve λ , the set $\mathbf{S} \setminus \lambda$ is a cylinder containing p. Thus there is exactly one arc contained in $\mathbf{S} \setminus \lambda$. If α is the image, under the projection map, of a line segment as in Proposition 4.1, the unique allowable closed curve not intersecting α is the projection of a line with the same slope. The present proposition thus follows from Proposition 4.1.

Recall that tagged arcs in (\mathbf{S}, p) are obtained from ordinary arcs by either tagging both ends plain or tagging both ends notched. Given a tagged arc α in (\mathbf{S}, p) , we define (up to isotopy) a curve $\kappa(\alpha)$, which coincides with α except in a small ball about p. If α is tagged plain at p, then $\kappa(\alpha)$ spirals clockwise into p at both ends, and if α is tagged notched at p, then $\kappa(\alpha)$ spirals counterclockwise into p at both ends. This is a special case of a map defined in [15, Section 5] from tagged arcs to allowable curves in any marked surface (\mathbf{S}, \mathbf{M}) , and [15, Lemma 5.1] states that κ is a bijection from tagged arcs to allowable curves that are not closed and that two tagged arcs α and γ are compatible if and only if the curves $\kappa(\alpha)$ and $\kappa(\gamma)$ are compatible. Thus Propositions 4.1 and 4.4 imply the following statement.

Proposition 4.5. The allowable curves in (\mathbf{S}, p) are as follows:

- (1) All curves obtained from the arcs described in Proposition 4.1 by replacing both endpoints by clockwise spirals into p.
- (2) All curves obtained from the arcs described in Proposition 4.1 by replacing both endpoints by counterclockwise spirals into p.
- (3) All closed curves described in Proposition 4.4.

We write cl(a, b) for the *closed* curve that is the projection of a line with slope in standard form b/a. For the other allowable curves associated to b/a, we write cw(a, b) for the curve with spirals *clockwise* into p and ccw(a, b) for the curve with spirals *counterclockwise* into p.

Proposition 4.6. The compatible pairs of allowable curves in (\mathbf{S}, p) are:

- (1) cl(a, b) and cw(a, b) for any slope b/a.
- (2) cl(a, b) and ccw(a, b) for any slope b/a.

- (3) cw(a,b) and cw(c,d) for slopes b/a and d/c with $ad bc = \pm 1$.
- (4) $\operatorname{ccw}(a, b)$ and $\operatorname{ccw}(c, d)$ for slopes b/a and d/c with $ad bc = \pm 1$.

Proof. Closed curves are compatible with other curves if and only if the corresponding slopes coincide. The remainder of the proposition is a direct consequence of Proposition 4.3 and the fact that two tagged arcs α and γ are compatible if and only if the curves $\kappa(\alpha)$ and $\kappa(\gamma)$ are compatible.

5. Explicit shear coordinates

In this section, we explicitly compute shear coordinates of allowable curves in the once-punctured torus. The purpose of this explicit calculation is twofold. First, we will use the explicit coordinates to show that the once-punctured torus has the Null Tangle Property. Second, the explicit coordinates appear in Theorem 1.1.

For the remainder of the paper, let T_0 be the triangulation of (\mathbf{S}, p) by three allowable arcs γ_1 , γ_2 , and γ_3 , corresponding respectively to slopes $0, \infty$, and -1. The signed adjacency matrix $B(T_0)$ is $B = \begin{bmatrix} 0 & 2 & -2 \\ -2 & 0 & 2 \\ 2 & -2 & 0 \end{bmatrix}$. The lifts of γ_1 to \mathbb{R}^2 are the segments connecting integer points [m, n] to adjacent points [m + 1, n]. Similarly, lifts of γ_2 connect [m, n] to [m, n+1] and lifts of γ_3 connect [m, n] to [m+1, n-1].

Proposition 5.1. The shear coordinates with respect to T_0 of allowable curves in (\mathbf{S}, p) are as follows:

- (1) The cyclic permutations of [1 b, a + 1, b a 1] for Farey points [a, b] with $a \ge 0$ and b > 0. (These are for curves with counterclockwise spirals.)
- (2) The cyclic permutations of [-1 b, a 1, b a + 1] for Farey points [a, b] with a > 0 and $b \ge 0$. (These are for curves with clockwise spirals.)
- (3) The nonzero integer vectors [x, y, z] with x + y + z = 0 such that x, y, and z have no common factors. (These are for closed curves.)

Proof. We first consider the curves ccw(a, b) and cl(a, b) for positive or infinite slopes with standard form b/a. As in the proof of Proposition 4.1, each lifted curve determines a word in the letters \mathbf{r} and \mathbf{t} , but we modify the words slightly to deal with spirals. For ccw(a, b), we begin the word with tr, encoding the interaction of the curve with the square with corners [0, 0] and [-1, 1]. We then record **r** each time the lifted curve exits a square to the right and t each time the curve exits a square on top. At the ending spiral point, we record an \mathbf{r} as the curve exits a square on the right to begin its spiral, and then we end the word. (More symmetrically, one might want to record rt at the spiral, but the argument below shows that r is correct.) For example, ccw(2,3) gives the word trtrtr as illustrated in the left picture of Figure 4. If $b/a = \infty$, so that a = 0 and b = 1, then the word is tr. For cl(a, b), we start at a point where some lift of the curve intersects the segment from [0, 0] to [1, 0], record a t for exiting the square with corners [0, 0] and [1, -1] and record r and t until we reach a translate of the starting point, where we again record a t. Thus for example cl(2,3) gives the word ttrtrt as illustrated in the right picture of Figure 4.

To calculate shear coordinates from these words, we record a contribution for each consecutive pair of letters. (Each interior letter in the word appear in two consecutive pairs.) Figure 5 illustrates these contributions. (Cf. Figure 2.) In the



FIGURE 4. Words and shear coordinates of curves ccw(3,2) and cl(3,2)



FIGURE 5. Shear coordinates from consecutive pairs in words

figure, lifts of γ_1 are labeled "1" and so forth. If the pair is **rr**, then we record the vector [0, 1, -1]. The 1 in the 2nd coordinate arises because after the second **r** is recorded, the curve next crosses a lift of γ_3 . If the pair is **rt**, then we record [-1, 0, 0]. The -1 arises because after the **t** is recorded, the curve next crosses a lift of γ_3 ; we ended the word for ccw(a, b) with **r** instead of **rt** to avoid incorrectly recording this -1. If the pair is **tr**, then we record [0, 1, 0]. If the pair is **tt**, then we record [-1, 0, 1]. Adding up all of these contributions, we obtain the shear coordinates of the curve with respect to T_0 . Thus for example the curves represented in Figure 4 have shear coordinates as shown in the figure.

