

```

> restart:
with(LinearAlgebra):
d:=1;

```

$$d := 1$$

(1)

We define the Lax matrix using Theorem 2.2

```

> checkL12:=-t[2*d+1]*lambda^(2*d):
for k from 0 to 2*d-1 do checkL12:=checkL12-t[2*d+1]*Qinfy[k]*
lambda^k: od:
checkL12:=checkL12;

```

$$checkL12 := -t_3 \lambda^2 - t_3 Qinfy_1 \lambda - t_3 Qinfy_0$$

(2)

```

> checkL11:=t00/lambda+t00/Qinfy[0]*lambda^(2*d-1):
for k from 0 to 2*d-1 do checkL11:=checkL11-Pinfy[2*d-1-k]*
lambda^k: od:
for k from 0 to 2*d-2 do for m from 0 to 2*d-2-k do checkL11:=
checkL11-Pinfy[m]*Qinfy[k+1+m]*lambda^k: od: od:
for k from 1 to 2*d-1 do checkL11:=checkL11+t00/Qinfy[0]*Qinfy
[k]*lambda^(k-1): od:
checkL11:=checkL11;

```

```
checkL22:=-checkL11:
```

$$checkL11 := \frac{t00}{\lambda} + \frac{t00 \lambda}{Qinfy_0} - Pinfy_1 - Pinfy_0 \lambda - Pinfy_0 Qinfy_1 + \frac{t00 Qinfy_1}{Qinfy_0}$$

(3)

```

> NumcheckL21poleinfinity:=-checkL11^2/checkL12:
for j from 2*d-1 to 4*d do for m from 0 to 4*d-j do
NumcheckL21poleinfinity:=NumcheckL21poleinfinity+t[2*d+1-m]*t[j+
m-2*d+1]*lambda^j/checkL12: od: od:
checkL21poleinfinity:=0:
for i from 1 to 100 do
checkL21poleinfinity:=checkL21poleinfinity-(residue
(NumcheckL21poleinfinity*lambda^(-i),lambda=infinity))*lambda^
(i-1): od:

checkL21polezero:=simplify(-(residue(NumcheckL21poleinfinity,
lambda=infinity))/lambda):
checkL21:=checkL21polezero+checkL21poleinfinity;

```

$$checkL21 := \frac{1}{Qinfy_0^2 t_3 \lambda} \left(\left(-2 t_3^2 Qinfy_1 + 2 t_3 t_2 \right) Qinfy_0^3 + \left(Qinfy_1^3 t_3^2 - 2 t_2 Qinfy_1^2 t_3 + \left(Pinfy_0^2 + 2 t_3 t_1 + t_2^2 \right) Qinfy_1 - 2 t_3 t_0 - 2 t_2 t_1 + 2 Pinfy_0 Pinfy_1 \right) Qinfy_0^2 \right)$$

(4)

$$-2 t_{00} (Pinfty_0 Qinfy_1 + Pinfty_1) Qinfy_0 + t_{00}^2 Qinfy_1) + \frac{\left(\frac{t_{00}}{Qinfy_0} - Pinfty_0\right)^2}{t_3} - 2 t_1$$

$$- \frac{t_2^2}{t_3} + 2 t_2 Qinfy_1 - \frac{t_3^2 Qinfy_1^2 - t_3^2 Qinfy_0}{t_3} - (-t_3 Qinfy_1 + 2 t_2) \lambda - t_3 \lambda^2$$

```
> checkLMatrix:=Matrix(2,2,0):
checkLMatrix[1,1]:=checkL11:
checkLMatrix[1,2]:=checkL12:
checkLMatrix[2,1]:=checkL21:
checkLMatrix[2,2]:=checkL22:
checkLMatrix:
```

We define the general auxiliary matrix using Theorem 2.2

```
> checkA12:=0:
for i from 0 to 2*d-1 do checkA12:=checkA12-t[2*d+1]*nu[i]*
lambda^(2*d-i): od:
for k from 1 to 2*d-1 do for i from 0 to k-1 do checkA12:=
checkA12-t[2*d+1]*nu[i]*Qinfy[k]*lambda^(k-i): od: od:
checkA12;
```

```
nu[2*d]:=simplify(-residue(lambda^(2*d-1)*checkA12/checkL12,
lambda=infinity));
```

$$-t_3 v_0 \lambda^2 - t_3 v_0 Qinfy_1 \lambda - t_3 v_1 \lambda$$

$$v_2 := -Qinfy_0 v_0 - Qinfy_1 v_1$$

(5)

```
> checkA11:=0:
NumcheckA11:=0:
for i from 0 to 2*d-1 do NumcheckA11:=NumcheckA11+ nu[i]*lambda^
(-i)*checkL11: od:
for i from 1 to 100 do checkA11:=checkA11-(residue(NumcheckA11*
lambda^(-i), lambda=infinity))*lambda^(i-1): od:
checkA11;
```

```
checkA22:=-checkA11:
```

$$v_0 \left(-Pinfty_1 - Pinfty_0 Qinfy_1 + \frac{t_{00} Qinfy_1}{Qinfy_0} \right) + v_1 \left(\frac{t_{00}}{Qinfy_0} - Pinfty_0 \right) + v_0 \left(\frac{t_{00}}{Qinfy_0} - Pinfty_0 \right) \lambda$$

