

```

> restart:
with(LinearAlgebra):
d:=2;

```

$$d := 2$$

(1)

We define the Lax matrix using Theorem 4.1

```

> checkLRed12:=-t[2*d+1]*lambda^(2*d):
for k from 0 to d-1 do checkLRed12:=checkLRed12-t[2*d+1]*Qinfy
[2*k]*lambda^(2*k): od:
checkLRed12:=checkLRed12;

```

$$checkLRed12 := -t_5 \lambda^4 - t_5 Qinfy_2 \lambda^2 - t_5 Qinfy_0$$

(2)

```

> checkLRed11:=t00/lambda+t00/Qinfy[0]*lambda^(2*d-1):
for k from 1 to d do checkLRed11:=checkLRed11-Pinfy[2*d-2*k]*
lambda^(2*k-1): od:
for k from 1 to d-1 do for m from 0 to d-1-k do checkLRed11:=
checkLRed11-Pinfy[2*m]*Qinfy[2*k+2*m]*lambda^(2*k-1): od: od:
for k from 1 to d-1 do checkLRed11:=checkLRed11+t00/Qinfy[0]*
Qinfy[2*k]*lambda^(2*k-1): od:
checkLRed11:=checkLRed11;

```

```
checkLRed22:=-checkLRed11:
```

$$checkLRed11 := \frac{t00}{\lambda} + \frac{t00 \lambda^3}{Qinfy_0} - Pinfy_2 \lambda - Pinfy_0 \lambda^3 - Pinfy_0 Qinfy_2 \lambda + \frac{t00 Qinfy_2 \lambda}{Qinfy_0}$$

(3)

```

> NumcheckLRed21poleinfinity:=-checkLRed11^2/checkLRed12:
for j from d to 2*d do for m from 0 to 2*d-j do
NumcheckLRed21poleinfinity:=NumcheckLRed21poleinfinity+t[2*d+1-2*
m]*t[2*j+2*m-2*d+1]*lambda^(2*j)/checkLRed12: od: od:
checkLRed21poleinfinity:=0:
for i from 1 to 100 do checkLRed21poleinfinity:=
checkLRed21poleinfinity-(residue(NumcheckLRed21poleinfinity*
lambda^(-i),lambda=infinity))*lambda^(i-1): od:

```

```
checkLRed21:=checkLRed21poleinfinity;
```

$$checkLRed21 := \frac{1}{t_5} \left(2 \left(\frac{t00}{Qinfy_0} - Pinfy_0 \right) \left(-Pinfy_2 - Pinfy_0 Qinfy_2 + \frac{t00 Qinfy_2}{Qinfy_0} \right) - \frac{(-Pinfy_0 Qinfy_0 + t00)^2 Qinfy_2}{Qinfy_0^2} \right) - 2 t_1 - \frac{t_3^2}{t_5} + 2 t_3 Qinfy_2 - \frac{t_5^2 Qinfy_2^2 - t_5^2 Qinfy_0}{t_5} - \left(- \frac{\left(\frac{t00}{Qinfy_0} - Pinfy_0 \right)^2}{t_5} + 2 t_3 - t_5 Qinfy_2 \right) \lambda^2 - t_5 \lambda^4$$

(4)

```

> checkLRedMatrix:=Matrix(2,2,0):
checkLRedMatrix[1,1]:=checkLRed11:
checkLRedMatrix[1,2]:=checkLRed12:
checkLRedMatrix[2,1]:=checkLRed21:
checkLRedMatrix[2,2]:=checkLRed22:
checkLRedMatrix:

```

We define the general auxiliary matrix using Theorem 4.1

```

> checkARed12:=0:
for i from 0 to d-1 do checkARed12:=checkARed12-t[2*d+1]*nu[2*
i+1]*lambda^(2*d-2*i-1): od:
for k from 1 to d-1 do for i from 0 to k-1 do checkARed12:=
checkARed12-t[2*d+1]*nu[2*i+1]*Qinfty[2*k]*lambda^(2*k-2*i-1):
od: od:
checkARed12;

nu[2*d]:=simplify(-residue(lambda^(2*d-1)*checkARed12/checkL12,
lambda=infinity));