The word for $\operatorname{ccw}(a, b)$ is tr followed by some sequence of a - 1 instances of r and b - 1 instances of t, and then a final r for a total length of a + b + 1 letters. If $b/a \leq 1$, then the word has no consecutive pairs tt. In this case, there are b - 1consecutive pairs rt and b consecutive pairs tr. The remaining a - b + 1 consecutive pairs are rr. Thus the shear coordinates of $\operatorname{ccw}(a, b)$ are

$$(b-1)[-1, 0, 0] + b[0, 1, 0] + (a-b+1)[0, 1, -1] = [1-b, a+1, b-a-1].$$

If b/a > 1, then the word has no consecutive pairs **rr**. (The condition b/a > 1 implies in particular that the first letter after the initial **tr** is **t** and that the last letter before the final **r** is also **t**.) Thus in this case, there are *a* consecutive pairs **rt** and a + 1 consecutive pairs **tr**, with the remaining b - a - 1 pairs being **tt**. Thus

the shear coordinates are

$$a[-1, 0, 0] + (a + 1)[0, 1, 0] + (b - a - 1)[-1, 0, 1] = [1 - b, a + 1, b - a - 1].$$

The calculation for cl(a, b) is very similar. The word for cl(a, b) begins and ends with t and has a total of a instances of r and b + 1 instances of t. If $b/a \leq 1$, then the word has rt b times, tr b times, and rr a - b times, giving shear coordinates

$$b[-1, 0, 0] + b[0, 1, 0] + (a - b)[0, 1, -1] = [-b, a, b - a].$$

If $b/a \ge 1$, then the word has rt *a* times, tr *a* times, and tt b-a times, giving the same formula for shear coordinates.

We have thus dealt with shear coordinates of $\operatorname{ccw}(a, b)$ and $\operatorname{cl}(a, b)$ for b/a positive or infinite. The remaining possibilities for b/a are now easily completed using the symmetries of the problem. The linear map $[a, b] \mapsto [-b, a + b]$ restricts to a bijection from $\{[a, b] : -a < b \leq 0\}$ to $\{[a, b] : a \geq 0, b > 0\}$. The map restricts further to a bijection on Farey points in these sets. Furthermore, if $-a < b \leq 0$ and the shear coordinates of $\operatorname{ccw}(-b, a + b)$ are [x, y, z], then by symmetry, the shear coordinates of $\operatorname{ccw}(a, b)$ are [y, z, x]. The same is true replacing $\operatorname{ccw}(a, b)$ with $\operatorname{cl}(a, b)$. Similarly, the map $[a, b] \mapsto [-a - b, a]$ restricts to a bijection from $\{[a, b] : 0 < a \leq -b\}$ to $\{[a, b] : a \geq 0, b > 0\}$, and restricts further to a bijection on Farey points. If $0 < a \leq -b$ and the shear coordinates of $\operatorname{ccw}(-a - b, a)$ are [x, y, z], then the shear coordinates of $\operatorname{ccw}(a, b)$ are [z, x, y], and the same is true for $\operatorname{cl}(a, b)$.

We have seen that the vectors described in item (1) of the theorem are exactly the shear coordinates of curves with counterclockwise spirals. A reflection through the line a = b induces a bijection from these curves to curves with clockwise spirals. The effect of this reflection on shear coordinates is to switch a and b, to swap the first two entries of the shear coordinates (since the reflection maps γ_1 to γ_2 and fixes γ_3) and to negate the shear coordinates (since the reflection reverses orientation). Thus the vectors described in item (2) of the theorem are exactly the shear coordinates of curves with clockwise spirals.

We have also seen that the shear coordinates of closed curves are given by cyclic permutations of [-b, a, b-a] for b/a the standard form for a positive rational number or ∞ . To complete the proof, it remains only to show that all nonzero integer vectors [x, y, z] with x + y + z = 0 such that x, y, and z have no common factors appear as cyclic permutations of such vectors [-b, a, b-a]. Any such vector [x, y, z] has one or more of its coordinates negative and one or more of its coordinates positive. In particular, up to a cyclic permutation of coordinates, we can take x negative and y nonnegative. Then setting b = -x and a = y, we obtain z = b - a, so that [x, y, z] is [-b, a, b-a].

6. The Null Tangle Property

In this section, we prove Theorem 3.2. The following proposition goes part of the way towards the proof.

Proposition 6.1. Suppose Ξ is a null tangle in (\mathbf{S}, p) . Then the support of Ξ contains only closed curves.

The proof of Proposition 6.1 uses the following lemma, which is far from an exhaustive list of Farey neighbors.

Lemma 6.2. Let [a, b] be a standard Farey point.

- (1) If a = 0, then the Farey neighbors of [a, b] include [1, n] for $n \ge 0$.
- (2) If a = 1, then the Farey neighbors of [a, b] include [n, bn 1] for $n \ge 1$.
- (3) If a > 1, then there exists an integer c_0 with $1 \le c_0 < a$ such that the Farey neighbors of [a, b] include $\left[(c_0 + an), \frac{b(c_0 + an) 1}{a}\right]$ for $n \ge 0$.

Proof. The condition $ad - bc = \pm 1$ implies that [c, d] is a Farey point because any common divisor of c and d is a divisor of ad - bc. Thus, the Farey neighbors of [a, b] are the integer points [c, d] such that a and c have weakly the same sign, b and d have weakly the same sign, and $ad - bc = \pm 1$.

If a = 0, then b = 1, and the statement is easy. If a = 1, then the statement is also easy. Now suppose a > 1. For each integer $c \ge 1$, the equation ad - bc = -1 has an integer solution $d = \frac{bc-1}{a}$ if and only if $bc \equiv 1 \mod a$. Since gcd(a, b) = 1, every integer bc for $1 \le c < a$ is in a distinct class mod a and none of these integers are multiples of a. Thus there exists an integer c_0 with $1 \le c_0 < a$ and $bc_0 \equiv 1 \mod a$. For each integer $n \ge 0$, the quantity $d = \frac{b(c_0+an)-1}{a}$ is also an integer.

Proof of Proposition 6.1. Suppose Ξ is a null tangle in (\mathbf{S}, p) . Proposition 4.5 says that each curve in Ξ is cw(a, b), ccw(a, b), or cl(a, b) for some slope with standard form b/a. For each curve λ , we write q_{λ} for this slope b/a.

First, suppose Ξ contains some curve λ of the form $\operatorname{ccw}(e, f)$ for some slope q_{λ} with standard form f/e. Since there are finitely many curves in Ξ , there is some slope $\bar{q} < q_{\lambda}$ such that every curve $\nu \in \Xi$ has either $q_{\nu} \ge q_{\lambda}$ or $q_{\nu} \le \bar{q}$. Lemma 6.2 lets us find a Farey neighbor [a, b] of [e, f] with $\bar{q} < b/a < f/e$. This is done by taking n large enough and setting [a, b] equal to [1, n] if e = 0, or [n, fn - 1] if e = 1, or $\left[(a_0 + en), \frac{f(a_0 + en)^{-1}}{e}\right]$ if e > 1. Let [c, d] be the Farey neighbor of [e, f] obtained by replacing n by n + 1 in the expression for [a, b]. Then $\bar{q} < b/a < d/c < f/e$, and furthermore, [a, b] and [c, d] are Farey neighbors. Let α be the arc associated to [a, b], let β be the arc associated to [c, d] and let γ be the arc associated to [e, f]. Then $T = \{\alpha, \beta, \gamma\}$ is a triangulation of (\mathbf{S}, p) .

To calculate shear coordinates, we look at the intersections of lifts of the curves with lifts of the arcs α, β, γ . When we do so, we see that $b_{\gamma}(T, \lambda) = 1$, as illustrated in Figure 6, with two preimages of α drawn in red, two preimages of β drawn in blue, and a preimage of γ drawn in purple. Furthermore, any other curve ν



FIGURE 6. Illustration for the proof of Proposition 6.1

with $b_{\gamma}(T,\nu) > 0$ has $b/a < q_{\nu} < f/e$. But no such curve ν exists in Ξ because $\bar{q} < b/a < f/e = q_{\lambda}$. Thus any $\nu \in \Xi$ with $\nu \neq \lambda$ has $b_{\gamma}(T,\nu)$ nonpositive. Proposition 3.1 says that λ has weight 0 in Ξ .