(6)

```
> checkA21:=(-t00)/t[2*d+1]/(Qinfy[0])^2*LQinfy[0]/lambda:
QuantitycheckA21:=checkL11/checkL12*(checkL11/checkL12*checkA12
-2*checkA11):
```

```

for i from 1 to 100 do checkA21:=checkA21-(residue
(QuantitycheckA21*lambda^(-i),lambda=infinity))*lambda^(i-1): od:
for i from 0 to 100 do checkA21:=checkA21+(residue
(QuantitycheckA21*lambda^(i),lambda=0))*lambda^(-i-1): od:
AdditionalTerm:=t00*(1-t00)/t[2*d+1]/Qinfy[0]^2/lambda*nu[2*d-1]
:
for k from 1 to 2*d-1 do AdditionalTerm:=AdditionalTerm+t00*(1-
t00)/t[2*d+1]/Qinfy[0]^2/lambda*nu[k-1]*Qinfy[k]: od:
checkA21:=checkA21+AdditionalTerm:
NumcheckA21:=0:
for k from 2*d to 4*d do for j from k to 4*d do for m from 0 to
4*d-j do NumcheckA21:=NumcheckA21- t[2*d+1-m]*t[j+m-2*d+1]*nu[j-
k]*lambda^k: od: od: od:
for i from 1 to 100 do checkA21:=checkA21-(residue(NumcheckA21/
(-checkL12)*lambda^(-i),lambda=infinity))*lambda^(i-1): od:
checkA21:=checkA21:
series(checkA21,lambda=infinity);

```

$$\begin{aligned}
& -t_3 v_0 \lambda^2 + \frac{(t_3^2 v_0 Qinfy_1 - 2 t_3 t_2 v_0 - t_3^2 v_1) \lambda}{t_3} + \frac{\left(\frac{t00}{Qinfy_0} - Pinfty_0 \right)^2 v_0}{t_3} + \frac{1}{t_3} \left(-2 t_3 t_1 v_0 \right. \\
& \quad \left. - t_2^2 v_0 - 2 t_3 t_2 v_1 - t_3^2 \left(-Qinfy_0 v_0 - Qinfy_1 v_1 \right) + t_3^2 v_0 Qinfy_0 - \left(t_3 v_0 Qinfy_1 - 2 v_0 t_2 \right. \right. \\
& \quad \left. \left. - t_3 v_1 \right) t_3 Qinfy_1 \right) + \frac{1}{\lambda} \left(-\frac{t00 L Qinfy_0}{t_3 Qinfy_0^2} + \frac{1}{Qinfy_0^4 t_3} \left(-2 t00 Pinfty_0 \right. \right. \\
& \quad \left. \left. Qinfy_0^3 Qinfy_1 v_0 + t00^2 Qinfy_0^2 Qinfy_1 v_0 - 2 t00 Pinfty_0 Qinfy_0^3 v_1 - 2 t00 Pinfty_1 \right. \right. \\
& \quad \left. \left. Qinfy_0^3 v_0 + t00^2 Qinfy_0^2 v_1 \right) + \frac{t00 (1 - t00) v_1}{t_3 Qinfy_0^2} + \frac{t00 (1 - t00) v_0 Qinfy_1}{t_3 Qinfy_0^2} \right)
\end{aligned} \tag{7}$$

```

> checkAMatrix:=Matrix(2,2,0):
checkAMatrix[1,1]:=checkA11:
checkAMatrix[1,2]:=checkA12:
checkAMatrix[2,1]:=checkA21:
checkAMatrix[2,2]:=checkA22:
checkAMatrix:

```

We define the derivatives of the Lax matrices. The derivative relatively to times and Darboux coordinates is specific to d=1 and should be adapted for other values of d.

```

> dcheckAMatrixdlambda:=Matrix(2,2,0):
for i from 1 to 2 do for j from 1 to 2 do dcheckAMatrixdlambda[i,
j]:=diff(checkAMatrix[i,j],lambda): od: od:
> LcheckLMatrix:=Matrix(2,2,0):
for i from 1 to 2 do for j from 1 to 2 do