```

$$\begin{aligned}
& -t_5 v_1 \lambda^3 - t_5 v_1 Q_{infty_2} \lambda - t_5 v_3 \lambda \\
& v_4 := 0
\end{aligned}$$

(5)

```

> checkARed11:=0:
NumcheckARed11:=0:
for i from 0 to d-1 do NumcheckARed11:=NumcheckARed11+ nu[2*i+1]*
lambda^(-2*i-1)*checkLRed11: od:
for i from 1 to 100 do checkARed11:=checkARed11-(residue
(NumcheckARed11*lambda^(-i),lambda=infinity))*lambda^(i-1): od:
checkARed11;

```

```
checkARed22:=-checkARed11:
```

$$\begin{aligned}
v_1 \left(-Pinfty_2 - Pinfty_0 Q_{infty_2} + \frac{t00 Q_{infty_2}}{Q_{infty_0}} \right) + v_3 \left(\frac{t00}{Q_{infty_0}} - Pinfty_0 \right) + v_1 \left(\frac{t00}{Q_{infty_0}} \right. \\
\left. - Pinfty_0 \right) \lambda^2
\end{aligned}$$

(6)

```

> checkARed21:=(-t00)/t[2*d+1]/(Qinfty[0])^2*LQinfty[0]/lambda:
QuantitycheckARed21:=checkLRed11/checkLRed12*
(checkLRed11/checkLRed12*checkARed12-2*checkARed11):
for i from 1 to 100 do checkARed21:=checkARed21-(residue
(QuantitycheckARed21*lambda^(-i),lambda=infinity))*lambda^(i-1):
od:
for i from 0 to 100 do checkARed21:=checkARed21+(residue
(QuantitycheckARed21*lambda^(i),lambda=0))*lambda^(-i-1): od:

```

```
AdditionalTermRed:=t00*(1-t00)/t[2*d+1]/Qinfy[0]^2/lambda*nu[2*
d-1]:
```

```
for k from 1 to d-1 do AdditionalTermRed:=AdditionalTermRed+t00*
(1-t00)/t[2*d+1]/Qinfy[0]^2/lambda*nu[2*k-1]*Qinfy[2*k]: od:
```

```
checkARed21:=checkARed21+AdditionalTermRed:
```

```
NumcheckARed21:=0:
```

```
for k from d to 2*d-1 do for j from k+1 to 2*d do for m from 0 to
2*d-j do NumcheckARed21:=NumcheckARed21- t[2*d+1-2*m]*t[2*j+2*
m-2*d+1]*nu[2*j-2*k-1]*lambda^(2*k+1): od: od: od:
```

```
for i from 1 to 100 do checkARed21:=checkARed21-(residue
(NumcheckARed21/(-checkLRed12)*lambda^(-i),lambda=infinity))*
lambda^(i-1): od:
```

```
checkARed21:=checkARed21:
```

```
series(checkARed21,lambda=infinity);
```

$$-t_5 v_1 \lambda^3 + \left(\frac{\left(\frac{t00}{Qinfy_0} - Pinfty_0 \right)^2 v_1}{t_5} + \frac{t_5^2 v_1 Qinfy_2 - 2 t_5 t_3 v_1 - t_5^2 v_3}{t_5} \right) \lambda + \frac{1}{\lambda} \left(\begin{aligned} & -\frac{t00 LQinfy_0}{t_5 Qinfy_0^2} + \frac{1}{Qinfy_0^4 t_5} \left(-2 t00 Pinfty_0 Qinfy_0^3 Qinfy_2 v_1 + t00^2 Qinfy_0^2 Qinfy_2 v_1 \right. \\ & \left. - 2 t00 Pinfty_0 Qinfy_0^3 v_3 - 2 t00 Pinfty_2 Qinfy_0^3 v_1 + t00^2 Qinfy_0^2 v_3 \right) + \frac{t00 (1 - t00) v_3}{t_5 Qinfy_0^2} \\ & \left. + \frac{t00 (1 - t00) v_1 Qinfy_2}{t_5 Qinfy_0^2} \right) \end{aligned} \right) \quad (7)$$

```
> checkARedMatrix:=Matrix(2,2,0):
```

```
checkARedMatrix[1,1]:=checkARed11:
```

```
checkARedMatrix[1,2]:=checkARed12:
```

```
checkARedMatrix[2,1]:=checkARed21:
```

```
checkARedMatrix[2,2]:=checkARed22:
```

```
checkARedMatrix:
```