Next suppose Ξ contains some curve λ of the form cw(a, b). Applying the symmetry of the once-punctured torus induced by reflecting \mathbb{R}^2 in the line a = b, we obtain a null tangle Ξ' . Let λ' be the image of λ under the symmetry. By the preceding argument, the weight of λ' in Ξ' is 0, so the weight of λ in Ξ is 0.

The following proposition is the specialization of [15, Proposition 7.9] to the oncepunctured torus.

Proposition 6.3. A tangle Ξ in (\mathbf{S}, \mathbf{M}) is null if and only if $\sum_{\lambda \in \Xi} w_{\lambda} \mathbf{b}(T, \lambda)$ is a B(T)-coherent linear relation for any triangulation T.

Proof of Theorem 3.2. Suppose Ξ is a null tangle. By Proposition 6.1, the support of Ξ contains only curves of the form cl(a, b). To complete the proof, we resort to working with explicit shear coordinates and Proposition 6.3. Let $\lambda = cl(a, b)$ be a curve in Ξ with weight w_{λ} . Let γ be the arc that is the projection of the segment connecting [0, 0] to [a, b]. Complete γ to a triangulation T' by adding two additional arcs. Index the arcs so that the shear coordinates of λ are [1, -1, 0]. If B(T') = -B, then we alter T' by flipping the arc γ . This preserves the shear coordinates of λ and makes B(T') equal to B. Taking the shear coordinates, with respect to T' of all of the curves in Ξ and applying Proposition 6.3, we obtain a B-coherent linear relation $c\mathbf{v} + \sum_{i \in S} c_i \mathbf{v}_i$ on nonzero integer vectors in the plane x + y + z = 0, with $\mathbf{v} = [1, -1, 0]$ and $c = w_{\lambda}$. We will show that c = 0. To show that c = 0, we consider $\eta_{21}^B = \eta_2^{-B} \circ \eta_1^B$ and its inverse η_{12}^B , restricting our

attention to the plane x + y + z = 0. Using (2.2), we calculate $\eta_{21}^B([x, y, z])$ to be

$$\eta_{21}^B([x, y, z]) = \begin{cases} [-x, -y, 2x + 2y + z], & \text{if } x \leq 0 \text{ and } y \leq 0, \\ [-x + 2y, -y, 2x + z], & \text{if } x \leq 0 \text{ and } y \geq 0, \\ [-x, -2x - y, 4x + 2y + z], & \text{if } x \geq 0 \text{ and } 2x + y \leq 0, \\ [3x + 2y, -2x - y, z], & \text{if } x \geq 0 \text{ and } 2x + y \geq 0. \end{cases}$$

Define D_0 to be the closed cone spanned by [-1, 0, 1] and [0, 1, -1]. For each integer j > 0, define D_j to be the closed cone spanned by [j-1, -j+2, -1] and [j, -j+1, -1]. For each integer j < 0, define D_j to be the closed cone spanned by [-j-2, j+1, 1] and [-j-1, j, 1]. Some of these cones are illustrated in Figure 7. The left picture establishes the coordinate system for the right picture by showing the intersections of the planes x = 0, y = 0 and z = 0 with the plane x + y + z = 0and by labeling several points in the plane. The map η_{21}^B fixes **v** and sends D_i to D_{j+2} for all j. The inverse map η_{12}^B fixes **v** and sends D_j to D_{j-2} for all j.

Now, we may as well assume that all of the vectors \mathbf{v}_i are contained in $D_1 \cup$ $\cdots \cup D_{m-2}$ for some $m \ge 3$. Otherwise, we can replace $c\mathbf{v} + \sum_{i \in S} c_i \mathbf{v}_i$ by $c\mathbf{v} + \sum_{i \in S} c_i \mathbf{v}_i$ $\sum_{i \in S} c_i(\eta_{21}^B)^\ell \mathbf{v}_i$ for large enough integer ℓ . Partition the set S into m (possibly empty) blocks U_1, \ldots, U_m with the following property: If $i \in U_j$, then $\mathbf{v}_i \in D_j$. There may not be a unique way to do this, because \mathbf{v}_i may be in $U_j \cap U_{j+1}$. For each j from 1 to m, let $\mathbf{w}_j = \sum_{i \in U_j} c_i \mathbf{v}_i$. Since this sum may have more than one term and since the c_i may be negative, the vector \mathbf{w}_i may not be contained in D_i .



FIGURE 7. The plane x + y + z = 0 and the cones D_i

For that reason, $\eta_{12}^B(\mathbf{w}_j)$ may not equal $\sum_{i \in U_j} c_i \eta_{12}^B(\mathbf{v}_i)$. Each D_j is contained in a domain of linearity of η_{12}^B , and we define θ_j to be the linear map that agrees with η_{12}^B on D_j . Furthermore, each D_j is contained in a domain of linearity of $(\eta_{12}^B)^k$ for any k. We write $\theta_j^{(k)}$ for the linear map that agrees with $(\eta_{12}^B)^k$ on D_j . Thus $\theta_j^{(k)}$ is $\theta_{j+2k-2} \circ \theta_{j+2k-4} \circ \cdots \circ \theta_j$ for $k \ge 1$ or $\theta_{j+2k+2}^{-1} \circ \theta_{j+2k+4}^{-1} \circ \cdots \circ \theta_j^{-1}$ for $k \le 1$. A key to the following argument is that, for all j, the maps θ_j and θ_{j+1} coincide on the line containing $D_j \cap D_{j+1}$, and both maps send that line to the line containing $D_{j+2} \cap D_{j+3}$.

Now we begin to apply the fact that $c\mathbf{v} + \sum_{i \in S} c_i \mathbf{v}_i$ is a *B*-coherent linear relation. Specifically, we inductively construct a list $\mathbf{u}_0, \mathbf{u}_1, \ldots, \mathbf{u}_m$ of vectors with two properties: First, each \mathbf{u}_ℓ is in the line containing the ray $D_\ell \cap D_{\ell+1}$, and second, $\mathbf{w}_j = \mathbf{u}_j - \mathbf{u}_{j-1}$ for j from 1 to m. We begin by setting $\mathbf{u}_0 = \mathbf{0}$. As a base for the induction, observe that all of the vectors \mathbf{v}_i with positive second coordinate have $i \in U_1$. Thus, subtracting (2.4) from (2.3) with $\mathbf{k} = \emptyset$ and restricting to the second coordinate, we see that \mathbf{w}_1 equals some vector \mathbf{u}_1 contained in the line y = 0, which is the line containing $D_1 \cap D_2$. Now suppose j > 1. By induction, we have already constructed a vector \mathbf{u}_{j-2} contained in the line containing $D_{j-2} \cap D_{j-1}$ and a vector \mathbf{u}_{j-1} contained in the line containing $D_{j-1} \cap D_j$, and we have $\mathbf{w}_{j-1} = \mathbf{u}_{j-1} - \mathbf{u}_{j-2}$.