```

```

LcheckLMatrix[i,j]:=diff(checkLMatrix[i,j],t[2])*alpha[2]+diff
(checkLMatrix[i,j],t[1])*alpha[1]+diff(checkLMatrix[i,j],Qinfy
[0])*LQinfy[0]+diff(checkLMatrix[i,j],Qinfy[1])*LQinfy[1]+diff
(checkLMatrix[i,j],Pinfty[0])*LPinfy[0]+ diff(checkLMatrix[i,j],
Pinfty[1])*LPinfy[1]: od: od:

```

We define the compatibility equations and solve them. This is the main test for the formulas of Theorem 2.2. This part is again specific to d=1 and should be adapted for other values of d

```

> CompatibilityEquations:=simplify(
dcheckAMatrixdlambda-LcheckLMatrix+Multiply
(checkAMatrix,checkLMatrix)-Multiply(checkLMatrix,checkAMatrix)
):
> simplify(series(CompatibilityEquations[1,1],lambda=0)):
series(simplify(series(CompatibilityEquations[1,1],lambda=
infinity)),lambda=infinity):
series(simplify(series(CompatibilityEquations[1,2],lambda=
infinity)),lambda=infinity):
series(simplify(series(CompatibilityEquations[2,1],lambda=
infinity)),lambda=infinity):
EQ1:=residue(CompatibilityEquations[1,1],lambda=0);
EQ2:=-residue(CompatibilityEquations[1,1]/lambda^2,lambda=
infinity);
EQ3:=-residue(CompatibilityEquations[1,1]/lambda^1,lambda=
infinity);
EQ4:=-residue(CompatibilityEquations[1,2]/lambda^2,lambda=
infinity);
EQ5:=-residue(CompatibilityEquations[1,2]/lambda^1,lambda=
infinity);

```

$$EQ1 := \frac{1}{Qinfy_0^2} \left(-2 \, t00 \, Pinfty_0 \, Qinfy_0^2 \, Qinfy_1 \, v_0 - 2 \, t00 \, Pinfty_0 \, Qinfy_0^2 \, v_1 - 2 \, t00 \, Pinfty_1 \right.$$

$$\left. Qinfy_0^2 \, v_0 + t00 \, Qinfy_0 \, Qinfy_1 \, v_0 - t00 \, LQinfy_0 \, Qinfy_0 + t00 \, Qinfy_0 \, v_1 \right)$$

$$EQ2 := \frac{1}{Qinfy_0^2} \left(\left(\left(4 \, Qinfy_1 \, t_3^2 - 4 \, t_2 \, t_3 \right) v_0 - 2 \, t_3^2 \, v_1 \right) Qinfy_0^3 + \left(\left(-Qinfy_1^3 \, t_3^2 + 2 \, t_2 \, Qinfy_1^2 \, t_3 \right. \right. \right.$$

$$\left. \left. + \left(-Pinfty_0^2 - 2 \, t_1 \, t_3 - t_2^2 \right) Qinfy_1 - 2 \, Pinfty_0 \, Pinfty_1 + 2 \, t_3 \, t_0 + 2 \, t_2 \, t_1 \right) v_0 + 3 \, Qinfy_1^2 \, t_3^2 \, v_1 \right.$$

$$\left. - 4 \, t_2 \, t_3 \, v_1 \, Qinfy_1 + \left(-Pinfty_0^2 + 2 \, t_1 \, t_3 + t_2^2 \right) v_1 + LPinfy_0 \right) Qinfy_0^2 - t00 \left(Qinfy_1 \, v_0 \right.$$

$$\left. + v_1 \right) \left(-1 + t00 \right)$$

$$EQ3 := \frac{1}{Qinfy_0^2} \left(2 \, v_0 \, t_3^2 \, Qinfy_0^4 + \left(\left(Qinfy_1^2 \, t_3^2 + Pinfty_0^2 - 2 \, t_1 \, t_3 - t_2^2 \right) v_0 + 4 \, t_3 \, v_1 \left(t_3 \, Qinfy_1 \right. \right. \right.$$

$$\left. \left. - t_2 \right) Qinfy_0^3 + \left(\left(-Qinfy_1^4 \, t_3^2 + 2 \, Qinfy_1^3 \, t_2 \, t_3 + \left(-Pinfty_0^2 - 2 \, t_1 \, t_3 - t_2^2 \right) Qinfy_1^2 + \left(\right. \right. \right.$$

$$\left. \left. - 2 \, Pinfty_0 \, Pinfty_1 + 2 \, t_3 \, t_0 + 2 \, t_2 \, t_1 \right) Qinfy_1 - 2 \, t00 \, Pinfty_0 - Pinfty_0 \right) v_0 - Qinfy_1^3 \, t_3^2 \, v_1 + 2$$