We define the derivatives of the Lax matrices. The derivative relatively to times and Darboux coordinates is specific to d=2 and should be adapted for other values of d.

```
> dcheckARedMatrixdlambda:=Matrix(2,2,0):
```

```
for i from 1 to 2 do for j from 1 to 2 do dcheckARedMatrixdlambda
[i,j]:=diff(checkARedMatrix[i,j],lambda): od: od:
```

```
> LcheckLRedMatrix:=Matrix(2,2,0):
```

```
for i from 1 to 2 do for j from 1 to 2 do
```

```
LcheckLRedMatrix[i,j]:=diff(checkLRedMatrix[i,j],t[3])*alpha[3]+
diff(checkLRedMatrix[i,j],t[1])*alpha[1]+diff(checkLRedMatrix[i,
j],Qinfy[0])*LQinfy[0]+diff(checkLRedMatrix[i,j],Qinfy[2])*
LQinfy[2]+diff(checkLRedMatrix[i,j],Pinfty[0])*LPinfy[0]+ diff
```

```
(checkLRedMatrix[i,j],Pinfty[2])*LPinfty[2] od: od:
```

We define the compatibility equations and solve them. This is the main test for the formulas of Theorem 4.1. This part is again specific to d=2 and should be adapted for other values of d

```
> CompatibilityEquations:=simplify( dcheckARedMatrixdlambda-
LcheckLRedMatrix+Multiply(checkARedMatrix,checkLRedMatrix)-
Multiply(checkLRedMatrix,checkARedMatrix) ):
> simplify(series(CompatibilityEquations[1,1],lambda=0)):
series(simplify(series(CompatibilityEquations[1,1],lambda=
infinity)),lambda=infinity):
series(simplify(series(CompatibilityEquations[1,2],lambda=
infinity)),lambda=infinity):
series(simplify(series(CompatibilityEquations[2,1],lambda=
infinity)),lambda=infinity):
simplify(residue(CompatibilityEquations[1,1]*lambda,lambda=0));
EQ1:=simplify(residue(CompatibilityEquations[1,1],lambda=0));

simplify(-residue(CompatibilityEquations[1,1]/lambda^5,lambda=
infinity));
EQ2:=-residue(CompatibilityEquations[1,1]/lambda^4,lambda=
infinity);
EQ3:=-residue(CompatibilityEquations[1,1]/lambda^3,lambda=
infinity);
EQ4:=-residue(CompatibilityEquations[1,1]/lambda^2,lambda=
infinity);
EQ5:=-residue(CompatibilityEquations[1,1]/lambda^1,lambda=
infinity);

simplify(-residue(CompatibilityEquations[1,2]/lambda^5,lambda=
infinity));
EQ6:=-residue(CompatibilityEquations[1,2]/lambda^4,lambda=
infinity);
EQ7:=-residue(CompatibilityEquations[1,2]/lambda^3,lambda=
infinity);
EQ8:=-residue(CompatibilityEquations[1,2]/lambda^2,lambda=
infinity);
EQ9:=-residue(CompatibilityEquations[1,2]/lambda^1,lambda=
infinity);
```