Consider first the case where j is even. All of the vectors $(\eta_{12}^B)^{j/2}(\mathbf{v}_i)$ with negative first coordinate are in the interior of $D_{-1} \cup D_0$, so that each corresponding \mathbf{v}_i is in the interior of $D_{j-1} \cup D_j$, or in other words, $i \in U_{j-1} \cup U_j$. Restricting (2.4) to its first coordinate, with \mathbf{k} the sequence $1212 \cdots$ of length j, we see that $\theta_{j-1}^{(j/2)}(\mathbf{w}_{j-1}) + \theta_{j}^{(j/2)}(\mathbf{w}_j)$ is a vector contained in the line x = 0. Now $\theta_{j-1}^{(j/2)}(\mathbf{w}_{j-1}) = \theta_{j-1}^{(j/2)}(\mathbf{u}_{j-1}) - \theta_{j-1}^{(j/2)}(\mathbf{u}_{j-2})$. Since \mathbf{u}_{j-2} is in the line containing $D_{j-2} \cap D_{j-1}$ and \mathbf{u}_{j-1} is in the line containing $D_{j-1} \cap D_j$, we see that $\theta_{j-1}^{(j/2)}(\mathbf{u}_{j-2})$ is in the line containing $D_{-2} \cap D_{-1}$ (i.e., the line x = 0) and that $\theta_{j-1}^{(j/2)}(\mathbf{u}_{j-1}) + \theta_j^{(j/2)}(\mathbf{w}_j)$ is in the line x = 0 means that $\theta_j^{(j/2)}(\mathbf{w}_j) = \mathbf{s} - \theta_{j-1}^{(j/2)}(\mathbf{u}_{j-1})$ for some vector \mathbf{s} in the line x = 0. Since \mathbf{u}_{j-1} is in the line containing $D_{j-1} \cap D_j$, the maps $\theta_{j-1}^{(j/2)}(\mathbf{w}_j)$ agree on the vector \mathbf{u}_{j-1} . Thus we write $\theta_j^{(j/2)}(\mathbf{w}_j) = \mathbf{s} - \theta_j^{(j/2)}(\mathbf{u}_{j-1})$, and we conclude that $\mathbf{w}_j = \mathbf{u}_j - \mathbf{u}_{j-1}$, where $\mathbf{u}_j = (\theta_j^{(j/2-1)})^{-1}\mathbf{s}$ is contained in the line containing $D_j \cap D_{j+1}$.

Next, consider the case where j is odd. All of the vectors $(\eta_{12}^B)^{(j-1)/2}(\mathbf{v}_i)$ with positive second coordinate are in the interior of $D_0 \cup D_1$, so that each corresponding i is in $U_{j-1} \cup U_j$. Thus, subtracting (2.4) from (2.3) with \mathbf{k} the sequence $1212\cdots$ of length j-1 and restricting to the second coordinate, we see that $\theta_{j-1}^{((j-1)/2)}(\mathbf{w}_{j-1}) + \theta_j^{((j-1)/2)}(\mathbf{w}_j)$ is a vector contained in the line y = 0, which is the line containing $D_1 \cap D_2$. But $\theta_j^{((j-1)/2)}(\mathbf{u}_{j-2})$ is also in the line y = 0 containing $D_{-1} \cap D_0$, so we conclude that $\theta_j^{((j-1)/2)}(\mathbf{w}_j) = \mathbf{s} - \theta_{j-1}^{((j-1)/2)}(\mathbf{u}_{j-1})$ for some vector \mathbf{s} in the line y = 0. Since \mathbf{u}_{j-1} is in the line containing $D_{j-1} \cap D_j$, the maps $\theta_{j-1}^{((j-1)/2)}(\mathbf{u}_{j-1})$, and we conclude that $\mathbf{w}_j = \mathbf{u}_j - \mathbf{u}_{j-1}$ where $\mathbf{u}_j = (\theta_j^{((j-1)/2)})^{-1}\mathbf{s}$ is contained in the line containing $D_j \cap D_{j+1}$. This completes our inductive construction of the \mathbf{u}_j .

By our choice of m, the set U_m is empty, so $\mathbf{w}_m = \mathbf{0}$. Since \mathbf{w}_m is $\mathbf{u}_m - \mathbf{u}_{m-1}$ with \mathbf{u}_m and \mathbf{u}_{m-1} contained in distinct lines through the origin, we conclude that $\mathbf{u}_m = \mathbf{u}_{m-1} = \mathbf{0}$. We rewrite the expression $c\mathbf{v} + \sum_{i \in S} c_i \mathbf{v}_i$ as $c\mathbf{v} + \sum_{j=1}^m \mathbf{w}_j$, and then further as a telescoping sum $c\mathbf{v} + \sum_{j=1}^m (\mathbf{u}_j - \mathbf{u}_{j-1}) = c\mathbf{v} + \mathbf{u}_m - \mathbf{u}_0$, which equals $c\mathbf{v}$. But this expression equals $\mathbf{0}$ and \mathbf{v} is a nonzero vector, so c = 0. Since λ is an arbitrary curve in Ξ , the proof is complete.

Now Corollary 3.3 combines with Proposition 5.1 to show that the vectors described in (1.1), (1.1), and (1.1) of Theorem 1.1 are a \mathbb{Z} - or \mathbb{Q} -basis for B. By Theorem 2.1, we have proved the first assertion of Theorem 1.1. The proof of Theorem 1.1 is completed in Section 8.

7. The mutation fan

In this section, we construct the mutation fan \mathcal{F}_B , which was pictured in Figure 1. We define six maps from \mathbb{R}^2 to \mathbb{R}^3 .

$$\phi_1 : [a, b] \mapsto [1 - b, a + 1, b - a - 1] \qquad \phi_4 : [a, b] \mapsto [-1 - b, a - 1, b - a + 1]$$

$$\phi_2 : [a, b] \mapsto [a + 1, b - a - 1, 1 - b] \qquad \phi_5 : [a, b] \mapsto [a - 1, b - a + 1, -1 - b]$$

$$\phi_3 : [a, b] \mapsto [b - a - 1, 1 - b, a + 1] \qquad \phi_6 : [a, b] \mapsto [b - a + 1, -1 - b, a - 1]$$

The first three maps are bijections from \mathbb{R}^2 to the plane given by x + y + z = 1, related to each other by a cyclic permutation of coordinates. The last three maps are bijections to the plane x + y + z = -1, related in the same way. We extend each map ϕ_i to a map Φ_i from closed polyhedra in \mathbb{R}^2 to closed polyhedral cones in \mathbb{R}^3 sending a polyhedron P to the closure of the nonnegative linear span of $\phi_i(P)$. In particular, these maps send Farey rays and Farey triangles to 2- and 3-dimensional simplicial cones. A Farey ray with vertex [a, b] is the limit, as $c \to \infty$, of the line segment from [a, b] to c[a, b]. Thus Φ_i sends the Farey ray to the limit, as $c \to \infty$, of the 2-dimensional cone spanned by $\phi_i([a, b])$ and $\phi_i([ca, cb])$, or equivalently the cone spanned by $\phi_i([a, b])$ and $\frac{1}{c}\phi_i([ca, cb])$. This limit is the cone spanned by $\phi_i([a, b])$ and $\lim_{c\to\infty} \frac{1}{c}\phi_i([ca, cb])$. For example, Φ_1 sends this ray to the cone spanned by [1-b, a+1, b-a-1] and [-b, a, b-a].