$$Qinfy_1^2 t_2 t_3 v_1 + \left((-Pinfty_0^2 - 2 t_1 t_3 - t_2^2) v_1 + LPinfty_0 \right) Qinfy_1 + (-2 Pinfty_0 Pinfty_1 + 2 t_3 t_0 + 2 t_2 t_1) v_1 + LQinfy_1 Pinfty_0 + LPinfty_1 \Big) Qinfy_0^2 + \left((t00 + 1) v_0 + 2 Pinfty_1 v_1 - LQinfy_1 \right) t00 Qinfy_0 - t00 Qinfy_1 \left(Qinfy_1 v_0 + v_1 \right) (-1 + t00) \Big)$$

$$EQ4 := t_3 \left((2 Pinfty_0 Qinfy_0 - 2) v_0 - 2 Pinfty_1 v_1 + LQinfy_1 \right)$$

$$EQ5 := t_3 \left(\left((2 Pinfty_0 Qinfy_1 + 2 Pinfty_1) Qinfy_0 - Qinfy_1 \right) v_0 + 2 Pinfty_0 Qinfy_0 v_1 - v_1 + LQinfy_0 \right) \quad (8)$$

```
> LQinfy[0]:=factor(solve(EQ1,LQinfy[0])) ;
LQinfy[1]:=factor(solve(EQ4,LQinfy[1])) ;
LPinfy[0]:=factor(solve(EQ2,LPinfy[0])) ;
LPinfy[1]:=factor(solve(EQ3,LPinfy[1])) ;
EQ1:=simplify(EQ1) ;
EQ2:=simplify(EQ2) ;
EQ3:=simplify(EQ3) ;
EQ4:=simplify(EQ4) ;
EQ5:=simplify(EQ5) ;
```

$$LQinfy_0 := -2 Pinfty_0 Qinfy_0 Qinfy_1 v_0 - 2 Pinfty_0 Qinfy_0 v_1 - 2 Pinfty_1 Qinfy_0 v_0 + Qinfy_1 v_0 + v_1$$

$$LQinfy_1 := -2 Pinfty_0 Qinfy_0 v_0 + 2 Pinfty_1 v_1 + 2 v_0$$

$$LPinfy_0 := \frac{1}{Qinfy_0^2} \left(Qinfy_0^2 Qinfy_1^3 v_0 t_3^2 - 4 Qinfy_0^3 Qinfy_1 v_0 t_3^2 - 2 Qinfy_0^2 Qinfy_1^2 v_0 t_2 t_3 - 3 Qinfy_0^2 Qinfy_1^2 v_1 t_3^2 + Pinfty_0^2 Qinfy_0^2 Qinfy_1 v_0 + 4 Qinfy_0^3 v_0 t_2 t_3 + 2 Qinfy_0^3 v_1 t_3^2 + 2 Qinfy_0^2 Qinfy_1 v_0 t_1 t_3 + Qinfy_0^2 Qinfy_1 v_0 t_2^2 + 4 Qinfy_0^2 Qinfy_1 v_1 t_2 t_3 + Pinfty_0^2 Qinfy_0^2 v_1 + 2 Pinfty_0 Pinfty_1 Qinfy_0^2 v_0 - 2 Qinfy_0^2 v_0 t_0 t_3 - 2 Qinfy_0^2 v_0 t_1 t_2 - 2 Qinfy_0^2 v_1 t_1 t_3 - Qinfy_0^2 v_1 t_2^2 + t00^2 Qinfy_1 v_0 + t00^2 v_1 - t00 Qinfy_1 v_0 - t00 v_1 \right)$$

$$LPinfy_1 := -\frac{1}{Qinfy_0} \left(-3 Qinfy_0^2 Qinfy_1^2 v_0 t_3^2 - 4 Qinfy_0 Qinfy_1^3 v_1 t_3^2 + 2 t_3^2 Qinfy_0^3 v_0 + 4 Qinfy_0^2 Qinfy_1 v_0 t_2 t_3 + 6 Qinfy_0^2 Qinfy_1 v_1 t_3^2 + 6 Qinfy_0 Qinfy_1^2 v_1 t_2 t_3 - Pinfty_0^2 Qinfy_0^2 v_0 - 2 Qinfy_0^2 v_0 t_1 t_3 - Qinfy_0^2 v_0 t_2^2 - 4 Qinfy_0^2 v_1 t_2 t_3 - 4 Qinfy_0 Qinfy_1 v_1 t_1 t_3 - 2 Qinfy_0 Qinfy_1 v_1 t_2^2 + 2 Qinfy_0 v_1 t_0 t_3 + 2 Qinfy_0 v_1 t_1 t_2 + t00^2 v_0 + Pinfty_0 Qinfy_0 v_0 - t00 v_0 \right)$$