0

$$EQ1 := -\frac{1}{Q_{\infty} y_0} \left(t_{00} \left(2 P_{\infty} y_0 Q_{\infty} y_0 Q_{\infty} y_2 v_1 + 2 P_{\infty} y_0 Q_{\infty} y_0 v_3 + 2 P_{\infty} y_2 Q_{\infty} y_0 v_1 \right. \right. \\ \left. \left. - Q_{\infty} y_2 v_1 + L Q_{\infty} y_0 - v_3 \right) \right)$$

0

$$EQ2 := \frac{1}{Qinfy_0^2} \left(-2 t_5^2 v_1 Qinfy_0^3 + \left(t_5^2 Qinfy_2^2 + \left(-Pinfty_0^2 - 2 t_5 t_3 \right) Qinfy_2 \right. \right. \\ \left. \left. - 2 Pinfty_2 Pinfty_0 + 2 t_5 t_1 + t_3^2 \right) v_1 - 2 Qinfy_2 t_5^2 v_3 + \left(-Pinfty_0^2 + 2 t_5 t_3 \right) v_3 + LPinfty_0 \right) \\ Qinfy_0^2 - t00 \left(Qinfy_2 v_1 + v_3 \right) \left(-1 + t00 \right)$$

$$EQ3 := 0$$

$$EQ4 := \frac{1}{Qinfy_0^2} \left(\left(\left(Pinfty_0^2 - 2 t_5 t_3 \right) v_1 - 2 t_5^2 v_3 \right) Qinfy_0^3 + \left(\left(Qinfy_2^3 t_5^2 + \left(-Pinfty_0^2 \right. \right. \right. \right. \\ \left. \left. - 2 t_5 t_3 \right) Qinfy_2^2 + \left(-2 Pinfty_2 Pinfty_0 + 2 t_5 t_1 + t_3^2 \right) Qinfy_2 - 2 Pinfty_0 \left(t00 + 1 \right) \right) v_1 + \\ Qinfy_2^2 t_5^2 v_3 + \left(\left(-Pinfty_0^2 - 2 t_5 t_3 \right) v_3 + LPinfty_0 \right) Qinfy_2 + \left(-2 Pinfty_2 Pinfty_0 + 2 t_5 t_1 + \right. \\ \left. t_3^2 \right) v_3 + LQinfy_2 Pinfty_0 + LPinfty_2 \right) Qinfy_0^2 + t00 \left(\left(t00 + 2 \right) v_1 + 2 Pinfty_2 v_3 \right. \\ \left. - LQinfy_2 \right) Qinfy_0 - t00 Qinfy_2 \left(Qinfy_2 v_1 + v_3 \right) \left(-1 + t00 \right)$$

$$EQ5 := 0$$

0

$$EQ6 := 0$$

$$EQ7 := t_5 \left(\left(2 Pinfty_0 Qinfy_0 - 3 \right) v_1 - 2 Pinfty_2 v_3 + LQinfy_2 \right)$$

$$EQ8 := 0$$

$$EQ9 := t_5 \left(\left(\left(2 Pinfty_0 Qinfy_2 + 2 Pinfty_2 \right) Qinfy_0 - Qinfy_2 \right) v_1 + 2 Pinfty_0 Qinfy_0 v_3 - v_3 \right. \\ \left. + LQinfy_0 \right)$$

(8)

```

> LQinfy[2]:=factor(solve(EQ7,LQinfy[2]));
LQinfy[0]:=factor(solve(EQ9,LQinfy[0]));
LPinfy[0]:=factor(solve(EQ2,LPinfy[0]));
LPinfy[2]:=factor(solve(EQ4,LPinfy[2]));
EQ1:=simplify(EQ1);
EQ2:=simplify(EQ2);
EQ3:=simplify(EQ3);
EQ4:=simplify(EQ4);
EQ5:=simplify(EQ5);
EQ6:=simplify(EQ6);
EQ7:=simplify(EQ7);
EQ8:=simplify(EQ8);
EQ9:=simplify(EQ9);