Theorem 7.1. Let $B = \begin{bmatrix} 0 & 2 & -2 \\ -2 & 0 & 2 \\ 2 & -2 & 0 \end{bmatrix}$. Then \mathcal{F}_B consists of the following cones and their faces:

- (1) The nonnegative and nonpositive orthants $\pm O$.
- (2) For each i = 1, 2, 3, 4, 5, 6, the image under Φ_i of all Farey triangles contained in the region $\{[a, b] \in \mathbb{R}^2 : a \ge -1, b \ge 1\}$.
- (3) For each i = 1, 2, 3, 4, 5, 6, the image under Φ_i of all Farey rays whose vertex is [a, b] with $a \ge 0$ and $b \ge 1$.
- (4) All rays contained in the plane x + y + z = 0.

All of the cones described above are maximal except for the rational rays in the plane x + y + z = 0, each of which is a proper face of two cones described in (7.1).

To prove Theorem 7.1, we need the following lemma.

Lemma 7.2. Every point in $\{[a, b] \in \mathbb{R}^2 : b \ge 1\}$ is contained in some Farey triangle or ray.

Proof. Suppose $[a, b] \in \mathbb{R}^2$ has $b \ge 1$. We argue by induction on [|a|] (the smallest integer greater than or equal to |a|). For $0 \le [a] \le 1$, the lemma follows from Lemma 6.2(6.2). If a > 1, then we apply the piecewise-linear map given by $[a, b] \mapsto [a-b, b]$ (if $a \ge b$) or $[a, b] \mapsto [b-a, a]$ (if $a \le b$). This map preserves Farey points, triangles, and rays. By induction, the image of [a, b] under the map is contained in some Farey triangle or ray. Therefore, the same is true of [a, b]. If a < 0, then we argue symmetrically and appeal to induction.

Proof of Theorem 7.1. We first explicitly construct $\mathcal{F}_{\mathbb{Q}}(T_0)$. The rays of $\mathcal{F}_{\mathbb{Q}}(T_0)$ are spanned by the shear coordinates of allowable curves in (\mathbf{S}, p) . Proposition 5.1 shows that these rays are the images of standard Farey points under the maps Φ_i and the rational rays in the plane x+y+z=0. We have $\lim_{c\to\infty}\frac{1}{c}\phi_1([ca, cb]) = [-b, a, b-a]$ for a Farey point [a, b] with $a \ge 0$ and $b \ge 1$. The proof of Proposition 5.1 shows that [-b, a, b-a] is $\mathbf{b}(T_0, \mathrm{cl}(a, b))$. By Proposition 4.6, we see that Φ_1 takes the Farey ray with vertex [a, b] to the 2-dimensional cone of $\mathcal{F}_{\mathbb{Q}}(T_0)$ spanned by the shear coordinates of $\mathrm{cl}(a, b)$ and $\mathrm{ccw}(a, b)$. By symmetry, Φ_i maps this Farey ray to a 2-dimensional cone of $\mathcal{F}_{\mathbb{Q}}(T_0)$ for all i.

Proposition 4.6 also implies that the full-dimensional cones of $\mathcal{F}_{\mathbb{Q}}(T_0)$ are obtained as follows: Take exactly one representative of each antipodal pair of Farey triangles. Each representative indexes two full-dimensional cones. One is obtained by computing shear coordinates of $\operatorname{ccw}(\cdot, \cdot)$ of each vertex and taking nonnegative span of the three resulting vectors. The other is obtained in the same way with $\operatorname{cw}(\cdot, \cdot)$. We deal first with the cones obtained from curves with counterclockwise spirals.

The proof of Proposition 5.1 establishes that, for Farey triangles contained in the region $\{[a, b] \in \mathbb{R}^2 : a \ge 0, b > 0\}$, the maximal cones for curves with counterclockwise spirals are obtained by applying the map Φ_1 . Furthermore, one checks directly that the shear coordinate vector of $\operatorname{ccw}([1, -n])$ is $[1 - n, 0, n] = \phi_1([-1, n])$. Thus the map Φ_1 takes all Farey triangles contained in $\{[a, b] \in \mathbb{R}^2 : a \ge -1, b \ge 1\}$ to full-dimensional cones of $\mathcal{F}_{\mathbb{Q}}(T_0)$. The map $[a, b] \mapsto [b, a - b]$ takes the region $\{[a, b] \in \mathbb{R}^2 : a + b \ge 1, b \le 1\}$ to $\{[a, b] \in \mathbb{R}^2 : a \ge -1, b \ge 1\}$ and, as pointed out in the proof of Proposition 5.1, corresponds to a cyclic permutation of the shear coordinates of $\operatorname{ccw}(a, b)$. The map $[a, b] \mapsto [a, -a - b]$ takes the region $\{[a, b] \in \mathbb{R}^2 : a \ge 1, a + b \le 1\}$ to $\{[a, b] \in \mathbb{R}^2 : a \ge -1, b \ge 1\}$ and corresponds to the other cyclic permutation of shear coordinates of ccw(a, b). The only remaining pair of antipodal Farey triangles is [0, 1], [-1, 0], [-1, 1] and its antipodal opposite. The shear coordinates of ccw(a, b) for vertices [a, b] of this triangle span the cone O.

We have established that the maximal cones in $\mathcal{F}_{\mathbb{Q}}(T_0)$ spanned by curves with counterclockwise spirals are given by O and the cones described in (7.1) for i = 1, 2, 3. To construct the maximal cones in $\mathcal{F}_{\mathbb{Q}}(T_0)$ spanned by curves with clockwise spirals, we use the same symmetry we used in the proof of Proposition 5.1 (reflection through the line a = b). Specifically, the cones for clockwise spirals are obtained from the cones for counterclockwise spirals by switching a and b, swapping the first two coordinates, and negating the shear coordinates. Thus the cones for clockwise spirals are -O and the cones described in (7.1) for i = 4, 5, 6. We have now shown that the maximal cones in $\mathcal{F}_{\mathbb{Q}}(T_0)$ are given by (7.1), (7.1), and (7.1). Each cone in (7.1) has a rational ray in the plane x + y + z = 0 as an extreme ray, and all rational cones in this plane occur, by Proposition 5.1.

Let U be the set $\{[a, b] \in \mathbb{R}^2 : a \ge -1, b \ge 1\}$. Then

$$\phi_1(U) = \left\{ [x, y, z] \in \mathbb{R}^3 : x + y + z = 1, \, x \le 0, \, y \ge 0 \right\}$$

and $\phi_2(U)$ and $\phi_3(U)$ are described similarly. We see that the plane x + y + z = 1 is the union

$$\phi_1(U) \cup \phi_2(U) \cup \phi_3(U) \cup \{ [x, y, x] \in \mathbb{R}^3 : x + y + z = 1, x \ge 0, y \ge 0, z \ge 0 \}.$$

By this observation, we now show that every point in \mathbb{R}^3 outside of the plane x + y + z = 0 is in some cone of $\mathcal{F}_{\mathbb{Q}}(T_0)$. Given such a point, some positive scaling of the point is in the plane x + y + z = 1 or in the plane x + y + z = -1. If the point scales to the plane x + y + z = 1, then it is in O or in $\Phi_1(U)$, $\Phi_2(U)$, or $\Phi_3(U)$. Lemma 7.2 implies that the point is in O or in the image of some Farey triangle or ray under Φ_1 , Φ_2 , or Φ_3 . Thus the point is in some cone of $\mathcal{F}_{\mathbb{Q}}(T_0)$. By symmetry, a point with a positive scaling to the plane x + y + z = -1 is also in some cone in $\mathcal{F}_{\mathbb{Q}}(T_0)$. We see that the images, under Φ_i for $i = 1, \ldots, 6$ of Farey triangles and rays in U cover the set of real vectors outside of the plane x + y + z = 0. Furthermore, since the images of Farey rays are two-dimensional and there are countably many Farey rays, the images of Farey triangles in U are dense in \mathbb{R}^3 .