$$EQ1 := 0$$

$$EQ2 := 0$$

$$EQ3 := 0$$

$$EQ4 := 0$$

$$EQ5 := 0$$

(9)

```
> series(simplify(series(CompatibilityEquations[2,1],lambda=
infinity)),lambda=infinity) ;
```

$$\frac{(-4 t_3^2 v_0 + 2 \alpha_2 t_3) \lambda}{t_3} + \frac{(4 Qinfy_1 v_0 - 2 v_1) t_3^2 + (-2 Qinfy_1 \alpha_2 - 6 v_0 t_2 + 2 \alpha_1) t_3 + 2 \alpha_2 t_2}{t_3} + \frac{1}{t_3 \lambda} \left(\begin{aligned} &-4 Qinfy_1^2 v_0 + 4 Qinfy_0 v_0 + 2 Qinfy_1 v_1 \right) t_3^2 + \left(2 Qinfy_1^2 \alpha_2 + (6 v_0 t_2 - 2 \alpha_1) Qinfy_1 \right. \\ &\left. - 4 v_0 t_1 - 2 v_1 t_2 - 2 Qinfy_0 \alpha_2 \right) t_3 - 2 Qinfy_1 \alpha_2 t_2 - 2 t_2^2 v_0 + 2 \alpha_2 t_1 + 2 \alpha_1 t_2 \end{aligned} \right) \quad (10)$$

In order to solve the entry (2,1) of the compatibility equations, we need to express the nu's in terms of the vector \alpha.

```
> solve(-4*nu[0]*t[3]^2+2*alpha[2]*t[3],nu[0]);
solve(2*nu[1]*t[3]^2-2*alpha[1]*t[3]+alpha[2]*t[2],nu[1]);
```

$$\frac{\alpha_2}{2 t_3} + \frac{2 \alpha_1 t_3 - \alpha_2 t_2}{2 t_3^2} \quad (11)$$

```
> M:=Matrix(2*d,2*d,0):
for i from 1 to 2*d do for j from 1 to i do
M[i,j]:=t[2*d+1-i+j]:
od: od:
M;
alphaVector:=Matrix(2*d,1,0):
for i from 1 to 2*d do alphaVector[i,1]:=alpha[2*d-i+1]/(2*d-i+1)
: od:
alphaVector;
nuVector:=Matrix(2*d,1,0):
for i from 1 to 2*d do nuVector[i,1]:=nu[i-1]: od:
nuVector;
```

$$\begin{bmatrix} t_3 & 0 \\ t_2 & t_3 \\ \frac{\alpha_2}{2} \\ \alpha_1 \\ v_0 \\ v_1 \end{bmatrix}$$

(12)

```
> nu[0]:=alpha[2]/(2*t[3]);
nu[1]:=(2*alpha[1]*t[3]-alpha[2]*t[2])/(2*t[3]^2);
```

simplify(Multiply(M,nuVector)-alphaVector);

$$\begin{aligned} v_0 &:= \frac{\alpha_2}{2 t_3} \\ v_1 &:= \frac{2 \alpha_1 t_3 - \alpha_2 t_2}{2 t_3^2} \\ &\begin{bmatrix} 0 \\ 0 \end{bmatrix} \end{aligned} \quad (13)$$

> simplify(CompatibilityEquations);

$$\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \quad (14)$$

This verifies that the relation between nu's and alpha's is correct. We check now that the formulas for the Hamiltonians are correct.

**> H01:=simplify(residue(checkL11^2+checkL12*checkL21+checkL12*diff
(checkL11/checkL12,lambda),lambda=0));**
for j from 0 to 2*d-2 do
Hinfy[j]:=simplify(-residue(lambda^(-j-1)*(checkL11^2+checkL12*
checkL21+checkL12*diff(checkL11/checkL12,lambda)),lambda=
infinity)): od;
Hinfy[0]:=Hinfy[0];