```

$$LQinfy_2 := -2 Pinfty_0 Qinfy_0 v_1 + 2 Pinfty_2 v_3 + 3 v_1$$

$$LQinfy_0 := -2 Pinfty_0 Qinfy_0 Qinfy_2 v_1 - 2 Pinfty_0 Qinfy_0 v_3 - 2 Pinfty_2 Qinfy_0 v_1 + Qinfy_2 v_1 \\ + v_3$$

$$LPinfty_0 := \frac{1}{Qinfy_0^2} \left(-Qinfy_0^2 Qinfy_2^2 v_1 t_5^2 + Pinfty_0^2 Qinfy_0^2 Qinfy_2 v_1 + 2 t_5^2 v_1 Qinfy_0^3 + 2 \right. \\ Qinfy_0^2 Qinfy_2 v_1 t_3 t_5 + 2 Qinfy_0^2 Qinfy_2 v_3 t_5^2 + Pinfty_0^2 Qinfy_0^2 v_3 + 2 Pinfty_0 Pinfty_2 \\ Qinfy_0^2 v_1 - 2 Qinfy_0^2 v_1 t_1 t_5 - Qinfy_0^2 v_1 t_3^2 - 2 Qinfy_0^2 v_3 t_3 t_5 + t00^2 Qinfy_2 v_1 + t00^2 v_3 \left. \right)$$

$$\begin{aligned}
& -t_{00} Q_{\infty y_2} v_1 - t_{00} v_3) \\
LP_{\infty y_2} := & -\frac{1}{Q_{\infty y_0}} \left(2 Q_{\infty y_0}^2 Q_{\infty y_2} v_1 t_5^2 + 3 Q_{\infty y_0} Q_{\infty y_2}^2 v_3 t_5^2 - P_{\infty y_0}^2 Q_{\infty y_0}^2 v_1 - 2 \right. \\
& Q_{\infty y_0}^2 v_1 t_3 t_5 - 2 Q_{\infty y_0}^2 v_3 t_5^2 - 4 Q_{\infty y_0} Q_{\infty y_2} v_3 t_3 t_5 + 2 Q_{\infty y_0} v_3 t_1 t_5 + Q_{\infty y_0} v_3 t_3^2 \\
& \left. + t_{00}^2 v_1 + P_{\infty y_0} Q_{\infty y_0} v_1 - t_{00} v_1 \right) \\
& EQ1 := 0 \\
& EQ2 := 0 \\
& EQ3 := 0 \\
& EQ4 := 0 \\
& EQ5 := 0 \\
& EQ6 := 0 \\
& EQ7 := 0 \\
& EQ8 := 0 \\
& EQ9 := 0
\end{aligned} \tag{9}$$

$$\begin{aligned}
& > \text{series}(\text{simplify}(\text{series}(\text{CompatibilityEquations}[2,1], \text{lambda} = \\
& \quad \text{infinity})), \text{lambda} = \text{infinity}); \\
& \frac{(-6 v_1 t_5^2 + 2 t_5 \alpha_3) \lambda^2}{t_5} \\
& + \frac{(6 Q_{\infty y_2} v_1 - 2 v_3) t_5^2 + (-2 Q_{\infty y_2} \alpha_3 - 8 v_1 t_3 + 2 \alpha_1) t_5 + 2 \alpha_3 t_3}{t_5}
\end{aligned} \tag{10}$$

In order to solve the entry (2,1) of the compatibility equations, we need to express the nu's in terms of the vector \alpha.

```

> MRed:=Matrix(d,d,0):
  for i from 1 to d do for j from 1 to i do
    MRed[i,j]:=t[2*d+1-2*i+2*j]:
  od: od:
MRed;
alphaVector:=Matrix(d,1,0):
  for i from 1 to d do alphaVector[i,1]:=alpha[2*d-2*i+1]/(2*d-2*
  i+1): od:
alphaVector;
nuVector:=Matrix(d,1,0):
  for i from 1 to d do nuVector[i,1]:=nu[2*i-1]: od:
nuVector;