Next, we show that all of the cones in $\mathcal{F}_{\mathbb{Q}}(T_0)$ are cones in \mathcal{F}_B . Proposition 3.4 states that the full-dimensional cones in $\mathcal{F}_{\mathbb{Q}}(T_0)$ are *B*-cones. The image *C* of a Farey ray under some map Φ_i is contained in a *B*-cone *D* by Proposition 3.4. The images of Farey triangles are disjoint from the plane x + y + z = 0, except at the origin, but *D* contains a nonzero point in the plane x + y + z = 0. Thus *D* is not the image of a Farey triangle in *U*. Since images of Farey triangles in *U* are dense in \mathbb{R}^3 , we see that *D* is 2-dimensional. Furthermore, the only possibilities for *D* are that D = C or that *D* is the union of *C* with the other cone in $\mathcal{F}_{\mathbb{Q}}(T_0)$ (on the other side of the plane x + y + z = 0) that shares an extreme ray with *C*. We rule out the latter case, however, because in that case *D* is a rational *B*-cone but not a cone in $\mathcal{F}_{\mathbb{Q}}(T_0)$, contradicting Proposition 3.4. Thus *C* equals the *B*-cone *D*.

It remains only to show that every ray in the plane x + y + z = 0 is a distinct *B*-cone. Suppose to the contrary that two non-parallel vectors [x, y, z] and [x', y', z']

in the plane x + y + z = 0 are in the same *B*-cone *C*. Find an integer point $[x'', y''] = c_1[x, y] + c_2[x', y']$ with $c_1 > 0$ and $c_2 > 0$ and set z'' = -x'' - y''. Then $[x'', y'', z''] = c_1[x, y, z] + c_2[x', y', z']$ is in *C* because *B*-cones are convex cones. Also [x'', y'', z''] is an integer vector in the plane x + y + z = 0, so as shown above, it spans an extreme ray of a 2-dimensional maximal *B*-cone *C'* not contained in the plane x + y + z = 0. But $C \cap C'$ is not a face of *C*, contradicting Theorem 2.3. \Box

In [15, Proposition 5.2], the **g**-vectors of cluster variables are realized in terms of shear coordinates of allowable curves, and the cones spanned by **g**-vectors of clusters are realized as the nonnegative linear spans of sets of pairwise compatible allowable curves. Combining this realization with Theorem 7.1, we obtain the following corollary.

Corollary 7.3. Let *B* be the matrix of Theorem 7.1, so that $B^T = \begin{bmatrix} 0 & -2 & 2 \\ 2 & 2 & 0 & -2 \\ -2 & 2 & 0 \end{bmatrix}$. Then the **g**-vectors of cluster variables associated to B^T are the cyclic permutations of vectors [1 - b, a + 1, b - a - 1], for all (possibly infinite) positive rational slopes with standard form b/a. The cones spanned by **g**-vectors of maximal sets of pairwise compatible cluster variables are exactly the images, under the maps Φ_1 , Φ_2 , and Φ_3 , of Farey triangles contained in the region $\{[a, b] \in \mathbb{R}^2 : a \ge -1, b \ge 1\}$.

The cones spanned by **g**-vectors of maximal sets of pairwise compatible cluster variables in particular constitute a fan. This fan, as it intersects the plane x + y + z = 1, is illustrated in Figure 8. The **g**-vectors are shown as blue dots. (Cf. [6, Figure 1] and [12, Figure 2].)

Remark 7.4. An exchange matrix B' is a **rescaling** of an exchange matrix B if $B' = \Sigma^{-1}B\Sigma$ for some diagonal matrix Σ with positive entries. Up to symmetry, the rescalings of $B = \begin{bmatrix} 0 & 2-2 \\ -2 & 0 & 2 \\ 2 & -2 & 0 \end{bmatrix}$ are $B' = \begin{bmatrix} 0 & 4-2 \\ -1 & 0 & 1 \\ 2 & -4 & 0 \end{bmatrix}$ and $B' = \begin{bmatrix} 0 & 4-4 \\ -1 & 0 & 2 \\ 1 & -2 & 0 \end{bmatrix}$. In [14, Section 7], it is explained how to obtain the mutation fan $\mathcal{F}_{B'}$, R-bases for B', \mathbf{g} -vectors for $(B')^T$, and so forth from the corresponding constructions for B, when B' is a rescaling of B. For example, Theorem 7.1 combines with [14, Proposition 7.8(3)] to yield the following statement.

Corollary 7.5. Let $B' = \begin{bmatrix} 0 & 4 & -2 \\ -1 & 0 & 1 \\ 2 & -4 & 0 \end{bmatrix}$. Then $\mathcal{F}_{B'}$ consists of the following cones and their faces:

- (1) The nonnegative and nonpositive orthants $\pm O$.
- (2) For each i = 1, 2, 3, 4, 5, 6, the cone obtained by applying the map $[x, y, z] \mapsto [x, 2y, z]$ to the image under Φ_i of all Farey triangles contained in the region $\{[a, b] \in \mathbb{R}^2 : a \ge -1, b \ge 1\}.$
- (3) For each i = 1, 2, 3, 4, 5, 6, the cone obtained by applying the map $[x, y, z] \mapsto [x, 2y, z]$ to the image under Φ_i of all Farey rays whose vertex is [a, b] with $a \ge 0$ and $b \ge 1$.
- (4) All rays contained in the plane 2x + y + 2z = 0.

All of the cones described above are maximal except for the rational rays in the plane 2x + y + 2z = 0, each of which is a proper face of the image of two Farey rays.



FIGURE 8. The **g**-vector fan for B^T as in Corollary 7.3

8. A positive \mathbb{R} -basis

In this section, we complete the proof of Theorem 1.1 by proving the assertion about universal geometric coefficients over \mathbb{R} . Theorem 7.1 implies that the vectors listed in Theorem 1.1 (1), (2) and (3') consist of one nonzero vector \mathbf{v}_{ρ} in each ray ρ of \mathcal{F}_B . By Proposition 2.5, to show that these vectors are a \mathbb{R} -basis for B, we need only verify that they are a \mathbb{R} -independent set for B. The assertion in Theorem 1.1 then follows by Theorem 2.1.

We begin by realizing the irrational rays of \mathcal{F}_B within the framework of curves in (\mathbf{S}, p) . For each real or infinite slope σ , choose a line in \mathbb{R}^2 with slope σ , not containing any integer points. (Fixing σ , the line is determined by its *x*-intercept. Thus, to avoid integer points, there are only countably many *x*-intercepts that must be avoided.) Let $\lambda(\sigma)$ be the projection of this line to the once-punctured torus. If σ is a rational number or ∞ with standard form b/a, then $\lambda(\sigma) = cl(a, b)$. Otherwise $\lambda(\sigma)$ is dense in the torus.