$$\begin{aligned} H01 &:= \frac{1}{Qinfy_0} \left((2 Qinfy_1 t_3^2 - 2 t_2 t_3) Qinfy_0^3 + (-Qinfy_1^3 t_3^2 + 2 t_2 Qinfy_1^2 t_3 + (-Pinfty_0^2 \right. \\ &\quad \left. - 2 t_1 t_3 - t_2^2) Qinfy_1 - 2 Pinfty_0 Pinfty_1 + 2 t_3 t_0 + 2 t_2 t_1) Qinfy_0^2 + t00 (-1 \right. \\ &\quad \left. + t00) Qinfy_1 \right) \\ Hinfy_0 &:= \frac{1}{Qinfy_0} \left(-t_3^2 Qinfy_0^3 + (3 Qinfy_1^2 t_3^2 - 4 Qinfy_1 t_2 t_3 - Pinfty_0^2 + 2 t_1 t_3 + t_2^2) Qinfy_0^2 \right. \\ &\quad \left. + (-Qinfy_1^4 t_3^2 + 2 Qinfy_1^3 t_2 t_3 + (-2 t_1 t_3 - t_2^2) Qinfy_1^2 + (2 t_3 t_0 + 2 t_2 t_1) Qinfy_1 + \right. \\ &\quad \left. Pinfty_1^2 + Pinfty_0) Qinfy_0 + t00^2 - t00 \right) \end{aligned} \quad (15)$$

> HamGeneral:=0;
for k from 0 to 2*d-2 do HamGeneral:=HamGeneral+nu[k+1]*Hinfy[k]
: od;
HamGeneral:=HamGeneral+nu[0]*(H01+2*d*Pinfty[2*d-1]):
for k from 0 to 2*d-2 do HamGeneral:=HamGeneral+nu[0]*(k+1)*
Qinfy[k+1]*Pinfty[k]: od;
HamGeneral:=simplify(HamGeneral);

$$\begin{aligned} HamGeneral &:= \frac{1}{2 Qinfy_0 t_3^2} \left(\left((2 Qinfy_1 \alpha_2 - 2 \alpha_1) t_3^3 - t_2 \alpha_2 t_3^2 \right) Qinfy_0^3 + \left((-Qinfy_1^3 \alpha_2 \right. \right. \\ &\quad \left. \left. + 6 Qinfy_1^2 \alpha_1) t_3^3 + \left((-Qinfy_1^2 t_2 - 2 t_1 Qinfy_1 + 2 t_0) \alpha_2 - 8 \alpha_1 \left(t_2 Qinfy_1 - \frac{t_1}{2} \right) \right) t_3^2 \right. \right. \end{aligned} \quad (16)$$

$$\begin{aligned}
& + \left(\left(-Pinfty_0^2 + 3 t_2^2 \right) Qinfy_1 - 2 Pinfty_0 Pinfty_1 \right) \alpha_2 + 2 t_2^2 \alpha_1 - 2 Pinfty_0^2 \alpha_1 \Big) t_3 + \left(\right. \\
& Pinfty_0^2 t_2 - t_2^3 \Big) \alpha_2 \Big) Qinfy_0^2 + \left(-2 Qinfy_1^4 \alpha_1 t_3^3 + \left(Qinfy_1^3 t_2 \alpha_2 + 4 \alpha_1 \left(Qinfy_1^2 t_2 \right. \right. \right. \\
& \left. \left. \left. - t_1 Qinfy_1 + t_0 \right) \right) Qinfy_1 t_3^2 + \left(\left(-2 Qinfy_1^3 t_2^2 + 2 Qinfy_1^2 t_1 t_2 + \left(-2 t_0 t_2 \right. \right. \right. \right. \\
& \left. \left. \left. + Pinfty_0 \right) Qinfy_1 + 2 Pinfty_1 \right) \alpha_2 + 2 \alpha_1 \left(-Qinfy_1^2 t_2^2 + 2 Qinfy_1 t_1 t_2 + Pinfty_1^2 \right. \right. \\
& \left. \left. \left. + Pinfty_0 \right) \right) t_3 - t_2 \alpha_2 \left(-Qinfy_1^2 t_2^2 + 2 Qinfy_1 t_1 t_2 + Pinfty_1^2 + Pinfty_0 \right) \right) Qinfy_0 \\
& + i00 \left(\left(Qinfy_1 \alpha_2 + 2 \alpha_1 \right) t_3 - \alpha_2 t_2 \right) \left(-1 + i00 \right)
\end{aligned}$$

```

> simplify(LQinfy[0]-diff(HamGeneral,Pinfty[0]));
simplify(LQinfy[1]-diff(HamGeneral,Pinfty[1]));
simplify(LPinfty[0]+diff(HamGeneral,Qinfy[0]));
simplify(LPinfty[1]+diff(HamGeneral,Qinfy[1]));