```

$$\begin{bmatrix} t_5 & 0 \\ t_3 & t_5 \\ \frac{\alpha_3}{3} \\ \alpha_1 \end{bmatrix}$$

$$\begin{bmatrix} v_1 \\ v_3 \end{bmatrix} \quad (11)$$

```
> nuVectorbis:=Multiply(MRed^(-1),alphaVector);
for k from 0 to d-1 do nu[2*k+1]:=nuVectorbis[k+1,1]: od:
nu[1]:=nu[1];
nu[3]:=nu[3];
```

$$nuVectorbis := \begin{bmatrix} \frac{\alpha_3}{3 t_5} \\ -\frac{t_3 \alpha_3}{3 t_5^2} + \frac{\alpha_1}{t_5} \end{bmatrix}$$

$$v_1 := \frac{\alpha_3}{3 t_5}$$

$$v_3 := -\frac{t_3 \alpha_3}{3 t_5^2} + \frac{\alpha_1}{t_5} \quad (12)$$

```
> simplify(CompatibilityEquations);
```

$$\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \quad (13)$$

This verifies that the relation between nu's and alpha's is correct. We check now that the formulas for the Hamiltonians are correct.

```
> for j from 0 to d-1 do
Hinfty[2*j]:=simplify(-residue(lambda^(-2*j-1)*(checkLRed11^2+
checkLRed12*checkLRed21+checkLRed12*diff(checkLRed11/checkLRed12,
lambda)),lambda=infinity)): od:
Hinfty[0]:=Hinfty[0];
Hinfty[2]:=Hinfty[2];
```

$$\begin{aligned} Hinfty_0 &:= \frac{1}{Qinfty_0} \left(-Qinfty_0^3 t_5^2 + (t_5^2 Qinfty_2^2 + (-Pinfty_0^2 - 2 t_5 t_3) Qinfty_2 - 2 Pinfty_2 Pinfty_0 \right. \\ &\quad \left. + 2 t_5 t_1 + t_3^2) Qinfty_0^2 + (Pinfty_0 Qinfty_2 + 3 Pinfty_2) Qinfty_0 + t00 Qinfty_2 (-1 + t00) \right) \\ Hinfty_2 &:= \frac{1}{Qinfty_0} \left((-2 Qinfty_2 t_5^2 - Pinfty_0^2 + 2 t_5 t_3) Qinfty_0^2 + (Qinfty_2^3 t_5^2 - 2 t_3 Qinfty_2^2 t_5 \right. \\ &\quad \left. + (2 t_5 t_1 + t_3^2) Qinfty_2 + Pinfty_2^2 + Pinfty_0) Qinfty_0 + t00^2 - t00 \right) \end{aligned} \quad (14)$$

```
> HamGeneralRed:=0:
for k from 0 to d-1 do HamGeneralRed:=HamGeneralRed+nu[2*k+1]*
Hinfty[2*k]: od:
HamGeneralRed:=simplify(HamGeneralRed);
```