The normalized shear coordinates $\overline{\mathbf{b}}(T_0, \lambda(\sigma)) = (\overline{b}_{\gamma}(T_0, \lambda(\sigma)) : \gamma \in T_0)$ of $\lambda(\sigma)$ with respect to T_0 are defined as follows: Start at any point on $\lambda(\sigma)$, fix a direction on the curve and mark off an arc length d in that direction. (The arc length d is calculated in the usual infinitesimal metric on the unpunctured torus,

inherited from \mathbb{R}^2 .) The marked off segment of the curve has shear coordinates given by the rule shown in Figure 2. For large enough d, these shear coordinates are nonzero and so can be normalized to unit length in the usual norm on \mathbb{R}^3 . The normalized shear coordinates of $\lambda(\sigma)$ are given by the limit of these unit vectors, as d goes to infinity. The discussion below in particular shows that this limit exists.

Suppose σ is positive or infinite. Consider a segment of the line with slope σ from y = 0 to y = k, and associate a word in **r** and **t** to this segment as in the proof of Proposition 5.1. This word starts and ends with **t** and has k + 1 instances of **t** and some number ℓ of instances of **r**. If $\sigma \ge 1$, then this word has no two consecutive letters **r**. Thus the word has **rt** ℓ times, has **tr** ℓ times, and has **tt** $k - \ell$ times. The shear coordinates of the segment are

$$\ell[-1, 0, 0] + \ell[0, 1, 0] + (k - \ell)[-1, 0, 1] = [-k, \ell, k - \ell].$$

If $\sigma \leq 1$, then the word has no two consecutive letters t. Thus it has rt k times, tr k times, and rr $\ell - k$ times so the shear coordinates of the segment are

$$k[-1, 0, 0] + k[0, 1, 0] + (\ell - k)[0, 1, -1] = [-k, \ell, k - \ell].$$

As k goes to infinity, the ratio k/ℓ goes to σ , so the limit of the unit vectors in the direction $[-k, \ell, k - \ell]$ is the unit vector in the direction $[-\sigma, 1, \sigma - 1]$.

Nonpositive slopes are dealt with by symmetry as in the proof of Proposition 5.1. Specifically, if $-1 < \sigma \leq 0$ then the map $[a, b] \mapsto [-b, a + b]$ takes $[1, \sigma]$ to $[-\sigma, \sigma + 1]$, which corresponds to a slope $\frac{-\sigma-1}{\sigma}$. If $\sigma \leq -1$ then the map $[a, b] \mapsto [-a-b, a]$ takes $[1, \sigma]$ to $[-1-\sigma, 1]$, corresponding to a slope $\frac{-1}{1+\sigma}$. We see that the normalized shear coordinates of curves $\lambda(\sigma)$ are the cyclic permutations of the unit vectors in the direction of $[-\sigma, 1, \sigma-1]$ for positive real numbers σ or $\sigma = \infty$. (In the latter case, the unit vector is $\frac{1}{\sqrt{2}}[-1, 0, 1]$.) This calculation shows in particular that the normalized shear coordinates of $\lambda(\sigma)$ depend only on σ and not on the particular choice of a line of slope sigma. When σ is rational or infinite with standard form b/a, the normalized shear coordinates of $\lambda(\sigma)$ are obtained from the shear coordinates of cl(a, b) by normalizing to unit length.

As part of the proof of Proposition 5.1, we showed that all nonzero integer vectors [x, y, z] with x + y + z = 0 such that x, y, and z have no common factors appear as cyclic permutations of vectors [-b, a, b - a] such that b/a is the standard form of a rational slope or ∞ . The same proof shows that the map $\sigma \mapsto \mathbf{b}(T, \lambda(\sigma))$ is a bijection from real or infinite slopes to unit vectors in the plane x + y + z = 0. Thus by Theorem 7.1, the rays of the mutation fan \mathcal{F}_B are spanned by the shear coordinates of curves cw(a, b) and ccw(a, b) and by the normalized shear coordinates of curves $\lambda(\sigma)$.

The discussion above establishes that normalized shear coordinates of projected lines exist with respect to the fixed triangulation T, but the analogous procedure defines normalized shear coordinates of projected lines exist with respect to any triangulation.

These considerations also suggest the definition of a **real tangle** in the oncepunctured torus. This is a finite collection of distinct curves of the form ccw(a, b) or cw(a, b) for standard Farey points [a, b] or $\lambda(\sigma)$ for real or infinite slopes σ . Each curve is given a real weight. The shear coordinates of a real tangle are the weighted sum of (normalized) shear coordinates of the curves in the tangle. A real tangle is null if its shear coordinates are zero with respect to every triangulation.

Proposition 6.3 extends to real null tangles, as we now explain. To begin with, [15, Theorem 3.9] (which is part of [8, Theorem 13.5]) states that when a triangulation T is altered by a flip, the shear coordinate vector of an allowable curve λ is altered by the corresponding mutation map. Since the normalized shear coordinates of curves $\lambda(\sigma)$ are limits of normalizations of shear coordinates of allowable curves, and since mutation maps are continuous, [15, Theorem 3.9] extends to curves $\lambda(\sigma)$. The extension of Proposition 6.3 parallels the proof given in [15, Proposition 7.9] for (integer) null tangles: The extension of [15, Theorem 3.9] implies that, for any triangulation T, a real null tangle corresponds to a linear relation among normalized shear coordinates that is preserved under all mutation maps. Then [15, Proposition 2.3] says that a real null tangle corresponds to a B(T)-coherent linear relation among normalized shear coordinates.

Proposition 3.1 also extends to real tangles. The proof is a straightforward concatenation of the extension of Proposition 6.3 with [14, Proposition 4.12]. The latter is a version of Proposition 3.1 which holds for all *B*-coherent linear relations.

The extension of Proposition 6.3 to real tangles means that we can complete the proof of Theorem 1.1 by establishing the following "Real Null Tangle Property" of the once-punctured torus. (We emphasize, however, that we have no definition, for general surfaces, of a real tangle.)

Theorem 8.1. Every real null tangle in (\mathbf{S}, p) is trivial.

To prove the theorem, we first prove several lemmas.

Lemma 8.2. Suppose $q_1 < q_2 < q_3$ are slopes with standard forms $b/a = q_1$, $d/c = q_2$, and $f/e = q_3$. Suppose also that the corresponding arcs α_1 , α_2 , and α_3 constitute a triangulation T of (\mathbf{S}, p) . Then a curve $\lambda(\sigma)$ has $\overline{b}_{\alpha_3}(T, \lambda(\sigma)) > 0$ if and only if $\frac{b+d}{a+c} < \sigma < \frac{f}{e}$.

Proof. The situation is illustrated in Figure 9. Two preimages of α_1 are drawn in red, two preimages of α_2 are drawn in blue, and one preimage of α_3 is drawn in purple. The arc associated to $\frac{b+d}{a+c}$ is drawn gray. (For readers viewing the article in black



FIGURE 9. Illustration for the proof of Lemma 8.2

and white: The purple arc is the shorter of the two diagonals of the parallelogram.) It is immediate that $\frac{b+d}{a+c} < \sigma < \frac{f}{e}$ is a necessary condition for $\overline{b}_{\alpha_3}(T,\lambda(\sigma))$ to be positive. On the other hand, if $\frac{b+d}{a+c} < \sigma < \frac{f}{e}$, then there exists a line with slope σ that intersects the parallelogram in such a way as to have a positive normalized shear

coordinate. The normalized shear coordinates depend only on σ , so $\bar{b}_{\alpha_3}(T,\lambda(\sigma)) > 0$.