```

0
0
0
0

(17)

```

> HamGeneralFunction:=unapply(HamGeneral,alpha[1],alpha[2]):
Hamt1:=simplify(HamGeneralFunction(1,0));
Hamt2:=simplify(HamGeneralFunction(0,1));
VectorHam:=Matrix(2*d,1,0):
VectorHam[1,1]:=1*Hamt1:
VectorHam[2,1]:=2*Hamt2:
HVector:=Matrix(2*d,1,0):
for k from 1 to 2*d-1 do
HVector[k,1]:=Hinfy[2*d-1-k]: od:
HVector[2*d,1]:=H01+2*d*Pinfty[2*d-1]:
for k from 0 to 2*d-2 do HVector[2*d,1]:=HVector[2*d,1]+(k+1)*
Qinfy[k+1]*Pinfty[k]: od:
HVector[2*d,1]:=simplify(HVector[2*d,1]):

simplify(VectorHam-Multiply(M^(-1),HVector));

```

$$Hamt1 := \frac{1}{t_3 Qinfy_0} \left(-t_3^2 Qinfy_0^3 + \left(3 Qinfy_1^2 t_3^2 + \left(-4 t_2 Qinfy_1 + 2 t_1 \right) t_3 + t_2^2 - Pinfty_0^2 \right) \right.$$

$$\begin{aligned}
& Qinfy_0^2 + \left(-Qinfy_1^4 t_3^2 + 2 Qinfy_1 \left(Qinfy_1^2 t_2 - t_1 Qinfy_1 + t_0 \right) t_3 - Qinfy_1^2 t_2^2 \right. \\
& \left. + 2 Qinfy_1 t_1 t_2 + Pinfty_1^2 + Pinfty_0 \right) Qinfy_0 + i00^2 - i00 \Big)
\end{aligned}$$

$$\begin{aligned}
Hamt2 := \frac{1}{2 Qinfy_0 t_3^2} & \left(\left(2 Qinfy_1 t_3^3 - t_2 t_3^2 \right) Qinfy_0^3 + \left(-Qinfy_1^3 t_3^3 + \left(-Qinfy_1^2 t_2 \right. \right. \right. \\
& \left. \left. \left. - 2 t_1 Qinfy_1 + 2 t_0 \right) t_3^2 + \left(\left(-Pinfty_0^2 + 3 t_2^2 \right) Qinfy_1 - 2 Pinfty_0 Pinfty_1 \right) t_3 + Pinfty_0^2 t_2 - \right. \right. \\
& \left. \left. t_2^3 \right) Qinfy_0^2 + \left(Qinfy_1^4 t_2 t_3^2 + \left(-2 Qinfy_1^3 t_2^2 + 2 Qinfy_1^2 t_1 t_2 + \left(-2 t_0 t_2 + Pinfty_0 \right) Qinfy_1 \right. \right. \right.
\end{aligned}$$

$$\begin{aligned}
& + 2 \text{Pinfty}_1) t_3 + t_2^3 \text{Qinfty}_1^2 - 2 t_1 t_2^2 \text{Qinfty}_1 - t_2 (\text{Pinfty}_1^2 + \text{Pinfty}_0) \text{Qinfty}_0 - t00 (-t_3 \text{Qinfty}_1 + t_2) (-1 + t00) \Big) \text{Qinfty}_0 - t00 \Big(\\
& \left[\begin{array}{c} 0 \\ 0 \end{array} \right]
\end{aligned} \tag{18}$$

```

> series(checkL12,lambda);
series(checkL11,lambda);
series(checkL21,lambda);
expand(simplify(residue(checkL21,lambda=0)));

```

$$\begin{aligned}
& -\text{Qinfty}_0 t_3 - t_3 \text{Qinfty}_1 \lambda - t_3 \lambda^2 \\
& t00 \lambda^{-1} + -\text{Pinfty}_1 - \text{Pinfty}_0 \text{Qinfty}_1 + \frac{t00 \text{Qinfty}_1}{\text{Qinfty}_0} + \left(\frac{t00}{\text{Qinfty}_0} - \text{Pinfty}_0 \right) \lambda \\
& t_3 \text{Qinfty}_1^3 - 2 \text{Qinfty}_0 t_3 \text{Qinfty}_1 - 2 \text{Qinfty}_1^2 t_2 + \frac{\text{Pinfty}_0^2 \text{Qinfty}_1}{t_3} + 2 \text{Qinfty}_0 t_2 + 2 t_1 \text{Qinfty}_1 \\
& + \frac{t_2^2 \text{Qinfty}_1}{t_3} - \frac{2 t00 \text{Pinfty}_0 \text{Qinfty}_1}{\text{Qinfty}_0 t_3} + \frac{2 \text{Pinfty}_0 \text{Pinfty}_1}{t_3} - 2 t_0 - \frac{2 t_2 t_1}{t_3} + \frac{t00^2 \text{Qinfty}_1}{\text{Qinfty}_0^2 t_3} \\
& - \frac{2 t00 \text{Pinfty}_1}{\text{Qinfty}_0 t_3}
\end{aligned} \tag{19}$$

```

> solve({nu0 = alpha[2]/(2*t[3]) , nu1 = (2*alpha[1]*t[3]-alpha[2]*
t[2])/(2*t[3]^2)}, {alpha[1],alpha[2]});
alpha[1] := nu0*t[2]+nu1*t[3];
alpha[2] := 2*nu0*t[3];
simplify(nu[0]-nu0);
simplify(nu[1]-nu1);
checkA12:=simplify(checkA12);
checkA11:=simplify(checkA11);
checkA21:=simplify(checkA21);
series(checkA12,lambda);
expand(series(checkA11,lambda));
expand(series(checkA21,lambda));