$$\begin{aligned}
\text{HamGeneralRed} := & \frac{1}{3 t_5^2 \text{Qinfy}_0} \left(-\text{Qinfy}_0^3 t_5^3 \alpha_3 + \left(\text{Qinfy}_2 \left(\text{Qinfy}_2 \alpha_3 - 6 \alpha_1 \right) t_5^3 + \left(6 \alpha_1 t_3 \right. \right. \right. \\
& + 2 \alpha_3 t_1 \left. \right) t_5^2 + \left(\left(-\text{Qinfy}_2 \text{Pinfy}_0^2 - 2 \text{Pinfy}_2 \text{Pinfy}_0 - t_3^2 \right) \alpha_3 - 3 \text{Pinfy}_0^2 \alpha_1 \right) t_5 + t_3 \\
& \text{Pinfy}_0^2 \alpha_3 \left. \right) \text{Qinfy}_0^2 + \left(3 \text{Qinfy}_2^3 \alpha_1 t_5^3 - \left(\text{Qinfy}_2^2 t_3 \alpha_3 + 6 \alpha_1 \left(t_3 \text{Qinfy}_2 - t_1 \right) \right) \text{Qinfy}_2 t_5^2 \right. \\
& + \left(\left(2 \text{Qinfy}_2^2 t_3^2 + \left(-2 t_1 t_3 + \text{Pinfy}_0 \right) \text{Qinfy}_2 + 3 \text{Pinfy}_2 \right) \alpha_3 + 3 \alpha_1 \left(\text{Qinfy}_2 t_3^2 + \text{Pinfy}_2^2 \right. \right. \\
& + \text{Pinfy}_0 \left. \right) \left. \right) t_5 - t_3 \alpha_3 \left(\text{Qinfy}_2 t_3^2 + \text{Pinfy}_2^2 + \text{Pinfy}_0 \right) \left. \right) \text{Qinfy}_0 + (-1 \\
& + t00) t00 \left(\left(\text{Qinfy}_2 \alpha_3 + 3 \alpha_1 \right) t_5 - \alpha_3 t_3 \right)
\end{aligned} \tag{15}$$

```

> simplify(LQinfy[0]-diff(HamGeneralRed,Pinfy[0]));
simplify(LQinfy[2]-diff(HamGeneralRed,Pinfy[2]));
simplify(LPinfy[0]+diff(HamGeneralRed,Qinfy[0]));
simplify(LPinfy[2]+diff(HamGeneralRed,Qinfy[2]));
0
0
0
0

```

```

> HamGeneralRedFunction:=unapply(HamGeneralRed,alpha[1],alpha[3]):
HamRedt1:=simplify(HamGeneralRedFunction(1,0)):
HamRedt3:=simplify(HamGeneralRedFunction(0,1)):
VectorHamRed:=Matrix(d,1,0):
VectorHamRed[1,1]:=1*HamRedt1:
VectorHamRed[2,1]:=3*HamRedt3:
VectorHamRed:
HVectorRed:=Matrix(d,1,0):
for k from 1 to d do
HVectorRed[k,1]:=Hinfy[2*d-2*k]: od:

simplify(VectorHamRed-Multiply(MRed^(-1),HVectorRed)):
0
0

```

```

> series(simplify(checkLRed11),lambda);
series(simplify(checkLRed12),lambda);
simplify(series(simplify(checkLRed21),lambda));
t00 lambda^-1 + (-Pinfy_0 Qinfy_2 - Pinfy_2) Qinfy_0 + t00 Qinfy_2
Qinfy_0 lambda + (-Pinfy_0 Qinfy_0 + t00
Qinfy_0 lambda^3
-Qinfy_0 t_5 - t_5 Qinfy_2 lambda^2 - t_5 lambda^4
1
t_5 Qinfy_0^2 (Qinfy_0^3 t_5^2 + (-t_5^2 Qinfy_2^2 + (Pinfy_0^2 + 2 t_5 t_3) Qinfy_2 + 2 Pinfy_2 Pinfy_0 - 2 t_5 t_1 -
t_3^2) Qinfy_0^2 - 2 t00 (Pinfy_0 Qinfy_2 + Pinfy_2) Qinfy_0 + t00^2 Qinfy_2)

```

$$+ \frac{(Q_{\infty y_2} t_5^2 + P_{\infty y_0}^2 - 2 t_5 t_3) Q_{\infty y_0}^2 - 2 P_{\infty y_0} t_{00} Q_{\infty y_0} + t_{00}^2}{t_5 Q_{\infty y_0}^2} \lambda^2 - t_5 \lambda^4$$

```
> solve({nu1 = alpha[3]/(3*t[5]), nu3 = -t[3]*alpha[3]/(3*t[5]^2) +
alpha[1]/t[5]}, {alpha[1], alpha[3]});
alpha[1] := nu1*t[3] + nu3*t[5];
alpha[3] := 3*nu1*t[5];
simplify(nu[1] - nu1);
simplify(nu[3] - nu3);
```