Lemma 8.3. Given a rational number q, there are at most finitely many pairs of Farey points [a, b] and [c, d] that are Farey neighbors and that have b/a < q < d/c.

Proof. Suppose [a, b] and [c, d] are Farey neighbors with b/a < q < d/c. In particular, a and c weakly agree in sign, so it is enough to show that there are finitely many possibilities with $a \ge 0$ and $c \ge 0$. Proposition 4.3 says that ad - bc = 1.

If a = 0, then since b/a < q, we have [a, b] = [0, -1]. Thus ad - bc = c = 1 and $d \leq 0$. There are at most finitely many integers $d \leq 0$ such that d > q. Similarly, if c = 0 then [c, d] = [0, 1], so that a = 1 and $b \geq 0$. There are finitely many integers $b \geq 0$ such that b < q.

Now suppose a > 0 and c > 0. Rewrite the identity ad - bc = 1 as b/a = d/c - 1/(ac), so that d/c - 1/(ac) < q < d/c and multiply through by c to obtain d - 1/a < cq < d. For a large enough, there are no multiples of q strictly between an integer d and the quantity d - 1/a, because q is rational. Thus there are only finitely many possible values of a.

Now use the identity b/a = d/c - 1/(ac) to rewrite the inequality b/a < q < d/cas b/a < q < b/a + 1/(ac) and multiply through by a to obtain b < aq < b + 1/c. We have $1/c \leq 1$, and so for each fixed a there is at most one b such that b < aq < b + 1/c. We have shown that there are only finitely many possible points [a, b].

The symmetric argument shows that there are at most finitely many points [c, d]. Specifically, for large enough c, the inequality b < aq < b + 1/c cannot be satisfied. Also, for fixed c, there is at most one d satisfying d - 1/a < cq < d.

Lemma 8.4. Given real numbers x < y with y irrational, there exists a Farey triangle with vertices [a, b], [c, d], and [e, f] having b/a < d/c < f/e such that $x < \frac{b+d}{a+c} < y < \frac{f}{e}$.

Proof. We will find s > 0 such that the vector s[1, y] is in such a Farey triangle. Since y is irrational, no vector s[1, y] is in a Farey ray. The symmetric statement to Lemma 7.2 (switching a and b) implies that for s > 1, the vector s[1, y] is in some Farey triangle. Choose a rational number q strictly between x and y. Lemma 8.3 implies that there are only finitely many Farey triangles having a vertex whose corresponding slope is less than q and having a vertex whose corresponding slope is greater than q. Thus there is some number $s_{\lim} > 1$ such that for $s > s_{\lim}$, the vector s[1, y] is in some Farey triangle all of whose vertices correspond to slopes greater than or equal to q.

Let Δ_0 be some Farey triangle containing $s_0[1, y]$ for some $s_0 > s_{\lim}$. As s increases from s_0 , the point s[1, y] passes through a sequence $\Delta_0, \Delta_1, \Delta_2, \ldots$ of Farey triangles. We claim that there exists k > 0 such that, writing [a, b], [c, d], and [e, f] for the vertices of Δ_k with b/a < d/c < f/e, the triangle Δ_{k+1} shares the vertices [c, d] and [e, f] with Δ_k . If not, then for any $k \ge 0$, the vector s[1, y] passes through infinitely many edges defined by Farey neighbors one of which is [a, b] and the other of which corresponds to a slope greater than y. This gives a contradiction to Lemma 8.3 for any rational number q' with b/a < q' < y. This contradiction proves the claim.

For Δ_k as in the claim, we have b/a < d/c < y < f/e. Also, by construction $x < q \leq b/a$. We can complete the proof by showing that b/a < (b+d)/(a+c) < d/c. Since x < b/a, we have $[a, b] \neq [0, -1]$, and since d/c > f/e, we also have $[c, d] \neq [0, 1]$. Thus both a and c are positive, so the inequality b/a < (b+d)/(a+c) follows easily from b/a < d/c. Similarly, (b+d)/(a+c) < d/c.

Proof of Theorem 8.1. Let Ξ be a real null tangle that is not trivial. The proof of Proposition 6.1 shows that Ξ is supported on curves of the form $\lambda(\sigma)$ (using the extension of Proposition 3.1 to real tangles). The remainder of the proof of Theorem 3.2 shows that Ξ is supported on curves $\lambda(\sigma)$ for σ irrational (using the extension of Proposition 6.3 to real tangles). The support of Ξ has at least two curves. Let σ_1 and σ_2 be the largest two numbers indexing curves in the support of Ξ , with $\sigma_1 < \sigma_2$. Lemma 8.4 says that there exists a Farey triangle with vertices [a, b], [c, d], and [e, f] with b/a < d/c < f/e such that $\sigma_1 < \frac{b+d}{a+c} < \sigma_2 < \frac{f}{e}$. By Propositions 4.1 and 4.3, the arcs given by slopes b/a, d/c, and f/e form a triangulation T of (\mathbf{S}, p) . Let γ be the arc associated to f/e. Lemma 8.2 and our choice of σ_1 and σ_2 imply that $\lambda(\sigma_1)$ is the unique curve in the support of Ξ whose normalized shear coordinates with respect to T have a positive entry in the position indexed by γ . By the extension of Proposition 3.1, we conclude that $\lambda(\sigma_1)$ appears with coefficient 0 in Ξ , and this contradiction proves the theorem.

9. Denominator vectors

We close with an aside about denominator vectors (**d**-vectors). Denominator vectors for marked surfaces are given by intersection numbers, as described in [7, Theorem 8.6]. These intersection numbers are easy to compute in the case of the once-punctured torus. Specifically, Proposition 4.1 combines with [7, Theorem 8.6] to prove the following proposition, which was already pointed out in [13, Example 2.18] with the same proof.

Proposition 9.1. Let $B = \begin{bmatrix} 0 & 2 & -2 \\ -2 & 0 & 0 \\ 2 & -2 & 0 \end{bmatrix}$. Then the **d**-vectors of cluster variables associated to B are the cyclic permutations of vectors [a - 1, b - 1, a + b - 1], for all (possibly infinite) positive rational slopes with standard form b/a.

Proposition 4.3 allows us to picture the **d**-vector fan as well. Two stereographic views are shown in Figure 10.

10. Extensions

A natural question is to what extent the results of this paper can be extended to other surfaces or to other cluster algebras. One would expect that the natural extension is to once-punctured surfaces of higher genus. But it is difficult to see how to proceed in higher genus. The key to the results for the torus is the fact that curves are indexed by rational slopes and that compatibility of curves is described by the Farey condition. In higher genus, curves and compatibility appear to be much more complicated.

However, there is another surface where rational slopes and Farey-type conditions describe curves and compatibility: the four-punctured sphere. In [1], Barnard, Meehan, Polster, and the author extend the results of this paper to that surface. Some



FIGURE 10. Two views of the **d**-vector fan for the once-punctured torus

of the preliminary results from [1] are already present in [2, Section 5]. Indeed, the four-punctured sphere is the simplest of the 4 *tubular cluster algebras* discussed in [2, 3] and is the only one of the 4 associated to a surface. Given the prominence of rational slopes and the Farey condition in [2, 3], it seems plausible that the results of this paper (except as they pertain to marked surfaces) extend in some form to the other 3 tubular cluster algebras as well. It also seems reasonable to wonder to what extent the once-punctured torus itself can be treated as a tubular cluster algebra.

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