```

```

simplify(residue(checkA21,lambda=0));

```

$$\begin{aligned}
& \{ \alpha_1 = \nu0 t_2 + \nu1 t_3, \alpha_2 = 2 \nu0 t_3 \} \\
& \alpha_1 := \nu0 t_2 + \nu1 t_3 \\
& \alpha_2 := 2 \nu0 t_3 \\
& 0 \\
& 0 \\
& -(\nu0 \text{Qinfty}_1 + \nu1) t_3 \lambda - \nu0 t_3 \lambda^2
\end{aligned}$$

$$\begin{aligned}
& -\nu_0 \text{Pinfty}_0 \text{Qinfty}_1 + \frac{\nu_0 t_{00} \text{Qinfty}_1}{\text{Qinfty}_0} - \nu_0 \text{Pinfty}_1 - \nu_l \text{Pinfty}_0 + \frac{\nu_l t_{00}}{\text{Qinfty}_0} + \left(-\text{Pinfty}_0 \nu_0 \right. \\
& \quad \left. + \frac{\nu_0 t_{00}}{\text{Qinfty}_0} \right) \lambda \\
& -t_3 \nu_0 \text{Qinfty}_1^2 + 2 \text{Qinfty}_0 t_3 \nu_0 + 2 \nu_0 \text{Qinfty}_1 t_2 + 2 t_3 \nu_l \text{Qinfty}_1 + \frac{\nu_0 \text{Pinfty}_0^2}{t_3} - 2 \nu_0 t_1 \\
& \quad - \frac{\nu_0 t_2^2}{t_3} - 2 \nu_l t_2 - \frac{2 \nu_0 t_{00} \text{Pinfty}_0}{\text{Qinfty}_0 t_3} + \frac{\nu_0 t_{00}^2}{\text{Qinfty}_0^2 t_3} + \left(\text{Qinfty}_1 \nu_0 t_3 - 2 \nu_0 t_2 - \nu_l t_3 \right) \lambda \\
& \quad - \nu_0 t_3 \lambda^2 \\
& \quad \quad \quad 0
\end{aligned} \tag{20}$$

$$\begin{aligned}
& \text{> expand(series(Hinfty[0],Qinfty[0])) ;} \\
& (t_{00}^2 - t_{00}) \text{Qinfty}_0^{-1} + -\text{Qinfty}_1^4 t_3^2 + 2 \text{Qinfty}_1^3 t_2 t_3 - 2 \text{Qinfty}_1^2 t_1 t_3 - \text{Qinfty}_1^2 t_2^2 \\
& \quad + 2 \text{Qinfty}_1 t_0 t_3 + 2 \text{Qinfty}_1 t_1 t_2 + \text{Pinfty}_1^2 + \text{Pinfty}_0 + \left(3 \text{Qinfty}_1^2 t_3^2 - 4 \text{Qinfty}_1 t_2 t_3 - \text{Pinfty}_0^2 \right. \\
& \quad \left. + 2 t_1 t_3 + t_2^2 \right) \text{Qinfty}_0 - t_3^2 \text{Qinfty}_0^2
\end{aligned} \tag{21}$$

$$\begin{aligned}
& \text{> expand(series(H01,Qinfty[0])) ;} \\
& (t_{00}^2 \text{Qinfty}_1 - t_{00} \text{Qinfty}_1) \text{Qinfty}_0^{-1} + \left(-\text{Qinfty}_1^3 t_3^2 + 2 t_2 \text{Qinfty}_1^2 t_3 - \text{Pinfty}_0^2 \text{Qinfty}_1 \right. \\
& \quad - 2 \text{Qinfty}_1 t_1 t_3 - \text{Qinfty}_1 t_2^2 - 2 \text{Pinfty}_0 \text{Pinfty}_1 + 2 t_3 t_0 + 2 t_2 t_1 \left. \right) \text{Qinfty}_0 + \left(2 \text{Qinfty}_1 t_3^2 \right. \\
& \quad \left. - 2 t_2 t_3 \right) \text{Qinfty}_0^2
\end{aligned} \tag{22}$$