$$\{\alpha_1 = v_1 t_3 + v_3 t_5, \alpha_3 = 3 v_1 t_5\}$$

$$\alpha_1 := v_1 t_3 + v_3 t_5$$

$$\alpha_3 := 3 v_1 t_5$$

$$\begin{matrix} 0 \\ 0 \end{matrix}$$

(19)

```
> simplify(series(simplify(checkARed11), lambda=0));
simplify(series(simplify(checkARed12), lambda=0));
simplify(series(simplify(checkARed21), lambda=0));
(( -P_{\infty y_0} Q_{\infty y_2} - P_{\infty y_2}) v_1 - v_3 P_{\infty y_0}) Q_{\infty y_0} + (Q_{\infty y_2} v_1 + v_3) t_{00}
```

$$+ \frac{v_1 (-P_{\infty y_0} Q_{\infty y_0} + t_{00})}{Q_{\infty y_0}} \lambda^2$$

$$- t_5 (Q_{\infty y_2} v_1 + v_3) \lambda - v_1 t_5 \lambda^3$$

$$\frac{((Q_{\infty y_2} t_5^2 + P_{\infty y_0}^2 - 2 t_5 t_3) v_1 - v_3 t_5^2) Q_{\infty y_0}^2 - 2 v_1 t_{00} P_{\infty y_0} Q_{\infty y_0} + v_1 t_{00}^2}{t_5 Q_{\infty y_0}^2} \lambda$$

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$$- v_1 t_5 \lambda^3$$

```
> HamRedt3bis := t_{00} * (Q_{\infty y_2} * t[5] - t[3]) * (-1 + t_{00}) / (3 * t[5]^2) / Q_{\infty y_0}
[0] - (1/3) * t[5] * Q_{\infty y_0}^2 - (1/3) * Q_{\infty y_0} * (Q_{\infty y_2} * t[5] - t[3]) *
P_{\infty y_0}^2 / t[5]^2 - (1/3) * P_{\infty y_2}^2 * t[3] / t[5]^2 - (1/3) * Q_{\infty y_2}^2
^3 * t[3] + (1/3) * (Q_{\infty y_0} * t[5]^2 + 2 * t[3]^2) * Q_{\infty y_2}^2 / t[5] + (1/3) *
(-2 * P_{\infty y_0} * P_{\infty y_2} + 2 * t[1] * t[5] - t[3]^2) * Q_{\infty y_0} / t[5] +
(P_{\infty y_2}) / (t[5]) + (1/3) * (Q_{\infty y_2} * t[5] - t[3]) * P_{\infty y_0} / t[5]^2 -
Q_{\infty y_2} * t[3] * (2 * t[1] * t[5] + t[3]^2) / (3 * t[5]^2);
series(simplify(HamRedt3 - HamRedt3bis), P_{\infty y_0});
```

$$HamRedt3bis := \frac{t_{00} (t_5 Q_{\infty y_2} - t_3) (-1 + t_{00})}{3 t_5^2 Q_{\infty y_0}} - \frac{t_5 Q_{\infty y_0}^2}{3}$$

$$- \frac{Q_{\infty y_0} (t_5 Q_{\infty y_2} - t_3) P_{\infty y_0}^2}{3 t_5^2} - \frac{P_{\infty y_2}^2 t_3}{3 t_5^2} - \frac{Q_{\infty y_2}^3 t_3}{3}$$

$$\left[\begin{aligned}
& + \frac{\left(Q_{inf}t_{y_0}t_5^2 + 2t_3^2 \right) Q_{inf}t_{y_2}^2}{3t_5} + \frac{\left(-2P_{inf}t_{y_2}P_{inf}t_{y_0} + 2t_5t_1 - t_3^2 \right) Q_{inf}t_{y_0}}{3t_5} + \frac{P_{inf}t_{y_2}}{t_5} \\
& + \frac{\left(t_5Q_{inf}t_{y_2} - t_3 \right) P_{inf}t_{y_0}}{3t_5^2} - \frac{Q_{inf}t_{y_2}t_3 \left(2t_5t_1 + t_3^2 \right)}{3t_5^2} \\
& \qquad \qquad \qquad 0
\end{aligned} \right.$$

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[> ?